# Grammar-based Compression of Unranked Trees 

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Received: date / Accepted: date


#### Abstract

We introduce forest straight-line programs (FSLPs for short) as a compressed representation of unranked ordered node-labelled trees. FSLPs are based on the operations of forest algebra and generalize tree straight-line programs. We compare the succinctness of FSLPs with two other compression schemes for unranked trees: top dags and tree straight-line programs of firstchild/next sibling encodings. Efficient translations between these formalisms are provided. Finally, we show that equality of unranked trees in the setting where certain symbols are associative and/or commutative can be tested in polynomial time. This generalizes previous results for testing isomorphism of compressed unordered ranked trees. An extended abstract of this paper appeared in [14].


Keywords grammar-based tree compression • top dags • equality testing • forest

CR Subject Classification E. 4 Data compaction and compression

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Mathematics Subject Classification (2000) 68Q42; 68P30

## 1 Introduction

Grammar-based compression represents an object succinctly by means of a small context-free grammar. In many grammar-based compression formalisms such a grammar can be exponentially smaller than the object. Several string compressors use this idea and represent an input string $w$ by a context-free grammar that produces only $w[8]$; such grammars are also known as straightline programs - in this paper we use the term string straight-line program, SSLP for short. One of the biggest advantages of grammar-based compressors is that many algorithmic problems allow for efficient algorithms that work directly on the grammar and do not need prior decompression, see the survey [20] for references. One of the most well-known and fundamental such problems is testing equality of the strings produced by two string straight-line programs. Polynomial time solutions to this problem were discovered, in different contexts by different groups of people [ $15,17,27,28]$.

Grammar-based compression has been generalized from strings to ordered ranked node-labelled trees, by means of linear context-free tree grammars generating exactly one tree [7]. Such grammars are also known as tree straight-line programs, TSLPs for short, see [21] for a survey. Equality of the trees produced by two TSLPs can also be checked in polynomial time: one constructs SSLPs for the pre-order traversals of the trees, and then applies the above mentioned result for SSLPs, see [7]. The tree case becomes more complex when unordered ranked trees are considered. Such trees can be represented using TSLPs, by simply ignoring the order of children in the produced tree. Checking isomorphism of unordered ranked trees generated by TSLPs was recently shown to be solvable in polynomial time [23]. The solution transforms the TSLPs so that they generate canonical representations of the original trees and then checks equality of these canonical forms.

The aforementioned result for ranked trees cannot be applied to unranked trees (where the number of children of a node is not bounded), which arise for instance in XML document trees. This is unfortunate, because ( $i$ ) grammarbased compression is particularly effective for XML document trees (see [22]), and (ii) XML document trees can often be considered unordered (one speaks of "data-centric XML", see e.g. [1,4,6,29,30]), allowing even stronger grammarbased compressions [24].

In this paper we introduce a generalization of TSLPs and SSLPs that allows to produce ordered unranked node-labelled trees and forests (i.e., ordered sequences of trees) that we call forest straight-line programs, FSLPs for short. In contrast to TSLPs, FSLPs can compress very wide and flat trees. For instance, the tree $f(a, \ldots, a)$ with $n$ many $a$ 's is not compressible with TSLPs but can be produced by an FSLP of $\operatorname{size} \Theta(\log n)$. FSLPs are based on the operations of horizontal and vertical forest composition from forest algebras [5].

In the following Sections 1.1 and 1.2 we explain the the main contributions of this paper.

### 1.1 Comparison with other formalisms

We compare the succinctness of FSLPs with two other grammar-based formalisms for compressing unranked node-labelled ordered trees: TSLPs for "first-child/next-sibling" (fcns) encodings and top dags. The fcns-encoding is the standard way of transforming an unranked tree into a binary tree. Then the resulting binary tree can be succinctly represented by a TSLP. This approach was used to apply the TreeRePair-compressor from [22] to unranked trees. We prove that FSLPs and TSLPs for fcns-encodings are equally succinct up to constant multiplicative factors and that one can change between both representations in linear time (Propositions 3 and 4).

Top dags are another formalism for compressing unranked trees [3]. Top dags use horizontal and vertical merge operations for tree construction, which are very similar to the horizontal and vertical concatenation operations from FSLPs. Whereas a top dag can be transformed in linear time into an equivalent FSLP with a constant multiplicative blow-up (Proposition 1), the reverse transformation (from an FSLP to a top dag) needs time $\mathcal{O}(\sigma \cdot n)$ and involves a multiplicative blow-up of size $\mathcal{O}(\sigma)$ where $\sigma$ is the number of node labels of the tree (Proposition 2). A simple example (Example 6) shows that this $\sigma$-factor is unavoidable. The reason for the $\sigma$-factor is a technical restriction in the definition of top dags: In contrast to FSLPs, top dags only allow sharing of common subtrees but not of common subforests. Hence, sharing between (large) subtrees which only differ in their root labels may be impossible at all (as illustrated by Example 6), and this leads to the blow-up by a factor of $\sigma$ in comparison to FSLPs. The impossibility of sharing subforests would also complicate the technical details of our main algorithmic results for FSLPs (in particular Proposition 4 and Theorem 3 which is discussed below) for which we make heavy use of a particular normal form for FSLPs that exploits the sharing of proper subforests. We therefore believe that at least for our purposes, FSLPs are a more adequate formalism than top dags.

### 1.2 Testing equality modulo associativity and commutativity

Our main algorithmic result for FSLPs can be formulated as follows: Fix a set $\Sigma$ of node labels and take a subset $\mathcal{C} \subseteq \Sigma$ of "commutative" node labels and a subset $\mathcal{A} \subseteq \Sigma$ of "associative" node labels. This means that for all $a \in \mathcal{A}$, $c \in \mathcal{C}$ and all trees $t_{1}, t_{2}, \ldots, t_{n}$ we do not distinguish
(i) between $c\left(t_{1}, \ldots, t_{n}\right)$ and $c\left(t_{\xi(1)}, \ldots, t_{\xi(n)}\right)$ for any permutation $\xi$ (commutativity), and
(ii) between $a\left(t_{1}, \ldots, t_{n}\right)$ and $a\left(t_{1}, \ldots, t_{i-1}, a\left(t_{i}, \ldots, t_{j-1}\right), t_{j}, \ldots, t_{n}\right)$ for any indices $i, j$ with $1 \leq i \leq j \leq n+1$ (associativity).

We then show that for two given FSLPs $F_{1}$ and $F_{2}$ that produce trees $t_{1}$ and $t_{2}$ (of possible exponential size), one can check in polynomial time whether $t_{1}$ and $t_{2}$ are equal modulo commutativity and associativity (Theorem 3). Note that unordered tree isomorphism corresponds to the case $\mathcal{C}=\Sigma$ and $\mathcal{A}=\emptyset$ (in particular we generalize the result from [23] for ranked unordered trees). Theorem 3 also holds if the trees $t_{1}$ and $t_{2}$ are given by top dags or TSLPs for the fcns-encodings, since these formalisms can be transformed efficiently into FSLPs. Theorem 3 also shows the usefulness of FSLPs even if one is only interested in say binary trees, which are represented by TSLPs. The law of associativity will yield very wide and flat trees that are no longer compressible with TSLPs but are still compressible with FSLPs.

### 1.3 Related work

In the recent paper [12] a general balancing result is shown, which also applies to FSLPs: From a given FSLP of size $n$ that produces a forest of size $N$ one can construct in linear time an equivalent FSLP of size $\mathcal{O}(n)$ and height $\mathcal{O}(\log N)$ [12, Corollary 11.5]. A corresponding result for top dags is shown as well [12, Corollary 12.3].

## 2 Straight-line programs over algebras

We will produce strings, trees and forests by algebraic expressions over certain algebras. These expressions will be compressed by directed acyclic graphs. In this section, we introduce the general framework, which will be reused several times in this paper.

An algebraic structure is a tuple $\mathcal{A}=\left(A, f_{1}, \ldots, f_{k}\right)$ where $A$ is the universe and every $f_{i}: A^{n_{i}} \rightarrow A$ is an operation of a certain arity $n_{i}$. In this paper, the arity of all operations will be at most two. If $n_{i}=0$, then $f_{i}$ is called a constant. Moreover, it will be convenient to allow partial operations for the $f_{i}$. We will make use of such partial functions but we will not construct expressions that evaluate to undefined. Algebraic expressions over $\mathcal{A}$ are defined in the usual way: if $e_{1}, \ldots, e_{n_{i}}$ are algebraic expressions over $\mathcal{A}$, then also $f_{i}\left(e_{1}, \ldots, e_{n_{i}}\right)$ is an algebraic expressions over $\mathcal{A}$. For an algebraic expression $e, \llbracket e \rrbracket \in A$ denotes the element to which $e$ evaluates (it can be undefined).

A straight-line program (SLP for short) over $\mathcal{A}$ is a tuple $P=(V, S, \rho)$, where $V$ is a set of variables, $S \in V$ is the start variable, and $\rho$ maps every variable $A \in V$ to an expression of the form $f_{i}\left(A_{1}, \ldots, A_{n_{i}}\right)$ (the so called right-hand side of $A$ ) such that $A_{1}, \ldots, A_{n_{i}} \in V$ and the edge relation $E(P)=$ $\{(B, A) \in V \times V \mid B$ occurs in $\rho(A)\}$ is acyclic. This allows to define for every variable $A \in V$ its value $\llbracket A \rrbracket_{P}$ inductively by $\llbracket A \rrbracket_{P}=f_{i}\left(\llbracket A_{1} \rrbracket_{P}, \ldots, \llbracket A_{n_{i}} \rrbracket_{P}\right)$ if $\rho(A)=f_{i}\left(A_{1}, \ldots, A_{n_{i}}\right)$. Since the $f_{i}$ can be partially defined, the value of a variable can be undefined. The SLP $P$ will be called valid if all values $\llbracket A \rrbracket_{P}$ $(A \in V)$ are defined. We will only construct SLPs that are valid. Moreover,
for each of our algebras, it will be easy to check whether an SLP is valid. The value of $P$ is $\llbracket P \rrbracket=\llbracket S \rrbracket_{P}$. Usually, we prove properties of an SLP $P$ by induction on the finite partial order $\leq_{P}=E(P)^{*}$.

It will be convenient to allow for the right-hand sides $\rho(A)$ algebraic expressions over $\mathcal{A}$, where the variables from $V$ can appear as atomic expressions. By introducing additional variables, we can transform such an SLP into an equivalent SLP of the original form. We define the size $|P|$ of an SLP $P$ as the total number of occurrences of operations $f_{1}, \ldots, f_{k}$ in all right-hand sides (which is the number of variables if all right-hand sides have the standard form $\left.f_{i}\left(A_{1}, \ldots, A_{n_{i}}\right)\right)$.

Sometimes it is useful to view an SLP $P=(V, S, \rho)$ as a directed acyclic graph (dag) ( $V, E(P)$ ), together with the distinguished output node $S$, and the node labelling that associates the label $f_{i}$ with the node $A \in V$ if $\rho(A)=$ $f_{i}\left(A_{1}, \ldots, A_{n_{i}}\right)$. Note that the outgoing edges $\left(A, A_{1}\right), \ldots,\left(A, A_{n_{i}}\right)$ have to be ordered since $f_{i}$ is in general not commutative and that multi-edges have to be allowed. Such dags are also known as algebraic circuits in the literature (see [2] for the special case of algebraic circuits over fields and [19] for arbitrary algebraic structures).

### 2.1 String straight-line programs

A widely studied type of SLPs are SLPs over a free monoid $\left(\Sigma^{*}, \cdot, \varepsilon,(a)_{a \in \Sigma}\right)$, where • is the concatenation operator (which, as usual, is not written explicitly in expressions) and the empty string $\varepsilon$ and every alphabet symbol $a \in \Sigma$ are added as constants. We use the term string straight-line programs (SSLPs for short) for these SLPs. If we want to emphasize the alphabet $\Sigma$, we speak of an SSLP over $\Sigma$. In many papers, SSLPs are just called straight-line programs; see [20] for a survey. Occasionally we consider SSLPs without a start variable $S$ and then write ( $V, \rho$ ).

Example 1 Consider the SSLP $G=(\{S, A, B, C\}, S, \rho)$ over the alphabet $\{a, b\}$ with $\rho(S)=A A B, \rho(A)=C B B, \rho(B)=C a C, \rho(C)=b$. We have $\llbracket B \rrbracket_{G}=b a b, \llbracket A \rrbracket_{G}=b b a b b a b$, and $\llbracket G \rrbracket=b b a b b a b b b a b b a b b a b$. The size of $G$ is 8 (six concatenation operators are used in the right-hand sides, and there are two occurrences of constants).

In the next two sections, we introduce two types of algebras for trees and forests.

## 3 Forest algebras and forest straight-line programs

### 3.1 Trees and forests

Let us fix a finite set $\Sigma$ of node labels for the rest of the paper. We consider $\Sigma$-labelled rooted ordered trees, where "ordered" means that the children of a
node are totally ordered. Every node has a label from $\Sigma$. Note that we make no rank assumption: the number of children of a node (also called its degree) is not determined by its node label. The set of nodes (resp. edges) of $t$ is denoted by $V(t)$ (resp., $E(t)$ ). A forest is a (possibly empty) sequence of trees. The size $|f|$ of a forest is the total number of nodes in $f$. The set of all $\Sigma$-labelled forests is denoted by $\mathcal{F}_{0}(\Sigma)$ and the set of all $\Sigma$-labelled trees is denoted by $\mathcal{T}_{0}(\Sigma)$. As usual, we can identify trees with expressions built up from symbols in $\Sigma$ and parentheses. Formally, $\mathcal{F}_{0}(\Sigma)$ and $\mathcal{T}_{0}(\Sigma)$ can be inductively defined as the following sets of strings over the alphabet $\Sigma \cup\{()$,$\} .$

- If $t_{1}, \ldots, t_{n}$ are $\Sigma$-labelled trees with $n \geq 0$, then the string $t_{1} t_{2} \cdots t_{n}$ is a $\Sigma$-labelled forest (in particular, the empty string $\varepsilon$ is a $\Sigma$-labelled forest).
- If $f$ is a $\Sigma$-labelled forest and $a \in \Sigma$, then $a(f)$ is a $\Sigma$-labelled tree (where the singleton tree $a()$ is usually written as $a)$.

Let us fix a distinguished symbol $x \notin \Sigma$ for the rest of the paper (called the parameter). The set of forests $f \in \mathcal{F}_{0}(\Sigma \cup\{x\})$ such that $x$ has a unique occurrence in $f$ and this occurrence is at a leaf node is denoted by $\mathcal{F}_{1}(\Sigma)$. Similarly, the set of trees $t \in \mathcal{T}_{0}(\Sigma \cup\{x\})$ such that $x$ has a unique occurrence in $t$ and this occurrence is at a leaf node is denoted by $\mathcal{T}_{1}(\Sigma)$. Elements of $\mathcal{T}_{1}(\Sigma)$ (resp., $\mathcal{F}_{1}(\Sigma)$ ) are called tree contexts (resp., forest contexts). We finally define $\mathcal{F}(\Sigma)=\mathcal{F}_{0}(\Sigma) \cup \mathcal{F}_{1}(\Sigma)$ and $\mathcal{T}(\Sigma)=\mathcal{T}_{0}(\Sigma) \cup \mathcal{T}_{1}(\Sigma)$. Following [5], we define the forest algebra $\mathrm{FA}(\Sigma)=\left(\mathcal{F}(\Sigma), \boxtimes, \mathbb{\square},(a)_{a \in \Sigma}, \varepsilon, x\right)$ as follows:
$-\boxtimes$ is the horizontal concatenation operator: for forests $f_{1}, f_{2} \in \mathcal{F}(\Sigma), f_{1} \boxtimes f_{2}$ is defined if $f_{1} \in \mathcal{F}_{0}(\Sigma)$ or $f_{2} \in \mathcal{F}_{0}(\Sigma)$ and in this case we set $f_{1} \boxtimes f_{2}=f_{1} f_{2}$ (i.e., we concatenate the corresponding sequences of trees).

- $\square$ is the vertical concatenation operator: for forests $f_{1}, f_{2} \in \mathcal{F}(\Sigma), f_{1} \boxplus f_{2}$ is defined if $f_{1} \in \mathcal{F}_{1}(\Sigma)$ and in this case $f_{1} \boxtimes f_{2}$ is obtained by replacing in $f_{1}$ the unique occurrence of the parameter $x$ by the forest $f_{2}$.
- Every $a \in \Sigma$ is identified with the unary function $a: \mathcal{F}(\Sigma) \rightarrow \mathcal{T}(\Sigma)$ that produces $a(f)$ when applied to $f \in \mathcal{F}(\Sigma)$.
$-\varepsilon \in \mathcal{F}_{0}(\Sigma)$ and $x \in \mathcal{F}_{1}(\Sigma)$ are constants of the forest algebra.
For better readability, we also write $f\langle g\rangle$ instead of $f \boxtimes g, f g$ instead of $f \square g$, and $a$ instead of $a(\varepsilon)$.

As an example for the vertical concatenation, consider the forests $f=$ $a a(b x b)$ and $g=c(d d) c(d)$, where we have $f \boxplus g=f\langle g\rangle=a a(b c(d d) c(d) b)$.

### 3.2 First-child/next-sibling encoding

The first-child/next-sibling encoding transforms a forest over some alphabet $\Sigma$ into a binary tree over $\Sigma \uplus\{\perp\}$, where every node labelled with $a \in \Sigma$ has degree 2 and every node labelled with $\perp$ has degree 0 . We define fcns: $\mathcal{F}_{0}(\Sigma) \rightarrow$ $\mathcal{T}_{0}(\Sigma \uplus\{\perp\})$ inductively by:
$-\operatorname{fcns}(\varepsilon)=\perp$,
$-\mathrm{fcns}(a(f) g)=a(\mathrm{fcns}(f) \operatorname{fcns}(g))$ for $f, g \in \mathcal{F}_{0}(\Sigma), a \in \Sigma$.


Fig. 1 Forest $f$ on the left and $\mathrm{fcns}(f)$ on the right from Example 2.


Fig. 2 Forest $\llbracket F \rrbracket$ for $n=2$ from Example 3.

Thus, the left (resp., right) child of a node in fcns $(f)$ is the first child (resp., right sibling) of the node in $f$ or a $\perp$-labelled leaf if it does not exist.

Example 2 If $f=a(b c) d(e)$ then

$$
\begin{aligned}
\operatorname{fcns}(f) & =\operatorname{fcns}(a(b c) d(e))=a(\operatorname{fcns}(b c) \operatorname{fcns}(d(e))) \\
& =a(b(\perp \operatorname{fcns}(c)) d(\operatorname{fcns}(e) \perp))=a(b(\perp c(\perp \perp)) d(e(\perp \perp) \perp)),
\end{aligned}
$$

see also Figure 1.

### 3.3 Forest straight-line programs

A forest straight-line program over $\Sigma$, FSLP for short, is a valid straight-line program over the algebra $\mathrm{FA}(\Sigma)$ such that $\llbracket F \rrbracket \in \mathcal{F}_{0}(\Sigma)$. Iterated vertical and horizontal concatenations allow to generate forests, whose depth and width is exponential in the FSLP size. For an FSLP $F=(V, S, \rho)$ and $i \in\{0,1\}$ we define $V_{i}=\left\{A \in V \mid \llbracket A \rrbracket_{F} \in \mathcal{F}_{i}(\Sigma)\right\}$.

Example 3 Let $n \in \mathbb{N}$ and let $F=(S, V, \rho)$ be the FSLP over $\{a, b, c\}$ with $V_{0}=\left\{S, A_{0}, \ldots, A_{n}\right\}, V_{1}=\left\{B_{0}, \ldots, B_{n}\right\}$ where $\rho$ is defined by $\rho\left(A_{0}\right)=a$, $\rho\left(B_{0}\right)=b\left(A_{n} x A_{n}\right), \rho\left(A_{i}\right)=A_{i-1} A_{i-1}$ and $\rho\left(B_{i}\right)=B_{i-1}\left\langle B_{i-1}\right\rangle$ for $1 \leq i \leq n$, and $\rho(S)=B_{n}\langle c\rangle$. Then we have $\llbracket F \rrbracket=b\left(a^{2^{n}} b\left(a^{2^{n}} \cdots b\left(a^{2^{n}} c a^{2^{n}}\right) \cdots a^{2^{n}}\right) a^{2^{n}}\right)$, where $b$ occurs $2^{n}$ many times. This is a forest whose width and depth is exponential in the size of the FSLP $F$. See Figure 2 for $n=2$.

