Advanced Logic

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General comments

Informations concerning the lecture can be found at

https://www.eti.uni-siegen.de/ti/lehre/sommer_2022/advancedlogic/advancedlogic.html

- current version of the slides
- links to the videos
- exercise sheets

Literature:

 Schöning: Logik für Informatiker, Spektrum Akademischer Verlag 2013
 (5. - Li L. 5. Livit, J. 6. Construction, Di Lluii, 2000)

(English Edition: Logic for Computer Scientists, Birkhäuser 2008)

 Ebbinghaus, Flum, Thomas: Einführung in the mathematische Logik, Spektrum Akademischer Verlag (English Edition: Mathematical Logic, Springer 1994)

The tutorials will be organized by Louisa Seelbach.

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Recapitulation from the lecture GTI

Definition (recursively enumerable)

A language $L \subseteq \Sigma^*$ is recursively enumerable, if there is an algorithm with the following properties:

For $x \in \Sigma^*$ we have:

- If $x \in L$, then the algorithm terminates with input x.
- If $x \notin L$, then the algorithm does not terminate with input x.

German term: semi-entscheidbar.

Lemma

A language $L \subseteq \Sigma^*$ is recursively enumerable if and only if there is a computable total function $f : \mathbb{N} \to \Sigma^*$ with $L = \{f(i) \mid i \in \mathbb{N}\}$.

Recapitulation from the lecture GTI

Definition (decidable and undecidable)

A language $L \subseteq \Sigma^*$ is decidable, if there is an algorithm with the following properties: for all $x \in \Sigma^*$ we have:

▶ If $x \in L$, then the algorithm terminates on input x with output "Yes".

▶ If $x \notin L$, then the algorithm terminates on input x with output "No".

A language $L \subseteq \Sigma^*$ is undecidable, if L is not decidable.

Theorem

A language $L \subseteq \Sigma^*$ is decidable if and only if L and $\Sigma^* \setminus L$ are both recursively enumerable.

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Recapitulation from the lecture Logik I

We assume the following notions/definitions from Logik I

- Formulas of predicate logic (Formel der Prädikatenlogik) Example: G = ∀x∃y(P(x, f(y)) ∧ ¬Q(g(z, x)))
- Sentence = formulas without free variable (Aussagen) Example: F = ∀x∃y(P(x, y) ∧ ¬P(f(x), x))
- structure (Struktur) A = (U_A, I_A), where U_A is the universe of the structure and I_A is the interpretation function (we write f^A = I_A(f)). Example: U_A = ℕ, f^A(n) = n², P^A = {(n, m) | n < m}.
- Structure A is suitable (passend) for a formula F.
 Example: A is suitable for F, but not suitable for G.
- A ⊨ F: F evaluates to 1 (= true) in the structure A.
 Whenever we write A ⊨ F, we implicitly assume that A is suitable for F.

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Recapitulation from the lecture Logik I

A formula F of predicate logic is:

Satisfiable, if there is a structure A such that A ⊨ F (F is true in the structure A).

• valid, if $\mathcal{A} \models F$ holds for every structure \mathcal{A} .

Corollary of Gilmore's theorem

The set of all unsatisfiable formulas of predicate logic is recursively enumerable.

Corollary

The set of all valid formulas of predicate logic is recursively enumerable.

Proof: *F* is valid if and only if $\neg F$ is unsatisfiable.

Undecidability in predicate logic

We want to prove the following important result:

Church's theorem

The set of valid formulas of predicate logic is undecidable.

Corollary

The set of satisfiable formulas of predicate logic is not recursively enumerable.

Proof: The set of unsatisfiable formulas of predicate logic is recursively enumerable.

If the set of satisfiable formulas of predicate logic would be recursively enumerable, then it would be decidable.

Hence, also the set of unsatisfiable (and hence the set of valid) formulas would be decidable.

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We prove Church's theorem by a reduction from the halting problem for register machine programs.

Let R_1, R_2, \ldots be (names for) registers.

Intuition: Every register stores a natural number.

A register machine program (RMP for short) P is a sequence of instructions $A_1; A_2; ...; A_l$, where A_l is the STOP instruction, and for all $1 \le i \le l-1$ the instruction A_i is of one of the following types:

▶
$$R_j := R_j + 1$$
 for some $1 \le j \le l$

•
$$R_j := R_j - 1$$
 for some $1 \le j \le l$

▶ IF $R_j = 0$ THEN k_1 ELSE k_2 for some $1 \le j, k_1, k_2 \le l$.

Note: We assume that only the registers R_1, \ldots, R_l are used in an RMP with l instructions. This is no restriction.

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A configuration of P is a tuple $(i, n_1, \ldots, n_l) \in \mathbb{N}^{l+1}$ with $1 \leq i \leq l$.

Intuition: *i* is the number of the instruction that is executed next and n_j is the current content of register R_j .

For configurations (i, n_1, \ldots, n_l) and (i', n'_1, \ldots, n'_l) we write

$$(i, n_1, \ldots, n_l) \rightarrow_P (i', n'_1, \ldots, n'_l)$$

if and only if $1 \le i \le l-1$ and one of the following cases holds:

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Example: The following RMP *P* simulates $R_1 := R_1 + R_2$:

1: IF $R_2 = 0$ THEN 5 ELSE 2; 2: $R_1 := R_1 + 1$; 3: $R_2 := R_2 - 1$; 4: IF $R_1 = 0$ THEN 1 ELSE 1; 5: STOP

More precisely: For all numbers n_1 , n_2 we have

$$(1, n_1, n_2, 0, 0, 0) \rightarrow^*_P (5, n_1 + n_2, 0, 0, 0, 0).$$

The configuration is (1, 0, ..., 0) (all registers contain 0, first instruction is executed) is also called starting configuration.

We define

$$\mathsf{HALT} = \{ P \mid P = A_1; A_2; \dots; A_l \text{ is a RMP with } l \text{ instructions,} \\ (1, 0, \dots, 0) \rightarrow_P^* (l, n_1, \dots, n_l) \text{ for } n_1, \dots, n_l \ge 0 \}.$$

Register machine programs exactly correspond to GOTO-programs from the GTI lecture.

In GTI we proved that Turing machines and GOTO-programs can simulate each other.

Since the halting problem for Turing machines starting with the empty tape (does a given Turing machine finally terminate when it is started with a tape where every cell contains the blank symbol?) is undecidable, we get:

Theorem (undecidability of the halting problem for RMPs) The set HALT is undecidable.

Remark: HALT is recursively enumerable: Simulate a given RMP on the starting configuration (1, 0, ..., 0) and stop, if the RMP reaches the STOP-instruction.

We prove Church's theorem by constructing from a given RMP P a formula F_P such that:

$$F_P$$
 is valid $\iff P \in \mathsf{HALT}$

Let $P = A_1; A_2; \ldots; A_l$ be an RMP.

We fix the following symbols:

- <: binary predicate symbol</p>
- c: constant
- ► *f*,*g*: unary function symbols
- R: (1+2)-ary predicate symbol

We define a structure \mathcal{A}_P by case distinction:

Case 1: $P \notin HALT$:

(

► Universe
$$U_{\mathcal{A}_P} = \mathbb{N}$$
► $\langle \mathcal{A}_P = \{(n,m) \mid n < m\}$ (the standard order on \mathbb{N})
► $c^{\mathcal{A}_P} = 0$
► $f^{\mathcal{A}_P}(n) = n + 1, g^{\mathcal{A}_P}(n+1) = n, g^{\mathcal{A}_P}(0) = 0$
► $R^{\mathcal{A}_P} = \{(s, i, n_1, \dots, n_l) \mid (1, 0, \dots, 0) \rightarrow_P^s (i, n_1, \dots, n_l)\}$
Case 2: $P \in \text{HALT}$:

Let *t* such that $(1, 0, ..., 0) \rightarrow_P^t (l, n_1, ..., n_l)$ and $e = \max\{t, l\}$.

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In the following we write \overline{m} for the term $f^m(c) = \underbrace{f(f(\cdots f(c) \cdots))}_{m \text{ many}}$.

We define a sentence G_P (in which <, c, f, g and R are used) with the following properties:

(A) $\mathcal{A}_P \models \mathcal{G}_P$

(B) For every model \mathcal{A} of G_P the following holds: If $(1, 0, ..., 0) \rightarrow_P^s (i, n_1, ..., n_l)$, then:

$$\mathcal{A} \models R(\overline{s}, \overline{i}, \overline{n_1}, \ldots, \overline{n_l}) \land \bigwedge_{q=0}^{s-1} \overline{q} < \overline{q+1}.$$

We define $G_P = G_0 \wedge R(\overline{0}, \overline{1}, \overline{0}, \dots, \overline{0}) \wedge G_1 \wedge \dots \wedge G_{l-1}$.

The sentences $G_0, G_1, \ldots, G_{l-1}$ are defined as follows.

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 G_0 expresses that

 \triangleright < is a strict linear order with smallest element c,

•
$$x \leq f(x)$$
 and $g(x) \leq x$ for all x ,

- for every x, which is not the largest element with respect to <, f(x) is the direct successor of x, and</p>
- for every x with $x \neq c$, g(x) is the direct predecessor of x.

$$\begin{aligned} \forall x, y, z \ (\neg x < x) \land (x = y \lor x < y \lor y < x) \land ((x < y \land y < z) \rightarrow x < z) \\ \land (x = c \lor c < x) \\ \land (x = f(x) \lor x < f(x)) \\ \land (x = g(x) \lor g(x) < x) \\ \land (\exists u(x < u) \rightarrow (x < f(x) \land \forall u(x < u \rightarrow (u = f(x) \lor f(x) < u)))) \\ \land (\exists u(u < x) \rightarrow (g(x) < x \land \forall u(u < x \rightarrow (u = g(x) \lor u < g(x))))) \end{aligned}$$

Remark: For every model \mathcal{A} of G_0 we have:

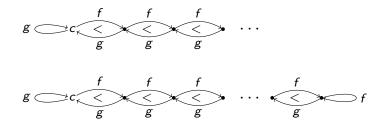
$$A \models g(c) = c A \models \forall x (\exists u(x < u) \rightarrow g(f(x)) = x)$$

 $\mathcal{A} \models g(c) = c$: We have $g(c) = c \lor c < g(c)$ and $c = g(c) \lor g(c) < c$. Hence, if $g(c) \neq c$ then we would obtain $c < g(c) \land g(c) < c$ and hence c < c, which is a contradiction.

$$\mathcal{A} \models \forall x \ (\exists u(x < u) \rightarrow g(f(x)) = x): \text{ Assume that } \exists u(x < u).$$

We get $x < f(x) \land \forall u(x < u \rightarrow (u = f(x) \lor f(x) < u)).$
Thus, $g(f(x)) < f(x) \land \forall u(u < f(x) \rightarrow (u = g(f(x)) \lor u < g(f(x)))).$
Since $x < f(x)$ we obtain $x = g(f(x)) \lor x < g(f(x)).$
But $x < g(f(x)) < f(x)$ is not possible $(f(x) = \text{direct successor of } x).$

Typical models of G_0 :



In particular: \mathcal{A}_P is a model of \mathcal{G}_0 .