Example 4 Consider the alphabet $\Sigma=\{a, b, c, d, e\}$. Let $n \geq 0$ be a natural number, and let $F=\left(V, S_{1}, \rho\right)$ be the FSLP with

$$
\begin{aligned}
V_{0} & =\left\{A_{1}, A_{2}, B, S_{1}\right\}, \\
V_{1} & =\left\{B_{0}, \ldots, B_{n}, C_{0}, \ldots, C_{n}\right\}, \\
\rho\left(A_{1}\right) & =e(e(a b) c), \\
\rho\left(A_{2}\right) & =e(a e(b c)), \\
\rho\left(B_{0}\right) & =A_{1} x A_{2}, \\
\rho\left(B_{i}\right) & =B_{i-1}\left\langle B_{i-1}\right\rangle \text { for } 1 \leq i \leq n, \\
\rho(B) & =B_{n}\left\langle A_{1}\right\rangle, \\
\rho\left(C_{0}\right) & =d(x B), \\
\rho\left(C_{i}\right) & =C_{i-1}\left\langle C_{i-1}\right\rangle \text { for } 1 \leq i \leq n, \text { and } \\
\rho\left(S_{1}\right) & =C_{n}\langle B\rangle .
\end{aligned}
$$

Note that, although $F$ has size $\mathcal{O}(n), \llbracket F \rrbracket$ has exponential width and depth, as it is the tree

$$
\underbrace{d(d(\cdots d(d}_{2^{n} \text { many } d( }(\underbrace{f) f) \cdots f) f)}_{\left.2^{n} \text { many } f\right)}
$$

where $f=\llbracket B \rrbracket_{F}$ is the forest $(e(e(a b) c))^{2^{n}+1}(e(a e(b c)))^{2^{n}}$; see Figure 3 for $n=1$.

Now consider a second FSLP $F^{\prime}=\left(V^{\prime}, S_{2}, \rho^{\prime}\right)$ over $\Sigma$ with

$$
\begin{aligned}
V_{0}^{\prime} & =\left\{D, E_{0}, \ldots, E_{n}, E, S_{2}\right\}, \\
V_{1}^{\prime} & =\left\{F_{0}, \ldots, F_{n}\right\}, \\
\rho(D) & =e(a b c), \\
\rho\left(E_{0}\right) & =D D, \\
\rho\left(E_{i}\right) & =E_{i-1} E_{i-1} \text { for } 1 \leq i \leq n, \\
\rho(E) & =E_{n} D, \\
\rho\left(F_{0}\right) & =d(E x), \\
\rho\left(F_{i}\right) & =F_{i-1}\left\langle F_{i-1}\right\rangle \text { for } 1 \leq i \leq n, \text { and } \\
\rho\left(S_{2}\right) & =F_{n}\langle E\rangle .
\end{aligned}
$$

Then $\llbracket F^{\prime} \rrbracket$ is the tree

$$
\underbrace{d\left(f ^ { \prime } d \left(f ^ { \prime } \cdots d \left(f ^ { \prime } d \left(f^{\prime}\right.\right.\right.\right.}_{2^{n} \text { many } d\left(f^{\prime}\right.} f^{\prime})) \cdots))
$$

where $f^{\prime}=\llbracket E \rrbracket_{F^{\prime}}$ is the forest $e(a b c)^{2^{n+1}+1}$; see Figure 3 for $n=1$.
Note that if we consider $e$ as associative then $f$ and $f^{\prime}$ represent the same forest. If in addition we consider $d$ as commutative then the FSLPs $F$ and $F^{\prime}$ in fact represent the same unranked tree. Our main contribution is a polynomial time algorithm for performing this kind of equivalence check.


Fig. 3 Example 4 for $n=1$.

FSLPs generalize tree straight-line programs (TSLPs for short) that have been used for the compression of ranked trees before, see e.g. [21]. In this work, we only use TSLPs for binary trees. A TSLP over $\Sigma$ can then be defined as an FSLP $T=(V, S, \rho)$ such that for every $A \in V, \rho(A)$ has the form $a$, $a(B C), a(x B), a(B x)$, or $B\langle C\rangle$ with $a \in \Sigma, B, C \in V$. TSLPs can be used to compress the fcns-encoding of an unranked tree; see also [22]. It is not hard to see that an FSLP $F$ that produces a binary tree can be transformed into a TSLP $T$ such that $\llbracket F \rrbracket=\llbracket T \rrbracket$ and $|T| \in \mathcal{O}(|F|)$. This is an easy corollary of our normal form for FSLPs that we introduce in Section 3.5 (see also the proof of Proposition 3). For the construction of the normal form, we first need a technical result about SSLP factorizations that we show in the next section.

### 3.4 Factorization of SSLPs

Let $\Sigma$ be an alphabet, let $\Sigma_{1} \subseteq \Sigma$ and $\Sigma_{2}=\Sigma \backslash \Sigma_{1}$. Then every string $w \in \Sigma^{*}$ has a unique factorization $w=v_{0} a_{1} v_{1} \cdots a_{n} v_{n}$ with $n \geq 0, a_{i} \in \Sigma_{1}$ and $v_{0}, v_{i} \in \Sigma_{2}^{*}$ for $1 \leq i \leq n$, which we call the $\Sigma_{1}$-factorization of $w$. Let $G=(V, \rho)$ and $G^{\prime}=\left(V^{\prime}, \rho^{\prime}\right)$ be SSLPs over $\Sigma$. We call $G^{\prime}$ a $\Sigma_{1}$-factorization of $G$ if $\llbracket A \rrbracket_{G}=\llbracket A \rrbracket_{G^{\prime}}$ for all $A \in V$, and there are sets $\mathcal{U}, \mathcal{L}$ of (upper and lower) variables such that $V^{\prime}=V \uplus \mathcal{U} \uplus \mathcal{L}$ and

$$
\begin{aligned}
\rho^{\prime}(V) & \subseteq \mathcal{L} \cup \mathcal{L} \Sigma_{1} \mathcal{L} \cup \mathcal{L} \mathcal{U} \Sigma_{1} \mathcal{L} \\
\rho^{\prime}(\mathcal{U}) & \subseteq \Sigma_{1} \mathcal{L} \cup \mathcal{U} \mathcal{U} \\
\rho^{\prime}(\mathcal{L}) & \subseteq\{\varepsilon\} \cup \Sigma_{2} \cup \mathcal{L L}
\end{aligned}
$$

Note that the partition $V^{\prime}=V \uplus \mathcal{U} \uplus \mathcal{L}$ is uniquely determined by $V^{\prime}$ and $\rho$. Moreover, $\llbracket A \rrbracket_{G^{\prime}} \in \Sigma_{2}^{*}$ for every $A \in \mathcal{L}$ and $\llbracket A \rrbracket_{G^{\prime}} \in\left(\Sigma_{1} \Sigma_{2}^{*}\right)^{*}$ for every $A \in \mathcal{U}$. This implies that $G^{\prime}$ describes the $\Sigma_{1}$-factorization $w=v_{0} a_{1} v_{1} \cdots a_{n} v_{n}$ for every string $w=\llbracket A \rrbracket_{G^{\prime}}=\llbracket A \rrbracket_{G}(A \in V)$ in the following sense: If $\rho^{\prime}(A)=$
$B \in \mathcal{L}$, then $n=0$ and $\llbracket B \rrbracket_{G^{\prime}}=v_{0}$. If $\rho^{\prime}(A)=B a C \in \mathcal{L} \Sigma_{1} \mathcal{L}$, then $n=1$, $\llbracket B \rrbracket_{G^{\prime}}=v_{0}, a=a_{1}$ and $\llbracket C \rrbracket_{G^{\prime}}=v_{1}$. Finally, if $\rho^{\prime}(A)=B C a D \in \mathcal{L} \mathcal{U} \Sigma_{1} \mathcal{L}$ then $n \geq 2, \llbracket B \rrbracket_{G^{\prime}}=v_{0}, a=a_{n}, \llbracket D \rrbracket_{G^{\prime}}=v_{n}$ and there are variables $C_{i}, D_{i}$ with $\llbracket C \rrbracket_{G^{\prime}}=\llbracket C_{1} \rrbracket_{G^{\prime}} \cdots \llbracket C_{n-1} \rrbracket_{G^{\prime}}, \rho\left(C_{i}\right)=a_{i} D_{i}$ and $\llbracket D_{i} \rrbracket_{G^{\prime}}=v_{i}$ for $1 \leq i<n$.

Lemma 1 Let $G=(V, \rho)$ be an SSLP over $\Sigma$ and let $\Sigma_{1} \subseteq \Sigma$. We can compute in linear time a $\Sigma_{1}$-factorization of $G$ of size $\mathcal{O}(|G|)$.

Proof We may assume w.l.o.g. that $\rho(V) \subseteq V V \cup \Sigma$. For every string $w \in \Sigma^{*}$ with $\Sigma_{1}$-factorization $w=v_{0} a_{1} v_{1} \cdots a_{n} v_{n}$ we define $w_{\ell}, w_{m}, w_{r} \in \Sigma^{*}$ and $\sigma_{w} \in \Sigma_{1} \cup\{\varepsilon\}$ as follows:

- If $n=0$ then $w_{\ell}=v_{0}$ and $w_{m}=w_{r}=\sigma_{w}=\varepsilon$.
- If $n>0$ then $w_{\ell}=v_{0}, w_{m}=a_{1} v_{1} \cdots a_{n-1} v_{n-1}, \sigma_{w}=a_{n}$ and $w_{r}=v_{n}$.

Note that in both cases $w=w_{\ell} w_{m} \sigma_{w} w_{r}$ and $w_{\ell}, w_{m}, \sigma_{w}, w_{r}$ satisfy the following equations:

- If $w=\varepsilon$ then $w_{\ell}=w_{m}=\sigma_{w}=w_{r}=\varepsilon$.
- If $w=a \in \Sigma_{1}$ then $\sigma_{w}=a$ and $w_{\ell}=w_{m}=w_{r}=\varepsilon$.
- If $w=b \in \Sigma_{2}$ then $w_{\ell}=b$ and $w_{m}=\sigma_{w}=w_{r}=\varepsilon$.
- If $w=u v$ with $u, v \in \Sigma^{*}$ then
- if $\sigma_{u}=\varepsilon$ then also $u_{m}=u_{r}=\varepsilon$, hence $w_{\ell}=u_{\ell} v_{\ell}, w_{m}=v_{m}, \sigma_{w}=\sigma_{v}$ and $w_{r}=v_{r}$,
- if $\sigma_{u} \in \Sigma_{1}$ and $\sigma_{v}=\varepsilon$ then also $v_{m}=v_{r}=\varepsilon$, hence $w_{\ell}=u_{\ell}, w_{m}=u_{m}$, $\sigma_{w}=\sigma_{u}$ and $w_{r}=u_{r} v_{\ell}$,
- if $\sigma_{u}, \sigma_{v} \in \Sigma_{1}$ then $w_{\ell}=u_{\ell}, w_{m}=u_{m} \sigma_{u} u_{r} v_{\ell} v_{m}, \sigma_{w}=\sigma_{v}$ and $w_{r}=v_{r}$.

We use these equations as a guideline for the construction of a $\Sigma_{1}$-factorization $G^{\prime}=\left(V \uplus \mathcal{U} \uplus \mathcal{L}, \rho^{\prime}\right)$ of $G$. Take new variables $A_{\ell}, A_{m}, A_{r}, U_{B C}, U_{B C}^{\prime}, L_{B C} \notin V$ and let

$$
\begin{aligned}
\mathcal{U} & =\left\{A_{m} \mid A \in V\right\} \cup\left\{U_{B C}, U_{B C}^{\prime} \mid B C \in \rho(V)\right\} \\
\mathcal{L} & =\left\{A_{\ell}, A_{r} \mid A \in V\right\} \cup\left\{L_{B C} \mid B C \in \rho(V)\right\}
\end{aligned}
$$

For every $A \in V$ we define $\sigma_{A} \in \Sigma_{1} \cup\{\varepsilon\}$ and the right-hand sides of the new variables by the following induction on $\leq_{G}$ :

- If $\rho(A)=a \in \Sigma_{1}$ then $\sigma_{A}=a$ and $\rho^{\prime}\left(A_{\ell}\right)=\rho^{\prime}\left(A_{m}\right)=\rho^{\prime}\left(A_{r}\right)=\varepsilon$.
- If $\rho(A)=b \in \Sigma_{2}$ then $\rho^{\prime}\left(A_{\ell}\right)=b$ and $\rho^{\prime}\left(A_{m}\right)=\sigma_{A}=\rho^{\prime}\left(A_{r}\right)=\varepsilon$.
- If $\rho(A)=B C$ then
- if $\sigma_{B}=\varepsilon$ then $\rho^{\prime}\left(A_{\ell}\right)=B_{\ell} C_{\ell}, \rho^{\prime}\left(A_{m}\right)=\rho^{\prime}\left(C_{m}\right), \sigma_{A}=\sigma_{C}$ and $\rho^{\prime}\left(A_{r}\right)=$ $\rho^{\prime}\left(C_{r}\right)$,
- if $\sigma_{B} \in \Sigma_{1}$ and $\sigma_{C}=\varepsilon$ then $\rho^{\prime}\left(A_{\ell}\right)=\rho^{\prime}\left(B_{\ell}\right), \rho^{\prime}\left(A_{m}\right)=\rho^{\prime}\left(B_{m}\right), \sigma_{A}=\sigma_{B}$ and $\rho^{\prime}\left(A_{r}\right)=B_{r} C_{\ell}$,
- if $\sigma_{B}, \sigma_{C} \in \Sigma_{1}$ then
- $\rho^{\prime}\left(A_{\ell}\right)=\rho^{\prime}\left(B_{\ell}\right)$,
- $\rho^{\prime}\left(A_{m}\right)=\rho^{\prime}\left(U_{B C}^{\prime}\right)$ if $\rho^{\prime}\left(B_{m}\right)=\varepsilon$, otherwise $\rho^{\prime}\left(A_{m}\right)=B_{m} U_{B C}^{\prime}$,
- $\rho^{\prime}\left(U_{B C}^{\prime}\right)=\rho^{\prime}\left(U_{B C}\right)$ if $\rho^{\prime}\left(C_{m}\right)=\varepsilon$, otherwise $\rho^{\prime}\left(U_{B C}^{\prime}\right)=U_{B C} C_{m}$,
- $\rho^{\prime}\left(U_{B C}\right)=\sigma_{B} L_{B C}$,
- $\rho^{\prime}\left(L_{B C}\right)=B_{r} C_{\ell}$,
- $\sigma_{A}=\sigma_{C}$,
- $\rho^{\prime}\left(A_{r}\right)=\rho^{\prime}\left(C_{r}\right)$.

Finally we remove every variable $A_{m}$ with $\rho^{\prime}\left(A_{m}\right)=\varepsilon$ from $\mathcal{U}$ and define $\rho^{\prime}(A)$ for every $A \in V$ as follows: If $\sigma_{A}=\varepsilon$ then $\rho^{\prime}(A)=A_{\ell} \in \mathcal{L}$. If $\sigma_{A} \in \Sigma_{1}$ and $A_{m} \notin \mathcal{U}$ then $\rho^{\prime}(A)=A_{\ell} \sigma_{A} A_{r} \in \mathcal{L} \Sigma_{1} \mathcal{L}$. Otherwise $\rho^{\prime}(A)=A_{\ell} A_{m} \sigma_{A} A_{r} \in$ $\mathcal{L} \mathcal{U} \Sigma_{1} \mathcal{L}$.

A straightforward induction on $\leq_{G}$ shows that $\llbracket A_{\ell} \rrbracket_{G^{\prime}}=w_{\ell}, \llbracket A_{m} \rrbracket_{G^{\prime}}=w_{m}$, $\sigma_{A}=\sigma_{w}$ and $\llbracket A_{r} \rrbracket_{G^{\prime}}=w_{r}$ whenever $\llbracket A \rrbracket_{G}=w$. From this and the definition of the new right-hand sides $\rho^{\prime}(A)$ we finally obtain

$$
\llbracket A \rrbracket_{G^{\prime}}=\left(\llbracket A_{\ell} \rrbracket_{G^{\prime}}\right)\left(\llbracket A_{m} \rrbracket_{G^{\prime}}\right) \sigma_{A}\left(\llbracket A_{r} \rrbracket_{G^{\prime}}\right)=w_{\ell} w_{m} \sigma_{w} w_{r}=w .
$$

This proves the lemma.

### 3.5 Normal form FSLPs

In this subsection, we introduce a normal form for FSLPs that turns out to be crucial in the rest of the paper. An FSLP $F=(V, S, \rho)$ is in normal form if $V_{0}=V_{0}^{\top} \uplus V_{0}^{\perp}$ and all right-hand sides have one of the following forms:

- $\rho(A)=\varepsilon$, where $A \in V_{0}^{\top}$,
- $\rho(A)=B C$, where $A \in V_{0}^{\top}, B, C \in V_{0}$,
$-\rho(A)=B\langle C\rangle$, where $B \in V_{1}$ and either $A, C \in V_{0}^{\perp}$ or $A, C \in V_{1}$,
$-\rho(A)=a(B)$, where $A \in V_{0}^{\perp}, a \in \Sigma$ and $B \in V_{0}$,
$-\rho(A)=a(B x C)$, where $A \in V_{1}, a \in \Sigma$ and $B, C \in V_{0}$.
Note that the partition $V_{0}=V_{0}^{\top} \uplus V_{0}^{\perp}$ is uniquely determined by $\rho$. Also note that variables from $V_{1}$ produce tree contexts and variables from $V_{0}^{\perp}$ produce trees, whereas variables from $V_{0}^{\top}$ produce forests with arbitrarily many trees.

Let $F=(V, S, \rho)$ be a normal form FSLP. Every variable $A \in V_{1}$ produces a vertical concatenation of (possibly exponentially many) variables, whose right-hand sides have the form $a(B x C)$. This vertical concatenation is called the spine of $A$. Formally, we split $V_{1}$ into $V_{1}^{\top}=\left\{A \in V_{1} \mid \exists B, C \in V_{1}: \rho(A)=\right.$ $B\langle C\rangle\}$ and $V_{1}^{\perp}=V_{1} \backslash V_{1}^{\top}$. We then define the vertical SSLP $F^{\square}=\left(V_{1}^{\top}, \rho_{1}\right)$ over $V_{1}^{\perp}$ with $\rho_{1}(A)=B C$ whenever $\rho(A)=B\langle C\rangle$. For every $A \in V_{1}$ the string $\llbracket A \rrbracket_{F^{\varpi}} \in\left(V_{1}^{\perp}\right)^{*}$ is called the spine of $A$, denoted by $\operatorname{spine}_{F}(A)$ or just $\operatorname{spine}(A)$ if $F$ is clear from the context. We also define the horizontal SSLP $F^{\square}=\left(V_{0}^{\top}, \rho_{0}\right)$ over $V_{0}^{\perp}$, where $\rho_{0}$ is the restriction of $\rho$ to $V_{0}^{\top}$. For every $A \in V_{0}$ we denote the string $\llbracket A \rrbracket_{F ■} \in\left(V_{0}^{\perp}\right)^{*}$ by $\operatorname{hor}_{F}(A)$ or just $\operatorname{hor}(A)$ if $F$ is clear from the context. Note that $\operatorname{spine}(A)=A$ (resp., $\operatorname{hor}(A)=A$ ) for every $A \in V_{1}^{\perp}$ (resp., $A \in V_{0}^{\perp}$ ).

The intuition behind the normal form can be explained as follows: Consider a tree context $t \in \mathcal{T}_{1}(\Sigma) \backslash\{x\}$. By decomposing $t$ along the nodes on the unique path from the root to the $x$-labelled leaf, we can write $t$ as a vertical concatenation of tree contexts $a_{1}\left(f_{1} x g_{1}\right), \ldots, a_{n}\left(f_{n} x g_{n}\right)$ for forests $f_{1}, g_{1}, \ldots, f_{n}, g_{n}$
and symbols $a_{1}, \ldots, a_{n}$. In a normal form FSLP one would produce $t$ by first deriving a vertical concatenation $A_{1}\left\langle\cdots\left\langle A_{n}\right\rangle \cdots\right\rangle$. Every $A_{i}$ is then derived to $a_{i}\left(B_{i} x C_{i}\right)$, where $B_{i}$ (resp., $C_{i}$ ) produces the forest $f_{i}$ (resp., $g_{i}$ ). Computing an FSLP for this decomposition for a tree context that is already given by an FSLP is the main step in the proof of the normal form theorem below. Another insight is that proper forest contexts from $\mathcal{F}_{1}(\Sigma) \backslash \mathcal{T}_{1}(\Sigma)$ can be eliminated without significant size blow-up.

Theorem 1 From a given FSLP F one can construct in linear time an FSLP $F^{\prime}$ in normal form such that $\llbracket F^{\prime} \rrbracket=\llbracket F \rrbracket$ and $\left|F^{\prime}\right| \in \mathcal{O}(|F|)$.

Proof To convert an FSLP to normal form, we first introduce a weak normal form, where all right-hand sides have one of the following forms:
$-\rho(A)=\varepsilon$, where $A \in V_{0}$,
$-\rho(A)=B\langle C\rangle$, where $A, C \in V_{0}$ and $B \in V_{1}$,
$-\rho(A)=B\langle C\rangle$, where $A, B, C \in V_{1}$,
$-\rho(A)=a(x)$, where $A \in V_{1}, a \in \Sigma$,
$-\rho(A)=B x C$, where $A \in V_{1}, B, C \in V_{0}$.
Converting an FSLP into weak normal form is straightforward: By splitting up right-hand sides, we can assume that all right-hand sides have the form $\varepsilon, x, a(x), B C$, or $B\langle C\rangle$ for $a \in \Sigma, B, C \in V$. This transformation does not increase the size of the FSLP. Right-hand sides of the form $\rho(A)=B C$, where w.l.o.g. $B \in V_{0}$, can be replaced by $\rho(A)=B^{\prime}\langle C\rangle$ and $\rho\left(B^{\prime}\right)=B x$, where $B^{\prime}$ is a new variable.

We may now assume that $F=(V, S, \rho)$ is in weak normal form. Like we did with FSLPs in normal form, we split $V_{1}$ into $V_{1}^{\top}=\left\{A \in V_{1} \mid \exists B, C \in V_{1}\right.$ : $\rho(A)=B\langle C\rangle\}$ and $V_{1}^{\perp}=V_{1} \backslash V_{1}^{\top}$ and define its vertical SSLP as the SSLP $F^{\amalg}=\left(V_{1}^{\top}, \rho_{1}\right)$ over $V_{1}^{\perp}$ with $\rho_{1}(A)=B C$ whenever $\rho(A)=B\langle C\rangle$.

Let $\mathcal{V}=\left\{A \in V_{1}^{\perp} \mid \rho(A)\right.$ has the form $\left.a(x)\right\}$ and $\mathcal{H}=V_{1}^{\perp} \backslash \mathcal{V}$. Thus, $\rho(A)$ has the form $B x C$ for $A \in \mathcal{H}$. The idea of the construction is to consider maximal factors of the form $A_{0} A_{1} \cdots A_{n}$ with $A_{0} \in \mathcal{V}$ and $A_{1}, \ldots, A_{n} \in \mathcal{H}$ in $\llbracket A \rrbracket_{F \text { ■ }}$ (for some $A \in V_{1}^{\top}$ ). In the FSLP $F$, such a factor corresponds to an iterated vertical concatenation $A_{0}\left\langle A_{1}\left\langle\cdots\left\langle A_{n}\right\rangle \cdots\right\rangle\right\rangle$. Assume that $\rho\left(A_{0}\right)=a(x)$ and $\rho\left(A_{i}\right)=B_{i} x C_{i}$ for $1 \leq i \leq n$. Then, $A_{0}\left\langle A_{1}\left\langle\cdots\left\langle A_{n}\right\rangle \cdots\right\rangle\right\rangle$ can be rewritten into $a\left(B_{1} B_{2} \cdots B_{n} x C_{n} \cdots C_{2} C_{1}\right)$. We will introduce additional variables in order to produce the horizontal concatenations $B_{1} B_{2} \cdots B_{n}$ and $C_{n} \cdots C_{2} C_{1}$ and a variable with right-hand side $a(B x C)$. Note that the latter form of right-hand sides is allowed in normal form FSLPs.

At this point, $\mathcal{V}$-factorizations turn out to be useful. The maximal factors $A_{0} \cdots A_{n}$ are explicitly generated by a $\mathcal{V}$-factorization of the vertical SSLP $F^{\square}$. By Lemma 1 we can compute in linear time a $\mathcal{V}$-factorization $G=\left(V_{1}^{\top} \uplus\right.$ $\left.\mathcal{U} \uplus \mathcal{L}, \rho_{G}\right)$ of $F^{\boxplus}$ with $|G| \in \mathcal{O}\left(\left|F^{\boxplus}\right|\right) \leq \mathcal{O}(|F|)$. From $F$ and $G$ we obtain the FSLP $F^{\prime}=\left(V^{\prime}, S, \rho^{\prime}\right)$ where $V_{0}^{\prime}=V_{0} \uplus\left\{A_{\ell}, A_{r} \mid A \in \mathcal{L}\right\}$ with new variables $A_{\ell}, A_{r}, V_{1}^{\prime}=\mathcal{U}$, and $\rho^{\prime}$ is defined by:

1. If $A \in \mathcal{L}$ with $\rho_{G}(A)=\varepsilon$ then $\rho^{\prime}\left(A_{\ell}\right)=\rho^{\prime}\left(A_{r}\right)=\varepsilon$.
2. If $A \in \mathcal{L}$ with $\rho_{G}(A)=B \in \mathcal{H}$ and $\rho(B)=C x D$ then $\rho^{\prime}\left(A_{\ell}\right)=C$ and $\rho^{\prime}\left(A_{r}\right)=D$.
3. If $A \in \mathcal{L}$ with $\rho_{G}(A)=B C \in \mathcal{L} \mathcal{L}$ then $\rho^{\prime}\left(A_{\ell}\right)=B_{\ell} C_{\ell}$ and $\rho^{\prime}\left(A_{r}\right)=C_{r} B_{r}$.
4. If $A \in \mathcal{U}$ with $\rho_{G}(A)=B C \in \mathcal{V} \mathcal{L}$ and $\rho(B)=a(x)$ then $\rho^{\prime}(A)=a\left(C_{\ell} x C_{r}\right)$.
5. If $A \in \mathcal{U}$ with $\rho_{G}(A)=B C \in \mathcal{U} \mathcal{U}$ then $\rho^{\prime}(A)=B\langle C\rangle$.
6. If $A \in V_{0}$ with $\rho(A)=\varepsilon$ then $\rho^{\prime}(A)=\varepsilon$.
7. If $A \in V_{0}$ with $\rho(A)=B\left\langle A_{0}\right\rangle, B \in V_{1}^{\perp}$ and $\rho(B)=a(x)$ then $\rho^{\prime}(A)=$ $a\left(A_{0}\right)$.
8. If $A \in V_{0}$ with $\rho(A)=B\left\langle A_{0}\right\rangle, B \in V_{1}^{\perp}$ and $\rho(B)=C x D$ then $\rho^{\prime}(A)=$ $C A_{0} D$.
9. If $A \in V_{0}$ with $\rho(A)=B\left\langle A_{0}\right\rangle, B \in V_{1}^{\top}$ and $\rho_{G}(B)=C \in \mathcal{L}$ then $\rho^{\prime}(A)=$ $C_{\ell} A_{0} C_{r}$.
10. If $A \in V_{0}$ with $\rho(A)=B\left\langle A_{0}\right\rangle, B \in V_{1}^{\top}, \rho_{G}(B)=C D E \in \mathcal{L} \mathcal{V} \mathcal{L}$ and $\rho(D)=a(x)$ then $\rho^{\prime}(A)=C_{\ell} a\left(E_{\ell} A_{0} E_{r}\right) C_{r}$.
11. If $A \in V_{0}$ with $\rho(A)=B\left\langle A_{0}\right\rangle, B \in V_{1}^{\top}, \rho_{G}(B)=C D D^{\prime} E \in \mathcal{L} \mathcal{U V} \mathcal{L}$ and $\rho\left(D^{\prime}\right)=a(x)$ then $\rho^{\prime}(A)=C_{\ell} D\left\langle a\left(E_{\ell} A_{0} E_{r}\right)\right\rangle C_{r}$.
Note that this FSLP is not in normal form, but by further splitting up $\rho^{\prime}(A)$ in points 8-11 (and eliminating the "chain definitions" in point 2), we can obtain normal form. For instance, in point 11, we have to introduce new variables $A_{1}, \ldots, A_{5}$ and set $\rho^{\prime}(A)=A_{1} C_{r}, \rho^{\prime}\left(A_{1}\right)=C_{\ell} A_{2}, \rho^{\prime}\left(A_{2}\right)=D\left\langle A_{3}\right\rangle, \rho^{\prime}\left(A_{3}\right)=$ $a\left\langle A_{4}\right\rangle, \rho^{\prime}\left(A_{4}\right)=A_{5} E_{r}$, and $\rho^{\prime}\left(A_{5}\right)=E_{\ell} A_{0}$. An easy induction on $\leq_{F^{\prime}}$ shows that

- if $B \in \mathcal{L}$ with $\llbracket B \rrbracket_{F 巴}=H_{1} \cdots H_{n} \in \mathcal{H}^{*}$ then $\llbracket H_{1}\left\langle\cdots\left\langle H_{n}\right\rangle \cdots\right\rangle \rrbracket_{F}=$ $\llbracket B_{\ell} x B_{r} \rrbracket_{F^{\prime}}$,
- if $A \in V_{0} \cup \mathcal{U}$ then $\llbracket A \rrbracket_{F}=\llbracket A \rrbracket_{F^{\prime}}$.

From the last point we finally obtain $\llbracket F \rrbracket=\llbracket S \rrbracket_{F}=\llbracket S \rrbracket_{F^{\prime}}=\llbracket F^{\prime} \rrbracket$.

## 4 Cluster algebras and top dags

In this section we introduce top dags $[3,16]$ as an alternative grammar-based formalism for the compression of unranked trees. A cluster of rank 0 is a tree $t \in \mathcal{T}_{0}(\Sigma)$ of size at least two. A cluster of rank 1 is a tree $t \in \mathcal{T}_{0}(\Sigma)$ of size at least two together with a distinguished leaf node that we call the bottom boundary node of $t$. In both cases, the root of $t$ is called the top boundary node of $t$. Note that in contrast to forest contexts there is no parameter $x$. Instead, one of the $\Sigma$-labelled leaf nodes may be declared as the bottom boundary node. When writing a cluster of rank 1 in term representation, we underline the bottom boundary node. For instance $a(b c(\underline{a} b))$ is a cluster of rank 1 . An atomic cluster is of the form $a(b)$ or $a(\underline{b})$ for $a, b \in \Sigma$. Let $\mathcal{C}_{i}(\Sigma)$ be the set of all clusters of rank $i \in\{0,1\}$ and let $\mathcal{C}(\Sigma)=\mathcal{C}_{0}(\Sigma) \cup \mathcal{C}_{1}(\Sigma)$. We write $\operatorname{rank}(s)=i$ if $s \in \mathcal{C}_{i}(\Sigma)$ for $i \in\{0,1\}$. We define the cluster algebra $\mathrm{CA}(\Sigma)=\left(\mathcal{C}(\Sigma), \odot, \oplus,(a(b), a(\underline{b}))_{a, b \in \Sigma)}\right)$ as follows:
$-\odot$ is the horizontal merge operator: $s \odot t$ is only defined if $\operatorname{rank}(s)+\operatorname{rank}(t) \leq$ 1 and $s, t$ are of the form $s=a(f), t=a(g)$, i.e., the root labels coincide.

Then $s \odot t=a(f g)$. Note that at most one symbol in the forest $f g$ is underlined. The rank of $s \odot t$ is $\operatorname{rank}(s)+\operatorname{rank}(t)$. For instance,

$$
a(b c(\underline{a} b)) \odot a(b c)=a(b c(\underline{a} b) b c)
$$

- $\left(1\right.$ is the vertical merge operator: $s \oplus t$ is only defined if $s \in \mathcal{C}_{1}(\Sigma)$ and the label of the root of $t$ (say $a$ ) is equal to the label of the bottom boundary node of $s$. We then obtain $s \oplus t$ by replacing the unique occurrence of $\underline{a}$ in $s$ by $t$. The rank of $s \oplus t$ is $\operatorname{rank}(t)$. For instance,

$$
a(b c(\underline{a} b)) \oplus a(b \underline{c})=a(b c(a(b \underline{c}) b)) .
$$

- The atomic clusters $a(b)$ and $a(\underline{b})$ are constants of the cluster algebra.

A top tree for a tree $t \in \mathcal{T}_{0}$ is an algebraic expression $e$ over the algebra $\mathrm{CA}(\Sigma)$ such that $\llbracket e \rrbracket=t$. A top dag over $\Sigma$ is a valid straight-line program $D$ over the algebra $\mathrm{CA}(\Sigma)$ such that $\llbracket D \rrbracket \in \mathcal{T}_{0}(\Sigma)$. In our terminology, cluster straight-line program would be a more appropriate name, but we prefer to call them top dags.

Example 5 Consider the top dag $D=\left(\left\{S, A_{0}, \ldots, A_{n}, B_{0}, \ldots, B_{n}\right\}, S, \rho\right)$ with $\rho\left(A_{0}\right)=b(a), \rho\left(A_{i}\right)=A_{i-1} \odot A_{i-1}$ for $1 \leq i \leq n, \rho\left(B_{0}\right)=A_{n} \odot b(\underline{b}) \odot A_{n}$, $\rho\left(B_{i}\right)=B_{i-1} \oplus B_{i-1}$ for $1 \leq i \leq n$, and $\rho(S)=B_{n} \oplus b(c)$. We have

$$
\llbracket D \rrbracket=b\left(a^{2^{n}} b\left(a^{2^{n}} \cdots b\left(a^{2^{n}} b(c) a^{2^{n}}\right) \cdots a^{2^{n}}\right) a^{2^{n}}\right),
$$

where $b$ occurs $2^{n}+1$ many times.

## 5 Relative succinctness

We have now three grammar-based formalisms for the compression of unranked trees: FSLPs, top dags, and TSLPs for fcns-encodings. In this section we study their relative succinctness. It turns out that up to multiplicative factors of size $|\Sigma|$ (number of node labels) all three formalisms are equally succinct. Moreover, the transformations between the formalisms can be computed in time linear in the output size. This allows us to transfer algorithmic results for FSLPs to top dags and TSLPs for fcns encodings, and vice versa. We start with top dags:

Proposition 1 For a given top dag $D$ one can compute in linear time an $F S L P F$ such that $\llbracket F \rrbracket=\llbracket D \rrbracket$ and $|F| \in \mathcal{O}(|D|)$.

Proof For $t \in \mathcal{T}(\Sigma)$ we denote with $\triangle(t)$ the forest obtained by removing from $t$ the root node. Translating a cluster with a bottom boundary node to a tree with a parameter is done by the function $\nabla_{\mathrm{x}}: \mathcal{C}_{1}(\Sigma) \rightarrow \mathcal{T}_{1}(\Sigma)$, where $\nabla_{\mathrm{x}}(t)$ replaces the bottom boundary node in $t$ labelled with $a \in \Sigma$ by the tree $a(x)$. We translate a cluster to a forest by $\varphi: \mathcal{C}(\Sigma) \rightarrow \mathcal{F}(\Sigma)$, where $\varphi(t)=\triangle(t)$ for
$t \in \mathcal{C}_{0}(\Sigma)$ and $\varphi(t)=\triangle\left(\nabla_{\mathbf{x}}(t)\right)$ for $t \in \mathcal{C}_{1}(\Sigma)$. Then the following identities hold:

$$
\begin{align*}
\varphi(s) \boxtimes \varphi(t) & =\varphi(s \odot t),  \tag{1}\\
\varphi(s) \boxtimes \varphi(t) & =\varphi(s \oplus t),  \tag{2}\\
\varphi(a(b)) & =b,  \tag{3}\\
\varphi(a(\underline{b})) & =b(x) . \tag{4}
\end{align*}
$$

Let $D=(V, S, \rho)$ be a top dag and let $\alpha$ be the label of the root of $\llbracket D \rrbracket$, which can be easily computed in linear time. We define $F=\left(V \uplus\left\{S^{\prime}\right\}, S^{\prime}, \rho^{\prime}\right)$, such that for every $A \in V$ we have $\llbracket A \rrbracket_{F}=\varphi\left(\llbracket A \rrbracket_{D}\right)$. We set $\rho^{\prime}\left(S^{\prime}\right)=\alpha(S)$, which yields

$$
\llbracket F \rrbracket=\llbracket S^{\prime} \rrbracket_{F}=\llbracket \alpha(S) \rrbracket_{F}=\alpha\left(\llbracket S \rrbracket_{F}\right)=\alpha\left(\triangle\left(\llbracket S \rrbracket_{D}\right)\right)=\llbracket S \rrbracket_{D}=\llbracket D \rrbracket .
$$

We translate the right-hand sides of the top dag as follows:

- If $\rho(A)=a(b)$ then $\rho^{\prime}(A)=b$.
- If $\rho(A)=a(\underline{b})$ then $\rho^{\prime}(A)=b(x)$.
- If $\rho(A)=B \odot C$ then $\rho^{\prime}(A)=B \boxtimes C$.
- If $\rho(A)=B \oplus C$ then $\rho^{\prime}(A)=B \square C$.

Then $\llbracket A \rrbracket_{F}=\varphi\left(\llbracket A \rrbracket_{D}\right)$ for all $A \in V$ follows immediately from (1)-(4).
Proposition 2 For a given FSLP $F$ with $\llbracket F \rrbracket \in \mathcal{T}_{0}(\Sigma)$ and $|\llbracket F \rrbracket| \geq 2$ one can compute in time $\mathcal{O}(|\Sigma| \cdot|F|)$ a top dag $D$ such that $\llbracket D \rrbracket=\llbracket F \rrbracket$ and $|D| \in$ $\mathcal{O}(|\Sigma| \cdot|F|)$.

Proof For every $a \in \Sigma$ we define the mapping $\psi_{a}: \mathcal{T}_{1}(\Sigma) \backslash\{x\} \rightarrow \mathcal{C}_{1}(\Sigma)$ as follows: for $t \in \mathcal{T}_{1}(\Sigma), t \neq x$, let $\psi_{a}(t)$ be the rank-1 cluster obtained from replacing in $t$ the label of the unique $x$-labelled node (which is not the root) by $a$ and declaring this node as the bottom boundary node. Then, the following identities are obvious, where $s, t \in \mathcal{T}_{1}(\Sigma) \backslash\{x\}, u \in \mathcal{T}_{0}(\Sigma),|u| \geq 2$, and $b \in \Sigma$ is the label of the roots of $t$ and $u$ :

$$
\begin{align*}
\psi_{a}(s\langle t\rangle) & =\psi_{b}(s) \oplus \psi_{a}(t)  \tag{5}\\
s\langle u\rangle & =\psi_{b}(s) \oplus u . \tag{6}
\end{align*}
$$

Moreover, for all forests $f, g \in \mathcal{F}_{0}(\Sigma)$ with $f \neq \varepsilon \neq g$ we have

$$
\begin{equation*}
a(f g)=a(f) \odot a(g) \tag{7}
\end{equation*}
$$

Let us now come to the construction for $T$. By Theorem 1 we can assume that the input FSLP $F=(V, S, \rho)$ is in normal form. We can easily eliminate righthand sides of the form $\varepsilon$ without a size increase. This might lead to "chain definitions" of the form $\rho(A)=B$ which can be also eliminated without size increase. After this preprocessing step, we may have also right-hand sides of the form $\rho(A)=a \in \Sigma$ (with $A \in V_{0}^{\perp}$ ), $\rho(A)=a(x), \rho(A)=a(B x)$ (with $B \in V_{0}$ ), and $\rho(A)=a(x C)$ (with $C \in V_{0}$ ). We still denote the resulting FSLP
with $F$. Since we started with an FSLP in normal form, we have $\llbracket A \rrbracket_{F} \in \mathcal{T}_{0}(\Sigma)$ for every $A \in V_{0}^{\perp}$ and $\llbracket A \rrbracket_{F} \in \mathcal{T}_{1}(\Sigma) \backslash\{x\}$ for every $A \in V_{1}$. Hence, for $A \in V_{0}^{\perp} \cup V_{1}$ we can define $\alpha_{A} \in \Sigma$ as the label of the root node in the tree (context) $\llbracket A \rrbracket_{F}$. Also note that every forest $\llbracket A \rrbracket_{F}$ for $A \in V_{0}$ has size at least one. Moreover, if $A \in V_{0}^{\perp}$ and $\rho(A) \notin \Sigma$ then the tree $\llbracket A \rrbracket_{F}$ has size at least two. Let $U_{0}^{\perp}=\left\{A \in V_{0}^{\perp} \mid \rho(A) \notin \Sigma\right\}$.