 G_i for $1 \le i \le l-1$ describes the effect of instruction A_i .

Case 1: $A_i = (R_j := R_j + 1)$. Define

$$G_i = \forall x \forall x_1 \cdots \forall x_l \left(R(x, \overline{i}, x_1, \dots, x_l) \rightarrow (x < f(x) \land R(f(x), \overline{i+1}, x_1, \dots, x_{j-1}, f(x_j), x_{j+1}, \dots, x_l)) \right)$$

Case 2: $A_i = (R_j := R_j - 1)$. Define

$$G_i = \forall x \forall x_1 \cdots \forall x_l \left(R(x, \overline{i}, x_1, \dots, x_l) \rightarrow (x < f(x) \land R(f(x), \overline{i+1}, x_1, \dots, x_{j-1}, g(x_j), x_{j+1}, \dots, x_l)) \right)$$

Case 3: $A_i = (\text{IF } R_j = 0 \text{ THEN } k_1 \text{ ELSE } k_2)$ for a $1 \le j, k_1, k_2 \le l$. Define

$$G_i = \forall x \forall x_1 \cdots \forall x_l \left(R(x, \overline{i}, x_1, \dots, x_l) \rightarrow (x < f(x) \land (x_j = c \land R(f(x), \overline{k_1}, x_1, \dots, x_l)) \lor (x_j > c \land R(f(x), \overline{k_2}, x_1, \dots, x_l))) \right)$$

Statement (A) follows directly from the definition of A_P and G_P :

▶ Since
$$(1,0,\ldots,0) \rightarrow_P^0 (1,0,\ldots,0)$$
 we have $(0,1,0,\ldots,0) \in R^{\mathcal{A}_P}$

► To see that A_P is a model of G_i (1 ≤ i ≤ l − 1), assume that for instance A_i = (R_j := R_j + 1).

Then for all $s, n_1, \ldots, n_l \in U_{\mathcal{A}_P}$ with $(1, 0, \ldots, 0) \rightarrow_P^s (i, n_1, \ldots, n_l)$, i.e., $(s, i, n_1, \ldots, n_l) \in R^{\mathcal{A}_P}$, we have:

Statement (B) is shown by induction on s.

Induction base: s = 0. Let $(1, 0, ..., 0) \rightarrow_P^0 (i, n_1, ..., n_l)$, i.e., i = 1 and $n_1 = n_2 = \cdots = n_l = 0$.

 $\mathcal{A} \models G_P$ implies $\mathcal{A} \models R(\overline{0}, \overline{1}, \overline{0}, \dots, \overline{0})$, i.e., $\mathcal{A} \models R(\overline{s}, \overline{i}, \overline{n_1}, \dots, \overline{n_l})$.

Induction step: Let s > 0 and assume that statement (B) holds for s - 1. Let $(1, 0, ..., 0) \rightarrow_P^s (i, n_1, ..., n_l)$. There are $j \le l - 1, m_1, ..., m_l$ with

$$(1,0,\ldots,0)\rightarrow_P^{s-1}(j,m_1,\ldots,m_l)\rightarrow_P(i,n_1,\ldots,n_l)$$

The induction hypothesis implies

$$\mathcal{A} \models R(\overline{s-1},\overline{j},\overline{m_1},\ldots,\overline{m_l}) \land \bigwedge_{q=0}^{s-2} \overline{q} < \overline{q+1}.$$

We continue with a case distinction with respect to the instruction A_j . We only consider the case that A_j is of the form $R_k := R_k - 1$.

We then have i = j + 1, $n_1 = m_1, \dots, n_{k-1} = m_{k-1}$, $n_{k+1} = m_{k+1}, \dots, n_l = m_l$, $(n_k = m_k = 0 \text{ or } m_k > 0 \text{ and } n_k = m_k - 1)$. Markus Lohrey (Universität Siegen) Advanced Logic Summer 2022 22/161

Because of $\mathcal{A} \models G_j$ we have:

$$\mathcal{A} \models \forall y, y_1, \dots, y_l \left(R(y, \overline{j}, y_1, \dots, y_l) \rightarrow (y < f(y) \land R(f(y), \overline{j+1}, y_1, \dots, y_{k-1}, g(y_k), y_{k+1}, \dots, y_l)) \right)$$

Since $\mathcal{A} \models R(\overline{s-1}, \overline{j}, \overline{m_1}, \dots, \overline{m_l})$, we get
$$\mathcal{A} \models \overline{s-1} < f(\overline{s-1}) \land R(f(\overline{s-1}), \overline{j+1}, \overline{m_1}, \dots, \overline{m_{k-1}}, g(\overline{m_k}), \overline{m_{k+1}}, \dots, \overline{m_l})$$

i.e., $\mathcal{A} \models \overline{s-1} < \overline{s} \land R(\overline{s}, \overline{i}, \overline{n_1}, \dots, \overline{n_{k-1}}, g(\overline{m_k}), \overline{n_{k+1}}, \dots, \overline{n_l})$.
Because of $\mathcal{A} \models \overline{s-1} < \overline{s}$, we have
$$\mathcal{A} \models \bigwedge^{s-1} \overline{q} < \overline{q+1}.$$
(1)

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q=0

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Moreover, $\mathcal{A} \models G_0$ implies $\mathcal{A} \models g(\overline{m_k}) = \overline{n_k}$:

• If
$$n_k = m_k = 0$$
 then $\overline{m_k} = \overline{n_k} = c$.

Since every model of G_0 satisfies g(c) = c (slide 17) we get $\mathcal{A} \models g(\overline{m_k}) = \overline{n_k}$.

• If $m_k > 0$ and $n_k = m_k - 1$ then $\overline{m_k} = f(\overline{n_k})$.

Since every model of G_0 satisfies $\forall x \ (\exists u(x < u) \rightarrow g(f(x)) = x)$ (slide 17) and $\mathcal{A} \models \overline{n_k} < \overline{n_k + 1} = \overline{m_k}$ by (1), we get

$$\mathcal{A} \models g(\overline{m_k}) = g(f(\overline{n_k})) = \overline{n_k}.$$

Therefore we have $\mathcal{A} \models R(\overline{s}, \overline{i}, \overline{n_1}, \dots, \overline{n_l})$. This shows (A) and (B).

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Proof of Church's theorem:

Define $F_P = (G_P \rightarrow \exists x \exists x_1 \cdots \exists x_l R(x, \overline{l}, x_1, \dots, x_l)).$ Claim: F_P is valid $\iff P \in HALT.$ If F_P is valid, then $\mathcal{A}_P \models F_P.$ (A) yields $\mathcal{A}_P \models \exists x \exists x_1 \cdots \exists x_l R(x, \overline{l}, x_1, \dots, x_l).$ Hence, there are $s, n_1, \dots, n_l \ge 0$ with $(s, l, n_1, \dots, n_l) \in R^{\mathcal{A}_P}.$ We obtain $P \in HALT.$

Now assume that $P \in HALT$.

- Assume that $(1, 0, \ldots, 0) \rightarrow_P^s (I, n_1, \ldots, n_l)$.
- Let \mathcal{A} be a structure with $\mathcal{A} \models G_P$.
- (B) implies $\mathcal{A} \models R(\overline{s}, \overline{l}, \overline{n_1}, \dots, \overline{n_l})$.

Hence, F_P is valid.

A formula F is finitely satisfiable if F has a model with a finite universe. If such a model does not exist then F is called finitely unsatisfiable.

Lemma

The set of finitely satisfiable formulas of predicate logic is recursively enumerable.

Proof:

Let $\mathcal{A}_1, \mathcal{A}_2, \mathcal{A}_3, \ldots$ be a systematic enumeration of all finite structures (we assume that the interpretation function $I_{\mathcal{A}_i}$ is only defined on those predicate and function symbols that appear in F).

The following algorithm terminates if and only if F is finitely satisfiable:

```
i := 1;
while true do
if A_i \models F then STOP else i := i + 1
end
```

A formula F is finitely valid if every finite structure is a model of F. Example: The formula

$$\forall x \forall y (f(x) = f(y) \rightarrow x = y) \leftrightarrow \forall y \exists x (f(x) = y)$$

is finitely valid but not valid.

Trachtenbrot's theorem

The set of finitely satisfiable formulas is undecidable.

Corollary

The set of finitely unsatisfiable formulas and the set of finitely valid formulas are not recursively enumerable.

Proof of Trachtenbrot's theorem:

We use the construction from the proof of Church's theorem.

Claim: G_P is finitely satisfiable $\iff P \in HALT$.

(1) Assume that $P \in HALT$.

Then \mathcal{A}_P is finite and $\mathcal{A}_P \models \mathcal{G}_P$ by statement (A).

Hence, G_P is finitely satisfiable.

(2) Let G_P be finitely satisfiable.

Let \mathcal{A} be a finite structure with $\mathcal{A} \models G_P$.

Assume that $P \notin HALT$.

Hence, for every $s \ge 0$ there exist i, n_1, \ldots, n_l with $(1, 0, \ldots, 0) \rightarrow_P^s (i, n_1, \ldots, n_l)$.

Statement (B) implies that $\mathcal{A} \models \overline{q} < \overline{q+1}$ for all $q \ge 0$.

Since $<^{\mathcal{A}}$ is a strict linear order (because $\mathcal{A} \models G_0$), the set $\{\mathcal{A}(\overline{i}) \mid i \ge 0\}$ must be infinite, which is a contradiction.

Let \mathcal{A} be a structure such that the domain of $I_{\mathcal{A}}$ is finite and contains no variables.

Let the domain of I_A consist of $f_1, \ldots, f_n, R_1, \ldots, R_m$.

We identify \mathcal{A} with the tuple $(U_{\mathcal{A}}, f_1^{\mathcal{A}}, \ldots, f_n^{\mathcal{A}}, R_1^{\mathcal{A}}, \ldots, R_m^{\mathcal{A}})$ for which we also write $(U_{\mathcal{A}}, f_1, \ldots, f_n, R_1, \ldots, R_m)$.

Definition

The theory of \mathcal{A} is the set of formulas

$$\mathsf{Th}(\mathcal{A}) = \{F \mid F \text{ is a sentence and } \mathcal{A} \models F\}.$$

We are interested in the question whether a given structure has a decidable theory.

Theorem

Let \mathcal{A} be an arbitrary structure. Then, $Th(\mathcal{A})$ is decidable if and only if $Th(\mathcal{A})$ is recursively enumerable.