We define a top dag $D=\left(V^{\prime}, S, \rho^{\prime}\right)$, where $V^{\prime}=V_{0}^{\prime} \cup V_{1}^{\prime}$ with

$$
\begin{aligned}
& V_{0}^{\prime}=U_{0}^{\perp} \uplus\left\{A^{a} \mid A \in V_{0}, a \in \Sigma\right\} \\
& V_{1}^{\prime}=\left\{A_{a} \mid A \in V_{1}, a \in \Sigma\right\}
\end{aligned}
$$

We will define the right-hand side mapping $\rho^{\prime}$ of $D$ such that the following identities hold:

$$
\begin{aligned}
\llbracket A \rrbracket_{D} & =\llbracket A \rrbracket_{F} \text { for every } A \in U_{0}^{\perp}, \\
\llbracket A^{a} \rrbracket_{D} & =a\left(\llbracket A \rrbracket_{F}\right) \text { for every } A \in V_{0}, \\
\llbracket A_{a} \rrbracket_{D} & =\psi_{a}\left(\llbracket A \rrbracket_{F}\right) \text { for every } A \in V_{1} .
\end{aligned}
$$

In order to obtain these identities, we define $\rho^{\prime}$ as follows:

- If $\rho(A)=B C$ for $A, B, C \in V_{0}$ then $\rho^{\prime}\left(A^{a}\right)=B^{a} \odot C^{a}$.
- If $A \in U_{0}^{\perp}$ then $\rho^{\prime}\left(A^{a}\right)=a\left(\alpha_{A}\right) \oplus A$.
- If $\rho(A)=b \in \Sigma$ then $\rho^{\prime}\left(A^{a}\right)=a(b)$.
- If $\rho(A)=a(B)$ (hence $A \in U_{0}^{\perp}$ ) then $\rho^{\prime}(A)=B^{a}$.
- If $\rho(A)=B\langle C\rangle$ for $A, C \in U_{0}^{\perp}$ and $B \in V_{1}$ then $\rho^{\prime}(A)=B_{\alpha_{C}} \Phi C$.
- If $\rho(A)=B\langle C\rangle, \rho(C)=a \in \Sigma$ and $C \in V_{1}$ (hence $A \in U_{0}^{\perp}$ ) then $\rho^{\prime}(A)=$ $B_{a}$.
- If $\rho(A)=B\langle C\rangle$ for $A, B, C \in V_{1}$ then $\rho^{\prime}\left(A_{a}\right)=B_{\alpha_{C}}\left\langle C_{a}\right\rangle$.
- If $\rho(A)=b(B x C)$ for $A \in V_{1}, B, C \in V_{0}$ then $\rho^{\prime}\left(A_{a}\right)=B^{b} \odot b(\underline{a}) \odot C^{b}$.
- If $\rho(A)=b(B x)$ for $A \in V_{1}, B \in V_{0}$ then $\rho^{\prime}\left(A_{a}\right)=B^{b} \odot b(\underline{a})$.
- If $\rho(A)=b(x C)$ for $A \in V_{1}, C \in V_{0}$ then $\rho^{\prime}\left(A_{a}\right)=b(\underline{a}) \odot C^{b}$.
- If $\rho(A)=b(x)$ for $A \in V_{1}$ then $\rho^{\prime}\left(A_{a}\right)=b(\underline{a})$.

The correctness of this construction follows easily by induction, using (5)-(7).
To conclude the proof, note that since $\llbracket F \rrbracket$ is a tree of size two, the start symbol $S$ of $F$ must belong to $U_{0}^{\perp}$. Hence, the above point $(i)$ implies $\llbracket D \rrbracket=$ $\llbracket F \rrbracket$.

The following example shows that the size bound in Proposition 2 is sharp:
Example 6 Let $\Sigma=\left\{a, a_{1}, \ldots, a_{\sigma}\right\}$ and let $t_{n}=a\left(a_{1}\left(a^{m}\right) \cdots a_{\sigma}\left(a^{m}\right)\right)$ where $n \geq 1$ and $m=2^{n}$. For every $n>\sigma$ the tree $t_{n}$ can be produced by an FSLP of size $\mathcal{O}(n)$ : using $n=\log m$ many variables we can produce the forest $a^{m}$ and then $\mathcal{O}(n+\sigma)=\mathcal{O}(n)$ many additional variables suffice to produce $t_{n}$. On the other hand, every top dag for $t_{n}$ has size $\Omega(\sigma \cdot n)$ : consider a top tree $e$ that evaluates to $t_{n}$. Then $e$ must contain a subexpression $e_{i}$ that evaluates to the subtree $a_{i}\left(a^{m}\right)(1 \leq i \leq \sigma)$ of $t_{n}$. The subexpression $e_{i}$ has to produce $a_{i}\left(a^{m}\right)$ using the $\odot$-operation from copies of $a_{i}(a)$. Hence, the expression for $a_{i}\left(a^{m}\right)$ has size $n=\log _{2} m$ and different $e_{i}$ contain no identical subexpressions. Therefore every top dag for $t_{n}$ has size at least $\sigma \cdot n$.

In contrast, FSLPs and TSLPs for fcns-encodings turn out to be equally succinct up to constant factors:
Proposition 3 Let $f \in \mathcal{F}(\Sigma)$ be a forest and let $F$ be an FSLP (or TSLP) over $\Sigma \uplus\{\perp\}$ with $\llbracket F \rrbracket=\operatorname{fcns}(f)$. Then we can transform $F$ in linear time into an $F S L P F^{\prime}$ over $\Sigma$ with $\llbracket F^{\prime} \rrbracket=f$ and $\left|F^{\prime}\right| \in \mathcal{O}(|F|)$.
Proof Let $F=(V, S, \rho)$ be an FSLP over $\Sigma \cup\{\perp\}$. By Theorem 1, we may assume that $F$ is in normal form and every variable is reachable from $S$. This implies $|\operatorname{hor}(A)| \leq 2$ for every $A \in V_{0}$, because $\operatorname{fcns}(f)$ is a binary tree. Hence we can compute the strings hor $(A)=\llbracket A \rrbracket_{F \boxminus} \in\left(V_{0}^{\perp}\right)^{*}$ with $A \in$ $V_{0}^{\top}$ all together in linear time, substitute $\operatorname{hor}(A)$ for each occurrence of $A$ in the right-hand sides, and finally erase the production for $A$. In particular, right-hand sides of the form $\varepsilon$ and $B C$ do not occur any more. Moreover, right-hand sides of the form $a(B x C)$ and $a(B)$ will be transformed as follows by the above replacement: In the first case $(a(B x C))$ we have $a \in \Sigma$ and $|\operatorname{hor}(B)|+|\operatorname{hor}(C)|=1$. Hence the substitution leads to $a(D x)$ or $a(x D)$ with $D \in V_{0}^{\perp}$. In the second case $(a(B))$ either $a=\perp$ and $|\operatorname{hor}(B)|=0$ or $a \in \Sigma$ and $|\operatorname{hor}(B)|=2$, hence the substitution leads to $\perp$ or $a(C D)$ with $C, D \in V_{0}^{\perp}$. Thus we finally obtain an FSLP in which all right-hand sides have one of the following forms:
$-\perp$,
$-a(B C)$,

- $a(B x)$,
$-a(x B)$,
- $B\langle C\rangle$.

This is in fact a TSLP as defined in Section 3. We can now easily translate right-hand sides of the above forms into right-hand sides of an FSLP $F^{\prime}$ for $f$ :
$-\rho(A)=\perp$ becomes $\rho(A)=\varepsilon$.
$-\rho(A)=a(B C)$ becomes $\rho(A)=a(B) C$.
$-\rho(A)=a(B x)$ becomes $\rho(A)=a(B) x$.
$-\rho(A)=a(x B)$ becomes $\rho(A)=a(x) B$.
$-\rho(A)=B\langle C\rangle$ stays the same.
For the correctness of the construction, we have to show that $\operatorname{fcns}\left(\llbracket F^{\prime} \rrbracket\right)=\llbracket F \rrbracket$.
In order to do this, we show the following properties:

$$
\begin{aligned}
\operatorname{fcns}\left(\llbracket A \rrbracket_{F^{\prime}}\right) & =\llbracket A \rrbracket_{F} \text { for all } A \in V_{0}, \\
\operatorname{fcns}\left(\llbracket A \rrbracket_{F^{\prime}}\langle f\rangle\right) & =\llbracket A \rrbracket_{F}\langle\operatorname{fcns}(f)\rangle \text { for all } A \in V_{1}, f \in \mathcal{F}_{0}(\Sigma) .
\end{aligned}
$$

These are shown using a simple induction and case analysis:
$-\rho(A)=\perp: \mathrm{fcns}\left(\llbracket A \rrbracket_{F^{\prime}}\right)=\mathrm{fcns}(\varepsilon)=\perp=\llbracket A \rrbracket_{F}$.
$-\rho(A)=a(B C)$ : We obtain ("ind" refers to induction on $B$ and $C$ )

$$
\begin{aligned}
\operatorname{fcns}\left(\llbracket A \rrbracket_{F^{\prime}}\right) & =\operatorname{fcns}\left(\llbracket a(B) C \rrbracket_{F^{\prime}}\right) \\
& =\operatorname{fcns}\left(a\left(\llbracket B \rrbracket_{F^{\prime}}\right) \llbracket C \rrbracket_{F^{\prime}}\right) \\
& =a\left(\operatorname{fcns}\left(\llbracket B \rrbracket_{F^{\prime}}\right) \operatorname{fcns}\left(\llbracket C \rrbracket_{F^{\prime}}\right)\right) \\
& \stackrel{\text { ind }}{=} a\left(\llbracket B \rrbracket_{F} \llbracket C \rrbracket_{F}\right)=\llbracket A \rrbracket_{F} .
\end{aligned}
$$

$-\rho(A)=a(B x)$ : We obtain

$$
\begin{aligned}
\operatorname{fcns}\left(\llbracket A \rrbracket_{F^{\prime}}\langle f\rangle\right) & =\operatorname{fcns}\left(\llbracket a(B) x \rrbracket_{F^{\prime}}\langle f\rangle\right) \\
& =\operatorname{fcns}\left(a\left(\llbracket B \rrbracket_{F^{\prime}}\right) f\right) \\
& =a\left(\operatorname{fcns}\left(\llbracket B \rrbracket_{F^{\prime}}\right) \operatorname{fcns}(f)\right) \\
& \stackrel{\operatorname{ind}}{=} a\left(\llbracket B \rrbracket_{F} \operatorname{fcns}(f)\right) \\
& =\llbracket a(B x) \rrbracket_{F}\langle\operatorname{fcns}(f)\rangle=\llbracket A \rrbracket_{F}\langle\operatorname{fcns}(f)\rangle .
\end{aligned}
$$

$-\rho(A)=a(x B)$ : We obtain

$$
\begin{aligned}
\operatorname{fcns}\left(\llbracket A \rrbracket_{F^{\prime}}\langle f\rangle\right) & =\operatorname{fcns}\left(\llbracket a(x) B \rrbracket_{F^{\prime}}\langle f\rangle\right) \\
& =\operatorname{fcns}\left(a(f) \llbracket B \rrbracket_{F^{\prime}}\right) \\
& =a\left(\operatorname{fcns}(f) \operatorname{fcns}\left(\llbracket B \rrbracket_{F^{\prime}}\right)\right) \\
& \stackrel{\operatorname{ind}}{=} a\left(\operatorname{fcns}(f) \llbracket B \rrbracket_{F}\right) \\
& =\llbracket a(x B) \rrbracket_{F}\langle\operatorname{fcns}(f)\rangle=\llbracket A \rrbracket_{F}\langle\operatorname{fcns}(f)\rangle .
\end{aligned}
$$

$-\rho(A)=B\langle C\rangle$ with $C \in V_{0}$ : We obtain the following, where the first (resp., second) induction step uses induction on $B$ (resp., $C$ ):

$$
\begin{aligned}
\operatorname{fcns}\left(\llbracket A \rrbracket_{F^{\prime}}\right) & =\mathrm{fcns}\left(\llbracket B\langle C\rangle \rrbracket_{F^{\prime}}\right) \\
& =\operatorname{fcns}\left(\llbracket B \rrbracket_{F^{\prime}}\left\langle\llbracket \rrbracket_{F^{\prime}}\right\rangle\right) \\
& \stackrel{\operatorname{ind}}{=} \llbracket B \rrbracket_{F}\left\langle\mathrm{fcns}\left(\llbracket C \rrbracket_{F^{\prime}}\right)\right\rangle \\
& \stackrel{\operatorname{ind}}{=} \llbracket B \rrbracket_{F}\left\langle\llbracket C \rrbracket_{F}\right\rangle \\
& =\llbracket B\langle C\rangle \rrbracket_{F}=\llbracket A \rrbracket_{F} .
\end{aligned}
$$

- $\rho(A)=B\langle C\rangle$ with $C \in V_{1}$ : We obtain

$$
\begin{aligned}
\operatorname{fcns}\left(\llbracket A \rrbracket_{F^{\prime}}\langle f\rangle\right) & =\mathrm{fcns}\left(\llbracket B\langle C\rangle \rrbracket_{F^{\prime}}\langle f\rangle\right) \\
& =\mathrm{fcns}\left(\left(\llbracket B \rrbracket_{F^{\prime}}\left\langle\llbracket C \rrbracket_{F^{\prime}}\right\rangle\right)\langle f\rangle\right) \\
& =\mathrm{fcns}\left(\llbracket B \rrbracket_{F^{\prime}}\left\langle\llbracket C \rrbracket_{F^{\prime}}\langle f\rangle\right\rangle\right) \\
& \stackrel{\text { ind }}{=} \llbracket B \rrbracket_{F}\left\langle\operatorname{fcns}\left(\llbracket C \rrbracket_{F^{\prime}}\langle f\rangle\right)\right\rangle \\
& \stackrel{\text { ind }}{=} \llbracket B \rrbracket_{F}\left\langle\llbracket C \rrbracket_{F}\langle\operatorname{fcns}(f)\rangle\right\rangle \\
& =\llbracket B\langle C\rangle \rrbracket_{F}\langle\mathrm{fcns}(f)\rangle=\llbracket A \rrbracket_{F}\langle\operatorname{fcns}(f)\rangle .
\end{aligned}
$$

This concludes the proof of the proposition.
Proposition 4 For every FSLP $F$ over $\Sigma$, we can construct in linear time a $T S L P T$ over $\Sigma \cup\{\perp\}$ with $\llbracket T \rrbracket=\mathrm{fcns}(\llbracket F \rrbracket)$ and $|T| \in \mathcal{O}(|F|)$.
Proof We start with the definition of two functions which are closely related to fcns. The first function $\pi: \mathcal{F}_{0}(\Sigma) \rightarrow \mathcal{T}_{1}(\Sigma \cup\{\perp\})$ is defined inductively by

$$
\begin{aligned}
\pi(\varepsilon) & =x \\
\pi(a(f) g) & =a(\operatorname{fcns}(f) \pi(g)) \text { for all } a \in \Sigma, f, g \in \mathcal{F}_{0}(\Sigma)
\end{aligned}
$$

in particular its restriction to $\mathcal{T}_{0}(\Sigma)$ is given by

$$
\begin{equation*}
\pi(a(f))=a(\operatorname{fcns}(f) x) \text { for all } a \in \Sigma, f \in \mathcal{F}_{0}(\Sigma) \tag{8}
\end{equation*}
$$

Simple inductive proofs show that

$$
\begin{align*}
\operatorname{fcns}(f) & =\pi(f)\langle\perp\rangle \text { for all } f \in \mathcal{F}_{0}(\Sigma)  \tag{9}\\
\pi(f g) & =\pi(f)\langle\pi(g)\rangle \text { for all } f, g \in \mathcal{F}_{0}(\Sigma) \tag{10}
\end{align*}
$$

The second function $\varphi: \mathcal{F}(\Sigma) \rightarrow \mathcal{T}(\Sigma \cup\{\perp\})$ is defined inductively by

$$
\begin{aligned}
\varphi(\varepsilon) & =\perp \\
\varphi(x g) & =x \text { for all } g \in \mathcal{F}_{0}(\Sigma) \\
\varphi(a(f) g) & =a(\varphi(f) \varphi(g)) \text { for all } a \in \Sigma, f, g \in \mathcal{F}(\Sigma) \text { with } a(f) g \in \mathcal{F}(\Sigma) .
\end{aligned}
$$

Simple inductive proofs show that

$$
\begin{align*}
\operatorname{fcns}(f) & =\varphi(f) \text { for all } f \in \mathcal{F}_{0}(\Sigma)  \tag{11}\\
\varphi(f x g) & =\pi(f) \text { for all } f, g \in \mathcal{F}_{0}(\Sigma) \tag{12}
\end{align*}
$$

The most important equation for $\varphi$ is

$$
\begin{align*}
\varphi(f\langle a(g)\rangle)= & \varphi(f)\langle a(\varphi(g) \mathrm{fcns}(\operatorname{sib}(f)))\rangle  \tag{13}\\
& \text { for all } f \in \mathcal{F}_{1}(\Sigma), a \in \Sigma, g \in \mathcal{F}_{0}(\Sigma)
\end{align*}
$$

where $\operatorname{sib}(f) \in \mathcal{F}_{0}(\Sigma)$ denotes the sequence of all right siblings of $x$ in $f \in$ $\mathcal{F}_{1}(\Sigma)$, i.e.,

$$
\begin{aligned}
\operatorname{sib}(x g) & =g \text { for all } g \in \mathcal{F}_{0}(\Sigma), \\
\operatorname{sib}(a(f) g) & =\left\{\begin{array}{l}
\operatorname{sib}(f) \text { if } f \in \mathcal{F}_{1}(\Sigma) \text { and } g \in \mathcal{F}_{0}(\Sigma), \\
\operatorname{sib}(g) \text { if } f \in \mathcal{F}_{0}(\Sigma) \text { and } g \in \mathcal{F}_{1}(\Sigma)
\end{array}\right.
\end{aligned}
$$

Equation (13) tells us how to obtain $\varphi(f\langle a(g)\rangle)$ from $\varphi(f)$ and $\varphi(g)$. For its proof note that $a(\varphi(g) \operatorname{fcns}(\operatorname{sib}(f)))=a(\varphi(g) \varphi(\operatorname{sib}(f)))=\varphi(a(g) \operatorname{sib}(f))$. Hence it suffices to prove

$$
\varphi(f\langle t\rangle)=\varphi(f)\langle\varphi(t \operatorname{sib}(f))\rangle \text { for all } f \in \mathcal{F}_{1}(\Sigma), t \in \mathcal{T}(\Sigma)
$$

which can be done by the following induction on the length of the sequence $f$ (and case distinction on the first element of $f$ ):
$-f=x g$ :
Then $g \in \mathcal{F}_{0}(\Sigma)$ and we have

$$
\varphi(f\langle t\rangle)=\varphi(t g)=x\langle\varphi(t g)\rangle=\varphi(f)\langle\varphi(t g)\rangle=\varphi(f)\langle\varphi(t \operatorname{sib}(f))\rangle
$$

$-f=a(g) h$ with $a \in \Sigma$ and $g \in \mathcal{F}_{0}(\Sigma)$ :
Then $h \in \mathcal{F}_{1}(\Sigma)$ and we obtain

$$
\begin{aligned}
\varphi(f\langle t\rangle) & =\varphi(a(g) h\langle t\rangle) \\
& =a(\varphi(g) \varphi(h\langle t\rangle)) \text { by the definition of } \varphi \\
& =a(\varphi(g) \varphi(h)\langle\varphi(t \operatorname{sib}(h))\rangle) \text { by induction for } h \\
& =a(\varphi(g) \varphi(h)\langle\varphi(t \operatorname{sib}(f))\rangle) \text { because } \operatorname{sib}(f)=\operatorname{sib}(h) \\
& =a(\varphi(g) \varphi(h))\langle\varphi(t \operatorname{sib}(f))\rangle \\
& =\varphi(f)\langle\varphi(t \operatorname{sib}(f))\rangle \text { by the definition of } \varphi .
\end{aligned}
$$

$-f=a(g) h$ with $a \in \Sigma$ and $g \in \mathcal{F}_{1}(\Sigma)$ :
Then $h \in \mathcal{F}_{0}(\Sigma)$ and the proof is the same as in the previous step except that the roles of $g$ and $h$ are exchanged.
Equations (8) to (13) are a guideline for the construction of the TSLP $T$. Let $F=(V, S, \rho)$. As usual we may assume that $F$ is in normal form. Then $T=\left(V^{\prime}, S, \rho^{\prime}\right)$ where

$$
\begin{aligned}
& V_{0}^{\prime}=V_{0} \uplus\left\{A_{\triangle} \mid A \in V_{0}^{\perp}\right\} \text { and } \\
& V_{1}^{\prime}=\left\{A^{\pi} \mid A \in V_{0}\right\} \uplus\left\{A_{\triangle} \mid A \in V_{1}\right\}
\end{aligned}
$$

with new variables $A_{\triangle}, A^{\pi} \notin V$. To explain the role of these variables let $\Delta: \mathcal{T}(\Sigma) \backslash\{x\} \rightarrow \mathcal{F}(\Sigma)$ be defined by $\Delta(a(f))=f$. We want to achieve that

$$
\begin{align*}
\llbracket A \rrbracket_{T} & =\mathrm{fcns}\left(\llbracket A \rrbracket_{F}\right) \text { for every } A \in V_{0},  \tag{14}\\
\llbracket A^{\pi} \rrbracket_{T} & =\pi\left(\llbracket A \rrbracket_{F}\right) \text { for every } A \in V_{0},  \tag{15}\\
\llbracket A \triangle \rrbracket_{T} & =\varphi\left(\Delta\left(\llbracket A \rrbracket_{F}\right)\right) \text { for every } A \in V_{0}^{\perp} \cup V_{1} . \tag{16}
\end{align*}
$$

From (14) we obtain $\llbracket T \rrbracket=\llbracket S \rrbracket_{T}=\mathrm{fcns}\left(\llbracket S \rrbracket_{F}\right)=\mathrm{fcns}(\llbracket F \rrbracket)$ which concludes the proof of the proposition (assuming that $T$ satisfies the size bound $|T| \in$ $\mathcal{O}(|F|))$.

It remains to define $\rho^{\prime}$ in such a way that (14), (15) and (16) are satisfied. For every $A \in V_{0}^{\perp} \cup V_{1}$ let $\alpha_{A}$ denote the root label of $\llbracket A \rrbracket_{F}$, and for every $A \in V_{1}$ let $R_{A} \in V_{0}$ be a variable with $\llbracket R_{A} \rrbracket_{F}=\operatorname{sib}\left(\llbracket A \rrbracket_{F}\right)$. Such a variable exists in $V_{0}$, namely
$-R_{A}=C$ if $\rho(A)=a(B x C)$,
$-R_{A}=R_{C}$ if $\rho(A)=B\langle C\rangle$ for $B, C \in V_{1}$.
Then we define $\rho^{\prime}$ by

- $\rho^{\prime}(A)=A^{\pi}\langle\perp\rangle$ if $A \in V_{0}$,
- $\rho^{\prime}\left(A^{\pi}\right)=\alpha_{A}\left(A_{\triangle} x\right)$ if $A \in V_{0}^{\perp}$,
- $\rho^{\prime}\left(A^{\pi}\right)=x$ if $A \in V_{0}^{\top}$ with $\rho(A)=\varepsilon$,
- $\rho^{\prime}\left(A^{\pi}\right)=B^{\pi}\left\langle C^{\pi}\right\rangle$ if $A \in V_{0}^{\top}$ with $\rho(A)=B C$,
- $\rho^{\prime}\left(A_{\triangle}\right)=B$ if $A \in V_{0}^{\perp}$ with $\rho(A)=a(B)$,
- $\rho^{\prime}\left(A_{\triangle}\right)=B^{\pi}$ if $A \in V_{1}$ with $\rho(A)=a(B x C)$,
$-\rho^{\prime}\left(A_{\triangle}\right)=B_{\triangle}\left\langle\alpha_{C}\left(C_{\triangle} R_{B}\right)\right\rangle$ if $A \in V_{0}^{\perp} \cup V_{1}$ with $\rho(A)=B\langle C\rangle$.
This concludes the definition of the TSLP $T$. It is clear that $T$ can be constructed from $F$ in linear time and that $|T| \in \mathcal{O}(|F|)$.

Equations (14), (15) and (16) are proved by the following induction on $\leq_{T}$. Note that $A_{\triangle} \leq_{T} A^{\pi}$ for all $A \in V_{0}^{\perp}$ and $A^{\pi} \leq_{T} A$ for all $A \in V_{0}$.

- If $A \in V_{0}$ then $\rho^{\prime}(A)=A^{\pi}\langle\perp\rangle$ and thus

$$
\begin{aligned}
\llbracket A \rrbracket_{T} & =\llbracket A^{\pi} \rrbracket_{T}\langle\perp\rangle \\
& =\pi\left(\llbracket A \rrbracket_{F}\right)\langle\perp\rangle \text { by induction for } A^{\pi} \\
& =\operatorname{fcns}\left(\llbracket A \rrbracket_{F}\right) \text { by equation }(9) .
\end{aligned}
$$

- If $A \in V_{0}^{\perp}$ with $\llbracket A \rrbracket_{F}=a(f)$ then $\rho^{\prime}\left(A^{\pi}\right)=a\left(A_{\triangle} x\right)$ and thus

$$
\begin{aligned}
\llbracket A^{\pi} \rrbracket_{T} & =a\left(\llbracket A_{\triangle} \rrbracket_{T} x\right) \\
& =a\left(\varphi\left(\Delta\left(\llbracket A \rrbracket_{F}\right)\right) x\right) \text { by induction for } A_{\triangle} \\
& =a(\varphi(f) x) \\
& =a(\operatorname{fcns}(f) x) \text { by equation }(11) \\
& =\pi(a(f)) \text { by equation }(8) \\
& =\pi\left(\llbracket A \rrbracket_{F}\right) .
\end{aligned}
$$

- If $A \in V_{0}^{\top}$ with $\rho(A)=\varepsilon$ then $\rho^{\prime}\left(A^{\pi}\right)=x$ and thus

$$
\begin{aligned}
\llbracket A^{\pi} \rrbracket_{T} & =x \\
& =\pi(\varepsilon) \text { by the definition of } \pi \\
& =\pi\left(\llbracket A \rrbracket_{F}\right) .
\end{aligned}
$$

- If $A \in V_{0}^{\top}$ with $\rho(A)=B C$ then $\rho^{\prime}\left(A^{\pi}\right)=B^{\pi}\left\langle C^{\pi}\right\rangle$ and thus

$$
\begin{aligned}
\llbracket A^{\pi} \rrbracket_{T} & =\llbracket B^{\pi} \rrbracket_{T}\left\langle\llbracket C^{\pi} \rrbracket_{T}\right\rangle \\
& =\pi\left(\llbracket B \rrbracket_{F}\right)\left\langle\pi\left(\llbracket C \rrbracket_{F}\right)\right\rangle \text { by induction for } B^{\pi} \text { and } C^{\pi} \\
& =\pi\left(\llbracket B \rrbracket_{F} \llbracket C \rrbracket_{F}\right) \text { by equation }(10) \\
& =\pi\left(\llbracket A \rrbracket_{F}\right) .
\end{aligned}
$$

- If $A \in V_{0}^{\perp}$ with $\rho(A)=a(B)$ then $\rho^{\prime}\left(A_{\triangle}\right)=B$ and thus

$$
\begin{aligned}
\llbracket A_{\triangle} \rrbracket_{T} & =\llbracket B \rrbracket_{T} \\
& =\operatorname{fcns}\left(\llbracket B \rrbracket_{F}\right) \text { by induction for } B \\
& =\varphi\left(\llbracket B \rrbracket_{F}\right) \text { by equation }(11) \\
& =\varphi\left(\Delta\left(\llbracket A \rrbracket_{F}\right)\right) .
\end{aligned}
$$

- If $A \in V_{1}$ with $\rho(A)=a(B x C)$ then $\rho^{\prime}\left(A_{\triangle}\right)=B^{\pi}$ and thus

$$
\begin{aligned}
\llbracket A_{\triangle} \rrbracket_{T} & =\llbracket B^{\pi} \rrbracket_{T} \\
& =\pi\left(\llbracket B \rrbracket_{F}\right) \text { by induction for } B \\
& =\varphi\left(\llbracket B \rrbracket_{F} x \llbracket C \rrbracket_{F}\right) \text { by equation }(12) \\
& =\varphi\left(\Delta\left(\llbracket A \rrbracket_{F}\right)\right) .
\end{aligned}
$$

- If $A \in V_{0}^{\perp} \cup V_{1}$ with $\rho(A)=B\langle C\rangle, \llbracket B \rrbracket_{F}=b(f)$ and $\llbracket C \rrbracket_{F}=c(g)$ then $\rho^{\prime}(A)=B_{\triangle}\left\langle c\left(C_{\triangle} R_{B}\right)\right\rangle$ and we have $\llbracket R_{B} \rrbracket_{F}=\operatorname{sib}(b(f))=\operatorname{sib}(f)$. Thus we obtain

$$
\begin{aligned}
\llbracket A_{\Delta} \rrbracket_{T} & =\llbracket B_{\triangle} \rrbracket_{T}\left\langle c\left(\llbracket C_{\triangle} \rrbracket_{T} \llbracket R_{B} \rrbracket_{T}\right)\right\rangle \\
& =\varphi\left(\Delta\left(\llbracket B \rrbracket_{F}\right)\right)\left\langle c\left(\varphi\left(\Delta\left(\llbracket C \rrbracket_{F}\right)\right) \operatorname{fcns}\left(\llbracket R_{B} \rrbracket_{F}\right)\right)\right\rangle
\end{aligned}
$$

$$
\text { by induction for } B_{\triangle}, C_{\triangle} \text { and } R_{B}
$$

$$
=\varphi(f)\langle c(\varphi(g) \operatorname{fcns}(\operatorname{sib}(f)))\rangle
$$

$$
=\varphi(f\langle c(g)\rangle) \text { by equation (13) }
$$

$$
=\varphi(\Delta(b(f)\langle c(g)\rangle))
$$

$$
=\varphi\left(\Delta\left(\llbracket B \rrbracket_{F}\left\langle\llbracket C \rrbracket_{F}\right\rangle\right)\right)
$$

$$
=\varphi\left(\Delta\left(\llbracket A \rrbracket_{F}\right)\right)
$$

This concludes the proof of Proposition 4.
Proposition 4 and the construction from [9, Proposition 8.3.2] allow to reduce the evaluation of forest automata on FSLPs (for a definition of forest and tree automata, see [9]) to the evaluation of ordinary tree automata on binary trees. The latter problem can be solved in polynomial time [25], which yields:
Corollary 1 Given a forest automaton $A$ and an FSLP (or top dag) $F$ we can check in polynomial time whether $A$ accepts $\llbracket F \rrbracket$.

Proof First, we construct a TSLP $T$ for fcns $(\llbracket F \rrbracket)$ using Proposition 4. We also convert $A$ in polynomial time into a tree automaton $A^{\prime}$ such that $A^{\prime}$ accepts $\mathrm{fcns}(f)$ if and only if $A$ accepts $f$, using the construction from [9, Proposition 8.3.2]. Finally, we use the result from [25] to check in polynomial time whether $A^{\prime}$ accepts $\llbracket T \rrbracket$.

In [3], a linear time algorithm is presented that constructs from a tree of size $n$ with $\sigma$ many node labels a top dag of size $\mathcal{O}\left(n / \log _{\sigma}^{0.19} n\right)$. In [16] this bound was improved to $\mathcal{O}\left(n \log \log n / \log _{\sigma} n\right)$ (for the same algorithm as in [3]). In [26] we recently presented an alternative construction that achieves the information-theoretic optimum of $\mathcal{O}\left(n / \log _{\sigma} n\right)$; another optimal construction was presented in [11]. Moreover, as in [3], the constructed top dag satisfies the additional size bound $\mathcal{O}(d \cdot \log n)$, where $d$ is the size of the minimal dag of $t$. With Proposition 1 and 4 we obtain:

Corollary 2 Let $t$ be a tree of size $n$ with $\sigma$ many node labels. Then we can construct in linear time an FSLP for $t$ (or a TSLP for $\mathrm{fcns}(t)$ ) of size $\mathcal{O}\left(n / \log _{\sigma} n\right) \cap \mathcal{O}(d \cdot \log n)$, where $d$ is the size of the minimal dag of $t$.

## 6 Testing equality modulo associativity and commutativity

In this section we will give an algorithmic application which proves the usefulness of FSLPs (even if we deal with binary trees). We fix two subsets $\mathcal{A} \subseteq \Sigma$ (the set of associative symbols) and $\mathcal{C} \subseteq \Sigma$ (the set of commutative symbols). This means that we impose the following identities for all $a \in \mathcal{A}, c \in \mathcal{C}$, all trees $t_{1}, \ldots, t_{n} \in \mathcal{T}_{0}(\Sigma)$, all permutations $\xi:\{1, \ldots, n\} \rightarrow\{1, \ldots, n\}$, and all $1 \leq i \leq j \leq n+1$ :

$$
\begin{align*}
a\left(t_{1} \cdots t_{n}\right) & =a\left(t_{1} \cdots t_{i-1} a\left(t_{i} \cdots t_{j-1}\right) t_{j} \cdots t_{n}\right)  \tag{ASSOC}\\
c\left(t_{1} \cdots t_{n}\right) & =c\left(t_{\xi(1)} \cdots t_{\xi(n)}\right) \tag{COMM}
\end{align*}
$$

Note that the standard law of associativity $x \circ(y \circ z)=(x \circ y) \circ z$ for a binary operator $\circ$ is an instance of (ASSOC) if we consider $\circ$ as a symbol in $\mathcal{A}$.

### 6.1 Associative symbols

Below, we define the associative normal form $\operatorname{nf}_{\mathcal{A}}(f)$ of a forest $f$ and show that from an FSLP $F$ we can compute in linear time an FSLP $F^{\prime}$ with $\llbracket F^{\prime} \rrbracket=$ $\mathrm{nf}_{\mathcal{A}}(\llbracket F \rrbracket)$. For trees $s, t \in \mathcal{T}_{0}(\Sigma)$ we have that $s=t$ modulo the identities in (ASSOC) if and only if $\operatorname{nf}_{\mathcal{A}}(s)=\operatorname{nf}_{\mathcal{A}}(t)$. The generalization to forests is needed for the induction, where a slight technical problem arises. Whether the forests $t_{1} \cdots t_{i-1} a\left(t_{i} \cdots t_{j-1}\right) t_{j} \cdots t_{n}$ and $t_{1} \cdots t_{n}$ are equal modulo the identities in (ASSOC) actually depends on the symbol on top of these two forests. If it is an $a$, and $a \in \mathcal{A}$, then the two forests are equal modulo associativity, otherwise not. To cope with this problem, we use for every associative symbol $a \in \mathcal{A}$ a function $\phi_{a}: \mathcal{F}_{0}(\Sigma) \rightarrow \mathcal{F}_{0}(\Sigma)$ that pulls up occurrences of $a$ whenever possible.

Let $\bullet \notin \Sigma$ be a new symbol. For every $a \in \Sigma \cup\{\bullet\}$ let $\phi_{a}: \mathcal{F}_{0}(\Sigma) \rightarrow \mathcal{F}_{0}(\Sigma)$ be defined as follows, where $f \in \mathcal{F}_{0}(\Sigma), n \geq 0$ and $t_{1}, \ldots, t_{n} \in \mathcal{T}_{0}(\Sigma)$ :

$$
\begin{aligned}
\phi_{a}(b(f)) & = \begin{cases}\phi_{a}(f) & \text { if } a \in \mathcal{A} \text { and } a=b, \\
b\left(\phi_{b}(f)\right) & \text { otherwise },\end{cases} \\
\phi_{a}\left(t_{1} \cdots t_{n}\right) & =\phi_{a}\left(t_{1}\right) \cdots \phi_{a}\left(t_{n}\right) .
\end{aligned}
$$

Note that $\phi_{a}(\varepsilon)=\varepsilon$. We define $\operatorname{nf}_{\mathcal{A}}: \mathcal{F}_{0}(\Sigma) \rightarrow \mathcal{F}_{0}(\Sigma)$ by $\operatorname{nf}_{\mathcal{A}}(f)=\phi_{\bullet}(f)$.
Example 7 Let $t=a(a(c d) b(c d) a(e))$ and $\mathcal{A}=\{a\}$. We obtain

$$
\begin{aligned}
\phi_{a}(t) & =\phi_{a}(a(c d) b(c d) a(e)) \\
& =\phi_{a}(a(c d)) \phi_{a}(b(c d)) \phi_{a}(a(e)) \\
& =\phi_{a}(c d) b\left(\phi_{b}(c d)\right) \phi_{a}(e) \\
& =c d b(c d) e \\
\phi_{b}(t) & =a\left(\phi_{a}(a(c d) b(c d) a(e))\right) \\
& =a(c d b(c d) e)
\end{aligned}
$$




Fig. $4 t$ on the left, $\phi_{a}(t)$ in the middle and $\phi_{b}(t)$ on the right from Example 7

To show the following simple lemma one considers the terminating and confluent rewriting system obtained by directing the equations in (ASSOC) from right to left.

Lemma 2 For two forests $f_{1}, f_{2} \in \mathcal{F}_{0}(\Sigma), \operatorname{nf}_{\mathcal{A}}\left(f_{1}\right)=\operatorname{nf}_{\mathcal{A}}\left(f_{2}\right)$ if and only if $f_{1}$ and $f_{2}$ are equal modulo the identities in (ASSOC) for all $a \in \mathcal{A}$.

Proof Consider the (infinite) term rewriting system consisting of all rules

$$
a\left(t_{1} \cdots t_{i-1} a\left(t_{i} \cdots t_{j-1}\right) t_{j} \cdots t_{n}\right) \rightarrow a\left(t_{1} \cdots t_{n}\right) \quad(\rightarrow-\mathrm{ASSOC})
$$

for $a \in \mathcal{A}, t_{1}, \ldots, t_{n} \in \mathcal{T}_{0}(\Sigma)$ and $1 \leq i \leq j \leq n+1$. Let $\rightarrow_{\mathcal{A}}$ be the resulting rewrite relation. It is clearly terminating. Moreover, by considering all possible overlappings of left-hand sides, one sees that the system is also confluent. Hence, every forest $f$ rewrites into a unique normal form, which is in fact $\mathrm{nf}_{\mathcal{A}}(f)$. The lemma follows since $f_{1}$ and $f_{2}$ are equal modulo the identities in (ASSOC) if and only if they rewrite into the same normal forms, which means that $\operatorname{nf}_{\mathcal{A}}\left(f_{1}\right)=\operatorname{nf}_{\mathcal{A}}\left(f_{2}\right)$.

Lemma 3 From a given $F S L P$ F over $\Sigma$ one can construct in time $\mathcal{O}(|F| \cdot|\Sigma|)$ an $F S L P F^{\prime}$ with $\llbracket F^{\prime} \rrbracket=\operatorname{nf}_{\mathcal{A}}(\llbracket F \rrbracket)$.

Proof By Theorem 1, we may assume that $F=(V, S, \rho)$ is in normal form. We introduce new variables $A_{a}$ for all $a \in \Sigma \cup\{\bullet\}$ and define the right-hand sides of $F^{\prime}$ such that $\llbracket A_{a} \rrbracket_{F^{\prime}}=\phi_{a}\left(\llbracket A \rrbracket_{F}\right)$ for all $A \in V_{0}$ and $\llbracket B_{a}\left\langle\phi_{b}(f)\right\rangle \rrbracket_{F^{\prime}}=$ $\phi_{a}\left(\llbracket B\langle f\rangle \rrbracket_{F}\right)$ for all $B \in V_{1}, f \in \mathcal{F}_{0}(\Sigma)$, where $b$ is the label of the parent node of the parameter $x$ in $\llbracket B \rrbracket_{F}$. This parent node exists since $F$ is in normal form. For every $B \in V_{1}$ let $\omega_{B}$ be the symbol above $x$ in $\llbracket B \rrbracket_{F}$. These symbols exist by definition of the normal form, and they can be computed all together in linear time. Now let $F^{\prime}=\left(V^{\prime}, S_{\bullet}, \rho^{\prime}\right)$ where $V^{\prime}=\left\{A_{a} \mid A \in V, a \in \Sigma \cup\{\bullet\}\right\}$, and $\rho^{\prime}$ is defined by
$-\rho^{\prime}\left(A_{a}\right)=\varepsilon$ if $\rho(A)=\varepsilon$,

- $\rho^{\prime}\left(A_{a}\right)=B_{a} C_{a}$ if $\rho(A)=B C$,
$-\rho^{\prime}\left(A_{a}\right)=B_{a}\left\langle C_{\omega_{B}}\right\rangle$ if $\rho(A)=B\langle C\rangle$,
- $\rho^{\prime}\left(A_{a}\right)=B_{a}$ if $\rho(A)=a(B)$ and $a \in \mathcal{A}$,
- $\rho^{\prime}\left(A_{a}\right)=b\left(B_{b}\right)$ if $\rho(A)=b(B)$ with $b \neq a$ or $b \notin \mathcal{A}$,
$-\rho^{\prime}\left(A_{a}\right)=B_{a} x C_{a}$ if $\rho(A)=a(B x C)$ with $a \in \mathcal{A}$,
- $\rho^{\prime}\left(A_{a}\right)=b\left(B_{b} x C_{b}\right)$ if $\rho(A)=b(B x C)$ with $b \neq a$ or $b \notin \mathcal{A}$.

An induction shows:
(i) $\llbracket A_{a} \rrbracket_{F^{\prime}}=\phi_{a}\left(\llbracket A \rrbracket_{F}\right)$ for all $A \in V_{0}$ and $a \in \Sigma \cup\{\bullet\}$, and
(ii) $\llbracket B_{a}\left\langle\phi_{\omega_{B}}(f)\right\rangle \rrbracket_{F^{\prime}}=\phi_{a}\left(\llbracket B\langle f\rangle \rrbracket_{F}\right)$ for all $B \in V_{1}, a \in \Sigma \cup\{\bullet\}$ and $f \in \mathcal{F}_{0}(\Sigma)$.