Proof: Let Th(A) be recursively enumerable and let F be an arbitrary sentence.

We either have $F \in \mathsf{Th}(\mathcal{A})$ or $\neg F \in \mathsf{Th}(\mathcal{A})$.

Therefore we can enumerate Th(A) until we either produce F or $\neg F$.

Exactly one of the formulas F or $\neg F$ will be produced after a finite number of steps.

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For the question whether a theory is decidable, we can restrict to so-called relational structures.

A structure $\mathcal{A} = (A, f_1, \dots, f_n, R_1, \dots, R_m)$ is relational if n = 0. For an arbitrary structure $\mathcal{A} = (A, f_1, \dots, f_n, R_1, \dots, R_m)$ we define

$$\mathcal{A}_{\mathsf{rel}} = (A, P_1, \dots, P_n, R_1, \dots, R_m),$$

where
$$P_i = \{(a_1, \dots, a_k, a) \in A^{k+1} \mid f_i(a_1, \dots, a_k) = a\}.$$

Lemma

 $\mathsf{Th}(\mathcal{A})$ is decidable $\iff \mathsf{Th}(\mathcal{A}_{rel})$ is decidable.

Proof: For \Leftarrow we construct from a sentence F that contains the symbols f_i, R_j a sentence F' that only contains the symbols P_i, R_j and such that:

$$\mathcal{A} \models \mathsf{F} \iff \mathcal{A}_{\mathsf{rel}} \models \mathsf{F}'$$

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Consider a subformula $R_i(t_1, \ldots, t_k)$ in F, where t_1, \ldots, t_k are terms, and replace it by

$$\exists x_1 \cdots \exists x_k \ (R_i(x_1, \ldots, x_k) \land \bigwedge_{i=1}^{\kappa} x_i = t_i).$$

for new variables x_1, \ldots, x_k .

We now replace equations $y = f_j(s_1, \ldots, s_l)$ with $l \ge 0$ by

$$\exists y_1 \cdots \exists y_l (P_j(y_1, \ldots, y_l, y) \land \bigwedge_{i=1}^l y_i = s_i)$$

for new variables y_1, \ldots, y_l until only equations of the form y = y' for variables y, y' remain.

The direction \implies from the lemma is very easy (Excercise).

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Undecidability of arithmetics

Theorem (Gödel 1931) Th $(\mathbb{N}, +, \cdot)$ is undecidable.

Corollary $Th(\mathbb{N}, +, \cdot)$ is not recursively enumerable.

For the proof we reduce the set HALT of terminating RMPs to $\mathsf{Th}(\mathbb{N},+,\cdot)$.

We follow the proof from the book of Ebbinghaus, Flum and Thomas.

In order make the proof less technical we consider $Th(\mathbb{N}, +, \cdot, s, 0)$ with s(n) = n + 1.

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Undecidability of arithmetics

We then have: $\mathsf{Th}(\mathbb{N}, +, \cdot, s, 0)$ decidable $\iff \mathsf{Th}(\mathbb{N}, +, \cdot)$ decidable:

- ▶ If $Th(\mathbb{N}, +, \cdot, s, 0)$ is decidable, then clearly $Th(\mathbb{N}, +, \cdot)$ is decidable.
- Assume that $Th(\mathbb{N}, +, \cdot)$ is decidable.

We transform a sentence F that contains $+, \cdot, s, 0$ into a sentence F' that only contains $+, \cdot$ and such that $F \in Th(\mathbb{N}, +, \cdot, s, 0)$ if and only if $F' \in Th(\mathbb{N}, +, \cdot)$.

Step 1: Replace F by

$$\exists x_0 \exists x_1 (x_0 + x_0 = x_0 \land x_1 \cdot x_1 = x_1 \land x_1 \neq x_0 \land F)$$

Step 2: Replace in the resulting sentence every occurrence of the constant 0 by x_0 and every term s(t) by $t + x_1$.

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Undecidability of arithmetics

Now assume that $P = A_1; A_2; \cdots; A_l$ is an RMP which uses the registers R_1, \ldots, R_l .

We construct an arithmetic formula F_P with the free variables x, x_1, \ldots, x_l such that for all $1 \le i \le l$ and all $n_1, \ldots, n_l \in \mathbb{N}$ the following statements are equivalent:

▶
$$(\mathbb{N}, +, \cdot, s, 0)_{[x/i, x_1/n_1, ..., x_l/n_l]} \models F_P$$

▶ $(1, 0, ..., 0) \rightarrow_P^* (i, n_1, ..., n_l)$

This implies $P \in \text{HALT} \iff (\mathbb{N}, +, \cdot, s, 0) \models \exists x_1 \cdots \exists x_l F_P[x/s^l(0)].$

Intuitively, F_P expresses the following:

There exists $t \ge 0$ and configurations C_0, C_1, \ldots, C_t with:

We encode the (l + 1)-tuples C_0, C_1, \ldots, C_t by an $(t + 1) \cdot (l + 1)$ -tuple. It remains to express the following, where k = l + 1:

There exist
$$t \ge 0$$
 and a tuple
 $(y_0, y_1, \dots, y_{k-1}, y_k, y_{k+1}, \dots, y_{2k-1}, \dots, y_{tk}, y_{tk+1}, \dots, y_{tk+k-1})$ with:
 $y_0 = 1, y_1 = 0, \dots, y_{k-1} = 0$
 $y_{tk} = x, y_{tk+1} = x_1, \dots, y_{tk+k-1} = x_l$
 $(y_{ik}, \dots, y_{ik+k-1}) \rightarrow_P (y_{(i+1)k}, \dots, y_{(i+1)+k-1})$ for all $0 \le i \le t - 1$

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If one tries to express this with an arithmetic formula, one encounters the problem that one cannot quantify over arbitrary sequences of numbers in predicate logic $(\exists y \exists x_1 \exists x_2 \cdots \exists x_y \text{ is not allowed}).$

In order to simulate quantification of sequences of arbitrary length, we need Gödel's β -function.

Lemma

There is a function $\beta : \mathbb{N}^3 \to \mathbb{N}$ with:

- For every sequence (a_0, \ldots, a_q) over \mathbb{N} there exist $p, r \in \mathbb{N}$ such that $\beta(p, r, i) = a_i$ for all $0 \le i \le q$.
- There is an arithmetic formula B with free variables v, x, y, z such that for all p, r, i, a ∈ N we have:

$$(\mathbb{N},+,\cdot,s,0)_{[v/p,\ x/r,\ y/i,\ z/a]}\models B\iff \beta(p,r,i)=a$$

One also says that β is arithmetically definable.

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Proof of the lemma:

Let (a_0, \ldots, a_q) be an arbitrary sequence over \mathbb{N} .

Let p be a prime number with p > q and $p > a_i$ for all i.

Furthermore, define

$$r = 0p^{0} + a_{0}p^{1} + 1p^{2} + a_{1}p^{3} + \dots + ip^{2i} + a_{i}p^{2i+1} + \dots + qp^{2q} + a_{q}p^{2q+1}$$

In other words: $(0, a_0, 1, a_1, \dots, i, a_i, \dots, q, a_q)$ is the base-*p* expansion of *r* (least significant digit on the left).

Note: since p is prime, we have the following for every $x \in \mathbb{N}$: There exists $m \in \mathbb{N}$ with $x = p^{2m}$ if and only if:

• x is a square
$$(\exists y : x = y^2)$$
 and

• for all $d \ge 2$ with d|x we have p|d.

Here, x|y stands for "x divides y" $(\exists z : x \cdot z = y)$.

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Claim 1: For all $a \in \mathbb{N}$ and all $0 \le i \le q$ we have: $a = a_i$ if and only if there exist $b_0, b_1, b_2 \in \mathbb{N}$ with:

(a)
$$r = b_0 + b_1(i + ap + b_2p^2)$$

(b)
$$a < p$$

(c)
$$b_0 < b_1$$

(d) b_1 is a square and p|d holds for all $d \ge 2$ with $d|b_1$. (equivalently: $\exists m : b_1 = p^{2m}$)

 \implies : If $a = a_i$ then we can choose b_0, b_1, b_2 as follows:

$$b_0 = 0p^0 + a_0p^1 + 1p^2 + a_1p^3 + \dots + (i-1)p^{2i-2} + a_{i-1}p^{2i-1}$$

$$b_1 = p^{2i}$$

$$b_2 = (i+1) + a_{i+1}p + \dots + qp^{2(q-i-1)} + a_qp^{2(q-i)-1}$$

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 \iff : Assume that (a)-(d) hold, i.e.,

$$r = b_0 + b_1(i + ap + b_2p^2)$$

= $b_0 + ip^{2m} + ap^{2m+1} + p^{2m+2}b_2.$

where $b_0 < b_1 = p^{2m}$, a < p and i < p.

Comparing this with

$$r = 0p^{0} + a_{0}p^{1} + 1p^{2} + a_{1}p^{3} + \dots + ip^{2i} + a_{i}p^{2i+1} + \dots + qp^{2q} + a_{q}p^{2q+1}$$

and using the uniqueness of the base-p expansion of numbers yields m = iand $a = a_i$.

This shows Claim 1.

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We can now define Gödel's β -function:

For all $p, r, i \in \mathbb{N}$ we define $\beta(p, r, i)$ as

- (i) the smallest number a ∈ N such that there are b₀, b₁, b₂ ∈ N with the properties (a)–(d) from Slide 40, respectively
- (ii) 0 if numbers $a, b_0, b_1, b_2 \in \mathbb{N}$ with the properties (a)–(d) do not exist.

Remarks:

- The choice of 0 in (ii) is not important (any other number would be also fine).
- Also the choice of the minimum for a in point (i) is not important. It is only important that we select a unique number a having the properties (a)-(d) (one could for instance take the largest number a with these properties).

Claim 2: For every sequence (a_0, \ldots, a_q) over \mathbb{N} there exist $p, r \in \mathbb{N}$ such that $\beta(p, r, i) = a_i$ holds for all $0 \le i \le q$.

Let (a_0, \ldots, a_q) be a sequence over \mathbb{N} .

Define p and r as on Slide 39.

Take an arbitrary number $0 \le i \le q$.

Due to Claim 1 (direction \Rightarrow) there are $a, b_0, b_1, b_2 \in \mathbb{N}$ such that (a)–(d) hold (take $a = a_i$ for this).

By definition of the function β there are $b_0, b_1, b_2 \in \mathbb{N}$ such that (a)–(d) also hold with $a = \beta(p, r, i)$.

By Claim 1 (direction \Leftarrow) we must have $\beta(p, r, i) = a_i$.

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Claim 3: β is arithmetically definable.

All four properties (a)–(d) on Slide 40 are arithmetically definable. For instance, property (d) can be expressed by the formula

$$\exists x: b_1 = x^2 \land \forall x: ((\exists y: s(s(x)) \cdot y = b_1) \to \exists z: (p \cdot z = s(s(x))).$$

Here, s(s(x)) stands for the number d in property (d) (the two applications of the successor function s ensure that $s(s(x)) \ge 2$ holds). With Claims 2 and 3, the proof of the lemma is complete.

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We can now conclude the undecidability proof for arithmetics.

We have to express the following statement (with free variables x, x_1, \ldots, x_l) by an arithmetic formula:

There is a number t and a tuple

$$(y_0, y_1, \ldots, y_{k-1}, y_k, y_{k+1}, \ldots, y_{2k-1}, \ldots, y_{tk}, y_{tk+1}, \ldots, y_{tk+k-1})$$

such that:

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This is equivalent to: there are t, p, r with:

•
$$\beta(p, r, 0) = 1$$
, $\beta(p, r, 1) = 0$, ..., $\beta(p, r, k - 1) = 0$

• $\beta(p, r, tk) = x, \ \beta(p, r, tk+1) = x_1, \dots, \beta(p, r, tk+k-1) = x_l$

• for all $0 \le i \le t - 1$ the following holds:

$$\left(eta(p,r,ik),\ldots,eta(p,r,ik+k-1)
ight)
ightarrow_P$$

 $\left(eta(p,r,(i+1)k),\ldots,eta(p,r,(i+1)k+k-1)
ight)$

It is straightforward to construct an arithmetic formula for

$$(y, y_1, \ldots, y_l) \rightarrow_P (z, z_1, \ldots, z_l)$$

as a disjunction over all instructions A_i of the RMP P (excercise).

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Advanced Logic

Automatic structures

In this section we will introduce automatic structures.

Our main results concerning automatic structures are:

- Every automatic structure has a decidable theory.
- $(\mathbb{N}, +)$ is automatic.
- (\mathbb{Q}, \leq) is automatically presentable.

Convolution of words

Let $n \ge 1$, let Σ be a finite alphabet and let $\# \notin \Sigma$ be a dummy symbol. Let $\Sigma_{\#} = \Sigma \cup \{\#\}$ in the following.

For $n \ge 1$ we consider the alphabet $\Sigma_{\#}^n$ that contains all *n*-tuples over $\Sigma_{\#}$. For words $w_1, w_2 \dots, w_n \in \Sigma^*$ we define the convolution

$$w_1 \otimes w_2 \otimes \cdots \otimes w_n \in (\Sigma^n_{\#})^*$$

as follows:

• Let
$$w_i = a_{i,1}a_{i,2}\cdots a_{i,\ell_i}$$
, (thus, $\ell_i = |w_i|$).

• Let
$$\ell = \max\{\ell_1, \ldots, \ell_n\}.$$

- For all $1 \le i \le n$ and $\ell_i < j \le \ell$ let $a_{i,j} = #$.
- $\blacktriangleright w_1 \otimes w_2 \otimes \cdots \otimes w_n := (a_{1,1}, \ldots, a_{n,1})(a_{1,2}, \ldots, a_{n,2}) \cdots (a_{1,\ell}, \ldots, a_{n,\ell}).$

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Convolution of words

Using the convolution, we encode an *n*-tuple (w_1, w_2, \ldots, w_n) of words by the single word $w_1 \otimes w_2 \otimes \cdots \otimes w_n$.

Examples:

$$abba \otimes babaaa = (a, b)(b, a)(b, b)(a, a)(\#, a)(\#, a)$$

 $abcd \otimes bcdab \otimes a = (a, b, a)(b, c, \#)(c, d, \#)(d, a, \#)(\#, b, \#)$

Note: The tuple $(\#, \#, \dots, \#)$ does not appear in a convolution.

In particular: $\varepsilon \otimes \varepsilon \otimes \cdots \otimes \varepsilon = \varepsilon$ (multiple convolution of the empty word yields the empty word)

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A synchronous *n*-tape automaton A over the alphabet Σ is an arbitrary finite automaton over the alphabet $\Sigma_{\#}^{n}$.

Hence, A accepts a language $L(A) \subseteq (\Sigma_{\#}^{n})^{*}$.

Note: for an automaton A we denote the accepted language with L(A) whereas in the GTI lecture we used T(A).

The synchronous *n*-tape automaton accepts the *n*-ary relation

$$\mathcal{K}(\mathcal{A}) := \{ (w_1, \ldots, w_n) \mid w_1, \ldots, w_n \in \Sigma^*, w_1 \otimes \cdots \otimes w_n \in \mathcal{L}(\mathcal{A}) \}.$$

An *n*-ary relation R over Σ^* is synchronously rational if there is a synchronous *n*-tape automaton A with K(A) = R.

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Words in L(A) that do not belong to $\{w_1 \otimes \cdots \otimes w_n \mid w_1, \ldots, w_n \in \Sigma^*\}$ have no influence on the relation K(A) (they are garbage in some sense).

On the other hand, from A one can easily construct a synchronous *n*-tape automaton B with $L(B) = L(A) \cap \{w_1 \otimes \cdots \otimes w_n \mid w_1, \dots, w_n \in \Sigma^*\}$. **Note:** $\{w_1 \otimes \cdots \otimes w_n \mid w_1, \dots, w_n \in \Sigma^*\} \subseteq (\Sigma^n_{\#})^*$ is regular.

v	b_0	b_1	<i>b</i> ₂	 b_{m-1}	b _m	#	 #
и	a ₀	a ₁	a ₂	 a_{m-1}	a _m	a_{m+1}	 a _n

Words in L(A) that do not belong to $\{w_1 \otimes \cdots \otimes w_n \mid w_1, \ldots, w_n \in \Sigma^*\}$ have no influence on the relation K(A) (they are garbage in some sense).

On the other hand, from A one can easily construct a synchronous *n*-tape automaton B with $L(B) = L(A) \cap \{w_1 \otimes \cdots \otimes w_n \mid w_1, \ldots, w_n \in \Sigma^*\}$. **Note:** $\{w_1 \otimes \cdots \otimes w_n \mid w_1, \ldots, w_n \in \Sigma^*\} \subseteq (\Sigma^n_{\#})^*$ is regular.

	q_0						
v	<i>b</i> 0	b_1	<i>b</i> ₂	 b_{m-1}	b _m	#	 #
и	a ₀	a ₁	a ₂	 a_{m-1}	a _m	a_{m+1}	 a _n

Words in L(A) that do not belong to $\{w_1 \otimes \cdots \otimes w_n \mid w_1, \ldots, w_n \in \Sigma^*\}$ have no influence on the relation K(A) (they are garbage in some sense).

On the other hand, from A one can easily construct a synchronous *n*-tape automaton B with $L(B) = L(A) \cap \{w_1 \otimes \cdots \otimes w_n \mid w_1, \dots, w_n \in \Sigma^*\}$. **Note:** $\{w_1 \otimes \cdots \otimes w_n \mid w_1, \dots, w_n \in \Sigma^*\} \subseteq (\Sigma^n_{\#})^*$ is regular.

		q_1					
v	<i>b</i> 0	<i>b</i> 1	<i>b</i> ₂	 b_{m-1}	b _m	#	 #
и	a ₀	a ₁	a ₂	 a_{m-1}	a _m	a_{m+1}	 a _n

Words in L(A) that do not belong to $\{w_1 \otimes \cdots \otimes w_n \mid w_1, \ldots, w_n \in \Sigma^*\}$ have no influence on the relation K(A) (they are garbage in some sense).

On the other hand, from A one can easily construct a synchronous *n*-tape automaton B with $L(B) = L(A) \cap \{w_1 \otimes \cdots \otimes w_n \mid w_1, \dots, w_n \in \Sigma^*\}$. **Note:** $\{w_1 \otimes \cdots \otimes w_n \mid w_1, \dots, w_n \in \Sigma^*\} \subseteq (\Sigma^n_{\#})^*$ is regular.

			q 2				
v	<i>b</i> 0	b_1	<i>b</i> ₂	 b_{m-1}	b _m	#	 #
и	a ₀	a ₁	a ₂	 a _{m-1}	a _m	a_{m+1}	 a _n

Words in L(A) that do not belong to $\{w_1 \otimes \cdots \otimes w_n \mid w_1, \ldots, w_n \in \Sigma^*\}$ have no influence on the relation K(A) (they are garbage in some sense).

On the other hand, from A one can easily construct a synchronous *n*-tape automaton B with $L(B) = L(A) \cap \{w_1 \otimes \cdots \otimes w_n \mid w_1, \dots, w_n \in \Sigma^*\}$. **Note:** $\{w_1 \otimes \cdots \otimes w_n \mid w_1, \dots, w_n \in \Sigma^*\} \subseteq (\Sigma^n_{\#})^*$ is regular.

Illustration of a synchronous 2-tape automaton:

					q _m		
v	<i>b</i> 0	b_1	<i>b</i> ₂	 b_{m-1}	b _m	#	 #
и	a ₀	a ₁	a ₂	 a _{m-1}	a _m	a _{m+1}	 a _n

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Words in L(A) that do not belong to $\{w_1 \otimes \cdots \otimes w_n \mid w_1, \ldots, w_n \in \Sigma^*\}$ have no influence on the relation K(A) (they are garbage in some sense).

On the other hand, from A one can easily construct a synchronous *n*-tape automaton B with $L(B) = L(A) \cap \{w_1 \otimes \cdots \otimes w_n \mid w_1, \dots, w_n \in \Sigma^*\}$. **Note:** $\{w_1 \otimes \cdots \otimes w_n \mid w_1, \dots, w_n \in \Sigma^*\} \subseteq (\Sigma^n_{\#})^*$ is regular.

						q_{m+1}	
v	<i>b</i> 0	b_1	<i>b</i> ₂	 b_{m-1}	b _m	#	 #
и	a ₀	a ₁	a ₂	 a_{m-1}	a _m	a _{m+1}	 a _n

Words in L(A) that do not belong to $\{w_1 \otimes \cdots \otimes w_n \mid w_1, \ldots, w_n \in \Sigma^*\}$ have no influence on the relation K(A) (they are garbage in some sense).

On the other hand, from A one can easily construct a synchronous *n*-tape automaton B with $L(B) = L(A) \cap \{w_1 \otimes \cdots \otimes w_n \mid w_1, \dots, w_n \in \Sigma^*\}$. **Note:** $\{w_1 \otimes \cdots \otimes w_n \mid w_1, \dots, w_n \in \Sigma^*\} \subseteq (\Sigma^n_{\#})^*$ is regular.

							q_n
v	<i>b</i> 0	b_1	<i>b</i> ₂	 b_{m-1}	b _m	#	 #
и	a ₀	a ₁	a ₂	 a_{m-1}	a _m	a_{m+1}	 a _n

Example: Let *A* be the following synchronous 2-tape automaton:

$$(a, a), (b, b)$$
 $(\#, a), (\#, b)$
 $(\#, a), (\#, b)$ $(\#, b)$ $(\#,$

We have $K(A) = \{(u, v) \mid u, v \in \{a, b\}^*, \exists w \in \{a, b\}^* : v = uw\}$ (the prefix relation).