From (i) we obtain $\llbracket F^{\prime} \rrbracket=\llbracket S_{\bullet} \rrbracket_{F^{\prime}}=\phi_{\bullet}\left(\llbracket S \rrbracket_{F}\right)=\operatorname{nf}_{\mathcal{A}}\left(\llbracket S \rrbracket_{F}\right)=\operatorname{nf}_{\mathcal{A}}(\llbracket F \rrbracket)$.

### 6.2 Commutative symbols

To test whether two trees over $\Sigma$ are equivalent with respect to commutativity, we define a commutative normal form $\operatorname{nf}_{\mathcal{C}}(t)$ of a tree $t \in \mathcal{T}_{0}(\Sigma)$ such that $\operatorname{nf}_{\mathcal{C}}\left(t_{1}\right)=\operatorname{nf}_{\mathcal{C}}\left(t_{2}\right)$ if and only if $t_{1}$ and $t_{2}$ are equivalent with respect to the identities in (COMM) for all $c \in \mathcal{C}$.

We start with a general definition: Let $<$ be a total order on a possibly infinite alphabet $\Delta$, and let $\leq$ be its reflexive closure. Then we define sort $^{<}: \Delta^{*} \rightarrow \Delta^{*}$ by sort $<\left(a_{1} \cdots a_{n}\right)=a_{i_{1}} \cdots a_{i_{n}}$ with $\left\{i_{1}, \ldots, i_{n}\right\}=\{1, \ldots, n\}$ and $a_{i_{1}} \leq \cdots \leq a_{i_{n}}$.

Lemma 4 Let $G$ be an SSLP over $\Delta$ and let $<$ be some total order on $\Delta$. We can construct in time $\mathcal{O}(|\Delta| \cdot|G|)$ an SSLP $G^{\prime}$ such that $\llbracket G^{\prime} \rrbracket=$ sort $^{<}(\llbracket G \rrbracket)$.

Proof Let $G=(V, S, \rho)$. We define the SSLP $G^{\prime}=\left(V^{\prime}, S, \rho^{\prime}\right)$ over $\Delta$ where $V^{\prime}=\{S\} \cup\left\{A_{a} \mid A \in V, a \in \Delta\right\}$ with new variables $A_{a} \notin V$, and $\rho^{\prime}$ defined by
$-\rho^{\prime}\left(A_{a}\right)=\varepsilon$ if $\rho(A) \in\{\varepsilon\} \cup(\Delta \backslash\{a\})$,

- $\rho^{\prime}\left(A_{a}\right)=a$ if $\rho(A)=a$,
$-\rho^{\prime}\left(A_{a}\right)=B_{a} C_{a}$ if $\rho(A)=B C$,
$-\rho^{\prime}(S)=S_{a_{1}} \cdots S_{a_{n}}$ if $\Delta=\left\{a_{1}, \ldots, a_{n}\right\}$ with $a_{1}<\cdots<a_{n}$.
A straightforward induction shows that $\llbracket A_{a} \rrbracket_{G^{\prime}}=a^{m_{a}}$ where $m_{a}$ is the number of occurrences of $a$ in $\llbracket A \rrbracket_{G}$. Hence $\llbracket G^{\prime} \rrbracket=\llbracket S_{a_{1}} \cdots S_{a_{m}} \rrbracket_{G^{\prime}}=\operatorname{sort}^{<}(\llbracket G \rrbracket)$.

In order to define the commutative normal form, we introduce a total order on the set $\mathcal{T}_{0}(\Sigma)$. To this end, let $<$ be an arbitrary total order on the alphabet $\Gamma=\Sigma \cup\{()$,$\} , and let <llex be the induced length-lexicographic order on \Gamma^{*}$, which is defined by

$$
\begin{aligned}
x<_{\text {llex }} y \Leftrightarrow & |x|<|y| \text { or } \\
& |x|=|y|, x=u a v, y=u b v^{\prime} \text { with } u, v, v^{\prime} \in \Gamma^{*}, a, b \in \Gamma, a<b .
\end{aligned}
$$

Note that $<_{\text {llex }}$ is a total order which can be restricted to $\mathcal{T}_{0}(\Sigma)$ or $\mathcal{F}_{0}(\Sigma)$. For the latter restriction we obtain:

Lemma 5 For two FSLPs $F_{1}$ and $F_{2}$ we can check in polynomial time whether $\llbracket F_{1} \rrbracket=\llbracket F_{2} \rrbracket, \llbracket F_{1} \rrbracket<_{\text {llex }} \llbracket F_{2} \rrbracket$ or $\llbracket F_{2} \rrbracket<_{\text {llex }} \llbracket F_{1} \rrbracket$.

Proof From $F_{1}$ and $F_{2}$ we first construct two SSLPs $G_{1}$ and $G_{2}$ that produce $\llbracket F_{1} \rrbracket$ and $\llbracket F_{2} \rrbracket$ as strings over the alphabet $\Gamma=\Sigma \cup\{()$,$\} . The construction is$ similar to the case of TSLPs; see [7]: Consider $F_{1}=(V, S, \rho)$. By Theorem 1 we can assume that $F_{1}$ is in normal form. We define the $\operatorname{SSLP} G_{1}=\left(V^{\prime}, S, \rho^{\prime}\right)$ over $\Gamma$, where $V^{\prime}=V_{0} \cup\left\{A_{\ell}, A_{r} \mid A \in V_{1}\right\}$ and $\rho^{\prime}$ is defined as follows:

- If $\rho(A)=\varepsilon$ or $\rho(A)=B C$ or $\rho(A)=a(B)$ then $\rho^{\prime}(A)=\rho(A)$.
- If $\rho(A)=B\langle C\rangle$ with $C \in V_{0}$ then $\rho^{\prime}(A)=B_{\ell} C B_{r}$.
- If $\rho(A)=a(B x C)$ then $\rho^{\prime}\left(A_{\ell}\right)=a\left(B\right.$, and $\left.\rho^{\prime}\left(A_{r}\right)=C\right)$.
- If $\rho(A)=B\langle C\rangle$ with $C \in V_{1}$ then $\rho^{\prime}\left(A_{\ell}\right)=B_{\ell} C_{\ell}$ and $\rho^{\prime}\left(A_{r}\right)=C_{r} B_{r}$.

Notice that in the above definition, "(" and ")" appear as elements of $\Gamma$ on the right-hand side of $\rho^{\prime}$.

The rest of the proof follows immediately from [23, Lemma 3]: Given SSLPs $G_{1}$ and $G_{2}$ over the same terminal alphabet $\Gamma$, we can check in polynomial time whether $\llbracket G_{1} \rrbracket<_{\text {llex }} \llbracket G_{2} \rrbracket$, $\llbracket G_{2} \rrbracket<_{\text {llex }} \llbracket G_{1} \rrbracket$ or $\llbracket G_{1} \rrbracket=\llbracket G_{2} \rrbracket$.

From now on we use $<_{\text {llex }}$ only to compare trees, i.e., we restrict $<_{\text {llex }}$ to $\mathcal{T}_{0}(\Sigma)$. From this restricted order we obtain the function sort ${ }^{<\text {llex }}$ on $\mathcal{F}_{0}(\Sigma)=\mathcal{T}_{0}(\Sigma)^{*}$, and we define $\operatorname{nf}_{\mathcal{C}}: \mathcal{F}_{0}(\Sigma) \rightarrow \mathcal{F}_{0}(\Sigma)$ inductively by

$$
\begin{aligned}
\operatorname{nf}_{\mathcal{C}}(a(f)) & = \begin{cases}a\left(\operatorname{sort}^{<\operatorname{lnex}}\left(\operatorname{nf}_{\mathcal{C}}(f)\right)\right) & \text { if } a \in \mathcal{C}, \\
a\left(\operatorname{nf}_{\mathcal{C}}(f)\right) & \text { otherwise },\end{cases} \\
\operatorname{nf}_{\mathcal{C}}\left(t_{1} \cdots t_{n}\right) & =\operatorname{nf}_{\mathcal{C}}\left(t_{1}\right) \cdots \operatorname{nf}_{\mathcal{C}}\left(t_{n}\right) .
\end{aligned}
$$

Obviously, $f_{1}, f_{2} \in \mathcal{F}(\Sigma)$ are equal modulo the identities in (COMM) for all $c \in \mathcal{C}$ if and only if $\operatorname{nf}_{\mathcal{C}}\left(f_{1}\right)=\operatorname{nf}_{\mathcal{C}}\left(f_{2}\right)$. Using this fact and Lemma 2 it is not hard to show:

Lemma 6 For $f_{1}, f_{2} \in \mathcal{F}_{0}(\Sigma)$ we have $\operatorname{nf}_{\mathcal{C}}\left(\operatorname{nf}_{\mathcal{A}}\left(f_{1}\right)\right)=\operatorname{nf}_{\mathcal{C}}\left(\operatorname{nf}_{\mathcal{A}}\left(f_{2}\right)\right)$ if and only if $f_{1}$ and $f_{2}$ are equal modulo the identities in (ASSOC) and (COMM) for all $a \in \mathcal{A}, c \in \mathcal{C}$.

Proof It suffices to show that $\operatorname{nf}_{\mathcal{C}}\left(\operatorname{nf}_{\mathcal{A}}\left(f_{1}\right)\right)=\operatorname{nf}_{\mathcal{C}}\left(\operatorname{nf}_{\mathcal{A}}\left(f_{2}\right)\right)$ if $f_{1}$ and $f_{2}$ can be transformed into each other by a single application of (ASSOC) or (COMM); let us write $f_{1}=\mathcal{A} f_{2}$ or $f_{1}=\mathcal{C} f_{2}$, respectively, for the latter. The case $f_{1}=\mathcal{A} f_{2}$ is clear, since this implies $\operatorname{nf}_{\mathcal{A}}\left(f_{1}\right)=\operatorname{nf}_{\mathcal{A}}\left(f_{2}\right)$ by Lemma 2 . Now assume that $f_{1}=\mathcal{C} f_{2}$. As in the proof of Lemma 2, consider the infinite rewriting system $\left(\rightarrow\right.$-ASSOC ) and the associated rewrite relation $\rightarrow_{\mathcal{A}}$. The crucial observation is that $f=_{\mathcal{C}} g \rightarrow_{\mathcal{A}} h$ implies $f \rightarrow_{\mathcal{A}} g^{\prime}=_{\mathcal{C}} h$ for some $g^{\prime} \in \mathcal{F}_{0}(\Sigma)$ (a single application of $(\rightarrow$-ASSOC $)$ commutes with a permutation of the children of a node). Since $f_{1}=\mathcal{C} f_{2} \rightarrow_{\mathcal{A}}^{*} \operatorname{nf}_{\mathcal{A}}\left(f_{2}\right)$, it follows that $f_{1} \rightarrow_{\mathcal{A}}^{*} f_{1}^{\prime}={ }_{\mathcal{C}} \operatorname{nf}_{\mathcal{A}}\left(f_{2}\right)$ for some $f_{1}^{\prime} \in \mathcal{F}_{0}(\Sigma)$. But $f_{1}^{\prime}=\mathcal{C} \operatorname{nf}_{\mathcal{A}}\left(f_{2}\right)$ implies that $f_{1}^{\prime}$ is irreducible with respect to $\rightarrow_{\mathcal{A}}$, i.e., $f_{1}^{\prime}=\operatorname{nf}_{\mathcal{A}}\left(f_{1}\right)$. Thus we obtain $\operatorname{nf}_{\mathcal{A}}\left(f_{1}\right)=\mathcal{C} \operatorname{nf}_{\mathcal{A}}\left(f_{2}\right)$ and hence $\operatorname{nf}_{\mathcal{C}}\left(\operatorname{nf}_{\mathcal{A}}\left(f_{1}\right)\right)=\operatorname{nf}_{\mathcal{C}}\left(\operatorname{nf}_{\mathcal{A}}\left(f_{2}\right)\right)$.

We now come to our main construction: From an FSLP $F=(V, S, \rho)$ in normal form we want to obtain in polynomial time an FSLP $F^{\prime}=\left(V^{\prime}, S, \rho^{\prime}\right)$ with $\llbracket F^{\prime} \rrbracket=\operatorname{nf}_{\mathcal{C}}(\llbracket F \rrbracket)$. We will construct $F^{\prime}=\left(V^{\prime}, S, \rho^{\prime}\right)$ in such a way that $V_{0} \subseteq V_{0}^{\prime}, V_{1} \subseteq V_{1}^{\prime}$ and $\llbracket A \rrbracket_{F^{\prime}}=\operatorname{nf}_{\mathcal{C}}\left(\llbracket A \rrbracket_{F}\right)$ for every $A \in V_{0}$. The new righthand sides $\rho^{\prime}(A)$ for all $A \in V$ will be defined by induction on $\leq_{F}$. Before we present the details we want to point out the main difficulties.

Let $A \in V_{0}^{\perp}$ with $\rho(A)=B\langle C\rangle \in V_{1}\left\langle V_{0}\right\rangle$ and let $\operatorname{spine}_{F}(B)=B_{1} \cdots B_{N} \in$ $\left(V_{1}^{\perp}\right)^{*}$. For $0 \leq p \leq N$ let $t_{p}=\llbracket B_{p+1}\left\langle\cdots\left\langle B_{N}\langle C\rangle\right\rangle \cdots\right\rangle \rrbracket_{F}$ be the tree which
is substituted for the parameter $x$ in $B_{p}$, in particular $t_{0}=\llbracket A \rrbracket_{F}$ and $t_{N}=$ $\llbracket C \rrbracket_{F}$. Note that $\left|t_{0}\right|>\cdots>\left|t_{N}\right|$ and that the length $N$ of the spine may be exponential in $|F|$, hence we may have exponentially many different trees $t_{p}$.

Let now $D \in V_{1}^{\perp}$ with $\rho(D)=a\langle L x R\rangle$ and $B_{p}=D$ for some position $p$ in the spine. Let $w=\llbracket L R \rrbracket_{F ■} \in\left(V_{0}^{\perp}\right)^{*}$. By induction we may assume for every variable $A^{\prime}$ in $w$ that $\llbracket A^{\prime} \rrbracket_{F^{\prime}}$ is already defined and that $\llbracket A^{\prime} \rrbracket_{F^{\prime}}=\operatorname{nf}_{\mathcal{C}}\left(\llbracket A^{\prime} \rrbracket_{F}\right)$. For the definition of $\rho^{\prime}(D)$ we distinguish two cases.

For $a \notin \mathcal{C}$ we set $\rho^{\prime}(D)=\rho(D)$. Then $\operatorname{nf}_{\mathcal{C}}\left(t_{p-1}\right)=\operatorname{nf}_{\mathcal{C}}\left(a\left(\llbracket L \rrbracket_{F} t_{p} \llbracket R \rrbracket_{F}\right)\right)=$ $a\left(\operatorname{nf}_{\mathcal{C}}\left(\llbracket L \rrbracket_{F}\right) \operatorname{nf}_{\mathcal{C}}\left(t_{p}\right) \operatorname{nf}_{\mathcal{C}}\left(\llbracket R \rrbracket_{F}\right)\right)=a\left(\llbracket L \rrbracket_{F^{\prime}} \operatorname{nf}_{\mathcal{C}}\left(t_{p}\right) \llbracket R \rrbracket_{F^{\prime}}\right)=\llbracket B_{p} \rrbracket_{F^{\prime}}\left\langle\operatorname{nf}_{\mathcal{C}}\left(t_{p}\right)\right\rangle$.

The problematic case is $a \in \mathcal{C}$. Then $\operatorname{nf}_{\mathcal{C}}\left(t_{p-1}\right)=\operatorname{nf}_{\mathcal{C}}\left(a\left(\llbracket L \rrbracket_{F} t_{p} \llbracket R \rrbracket_{F}\right)\right)=$ $a\left(\operatorname{sort}^{<1 \operatorname{lex}}\left(\operatorname{nf}_{\mathcal{C}}\left(\llbracket L R \rrbracket_{F}\right) \operatorname{nf}_{\mathcal{C}}\left(t_{p}\right)\right)\right)=a\left(\operatorname{sort}^{<1 \operatorname{lex}}\left(\operatorname{nf}_{\mathcal{C}}\left(\llbracket w \rrbracket_{F}\right) \operatorname{nf}_{\mathcal{C}}\left(t_{p}\right)\right)\right)$. The problem is that the position of $\operatorname{nf}_{\mathcal{C}}\left(t_{p}\right)$ in sort ${ }^{<\operatorname{llex}}\left(\operatorname{nf}_{\mathcal{C}}\left(\llbracket w \rrbracket_{F}\right) \operatorname{nf}_{\mathcal{C}}\left(t_{p}\right)\right)$ may depend on the index $p$. This problem disappears if $F$ satisfies a further condition: Let $F=(V, S, \rho)$ be an FSLP in normal form. For every $B \in V_{1}$ let

We say that $F$ is in strong normal form if $\llbracket C \rrbracket_{F} \in \operatorname{big}_{-\operatorname{args}_{F}(B)}$ for every $A \in V_{0}^{\perp}$ with $\rho(A)=B\langle C\rangle \in V_{1}\left\langle V_{0}\right\rangle$.

If we assume that $F$ is in strong normal form, then we have $\left|\operatorname{nf}_{\mathcal{C}}\left(t_{p}\right)\right|=$ $\left|t_{p}\right| \geq\left|\llbracket C \rrbracket_{F}\right| \geq\left|\llbracket B_{p}\langle\varepsilon\rangle \rrbracket_{F}\right|>\left|\llbracket A^{\prime} \rrbracket_{F}\right|=\left|\operatorname{nf}_{\mathcal{C}}\left(\llbracket A^{\prime} \rrbracket_{F}\right)\right|$ for all $p$ with $B_{p}=$ $D$ and all $A^{\prime}$ which occur in $w$. This means that for all $p$ with $B_{p}=D$ the tree $\operatorname{nf}_{\mathcal{C}}\left(t_{p}\right)$ goes to the last position in sort ${ }^{<11 \mathrm{ex}}\left(\operatorname{nf}_{\mathcal{C}}\left(\llbracket w \rrbracket_{F} \operatorname{nf}_{\mathcal{C}}\left(t_{p}\right)\right)\right.$. Hence we can set $\rho^{\prime}(D)=a\left(S_{w} x\right)$, where $S_{w}$ is a new nonterminal with $\llbracket S_{w} \rrbracket_{F^{\prime}}=$ $\operatorname{sort}^{<1 \operatorname{lex}}\left(\operatorname{nf}_{\mathcal{C}}\left(\llbracket w \rrbracket_{F}\right)\right)$. Such a nonterminal $S_{w}$ can be obtained with Lemma 5 and Lemma 4, see the proof of Theorem 2 for details. Thus we have $\operatorname{nf}_{\mathcal{C}}\left(t_{p-1}\right)=$ $a\left(\operatorname{sort}^{<\operatorname{llex}}\left(\operatorname{nf}_{\mathcal{C}}\left(\llbracket w \rrbracket_{F}\right)\right) \operatorname{nf}_{\mathcal{C}}\left(t_{p}\right)\right)=\llbracket a\left(S_{w} x\right) \rrbracket_{F^{\prime}}\left\langle\operatorname{nf}_{\mathcal{C}}\left(t_{p}\right)\right\rangle=\llbracket B_{p} \rrbracket_{F^{\prime}}\left\langle\operatorname{nf}_{\mathcal{C}}\left(t_{p}\right)\right\rangle$ as in the case $a \notin \mathcal{C}$.

Finally, we set $\rho^{\prime}(A)=\rho(A)$. Then we have $\llbracket C \rrbracket_{F^{\prime}}=\operatorname{nf}_{\mathcal{C}}\left(\llbracket C \rrbracket_{F}\right)=\operatorname{nf}_{\mathcal{C}}\left(t_{N}\right)$ by induction for $C$ hence $\operatorname{nf}_{\mathcal{C}}\left(\llbracket A \rrbracket_{F}\right)=\operatorname{nf}_{\mathcal{C}}\left(t_{0}\right)=\llbracket B_{1}\left\langle\cdots\left\langle B_{N}\right\rangle \cdots\right\rangle \rrbracket_{F^{\prime}}\left\langle\operatorname{nf}_{\mathcal{C}}\left(t_{N}\right)\right\rangle$ $=\llbracket B_{1}\left\langle\cdots\left\langle B_{N}\langle C\rangle\right\rangle \cdots\right\rangle \rrbracket_{F^{\prime}}=\llbracket A \rrbracket_{F^{\prime}}$ as desired.