On the other hand, the suffix relation $\{(u, v) \mid \exists w \in \{a, b\}^* : v = wu\}$ is not synchronously rational.

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Automatic structures

Definition

A relational structure $\mathcal{A} = (A, R_1, \dots, R_m)$ (with R_i an n_i -ary relation) is automatic if there exist a finite alphabet Σ , a finite automaton B over the alphabet Σ , and synchronous n_i -tape automata B_i over the alphabet Σ $(1 \le i \le m)$ such that:

$$\blacktriangleright \ L(B) = A$$

•
$$K(B_i) = R_i$$
 for $1 \le i \le m$

Definition

A structure \mathcal{A} is automatically presentable if \mathcal{A} is isomorphic to an automatic structure.

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Automatic structures

Excursion: isomorphic structures

Let $\mathcal{A} = (A, R_1, \dots, R_m)$ and $\mathcal{B} = (B, P_1, \dots, P_m)$ be relational structures, where R_i and P_i are both n_i -ary (for all $1 \le i \le m$).

We say that A and B are isomorphic if there is a bijection $h: A \to B$ such that for all $1 \le i \le m$ and all tuples $(a_1, \ldots, a_{n_i}) \in A^{n_i}$ we have:

$$(a_1,\ldots,a_{n_i})\in R_i\iff (h(a_1),\ldots,h(a_{n_i}))\in P_i.$$

Intuitively: \mathcal{B} can be obtained from \mathcal{A} by renaming the elements from the universe of \mathcal{A} .

If \mathcal{A} and \mathcal{B} are isomorph then $\mathsf{Th}(\mathcal{A})$ is decidable if and only if $\mathsf{Th}(\mathcal{B})$ is decidable (predicate logic cannot refer to the names of elements in the universe).

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Theorem $(\mathbb{N}, +)$ with $+ = \{(a, b, c) \mid a + b = c\}$ is automatically presentable.

Proof: Let A be a finite automaton with $L(A) = \{0\} \cup \{0,1\}^*1$.

Then, the following function $h: L(A) \to \mathbb{N}$ is a bijection:

$$h(0) = 0$$

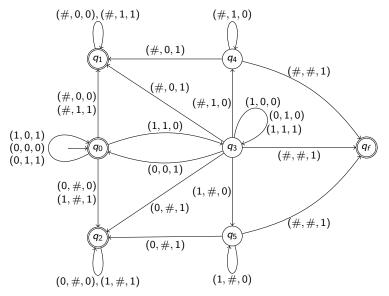
$$h(a_0a_1\cdots a_{n-1}1) = \sum_{i=0}^{n-1}a_i2^i + 2^n$$

Let B_+ be the synchronous 3-tape automaton from the next slide. B_+ "almost" recognizes the relation

$$\{(u, v, w) \in L(A)^3 \mid h(u) + h(v) = h(w)\}.$$

We have for instance $(00, 0000, 0000) \in \mathcal{K}(B_+)$.

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Let A_+ be a synchronous 3-tape automaton with

$$L(A_+) = L(B_+) \cap \{u \otimes v \otimes w \mid u, v, w \in L(A)\}.$$

We then get $K(A_+) = \{(u, v, w) \in L(A)^3 \mid h(u) + h(v) = h(w)\}.$

Intuition: The automaton from Slide 56 checks with the school method for addition whether the number on tape 3 is the sum of the numbers on tapes 1 and 2.

For this, the automaton stores the current carry in its state.

States q_0, q_1, q_2 correspond to carry 0 whereas states q_3, q_4, q_5 correspond to carry 1.

Three states are needed since the numbers on tapes 1 and 2 may have a different bit lengths.

States q_1, q_4 (q_2, q_5) are needed for the situation where the number on tape 1 (2) is shorter than the number on tape 2 (1).

State q_f is a failure state.

One can slightly extend the theorem on Slide 55: For every p > 1 the structure $(\mathbb{N}, +, |_p)$ with

$$x \mid_{p} y \iff \exists n, k \in \mathbb{N} : x = p^{n} \land y = k \cdot x$$

is automatically presentable.

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Linear orders

Our second example for an automatic structure is a linear order.

Recall (from the lecture DMI): a linear order is a structure (A, R), where R is a binary relation with the following properties:

►
$$\forall a \in A : (a, a) \in R$$
 (*R* is reflexive)

►
$$\forall a, b \in A : (a, b) \in R \land (b, a) \in R \rightarrow a = b$$
 (*R* is anti-symmetric)

▶
$$\forall a, b, c \in A : (a, b) \in R \land (b, c) \in R \rightarrow (a, c) \in R$$
 (*R* is transitive)

►
$$\forall a, b \in A : (a, b) \in R \lor (b, a) \in R$$
 (*R* is linear)

Instead of R we denote the binary relation of a linear order always with \leq (possibly with an index).

An element $a \in A$ is a smallest (resp., largest) element of the linear order (A, \leq) if: $\forall b \in A : a \leq b$ (resp., $\forall b \in A : b \leq a$).

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Linear orders

Theorem

The linear order (\mathbb{Q}, \leq) (where \leq is the standard order on \mathbb{Q}) is automatically presentable.

For the proof we use a famous theorem of Cantor.

It uses another property of linear orders (we write x < y for $x \le y \land x \ne y$): A linear order (A, \le) is dense if:

$$\forall x \forall y (x < y \rightarrow \exists z (x < z < y)).$$

Intuitively: between two different elements of A there is always a third element.

Cantor's theorem

Let (A, \leq_A) and (B, \leq_B) be countable dense linear orders without a smallest and largest element. Then (A, \leq_A) and (B, \leq_B) are isomorphic.

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Proof of Cantor's theorem:

We construct enumerations

 $a_1, a_2, a_3, a_4, \ldots$ and $b_1, b_2, b_3, b_4, \ldots$

with the following properties:

▶
$$a_i \neq a_j$$
 and $b_i \neq b_j$ for $i \neq j$
▶ $A = \{a_i \mid i \ge 1\}$ and $B = \{b_i \mid i \ge 1\}$
▶ $a_i < a_j$ if and only if $b_i < b_j$ for all i, j .
Then, $f : A \rightarrow B$ with $f(a_i) = b_i$ is an isomorphism.

Since A and B are countable and infinite, we can enumerate these sets:

$$A = \{x_1, x_2, x_3, \ldots\}$$
 and $B = \{y_1, y_2, y_3, \ldots\}$

The following "algorithm" constructs enumerations with the above properties:

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 $L_A := [x_1, x_2, x_3, \ldots]; \ L_B := [y_1, y_2, y_3, \ldots]$ $(a_1, \ldots, a_{i-1}, b_1, \ldots, b_{i-1} \text{ are already defined})$ for all i > 1 do if *i* is odd then let x be the first element from L_{Δ} remove x from the list L_A let y be an element from L_B with the following properties: $\forall 1 \leq j \leq i-1 : a_i < x \longleftrightarrow b_i < y$ (\dagger) remove y from the list L_B $a_i := x: b_i := v$ else let y be the first element from L_B remove y from the list L_{B} let x be an element from L_A with the following properties: $\forall 1 \leq j \leq i-1 : a_i < x \longleftrightarrow b_i < y$ (1)remove x from the list L_A $a_i := x; b_i := v$

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Remarks:

► The element y with the property (†) exists, since (B, ≤_B) is dense and neither has a smallest nor largest element.

This ensures that we find for x an element y that has the same position relative to b_1, \ldots, b_{i-1} as x to a_1, \ldots, a_{i-1} .

For the same reason, the element x with the property (\ddagger) exists.

Since the correspondence a_i → b_i must be bijective, we have to pair every element from the list L_A with exactly one element from the list L_B. Thereby, we also have to ensure that every element from the list L_B is paired.

This will be enforced by the case distinction between i odd and i even.

Illustration of the proof of Cantor's theorem:

Illustration of the proof of Cantor's theorem:

$$L_{A} := [x_{1}, x_{2}, x_{3}, x_{4}, x_{5}, x_{6}, x_{7}, \ldots]; \ L_{B} := [y_{1}, y_{2}, y_{3}, y_{4}, y_{5}, y_{6}, y_{7}, \ldots]$$

Illustration of the proof of Cantor's theorem:

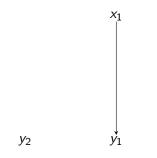
$$L_{\mathcal{A}} := [x_1, x_2, x_3, x_4, x_5, x_6, x_7, \ldots]; \ L_{\mathcal{B}} := [y_1, y_2, y_3, y_4, y_5, y_6, y_7, \ldots]$$

 x_1

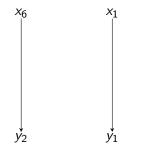
$$L_{A} := [x_{1}, x_{2}, x_{3}, x_{4}, x_{5}, x_{6}, x_{7}, \ldots]; \ L_{B} := [y_{1}, y_{2}, y_{3}, y_{4}, y_{5}, y_{6}, y_{7}, \ldots]$$



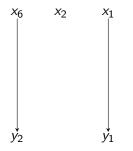
$$L_{A} := [x_{1}, x_{2}, x_{3}, x_{4}, x_{5}, x_{6}, x_{7}, \ldots]; \ L_{B} := [y_{1}, y_{2}, y_{3}, y_{4}, y_{5}, y_{6}, y_{7}, \ldots]$$



$$L_{A} := [x_{1}, x_{2}, x_{3}, x_{4}, x_{5}, x_{6}, x_{7}, \ldots]; \ L_{B} := [y_{1}, y_{2}, y_{3}, y_{4}, y_{5}, y_{6}, y_{7}, \ldots]$$



$$L_{A} := [x_{1}, x_{2}, x_{3}, x_{4}, x_{5}, x_{6}, x_{7}, \ldots]; \ L_{B} := [y_{1}, y_{2}, y_{3}, y_{4}, y_{5}, y_{6}, y_{7}, \ldots]$$



$$L_{A} := [x_{1}, x_{2}, x_{3}, x_{4}, x_{5}, x_{6}, x_{7}, \ldots]; \ L_{B} := [y_{1}, y_{2}, y_{3}, y_{4}, y_{5}, y_{6}, y_{7}, \ldots]$$

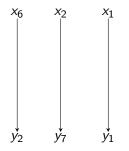
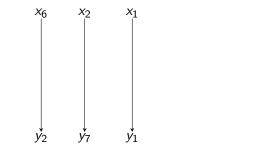


Illustration of the proof of Cantor's theorem:

$$L_{A} := [x_{1}, x_{2}, x_{3}, x_{4}, x_{5}, x_{6}, x_{7}, \ldots]; \ L_{B} := [y_{1}, y_{2}, y_{3}, y_{4}, y_{5}, y_{6}, y_{7}, \ldots]$$



*Y*3

Illustration of the proof of Cantor's theorem:

 $L_{A} := [x_{1}, x_{2}, x_{3}, x_{4}, x_{5}, x_{6}, x_{7}, \ldots]; \ L_{B} := [y_{1}, y_{2}, y_{3}, y_{4}, y_{5}, y_{6}, y_{7}, \ldots]$

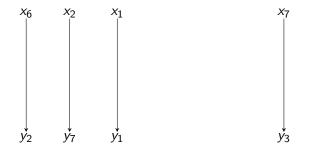


Illustration of the proof of Cantor's theorem:

 $L_{A} := [x_{1}, x_{2}, x_{3}, x_{4}, x_{5}, x_{6}, x_{7}, \ldots]; \ L_{B} := [y_{1}, y_{2}, y_{3}, y_{4}, y_{5}, y_{6}, y_{7}, \ldots]$

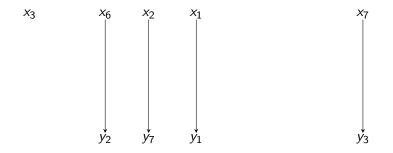
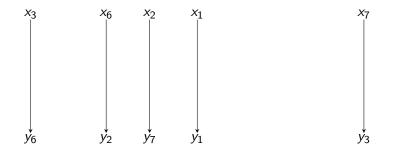


Illustration of the proof of Cantor's theorem:

 $L_{A} := [x_{1}, x_{2}, x_{3}, x_{4}, x_{5}, x_{6}, x_{7}, \ldots]; \ L_{B} := [y_{1}, y_{2}, y_{3}, y_{4}, y_{5}, y_{6}, y_{7}, \ldots]$



(\mathbb{Q},\leq) is automatically presentable

Proof that (\mathbb{Q}, \leq) is automatic:

Due to Cantor's theorem, it suffices to construct a countable dense automatic linear order which neither has a smallest nor a largest element.

Let $L = \{0, 1\}^* 1$.

Let \leq be the lexicographic order on *L*. That means, for $x, y \in L$ we have $x \leq y$ if and only if one of the following cases holds:

- There exists $u \in \{0,1\}^*$ with y = xu (x is a prefix of y)
- There exist $z, u, v \in \{0, 1\}^*$ with x = z0u and y = z1v.

Then (L, \leq) is a linear order (easy to check).

• (L, \leq) has no largest element:

Let $x \in L$ be arbitrary. Then $x < x1 \in L$.

(\mathbb{Q},\leq) is automatically presentable

- (L, \leq) has no smallest element: Let $x = u1 \in L$ be arbitrary. Then u01 < u1 = x
- ► (*L*, ≤) is dense:

Let $x, y \in L$ with x < y be arbitrary.

Case 1: x = u1, y = u1v1:

Then we have $x = u1 < u10^{|v|+1}1 < u1v1 = y$.

Case 2: x = u0v1, y = u1w:

Then we have $x = u0v1 < u01^{|v|+2} < u1w = y$.

Structures that are not automatically presentable

For the following structures one can show that they are not automatically presentable:

- $(\mathbb{R}, +)$ (because every automatic structure is countable)
- every structure with an undecidable theory (see next slide). Examples for this:
 - ($\mathbb{N}, +, \cdot$) (Gödel's theorem)
 - ▶ (Σ^*, \circ) (the free monoid over Σ) for $|\Sigma| > 1$ (Quine 1946)
- ▶ (\mathbb{N}, \cdot) and ($\mathbb{N}, |$)
- ▶ (ℚ, +) (Tsankov 2009)

Our main result on automatic structures is:

Theorem (Khoussainov, Nerode 1994) For every automatically presentable structure A, Th(A) is decidable.

Corollary (Presburger 1929) Th $(\mathbb{N}, +)$ is decidable.

Corollary $\mathsf{Th}(\mathbb{Q}, \leq)$ is decidable.

For the proof of the theorem of Khoussainov and Nerode we need some facts on regular languages.

From GTI we know that the regular languages are closed under all boolean operations (complement, union, intersection).

Moreover: From finite automata A and B over an input alphabet Γ one can construct finite automata for the languages $\Gamma^* \setminus L(A)$, $L(A) \cap L(B)$ and $L(A) \cup L(B)$.

We need two further closure properties for the regular languages.

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A homomorphism is a function $h: \Gamma^* \to \Sigma^*$ such that:

- Γ and Σ are finite alphabets.
- $h(\varepsilon) = \varepsilon$ (the empty word is mapped to the empty word)
- For all words $u, v \in \Gamma^*$ we have h(uv) = h(u)h(v).

In particular, for every word $u = a_1 a_2 \cdots a_n \ (a_1, \dots, a_n \in \Gamma)$:

$$h(a_1a_2\cdots a_n)=h(a_1)h(a_2)\cdots h(a_n).$$

In order to specify a homomorphism $h: \Gamma^* \to \Sigma^*$, it suffices to specify all words h(a) for $a \in \Gamma$.

Example: Let $h : \{a, b\}^* \to \{b, c\}^*$ be the homomorphism with h(a) = bcc and h(b) = cbc.

Then we have h(abba) = bcc cbc bcc.

Lemma (closure regular languages under homomorphisms) From a finite automaton A with input alphabet Γ and a homomorphism $h: \Gamma^* \to \Sigma^*$ one can construct a finite automaton B with

$$L(B) = h(L(A)) = \{h(w) \mid w \in L(A)\}.$$

Proof: Every transition $p \xrightarrow{a} q$ in the automaton A with $a \in \Gamma$ and $h(a) = b_1 b_2 \cdots b_n$ $(b_1, \ldots, b_n \in \Sigma)$ is replaced by the sequence of transitions

$$p \xrightarrow{b_1} r_1 \xrightarrow{b_2} r_2 \cdots \xrightarrow{b_{n-1}} r_{n-1} \xrightarrow{b_n} q.$$

Here, r_1, \ldots, r_{n-1} are new states that do not appear in other transitions. For all $v \in \Sigma^*$ we have:

$$v \in L(B) \iff \exists w \in L(A) : v = h(w) \iff v \in h(L(A)).$$

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But: What happens when if n = 0 and hence $h(a) = \varepsilon$ holds?

Then we replace the transition $p \xrightarrow{a} q$ by the ε -transition $p \xrightarrow{\varepsilon} q$.

 ε -transitions do not increase the power of finite automata:

From a finite automaton with ε -transitions one can construct an equivalent finite automaton without ε -transitions.

See e.g. slides 72 & 73 from the GTI lecture in summer semester 2020 (https://www.eti.uni-siegen.de/ti/lehre/ss20/gti/folien.pdf) or slides 31 & 32 from the Compiler Construction lecture in summer semester 2020 (https://www.eti.uni-siegen.de/ti/lehre/ss20/compilerbau/cb.pdf).

Lemma (closure regular languages under inverse homomorphisms) From a finite automaton B over the input alphabet Σ and a homomorphism $h: \Gamma^* \to \Sigma^*$ one can construct a finite automaton A with

$$L(A) = h^{-1}(L(B)) = \{ w \in \Gamma^* \mid h(w) \in L(B) \}.$$

Proof: The automaton A has the same set of states and the same initial/final states as B.

In the automaton A there is a transition $p \xrightarrow{a} q$ if and only if in the automaton B one can go with the word $h(a) \in \Sigma^*$ from state p to state q. For all $w \in \Gamma^*$ we have:

$$w \in L(A) \iff h(w) \in L(B) \iff w \in h^{-1}(L(B)).$$

Now we come to the

Proof of the theorem of Khoussainov and Nerode:

Let $\mathcal{A} = (L, R_1, \dots, R_m)$ be an automatic structure with $L \subseteq \Sigma^*$.

For every formula F which contains only free variables from $\{x_1, \ldots, x_n\}$ (not all variables x_1, \ldots, x_n have to be free in F) we construct by induction on the structure of F a synchronous *n*-tape automaton B_F such that

$$\mathcal{K}(\mathcal{B}_{\mathcal{F}}) = \{ (w_1, \ldots, w_n) \in \mathcal{L}^n \mid \mathcal{A}_{[x_1/w_1]\cdots [x_n/w_n]} \models \mathcal{F} \}.$$

Case 1: $F = R_i(x_{i_1}, \ldots, x_{i_k})$, where $1 \le i_1, \ldots, i_k \le n$: Define the homomorphism $f : (\Sigma_{\#}^n)^* \to (\Sigma_{\#}^k)^*$ as follows, where $a_1, \ldots, a_n \in \Sigma_{\#}$:

$$f(a_1,\ldots,a_n) = \begin{cases} \varepsilon & \text{if } a_{i_1} = \cdots = a_{i_k} = \#\\ (a_{i_1},\ldots,a_{i_k}) & \text{otherwise} \end{cases}$$

Note: $f(w_1 \otimes \cdots \otimes w_n) = w_{i_1} \otimes \cdots \otimes w_{i_k}$ for all $w_1, \ldots, w_n \in \Sigma^*$. Let B_i be the synchronous k-tape automaton for R_i .

From B_i we construct, using the lemma from slide 73, an *n*-tape automaton B_F with

$$L(B_F) = f^{-1}(L(B_i)) \cap \{w_1 \otimes \cdots \otimes w_n \mid w_1, \ldots, w_n \in L\}.$$

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We have for all $w_1, \ldots, w_n \in \Sigma^*$:

$$(w_{1}, \ldots, w_{n}) \in K(B_{F})$$

$$\iff w_{1} \otimes \cdots \otimes w_{n} \in L(B_{F})$$

$$\iff (w_{1}, \ldots, w_{n}) \in L^{n} \text{ and } w_{1} \otimes \cdots \otimes w_{n} \in f^{-1}(L(B_{i}))$$

$$\iff (w_{1}, \ldots, w_{n}) \in L^{n} \text{ and } f(w_{1} \otimes \cdots \otimes w_{n}) \in L(B_{i})$$

$$\iff (w_{1}, \ldots, w_{n}) \in L^{n} \text{ and } w_{i_{1}} \otimes \cdots \otimes w_{i_{k}} \in L(B_{i})$$

$$\iff (w_{1}, \ldots, w_{n}) \in L^{n} \text{ and } (w_{i_{1}}, \ldots, w_{i_{k}}) \in K(B_{i})$$

$$\iff (w_{1}, \ldots, w_{n}) \in L^{n} \text{ and } (w_{i_{1}}, \ldots, w_{i_{k}}) \in R_{i}^{\mathcal{A}}$$

$$\iff (w_{1}, \ldots, w_{n}) \in L^{n} \text{ and } \mathcal{A}_{[x_{1}/w_{1}]\cdots[x_{n}/w_{n}]} \models R_{i}(x_{i_{1}}, \ldots, x_{i_{k}})$$

Case 2: $F = (x_i = x_j)$, where $1 \le i, j \le n$:

Analogously to Case 1, since $\{(v, v) \mid v \in L\}$ is synchronously rational.