If $F$ is only in normal form, then we cannot expect that $\left|t_{p}\right| \geq\left|\llbracket B_{p}\langle\varepsilon\rangle \rrbracket_{F}\right|$ holds for all indices $p$, but we are close: Let $B_{p}=D$, where $p$ is not the last position of $D$ in the spine, i.e., $B_{q}=D$ for some $q>p$. Then $\left|t_{p}\right|=$ $\left|\llbracket B_{p+1}\left\langle\cdots\left\langle B_{N} C\right\rangle\right\rangle \cdots\right\rangle \rrbracket_{F}\left|\geq\left|\llbracket B_{q}\langle\varepsilon\rangle \rrbracket_{F}\right|=\left|\llbracket B_{p}\langle\varepsilon\rangle \rrbracket_{F}\right|\right.$. This means that the inequation $\left|t_{p}\right| \geq\left|\llbracket B_{p}\langle\varepsilon\rangle \rrbracket_{F}\right|$ can only fail, if $p$ is the last position of some variable $D$ in the spine. Example 8 shows that it can indeed fail for all these positions, even if the spine has exponential length and even if the distance between two subsequent last positions is growing exponentially. The only important point is that we have at most polynomially (even linearly) many of these last positions. This is the clue for proving the following lemma.

Lemma 7 From a given $F S L P F=(V, S, \rho)$ in normal form we can construct in polynomial time an $F S L P F^{\prime}=\left(V^{\prime}, S, \rho^{\prime}\right)$ in strong normal form with $\llbracket F \rrbracket=$ $\llbracket F^{\prime} \rrbracket$.

Proof We obtain $F^{\prime}$ from $F$ by modifying (only) the right-hand sides of variables $A \in V_{0}^{\perp}$ with $\rho(A) \in V_{1}\left\langle V_{0}\right\rangle$ : Let $\rho(A)=B\langle C\rangle$ with $\operatorname{spine}_{F}(B)=$
$B_{1} \cdots B_{N}(N \geq 1)$, and let $\left\{D_{1}, \ldots, D_{m}\right\} \subseteq\left(V_{1}\right)^{\perp}(m \geq 1)$ be the set of all variables which occur in $\operatorname{spine}_{F}(B)$. For $1 \leq i \leq m$ let $p_{i}$ be the position of the last occurrence of $D_{i}$ in $\operatorname{spine}_{F}(B)$, i.e., $p_{i}=\max \left\{1 \leq p \leq N \mid B_{p}=D_{i}\right\}$. The set $\left\{D_{1}, \ldots, D_{m}\right\}$ and the positions $p_{1}, \ldots, p_{m}$ can be computed from $F$ in polynomial time, hence we may assume w.l.o.g. that $p_{m}<\cdots<p_{1}$ by reordering the symbols $D_{i}$ in this way. This means in particular that $p_{1}=N$. Additionally, we set $p_{m+1}=0$.

The idea for the construction of $F^{\prime}$ is to divide the spine $B_{1} \cdots B_{N}$ into all nonempty spine segments of the form $B_{p_{i+1}+1} \cdots B_{p_{i}-1}$ (which do not contain any last occurences of the variables $D_{i}$ ) and the remaining singleton spine segments $B_{p_{i}}$ (which are the last occurences of the variables $D_{i}$ ). This can be achieved by introducing new variables $E_{i}, A_{i}, C_{i}$ with $\operatorname{spine}_{F^{\prime}}\left(E_{i}\right)=$ $B_{p_{i+1}+1} \cdots B_{p_{i}-1}, \rho^{\prime}\left(A_{i}\right)=E_{i}\left\langle C_{i}\right\rangle$ and $\rho^{\prime}\left(C_{i}\right)=D_{i}\left\langle A_{i-1}\right\rangle=B_{p_{i}}\left\langle A_{i-1}\right\rangle$. After this transformation the right-hand sides $\rho^{\prime}\left(A_{i}\right)$ satisfy the restriction of the strong normal form, because $\llbracket C_{i} \rrbracket_{F^{\prime}} \in \operatorname{big} \operatorname{args}_{F^{\prime}}\left(E_{i}\right)$, but the right-hand sides $\rho^{\prime}\left(C_{i}\right)$ need to be repaired: If $\rho\left(D_{i}\right)=L_{i} x R_{i}$ then we set $\rho^{\prime}\left(C_{i}\right)=L_{i} A_{i-1} R_{i}$, i.e., we get rid of the singleton spines $B_{p_{i}}=D_{i}$ by explicitly substituting $A_{i-1}$ for the parameter $x$ of $D_{i}$. The details, which are slightly more complicated, are as follows.

For $1 \leq i \leq m$ we construct in polynomial time $\operatorname{SSLPs} G_{i}=\left(N_{i}, E_{i}, \rho_{i}\right)$ over $V_{1}^{\perp}$ with $\llbracket G_{i} \rrbracket=B_{p_{i+1}+1} \cdots B_{p_{i}-1}$ (see e.g. [25, Lemma 1]). We may assume that the variable sets $N_{i}$ are pairwise disjoint and that they only contain new variables, i.e., variables which are not in $V$ and have not been added to $V^{\prime}$ by previous steps. We may also assume that $\rho_{i}\left(N_{i}\right) \subseteq V_{1}^{\perp} \cup N_{i} N_{i}$ whenever $\llbracket G_{i} \rrbracket \neq \varepsilon$. In this case we add each $X \in N_{i}$ to the variable set $V_{1}^{\prime}$ of $F^{\prime}$ and define its right-hand side by

- $\rho^{\prime}(X)=Y\langle Z\rangle$ if $\rho_{i}(X)=Y Z$,
- $\rho^{\prime}(X)=\rho(D)$ if $\rho_{i}(X)=D \in V_{1}^{\perp}$.

By induction on $\leq_{G_{i}}$ we obtain spine $_{F^{\prime}}(X)=\llbracket X \rrbracket_{G_{i}}$ for every $X \in N_{i}$, in particular $\operatorname{spine}_{F^{\prime}}\left(E_{i}\right)=\llbracket E_{i} \rrbracket G_{G_{i}}=\llbracket G_{i} \rrbracket=B_{p_{i+1}+1} \cdots B_{p_{i}-1}$ for all $1 \leq i \leq m$ with $\llbracket G_{i} \rrbracket \neq \varepsilon$.

Now we add new variables $A_{i}$ for $1 \leq i \leq m-1$ and $C_{i}, C_{i}^{\prime}, C_{i}^{\prime \prime}$ for $1 \leq i \leq m$ to the variable set $V_{0}^{\prime}$ of $F^{\prime}$. Additionally, we set $A_{0}=C$ and $A_{m}=A$. The right-hand sides of the new variables and the new right-hand side of $A=A_{m}$ are then defined by
(1) $\rho^{\prime}\left(C_{i}\right)=a\left(C_{i}^{\prime}\right), \rho^{\prime}\left(C_{i}^{\prime}\right)=L C_{i}^{\prime \prime}$ and $\rho^{\prime}\left(C_{i}^{\prime \prime}\right)=A_{i-1} R$ if $\rho\left(D_{i}\right)=a(L x R)$,
(2) $\rho^{\prime}\left(A_{i}\right)=E_{i}\left\langle C_{i}\right\rangle$ if $\llbracket E_{i} \rrbracket_{G} \neq \varepsilon$, otherwise $\rho^{\prime}\left(A_{i}\right)=\rho^{\prime}\left(C_{i}\right)$
for $1 \leq i \leq m$. Equation (1) means that

$$
\llbracket C_{i} \rrbracket_{F^{\prime}}=\llbracket a\left(C_{i}^{\prime}\right) \rrbracket_{F^{\prime}}=\llbracket a\left(L A_{i-1} R\right) \rrbracket_{F^{\prime}}=\llbracket D_{i}\left\langle A_{i-1}\right\rangle \rrbracket_{F^{\prime}}=\llbracket B_{p_{i}}\left\langle A_{i-1}\right\rangle \rrbracket_{F^{\prime}}
$$

because the right-hand side of $D_{i}$ is not modified. From this and (2) we obtain

$$
\llbracket A_{i} \rrbracket_{F^{\prime}}=\llbracket B_{p_{i+1}+1}\left\langle\cdots\left\langle B_{p_{i}}\left\langle A_{i-1}\right\rangle\right\rangle \cdots\right\rangle \rrbracket_{F^{\prime}} .
$$

Since $A_{0}=C$ an induction on $i$ implies $\llbracket A_{i} \rrbracket_{F^{\prime}}=\llbracket B_{p_{i+1}+1}\left\langle\cdots\left\langle B_{N}\langle C\rangle\right\rangle \cdots\right\rangle \rrbracket_{F^{\prime}}$ for $0 \leq i \leq m$, in particular $\llbracket A \rrbracket_{F^{\prime}}=\llbracket A_{m} \rrbracket_{F^{\prime}}=\llbracket B_{1}\left\langle\cdots\left\langle B_{N}\langle C\rangle\right\rangle \cdots\right\rangle \rrbracket_{F^{\prime}}$. Note that this holds for every $A \in V_{0}^{\perp}$ with $\rho(A) \in V_{1}\left\langle V_{0}\right\rangle$ and that the right-hand sides of other variables in $V$ are not modified. Thus we obtain $\llbracket A \rrbracket_{F^{\prime}}=\llbracket A \rrbracket_{F}$ for every $A \in V$ by induction on $\leq_{F}$, in particular $\llbracket F^{\prime} \rrbracket=\llbracket S \rrbracket_{F^{\prime}}=\llbracket S \rrbracket_{F}=\llbracket F \rrbracket$.

It remains to be shown that $F^{\prime}$ is in strong normal form. The only variables $A^{\prime} \in\left(V_{0}^{\prime}\right)^{\perp}$ with $\rho^{\prime}\left(A^{\prime}\right) \in V_{1}^{\prime}\left\langle V_{0}^{\prime}\right\rangle$ are the variables $A_{i}(1 \leq i \leq m)$ with $\rho^{\prime}\left(A_{i}\right)=E_{i}\left\langle C_{i}\right\rangle$. Hence it suffices to prove $\llbracket C_{i} \rrbracket F_{F^{\prime}} \in \operatorname{big}_{-} \operatorname{args}_{F^{\prime}}\left(E_{i}\right)$, i.e., $\left|\llbracket C_{i} \rrbracket_{F^{\prime}}\right| \geq\left|\llbracket D_{j}\langle\varepsilon\rangle \rrbracket_{F^{\prime}}\right|$ whenever $D_{j} \in V_{1}^{\perp}$ occurs in $\operatorname{spine}_{F^{\prime}}\left(E_{i}\right)$. If $j>i$, then $p_{j} \leq p_{i+1}$ is the last position of $D_{j}$ in $B_{1} \cdots B_{N}$, hence $D_{j}$ does not occur in $\operatorname{spine}_{F^{\prime}}\left(E_{i}\right)=B_{p_{i+1}+1} \cdots B_{p_{i}-1}$. If $j \leq i$, then $p_{i} \leq p_{j} \leq N$ and thus $\left|\llbracket C_{i} \rrbracket_{F^{\prime}}\right|=\left|\llbracket B_{p_{i}}\left\langle A_{i-1}\right\rangle \rrbracket_{F^{\prime}}\right|=\left|\llbracket B_{p_{i}}\left\langle\cdots\left\langle B_{N}\langle C\rangle\right\rangle \cdots\right\rangle \rrbracket_{F^{\prime}}\right| \geq\left|\llbracket B_{p_{j}}\langle\varepsilon\rangle \rrbracket_{F^{\prime}}\right|=$ $\left|\llbracket D_{j}\langle\varepsilon\rangle \rrbracket_{F^{\prime}}\right|$, which concludes the proof.
Example 8 For every $m \geq 1$ let $F_{m}=(V, S, \rho)$ be an FSLP over $\{a\}$ with $a \in \mathcal{C}$, $\left|F_{m}\right| \in \mathcal{O}(m), V \supseteq\{S, B, E\} \cup\left\{U_{i} \mid 0 \leq i \leq 2 m\right\} \cup\left\{D_{i}, L_{i}, R_{i} \mid 1 \leq i \leq m\right\}$ and

$$
\begin{aligned}
\rho(E) & =\varepsilon, \\
\rho\left(R_{1}\right) & =a(E), \\
\rho\left(R_{i}\right) & =R_{i-1} R_{i-1} \text { for } 2 \leq i \leq m, \\
\rho\left(U_{0}\right) & =a(E x E), \\
\rho\left(U_{i}\right) & =U_{i-1}\left\langle U_{i-1}\right\rangle, \text { for } 1 \leq i \leq 2 m, \\
\rho\left(L_{i}\right) & =U_{2 i}\left\langle R_{1}\right\rangle, \text { for } 1 \leq i \leq m, \\
\rho\left(D_{i}\right) & =a\left(L_{i} x R_{i}\right), \text { for } 1 \leq i \leq m, \\
\operatorname{spine}_{F_{m}}(B) & =D_{1}^{2^{m-1}} D_{m} D_{m} D_{1}^{2^{m-2}} D_{m-1} D_{m-1} \cdots D_{1}^{2^{1}} D_{2} D_{2} D_{1}, \\
\rho(S) & =B\left\langle R_{1}\right\rangle .
\end{aligned}
$$

Note that $\mathcal{O}(m)$ productions are sufficient to produce the spine of $B$. We do not present them in detail because they are irrelevant for the following illustration.

Let $p_{i}(1 \leq i \leq m)$ be the last position of $D_{i}$ in $\operatorname{spine}_{F_{m}}(B)$, and let $t_{p_{i}}$ be the tree which is substituted for $x$ in $D_{i}$ at this last position, i.e.,

$$
\begin{aligned}
t_{p_{1}} & =\llbracket R_{1} \rrbracket_{F_{m}}, \\
t_{p_{2}} & =\llbracket D_{1}\left\langle R_{1}\right\rangle \rrbracket_{F_{m}}, \\
t_{p_{i+1}} & =\llbracket \underbrace{D_{1}\left\langle\cdots \left\langle D_{1}\langle \right.\right.}_{2^{i-1}} D_{i}\left\langle D_{i}\left\langle t_{p_{i}}\right\rangle\right\rangle\rangle\rangle \cdots\rangle \rrbracket_{F_{m}} \text { for } 2 \leq i \leq m-1 .
\end{aligned}
$$

Let us define

$$
\begin{aligned}
u_{i} & :=\llbracket U_{i} \rrbracket_{F_{m}}=\underbrace{a(\ldots a}_{2^{i}}(x) \ldots) \text { for } 0 \leq i \leq 2 m, \\
\ell_{i} & :=\llbracket L_{i} \rrbracket_{F_{m}}=u_{2 i}\langle a\rangle=\underbrace{a(\ldots a(a)}_{4^{i}} \ldots) \text { for } 1 \leq i \leq m, \\
r_{i} & :=\llbracket R_{i} \rrbracket_{F_{m}}=a^{2^{i-1}} \text { for } 1 \leq i \leq m .
\end{aligned}
$$

For $1 \leq i \leq m$ we have $\left|\llbracket D_{i} \rrbracket_{F_{m}}\langle t\rangle\right|=\left|a\left(\ell_{i} t r_{i}\right)\right|=|t|+4^{i}+2^{i-1}+2$ for every $t \in \mathcal{T}_{0}(\{a\})$, hence $\left|t_{p_{i+1}}\right|=\left|t_{p_{i}}\right|+2 \cdot\left(4^{i}+2^{i-1}+2\right)+2^{i-1} \cdot 7 \leq\left|t_{p_{i}}\right|+3 \cdot 4^{i}$ for every $i \geq 3$. By induction on $i$ this implies $\left|t_{p_{i}}\right| \leq 4^{i}<\left|\ell_{i}\right|$ and thus $\operatorname{nf}_{\mathcal{C}}\left(t_{p_{i}}\right)<_{\text {llex }} \ell_{i}=\operatorname{nf}_{\mathcal{C}}\left(\ell_{i}\right)$ for $1 \leq i \leq m$, which explains the shape of the tree $\mathrm{nf}_{\mathcal{C}}\left(\llbracket F_{3} \rrbracket\right)$ in Figure 5.

By the construction of Lemma 7 we obtain the strong normal form FSLP $F_{m}^{\prime}$ from $F_{m}$ by modifying (only) the right-hand sides of the variables $S$ and $L_{1}, \ldots, L_{m}$. The modification of $\rho\left(L_{i}\right)$ is easy since $\rho\left(L_{i}\right)=U_{2 i}\left\langle R_{1}\right\rangle$ and only the variable $U_{0}$ occurs in the spine of $U_{2 i}$. Hence we focus on the modification of $\rho(S)=B\left\langle R_{1}\right\rangle$.

The spine of $B$ contains all the variables $D_{1}, \ldots, D_{m}$ and they are already ordered in such a way that $p_{m}<\cdots<p_{1}$ holds for their last positions $p_{i}$. Hence we obtain $F_{m}^{\prime}=\left(V^{\prime}, S, \rho^{\prime}\right)$ with

$$
V^{\prime} \supseteq V \cup\left\{C_{i}, C_{i}^{\prime}, C_{i}^{\prime \prime} \mid 1 \leq i \leq m\right\} \cup\left\{E_{i} \mid 2 \leq i \leq m\right\} \cup\left\{A_{i} \mid 1 \leq i<m\right\}
$$

$A_{0}=R_{1}, A_{m}=S$ and

$$
\begin{aligned}
\operatorname{spine}_{F_{m}^{\prime}}\left(E_{i}\right) & =D_{1}^{2^{i-1}} D_{i}, \text { for } 2 \leq i \leq m, \\
\rho^{\prime}\left(A_{1}\right) & =C_{1}, \\
\rho^{\prime}\left(A_{i}\right) & =E_{i}\left\langle C_{i}\right\rangle \text { for } 2 \leq i \leq m, \\
\rho^{\prime}\left(C_{i}\right) & =a\left(C_{i}^{\prime}\right) \text { for } 1 \leq i \leq m, \\
\rho^{\prime}\left(C_{i}^{\prime}\right) & =L_{i} C_{i}^{\prime \prime} \text { for } 1 \leq i \leq m, \\
\rho^{\prime}\left(C_{i}^{\prime \prime}\right) & =A_{i-1} R_{i} \text { for } 1 \leq i \leq m .
\end{aligned}
$$

Note that spine $F_{F_{m}^{\prime}}\left(E_{i}\right)$ is the spine segment between the last positions of $D_{i+1}$ and $D_{i}$ and that $E_{1}$ is missing in $V^{\prime}$ because this spine segment is empty for $i=1$.

The case $m=3$ is illustrated in Figure 5. We have

$$
\operatorname{spine}_{F_{3}}(B)=D_{1}^{4} D_{3} D_{3} D_{1}^{2} D_{2} D_{2} D_{1},
$$

hence $\left|\operatorname{spine}_{F_{3}}(B)\right|=11$. The positions of the last occurrences of $D_{1}, D_{2}, D_{3}$ in the spine are $p_{1}=11, p_{2}=10$ and $p_{3}=6$, respectively. These are the occurrences that are replaced by $C_{1}, C_{2}$ and $C_{3}$. We therefore obtain

$$
\begin{aligned}
\llbracket C_{1} \rrbracket_{F_{3}^{\prime}} & =\llbracket a\left(L_{1} A_{0} R_{1}\right) \rrbracket_{F_{3}^{\prime}}, \\
\rho^{\prime}\left(A_{1}\right) & =C_{1}, \\
\llbracket C_{2} \rrbracket_{F_{3}^{\prime}} & =\llbracket a\left(L_{2} A_{1} R_{2}\right) \rrbracket_{F_{3}^{\prime}}, \\
\operatorname{spine}_{F_{3}^{\prime}}\left(E_{2}\right) & =D_{1}^{2} D_{2}, \\
\rho^{\prime}\left(A_{2}\right) & =E_{2}\left\langle C_{2}\right\rangle, \\
\llbracket C_{3} \rrbracket_{F_{3}^{\prime}} & =\llbracket a\left(L_{3} A_{2} R_{3}\right) \rrbracket_{F_{3}^{\prime}}, \\
\operatorname{spine}_{F_{3}^{\prime}}\left(E_{3}\right) & =D_{1}^{4} D_{3}, \\
\rho^{\prime}\left(A_{3}\right) & =E_{3}\left\langle C_{3}\right\rangle .
\end{aligned}
$$


(5) (223) (1)

(5) (216) (1)

(5) (209) (1)

(5) (202) (1)

(132)

65) $\quad a \quad$ (4)

(5) (55) (1)

(28)

(1) (5) (223)
$r_{1} \quad \ell_{1} \quad a$
(1) (5) (216) $r_{1} \quad \ell_{1}$
(1) (5) (209)
$r_{1} \quad \ell_{1}$
(1) (5) (202)
(4) (65) $a$


(1) (5) (55)


1) (5) (48)

(2) $a \quad$ (17)

(1)

Fig. 5 The trees $\llbracket F_{3} \rrbracket=\llbracket F_{3}^{\prime} \rrbracket$ and $\operatorname{nf}_{\mathcal{C}}\left(\llbracket F_{3} \rrbracket\right)=\operatorname{nf}_{\mathcal{C}}\left(\llbracket F_{3}^{\prime} \rrbracket\right)$ for the FSLP $F_{3}$ from Example 8. The size of each subtree is written in () after the node label. The last positions of $D_{1}, D_{2}, D_{3}$ are $p_{1}=11, p_{2}=10$ and $p_{3}=6$, respectively. The roots of the trees $t_{p_{i}}$ and $\operatorname{nf}_{\mathcal{C}}\left(t_{p_{i}}\right)$ are marked with $A_{i}$ since $\llbracket A_{i} \rrbracket_{F_{3}^{\prime}}=t_{p_{i}}$. They are the only argument trees which are smaller
 to the right. The roots of $\llbracket C_{i} \rrbracket_{F_{3}^{\prime}}$ and $\operatorname{nf}_{\mathcal{C}}\left(\llbracket C_{i} \rrbracket_{F_{3}^{\prime}}\right)$ are marked with $C_{i}$.