Case 3: $F = \neg G$:

By induction hypothesis there exists an *n*-tape automaton B_G for G. We construct B_F such that:

$$L(B_F) = \{w_1 \otimes \cdots \otimes w_n \mid w_1, \ldots, w_n \in L\} \setminus L(B_G)$$

Case 4: $F = G \lor H$, where F contains only free variables from x_1, \ldots, x_n :

By the induction hypothesis there exist *n*-tape automata B_G and B_H for G and H, respectively.

We construct B_F such that $L(B_F) = L(B_G) \cup L(B_H)$.

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Case 5: $F = \exists x_{n+1} : G(x_1, \dots, x_n, x_{n+1})$:

By the induction hypothesis there exists an (n + 1)-tape automaton B_G for G.

Define the homomorphism $f: (\Sigma_{\#}^{n+1})^* \to (\Sigma_{\#}^n)^*$ as follows, where $a_1, \ldots, a_n, a_{n+1} \in \Sigma_{\#}$:

$$f(a_1, \dots, a_n, a_{n+1}) = \begin{cases} \varepsilon & \text{if } a_1 = \dots = a_n = \# \\ (a_1, \dots, a_n) & \text{otherwise} \end{cases}$$

Note: $f(w_1 \otimes \cdots \otimes w_n \otimes w_{n+1}) = w_1 \otimes \cdots \otimes w_n$ for all $w_1, \ldots, w_{n+1} \in \Sigma^*$. We then construct for B_F an *n*-tape automaton with $L(B_F) = f(L(B_G))$ By the lemma from slide 71 we can construct such an automaton B_F .

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We have for all $w_1, \ldots, w_n \in \Sigma^*$:

$$(w_1, \ldots, w_n) \in K(B_F)$$

$$\iff w_1 \otimes \cdots \otimes w_n \in L(B_F)$$

$$\iff w_1 \otimes \cdots \otimes w_n \in f(L(B_G))$$

$$\iff \exists w_{n+1} : w_1 \otimes \cdots \otimes w_n \otimes w_{n+1} \in L(B_G)$$

$$\iff \exists w_{n+1} : (w_1, \ldots, w_n, w_{n+1}) \in K(B_G)$$

$$\iff \exists w_{n+1} : (w_1, \ldots, w_n, w_{n+1}) \in L^{n+1} \text{ and } \mathcal{A}_{[x_1/w_1] \cdots [x_{n+1}/w_{n+1}]} \models G$$

$$\iff (w_1, \ldots, w_n) \in L^n \text{ and } \exists w_{n+1} \in L : \mathcal{A}_{[x_1/w_1] \cdots [x_{n+1}/w_{n+1}]} \models G$$

$$\iff (w_1, \ldots, w_n) \in L^n \text{ and } \mathcal{A}_{[x_1/w_1] \cdots [x_n/w_n]} \models F$$

This completes the construction of B_F .

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Assume now that F is a sentence (no free variables).

W.l.o.g. we can assume that F has the form $F = \exists x G(x)$ (we can always add a dummy \exists -quantifier).

We then have: $\mathcal{A} \models F \iff \mathcal{L}(\mathcal{B}_{\mathcal{G}}) \neq \emptyset$.

We can decide $L(B_G) \neq \emptyset$: the emptiness problem for finite automtata is decidable.

Remarks on the complexity: Our algorithm for checking $F \in Th(A)$ is not very efficient.

Reason: For every negation \neg we construct an automaton for the complement of the language of a previously constructed automaton. This increases the automaton size exponentially (power set construction)!

The running time of our algorithm is roughly $f_{|F|}(O(1))$, where $f_0(n) = n$ and $f_{i+1}(n) = 2^{f_i(n)}$ for $i \ge 0$ and |F| = length of the formula F.

This is not avoidable:

Let
$$T_2 = (\{0,1\}^*, S_0, S_1, \leq)$$
 where:

▶
$$S_0 = \{(w, w0) \mid w \in \{0, 1\}^*\}$$

•
$$S_1 = \{(w, w1) \mid w \in \{0, 1\}^*\}$$

▶
$$\leq = \{(w, wu) \mid w, u \in \{0, 1\}^*\}$$

Note: T_2 is an automatic structure.

Meyer 1974

There do not exist an $i \in \mathbb{N}$ and an algorithm that correctly decides $Th(T_2)$ and whose running time is bounded by $f_i(n)$ (for an input formula of length n).

One also says: there is no elementary algorithm for $Th(T_2)$.

But for many particular automatic structures one can come up with an elementary algorithm for the theory, for instance:

Oppen 1978

There is an algorithm that decides $Th(\mathbb{N},+)$ in time $2^{2^{2^{O(n)}}}$.

Oppen's algorithm uses the technique of quantifier elimination, which we will apply in the next section for another structure.

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We want to prove the following famous theorem of Alfred Tarski:

Satz (Tarski 1948)

 $\mathsf{Th}(\mathbb{R},+,\cdot)$ is decidable.

Note: $(\mathbb{R}, +, \cdot)$ is not an automatic structure, since \mathbb{R} is uncountable. The proof of Tarski's theorem is quite long.

First, we extend the structure $(\mathbb{R},+,\cdot)$ to $(\mathbb{R},+,\cdot,<,0,1,-1)$.

Note: If $\mathsf{Th}(\mathbb{R},+,\cdot,<,0,1,-1)$ is decidable then also $\mathsf{Th}(\mathbb{R},+,\cdot)$ is decidable.

In fact, also the reverse implication can be shown but this is not important for us.

We will show that $\mathsf{Th}(\mathbb{R},+,\cdot,<,0,1,-1)$ is decidable.

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In the following, we will simply write \mathbb{R} for $(\mathbb{R}, +, \cdot, <, 0, 1, -1)$. For our decidability proof we will apply the method of quantifier elimination:

Let *F* be a formula with the free variables y_0, \ldots, y_n .

We construct a quantifier-free formula F' (that means, neither \exists nor \forall occurs in F') with the free variables y_0, \ldots, y_n such that

$$\forall a_0, \dots, a_n \in \mathbb{R} : \mathbb{R}_{[y_0/a_0, \dots, y_n/a_n]} \models F \iff \mathbb{R}_{[y_0/a_0, \dots, y_n/a_n]} \models F'$$

We do this by induction over the structure of the formula F.

Since $\forall xG \equiv \neg \exists x \neg G$, the only difficult case is where *F* has the form $F = \exists x G$.

By induction, we can assume that G is already quantifier-free.

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Example: Let $F = \exists x : y = x \cdot x$.

The formula F expressed that y is a square.

A real number is a square if and only if it is not negative.

Hence, for every real number $a \in \mathbb{R}$ we have:

$$\mathbb{R}_{[y/a]} \models \exists x : y = x \cdot x \iff \mathbb{R}_{[y/a]} \models (y = 0 \lor 0 < y)$$

Thus, $F' = (y = 0 \lor 0 < y)$ is the desired quantifier-free formula.

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Assume for a moment that we have already proved the quantifier elimination property.

Let F be a sentence (formula without free variables).

We want to check whether $\mathbb{R} \models F$ holds.

We apply quantifier elimination to F and construct a quantifier-free sentence F' such that:

$$\mathbb{R}\models F\quad\Longleftrightarrow\quad \mathbb{R}\models F'.$$

Since F' is quantifier-free, we can easily check whether $\mathbb{R} \models F'$ holds:

- F' is a boolean combination of formulas a = b and a < b.
- ► Here, a and b are terms that are constructed from the constants 0,1,-1 using the operations · and +.
- We can evaluate these terms *a* and *b* in \mathbb{R} and then check whether a = b, resp. a < b, holds.

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Back to quantifier elimination for $F = \exists x G$ with G quantifier-free.

Let the free variables of G be x, y_0, \ldots, y_n ; then the free variables of F are y_0, \ldots, y_n .

For variables x_1, \ldots, x_n let $\mathbb{Z}[x_1, \ldots, x_n]$ denote the set of all polynomials in the variables x_1, \ldots, x_n with coefficients from \mathbb{Z} .

Example:
$$-3x_1^4x_2^2x_3 + 7x_1x_2^6x_3^8 - 8x_2^4x_3 + 12x_1 - 17$$

Atomic subformulas of G are of the form s = t and s < t, where s and t are terms that are constructed with + and \cdot from variables (x, y_0, \ldots, y_n) and the constants -1, 0, 1.

Such terms s and t can be evaluated to polynomials from $\mathbb{Z}[x, y_0, \dots, y_n]$.

In the following, we assume that $s, t \in \mathbb{Z}[x, y_0, \dots, y_n]$.

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Finally, we can bring G into the following form:

$$G = s(x, y_0, \dots, y_n) = 0 \land \bigwedge_{i=1}^m t_i(x, y_0, \dots, y_n) > 0,$$
 (2)

where $s, t_1, \ldots, t_m \in \mathbb{Z}[x, y_0, \ldots, y_n]$.

First we eliminate all negations in G using the following equivalences:

$$s_1 = s_2 \iff s_1 - s_2 = 0$$

$$s_1 < s_2 \iff s_2 - s_1 > 0$$

$$\neg (s = 0) \iff (s > 0 \lor -s > 0)$$

$$\neg (s > 0) \iff (s = 0 \lor -s > 0)$$

Then we bring G into disjunctive normal form (thereby we do not introduce new negations).

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Conjunctions of the form $\bigwedge_{i=1}^{k} s_i = 0$ can be replaced by a single equation using the following equivalence:

$$\bigwedge_{i=1}^k s_i = 0 \iff \sum_{i=1}^k s_i^2 = 0$$

Then we pull out the outermost disjunction using the following equivalence:

$$\exists x \big(\bigvee_{i=1}^k G_i\big) \equiv \bigvee_{i=1}^k \exists x \ G_i$$

Every formula $\exists x \ G_i$ has the desired form (2), and it suffices to apply quantifier elimination for each formula $\exists x \ G_i$.

We finally make a simple syntactic simplification.

Every polynomial $s, t_1, \ldots, t_m \in \mathbb{Z}[x, y_0, \ldots, y_n]$ in (2) can be uniquely written as a sum



with $0 \leq a_0 < a_1 < \cdots < a_d$ and $p_0, \ldots, p_d \in \mathbb{Z}[y_0, \ldots, y_n]$.