This concludes our example.
It remains to be shown how an FSLP $F$ in strong normal form can be turned into an FSLP $F^{\prime}$ with $\llbracket F^{\prime} \rrbracket=\operatorname{nf}_{\mathcal{C}}(\llbracket F \rrbracket)$. We have already given an outline of this construction. Now we present the details.

Theorem 2 From a given FSLP $F$ we can construct in polynomial time an $F S L P \quad F^{\prime}$ with $\llbracket F^{\prime} \rrbracket=\operatorname{nf}_{\mathcal{C}}(\llbracket F \rrbracket)$.

Proof Let $F=(V, S, \rho)$. By Theorem 1 and Lemma 7 we may assume that $F$ is already in strong normal form. We want to construct an FSLP $F^{\prime}=\left(V^{\prime}, S, \rho^{\prime}\right)$ with $V_{0} \subseteq V_{0}^{\prime}$ and $V_{1}=V_{1}^{\prime}$ such that
(1) $\llbracket A \rrbracket_{F^{\prime}}=\operatorname{nf}_{\mathcal{C}}\left(\llbracket A \rrbracket_{F}\right)$ for all $A \in V_{0}$,
(2) $\llbracket A \rrbracket_{F^{\prime}}\left\langle\operatorname{nf}_{\mathcal{C}}(t)\right\rangle=\operatorname{nf}_{\mathcal{C}}\left(\llbracket A \rrbracket_{F}\langle t\rangle\right)$ for all $A \in V_{1}, t \in \operatorname{big} \operatorname{args}_{F}(A)$.

From (1) we obtain $\llbracket F^{\prime} \rrbracket=\llbracket S \rrbracket_{F^{\prime}}=\operatorname{nf}_{\mathcal{C}}\left(\llbracket S \rrbracket_{F}\right)=\operatorname{nf}_{\mathcal{C}}(\llbracket F \rrbracket)$, which will be enough to conclude the proof.

To define $\rho^{\prime}$, let $V^{c}=\left\{A \in V_{0}^{\perp} \mid \rho(A) \in \mathcal{C}\left(V_{0}\right)\right\} \cup\left\{A \in V_{1}^{\perp} \mid \rho(A) \in\right.$ $\left.\mathcal{C}\left(V_{0} x V_{0}\right)\right\}$ be the set of commutative variables of $F$. We set $\rho^{\prime}(A)=\rho(A)$ for every $A \in V \backslash V^{c}$. For $A \in V^{c}$ we define $\rho^{\prime}(A)$ by induction on $\leq_{F}$ :

- If $\rho(A)=a(B) \in \mathcal{C}\left(V_{0}\right)$, then let $M_{A}=\left\{C \in V_{0}^{\perp} \mid C \leq_{F} A\right\}$ and $w=$ $\operatorname{hor}_{F}(B)=\llbracket B \rrbracket_{F ■} \in M_{A}^{*}$. By induction, $\rho^{\prime}(C)$ and hence $\llbracket C \rrbracket_{F^{\prime}}$ are already defined for every $C \in M_{A}$. By Lemma 5 , we can compute in polynomial time a total order $<$ on $M_{A}$ such that $C<D$ implies $\llbracket C \rrbracket_{F^{\prime}} \leq{ }_{\text {llex }} \llbracket D \rrbracket_{F^{\prime}}$ for all $C, D \in M_{A}$. By Lemma 4, we can construct in linear time an SSLP $G_{w}=\left(V_{w}, S_{w}, \rho_{w}\right)$ with $\llbracket G_{w} \rrbracket=$ sort $^{<}(w)$, and we may assume that all variables $D \in V_{w}$ are new. We add these variables to $V_{0}^{\prime}$ together with their right-hand sides $\rho^{\prime}(D)=\rho_{w}(D)$, and set $\rho^{\prime}(A)=a\left(S_{w}\right)$.
- If $\rho(A)=a(B x C) \in \mathcal{C}\left(V_{0} x V_{0}\right)$, then define $G_{w}=\left(V_{w}, S_{w}, \rho_{w}\right)$ as before, but with $w=\llbracket B C \rrbracket_{F \unlhd}$ instead of $w=\llbracket B \rrbracket_{F \unlhd}$, and set $\rho^{\prime}(A)=a\left(S_{w} x\right)$.
Properties (1) and (2) are proved by induction on $\leq_{F}$. We only consider the interesting cases, i.e., those in which $<_{\text {llex }}$ plays a role.
(i) $A \in V_{0}$ with $\rho(A)=a(B) \in \mathcal{C}\left(V_{0}\right)$ :

Let $w=\llbracket B \rrbracket_{F ■}=A_{1} \cdots A_{m}$ with $m \geq 0$. Then

$$
\begin{aligned}
\operatorname{nf}_{\mathcal{C}}\left(\llbracket A \rrbracket_{F}\right)= & \operatorname{nf}_{\mathcal{C}}\left(a\left(\llbracket B \rrbracket_{F}\right)\right) \\
= & a\left(\operatorname{sort}^{<1 \operatorname{lex}}\left(\operatorname{nf}_{\mathcal{C}}\left(\llbracket B \rrbracket_{F}\right)\right)\right) \text { by definition of } \operatorname{nf}_{\mathcal{C}} \text { since } a \in \mathcal{C} \\
= & a\left(\operatorname{sort}^{<1 \operatorname{lnex}}\left(\operatorname{nf}_{\mathcal{C}}\left(\llbracket A_{1} \rrbracket_{F}\right) \cdots \operatorname{nf}_{\mathcal{C}}\left(\llbracket A_{m} \rrbracket_{F}\right)\right)\right) \\
= & a\left(\text { sort }^{<1 \operatorname{lnex}}\left(\llbracket A_{1} \rrbracket_{F^{\prime}} \cdots \llbracket A_{m} \rrbracket_{F^{\prime}}\right)\right) \text { by induction for } A_{1}, \ldots, A_{m} \\
= & a\left(\text { sort }^{<1 \operatorname{lex}}\left(\llbracket w \rrbracket_{F^{\prime}}\right)\right) \\
= & a\left(\llbracket \text { sort }^{<}(w) \rrbracket_{F^{\prime}}\right) \\
& \quad \text { since } A_{i}<A_{j} \text { implies } \llbracket A_{i} \rrbracket_{F^{\prime}} \leq \text { llex } \llbracket A_{j} \rrbracket_{F^{\prime}} \text { for } 1 \leq i, j \leq m \\
= & a\left(\llbracket \operatorname{hor}_{F^{\prime}}\left(S_{w}\right) \rrbracket_{F^{\prime}}\right) \\
& \quad \text { since } \operatorname{hor}_{F^{\prime}}\left(S_{w}\right)=\llbracket S_{w} \rrbracket_{G_{w}}=\llbracket G_{w} \rrbracket=\operatorname{sort}^{<}(w) \\
= & a\left(\llbracket S_{w} \rrbracket_{F^{\prime}}\right) \\
= & \llbracket A \rrbracket_{F^{\prime}} \text { by definition of } \rho^{\prime}(A) .
\end{aligned}
$$

(ii) $A \in V_{0}$ with $\rho(A)=B\langle C\rangle \in V_{1}\left\langle V_{0}\right\rangle$ :

Then $\rho^{\prime}(A)=B\langle C\rangle$ and $\llbracket C \rrbracket_{F} \in \operatorname{big}_{\operatorname{Args}}^{F}$ ( $\left.B\right)$ by definition of the strong normal form. We obtain

$$
\begin{aligned}
\operatorname{nf}_{\mathcal{C}}\left(\llbracket A \rrbracket_{F}\right) & =\operatorname{nf}_{\mathcal{C}}\left(\llbracket B \rrbracket_{F}\left\langle\llbracket C \rrbracket_{F}\right\rangle\right) \\
& =\llbracket B \rrbracket_{F^{\prime}}\left\langle\mathrm{nf}_{\mathcal{C}}\left(\llbracket C \rrbracket_{F}\right)\right\rangle \text { by induction for } B \\
& =\llbracket B \rrbracket_{F^{\prime}}\left\langle\llbracket C \rrbracket_{F^{\prime}}\right\rangle \text { by induction for } C \\
& =\llbracket A \rrbracket_{F^{\prime}} .
\end{aligned}
$$

(iii) $A \in V_{1}$ with $\rho(A)=a(B x C) \in \mathcal{C}\left(V_{0} x V_{0}\right)$ :

Let $w=\llbracket B C \rrbracket_{F ■}=A_{1} \cdots A_{m}$ with $m \geq 0$, say $\llbracket B \rrbracket_{F ■}=A_{1} \cdots A_{k}$ and $\llbracket C \rrbracket_{F \bullet}=A_{k+1} \cdots A_{m}$ with $0 \leq k \leq m$. For every $t \in \operatorname{big}_{\text {_args }}^{F}(A)$ and $1 \leq i \leq m$ we have $\left|\operatorname{nf}_{\mathcal{C}}(t)\right|=|t| \geq\left|\llbracket A\langle\varepsilon\rangle \rrbracket_{F}\right|>\left|\llbracket B C \rrbracket_{F}\right| \geq\left|\llbracket A_{i} \rrbracket_{F}\right|=$ $\left|\operatorname{nf}_{\mathcal{C}}\left(\llbracket A_{i} \rrbracket_{F}\right)\right|$, which implies $\operatorname{nf}_{\mathcal{C}}\left(\llbracket A_{i} \rrbracket_{F}\right) \leq_{\text {llex }} \operatorname{nf}_{\mathcal{C}}(t)$. Hence we obtain

$$
\begin{aligned}
& \operatorname{nf}_{\mathcal{C}}\left(\llbracket A \rrbracket_{F}\langle t\rangle\right)=\operatorname{nf}_{\mathcal{C}}\left(a\left(\llbracket B \rrbracket_{F} t \llbracket C \rrbracket_{F}\right)\right) \\
& =a\left(\operatorname{sort}^{<\operatorname{llex}}\left(\operatorname{nf}_{\mathcal{C}}\left(\llbracket B \rrbracket_{F} t \llbracket C \rrbracket_{F}\right)\right)\right) \\
& \text { by definition of } \mathrm{nf}_{\mathcal{C}} \text { since } a \in \mathcal{C} \\
& =a\left(\text { sort }^{<1 \mathrm{lex}}\left(\mathrm{nf}_{\mathcal{C}}\left(\llbracket A_{1} \rrbracket_{F} \cdots \llbracket A_{k} \rrbracket_{F} t \llbracket A_{k+1} \rrbracket_{F} \cdots \llbracket A_{m} \rrbracket_{F}\right)\right)\right) \\
& =a\left(\text { sort } ^ { < 1 \operatorname { l e x } } \left(\operatorname{nf}_{\mathcal{C}}\left(\llbracket A_{1} \rrbracket_{F}\right) \cdots \operatorname{nf}_{\mathcal{C}}\left(\llbracket A_{k} \rrbracket_{F}\right) \operatorname{nf}_{\mathcal{C}}(t)\right.\right. \\
& \left.\left.\operatorname{nf}_{\mathcal{C}}\left(\llbracket A_{k+1} \rrbracket_{F}\right) \cdots \operatorname{nf}_{\mathcal{C}}\left(\llbracket A_{m} \rrbracket_{F}\right)\right)\right) \\
& \text { by definition of } \mathrm{nf}_{\mathcal{C}} \\
& =a\left(\operatorname{sort}^{<1 \operatorname{llex}}\left(\operatorname{nf}_{\mathcal{C}}\left(\llbracket A_{1} \rrbracket_{F}\right) \cdots \operatorname{nf}_{\mathcal{C}}\left(\llbracket A_{m} \rrbracket_{F}\right)\right) \operatorname{nf}_{\mathcal{C}}(t)\right) \\
& \text { since } \operatorname{nf}_{\mathcal{C}}\left(\llbracket A_{i} \rrbracket_{F}\right) \leq_{\text {llex }} \operatorname{nf}_{\mathcal{C}}(t) \text { for } 1 \leq i \leq m \\
& =a\left(\llbracket S_{w} \rrbracket_{F^{\prime}} \operatorname{nf}_{\mathcal{C}}(t)\right) \\
& \text { since } \llbracket S_{w} \rrbracket_{F^{\prime}}=\operatorname{sort}^{<\operatorname{llex}}\left(\operatorname{nf}_{\mathcal{C}}\left(\llbracket A_{1} \rrbracket_{F}\right) \cdots \operatorname{nf}_{\mathcal{C}}\left(\llbracket A_{m} \rrbracket_{F}\right)\right)
\end{aligned}
$$

by the same reasoning as in (i)
$=\llbracket a\left(S_{w} x\right) \rrbracket_{F^{\prime}}\left\langle\operatorname{nf}_{\mathcal{C}}(t)\right\rangle$
$=\llbracket A \rrbracket_{F^{\prime}}\left\langle\operatorname{nf}_{\mathcal{C}}(t)\right\rangle$ by definition of $\rho^{\prime}(A)$.
(iv) $A \in V_{1}$ with $\rho(A)=B\langle C\rangle \in V_{1}\left\langle V_{1}\right\rangle$ :

Since $\left|\llbracket C \rrbracket_{F}\langle t\rangle\right| \geq|t|$, we obtain $\llbracket C \rrbracket_{F}\langle t\rangle \in{\text { big_- } \operatorname{args}_{F}(B) \text { and thus }}$

$$
\begin{aligned}
\operatorname{nf}_{\mathcal{C}}\left(\llbracket A \rrbracket_{F}\langle t\rangle\right) & =\operatorname{nf}_{\mathcal{C}}\left(\llbracket B \rrbracket_{F}\left\langle\llbracket C \rrbracket_{F}\langle t\rangle\right\rangle\right) \\
& =\llbracket B \rrbracket_{F^{\prime}}\left\langle\mathrm{nf}_{\mathcal{C}}\left(\llbracket C \rrbracket_{F}\langle t\rangle\right)\right\rangle \text { by induction for } B \\
& =\llbracket B \rrbracket_{F^{\prime}}\left\langle\llbracket C \rrbracket_{F^{\prime}}\left\langle\mathrm{nf}_{\mathcal{C}}(t)\right\rangle\right\rangle \text { by induction for } C \\
& =\llbracket A{F^{\prime}}^{\prime}\left\langle\mathrm{nf}_{\mathcal{C}}(t)\right\rangle .
\end{aligned}
$$

This concludes the proof of the theorem.
Example 9 Let $F$ be the strong normal form FSLP $F_{m}^{\prime}=\left(V^{\prime}, S, \rho^{\prime}\right)(m \geq 1)$ which we obtained in Example 8. From $F$ we construct a new FSLP which produces $\operatorname{nf}_{\mathcal{C}}(\llbracket F \rrbracket)$. Again, we will only consider the spine of $B$ and ignore the
spines of the $U_{2 i}$. We have to replace the right-hand sides of $C_{i}$ and $D_{i}$ for $1 \leq i \leq m$. For $\rho^{\prime}\left(C_{i}\right)=a\left(C_{i}^{\prime}\right)$ we have

$$
w=\operatorname{hor}_{F}\left(C_{i}^{\prime}\right)=\llbracket L_{i} A_{i-1} R_{i} \rrbracket_{F \square}=L_{i} A_{i-1} R_{1}^{2^{i-1}}
$$

Let $<$ be the total order on $M_{C_{i}} \supseteq\left\{L_{i}, A_{i-1}, R_{1}\right\}$ from Theorem 2. Since $\llbracket A_{i-1} \rrbracket_{F}=t_{p_{i}}$ and $\llbracket R_{1} \rrbracket_{F}<_{\text {llex }} t_{p_{i}}<_{\text {llex }} \llbracket L_{i} \rrbracket_{F}$ for $2 \leq i \leq m$, we must have that $R_{1}<A_{i-1}<L_{i}$. For $i=1$ we have a special case because $R_{1}=A_{0}$, for which we have $\llbracket A_{0} \rrbracket_{F}<_{\text {llex }} \llbracket L_{1} \rrbracket_{F}$, so $R_{1}=A_{0}<L_{1}$. Altogether, we obtain

$$
\operatorname{sort}^{<}(w)=R_{1}^{2^{i-1}} A_{i-1} L_{i}
$$

Using Lemma 4, we introduce an SLP $G_{w}=\left(V_{w}, S_{w}, \rho_{w}\right)$ with $\llbracket G_{w} \rrbracket=$ sort ${ }^{<}(w)$. Finally, we set the new right-hand side of $C_{i}$ to $a\left(S_{w}\right)$.

For the right-hand sides $\rho^{\prime}\left(D_{i}\right)=a\left(L_{i} x R_{i}\right)$ for $1 \leq i \leq m$ we have

$$
w=\llbracket L_{i} R_{i} \rrbracket_{F ■}=L_{i} R_{1}^{2^{i-1}}
$$

Let $<$ be the total order on $M_{D_{i}} \supseteq\left\{R_{1}, L_{i}\right\}$ from Theorem 2. Since $\llbracket R_{1} \rrbracket_{F}<$ llex $\llbracket L_{i} \rrbracket_{F}$ for $1 \leq i \leq m$, we must have that $R_{1}<L_{i}$, and thus sort ${ }^{<}(w)=$ $R_{1}^{2^{i-1}} L_{i}$. Since $F$ is in strong normal form, $x$ always goes to the last position. We introduce $G_{w}=\left(V_{w}, S_{w}, \rho_{w}\right)$ with $\llbracket G_{w} \rrbracket=\operatorname{sort}^{<}(w)$ and set the new right-hand side of $D_{i}$ to $a\left(S_{w} x\right)$. This concludes our example.

As an immediate consequence of Theorem 2 we obtain our main result.
Theorem 3 For trees $s, t$ we can test in polynomial time whether $s$ and $t$ are equal modulo the identities in (ASSOC) and (COMM), if $s$ and $t$ are given succinctly by one of the following formalisms: (i) FSLPs, (ii) top dags, (iii) TSLPs for their fcns-encodings.

Proof By Proposition 1 and 3 it suffices to show Theorem 3 for the case that $t_{1}$ and $t_{2}$ are given by FSLPs $F_{1}$ and $F_{2}$, respectively. By Lemma 6 and Lemma 5 it suffices to compute in polynomial time FSLPs $F_{1}^{\prime}$ and $F_{2}^{\prime}$ for $\operatorname{nf}_{\mathcal{C}}\left(\operatorname{nf}_{\mathcal{A}}\left(t_{1}\right)\right)$ and $\operatorname{nf}_{\mathcal{C}}\left(\operatorname{nf}_{\mathcal{A}}\left(t_{2}\right)\right)$. This can be achieved using Lemma 3 and Theorem 2.

## 7 Future work

We have shown that simple algebraic manipulations (laws of associativity and commutativity) can be carried out efficiently on grammar-compressed trees. In the future, we plan to investigate other algebraic laws. We are optimistic that our approach can be extended by idempotent symbols (meaning that $a(f t t g)=a(f t g)$ for forests $f, g$ and a tree $t)$.

Another interesting open problem concerns context unification modulo associative and commutative symbols. The decidability of (plain) contextunification was a long standing open problem finally solved by Jeż [18], who showed the existence of a polynomial space algorithm. Jeż's algorithm uses his
recompression technique for TSLPs. One might try to extend this technique to FSLPs with the goal of proving decidability of context unification for terms that also contain associative and commutative symbols. For first-order unification and matching [13], context matching [13], and one-context unification [10] there exist algorithms for TSLP-compressed trees that match the complexity of their uncompressed counterparts. One might also try to extend these results to the associative and commutative setting.

Acknowledgements The first author was supported by the EPSRC grant EP/N510129/1 at the Alan Turing Institute and the EPSRC grant EP/J017728/2 at University of Edinburgh. The second author was supported by the DFG research project LO748/10-1.

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