Example:

$$7 - 4y_0y_1^2y_3^4 + x^2 + y_1^5y_3x + 6y_0y_1^2y_3^4 - 2y_0^2y_1y_3^3x + 17y_0^3x^2$$

= $(7 - 4y_0y_1^2y_3^4 + 6y_0y_1^2y_3^4) + (y_1^5y_3 - 2y_0^2y_1y_3^3) \cdot x + (17y_0^3 + 1) \cdot x^2$

We can now replace every coefficient polynomial p_i by a new coefficient variable z_i , which appears in the formula only once.

After transforming the resulting formula into a quantifier-free formula, we can replace each of the new coefficient variables z_i by the original polynomial p_i .

Example: a possible formula $F = \exists x G$ that one might obtain in this way is

$$\exists x: z_0 + z_1 x^2 + z_2 x^3 = 0 \land z_3 x + z_4 x^2 > 0 \land z_5 + z_6 x^3 > 0.$$

In the following, let z_0, \ldots, z_n be all coefficient variables in the formula G.

Recall that we want to construct a quantifier-free formula F' with:

$$\forall a_0, \dots, a_n \in \mathbb{R} : \mathbb{R}_{[z_0/a_0, \dots, z_n/a_n]} \models F \iff \mathbb{R}_{[z_0/a_0, \dots, z_n/a_n]} \models F'$$

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We show that it suffices to assume that F' satisfies the above equivalence only for all $a_0, \ldots, a_n \in \mathbb{R} \setminus \{0\}$.

For a subset $I \subseteq \{0, ..., n\}$ let G_I be the formula that is obtained from G by replacing for every $i \in I$ the variable z_i (and hence the term $z_i x^a$) by the constant 0.

Example: For our formula

$$G = (z_0 + z_1 x^2 + z_2 x^3 = 0 \land z_3 x + z_4 x^2 > 0 \land z_5 + z_6 x^3 > 0)$$

and $I = \{1, 3, 5\}$ we get

$$G_I = (z_0 + z_2 x^3 = 0 \land z_4 x^2 > 0 \land z_6 x^3 > 0).$$

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We then replace the formula $\exists x \ G$ by the formula

$$\bigwedge_{I\subseteq\{0,\ldots,n\}}\bigg(\bigwedge_{i\in I}z_i=0\land\bigwedge_{i\notin I}z_i\neq 0 \ \to \ \exists x\ G_I\bigg).$$

Here, the outer conjunction runs over all subsets $I \subseteq \{0, \ldots, n\}$.

Assume we have constructed for every formula $F_I := \exists x \ G_I$ a quantifier-free formula F'_I with:

$$\forall a_0, \dots, a_n \in \mathbb{R} \setminus \{0\} : \mathbb{R}_{[z_0/a_0, \dots, z_n/a_n]} \models F_I \iff \mathbb{R}_{[z_0/a_0, \dots, z_n/a_n]} \models F'_I.$$

Then, for all $a_0, \dots, a_n \in \mathbb{R}$ the following statements are equivalent:

$$\mathbb{R}_{[z_0/a_0,...,z_n/a_n]} \models \exists x G$$

$$\mathbb{R}_{[z_0/a_0,...,z_n/a_n]} \models \bigwedge_{I \subseteq \{0,...,n\}} \left(\bigwedge_{i \in I} z_i = 0 \land \bigwedge_{i \notin I} z_i \neq 0 \rightarrow \exists x G_I \right)$$

$$\mathbb{R}_{[z_0/a_0,...,z_n/a_n]} \models \bigwedge_{I \subseteq \{0,...,n\}} \left(\bigwedge_{i \in I} z_i = 0 \land \bigwedge_{i \notin I} z_i \neq 0 \rightarrow F_I' \right)$$

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Remaining goal: For a formula $F = \exists x : s = 0 \land \bigwedge_{i=1}^{m} t_i > 0$ we have to construct a quantifier-free formula F' such that:

$$\forall a_0, \ldots, a_n \in \mathbb{R} \setminus \{0\} : \mathbb{R}_{[z_0/a_0, \ldots, z_n/a_n]} \models F \iff \mathbb{R}_{[z_0/a_0, \ldots, z_n/a_n]} \models F'.$$

Here, s, t_1, \ldots, t_m are polynomials in the variables x, and the coefficients are parameters z_0, \ldots, z_n that only take values $\neq 0$. Every parameter z_i appears in F only once.

Moreover, we can assume that:

- ▶ $t_i \neq 0$ for all $1 \leq i \leq m$ and
- s = 0 or x appears in s.

For this note that:

- ▶ If e.g. $t_1 = 0$ (the zero polynomial), then *F* is always wrong (we can therefore output the quantifier-free formula 0 = 1).
- If $s \neq 0$ and x does not appear in s, then, again, F is always wrong.

We distinguish three cases:

- Case 1: x appears in s and m = 1.
- Case 2: x appears in s and m > 1

Case 3: s = 0.

Case 1: $G = (s = 0 \land t > 0)$, where x appears in the polynomial s.

Notation: For $k \ge 0$ let (#x : G) = k be a new formula with the following semantics:

For all $a_0, \ldots, a_n \in \mathbb{R} \setminus \{0\}$: $\mathbb{R}_{[z_0/a_0, \ldots, z_n/a_n]} \models (\#x : G) = k$ if and only if

$$|\{a \in \mathbb{R} \mid \mathbb{R}_{[x/a, z_0/a_0, \dots, z_n/a_n]} \models G\}| = k.$$

Strictly speaking, we extend here predicate logic by a new construct (the so-called counting quantifier #).

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Intuition: (#x : G) = k expresses that exactly k many x have the property G (i.e., $s = 0 \land t > 0$).

Note: if $d \ge 1$ is the x-degree of s (the largest number a such that x^a appears in s), then $\exists x G$ is equivalent in \mathbb{R} to

$$(\#x:G)=1\lor(\#x:G)=2\lor\cdots\lor(\#x:G)=d,$$

because a polynomial p(x) of degree d has at most d roots.

New goal: Find a quantifier-free formula which is equivalent to (#x : G) = k in \mathbb{R} .

For this we need some tools: polynomial division, Euclid's algorithm, Sturm sequences, formal derivates.

For $\overline{a} = (a_1, \dots, a_n) \in (\mathbb{R} \setminus \{0\})^n$ let $Var(\overline{a}) = |\{i < n \mid a_i a_{i+1} < 0\}|$. (number of sign flips).

For $\overline{a} \in \mathbb{R}^n$ let $Var(\overline{a}) = Var(\overline{b})$, where \overline{b} results from \overline{a} by removing all zeros.

Example: Var(0, 2, 4, 0, -3, 0, 0, 2, 5) = Var(2, 4, -3, 2, 5) = 2. (the red commas mark the sign flips)

For $\overline{f} = (f_1, \ldots, f_n) \in (\mathbb{R}[x])^n$ (an *n*-tuple of polynomials in the variables x) and $a \in \mathbb{R}$ let $\operatorname{Var}_a(\overline{f}) = \operatorname{Var}(f_1(a), \ldots, f_n(a)).$

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Recall from DMI: polynomial division with remainder

For polynomials $f, g \in \mathbb{R}[x]$ with $g \neq 0$ there exist unique polynomials $q, r \in \mathbb{R}[x]$ with

•
$$\deg(r) < \deg(g)$$
 or $r = 0$ and

•
$$f = q \cdot g + r$$
.

By replacing the remainder polynomial r by -r, we obtain $f = q \cdot g - r$.

Note: If deg(g) = 0, i.e., $g \in \mathbb{R} \setminus \{0\}$, then r = 0 holds.

$$(x^{5} + x) : (2x^{2} + 1) = \frac{1}{2}x^{3}$$
$$-(x^{5} + \frac{1}{2}x^{3})$$

$$(x^{5} + x) : (2x^{2} + 1) = \frac{1}{2}x^{3}$$
$$-\frac{(x^{5} + \frac{1}{2}x^{3})}{(-\frac{1}{2}x^{3} + x)}$$

$$(x^{5} + x) : (2x^{2} + 1) = \frac{1}{2}x^{3} - \frac{1}{4}x^{3}$$
$$-\frac{(x^{5} + \frac{1}{2}x^{3})}{(-\frac{1}{2}x^{3} + x)}$$
$$-(-\frac{1}{2}x^{3} - \frac{1}{4}x)$$

$$(x^{5} + x) : (2x^{2} + 1) = \frac{1}{2}x^{3} - \frac{1}{4}x^{3}$$
$$-\frac{(x^{5} + \frac{1}{2}x^{3})}{(-\frac{1}{2}x^{3} + x)}$$
$$-\frac{(-\frac{1}{2}x^{3} - \frac{1}{4}x)}{\frac{5}{4}x}$$
 (remainder)

Example: We divide $(x^5 + x)$ by $(2x^2 + 1)$:

$$(x^{5} + x) : (2x^{2} + 1) = \frac{1}{2}x^{3} - \frac{1}{4}x$$
$$-\frac{(x^{5} + \frac{1}{2}x^{3})}{(-\frac{1}{2}x^{3} + x)}$$
$$-\frac{(-\frac{1}{2}x^{3} - \frac{1}{4}x)}{\frac{5}{4}x} \text{ (remainder)}$$

We get:

$$(x^{5}+x) = (2x^{2}+1) \cdot (\frac{1}{2}x^{3}-\frac{1}{4}x) + \frac{5}{4}x = (2x^{2}+1) \cdot (\frac{1}{2}x^{3}-\frac{1}{4}x) - (-\frac{5}{4}x).$$

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Euclid's algorithm for polynomials:

Let $f, g \in \mathbb{R}[x] \setminus \{0\}$ be non-zero polynomials.

Define the polynomials $h_0(x), \ldots, h_n(x) \in \mathbb{R}[x] \setminus \{0\}$ uniquely by:

$$\begin{split} h_0(x) &= f(x) \\ h_1(x) &= g(x) \\ h_0(x) &= q_1(x)h_1(x) - h_2(x) & \deg(h_2) < \deg(h_1) \\ h_1(x) &= q_2(x)h_2(x) - h_3(x) & \deg(h_3) < \deg(h_2) \\ \vdots & \vdots & \vdots \\ h_{n-2}(x) &= q_{n-1}(x)h_{n-1}(x) - h_n(x) & \deg(h_n) < \deg(h_{n-1}) \\ h_{n-1}(x) &= q_n(x)h_n(x) \end{split}$$

 h_{i+2} = division remainder if we divide h_i by h_{i+1} .

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Remarks:

- Since deg(h_{i+1}) < deg(h_i) for all 1 ≤ i ≤ n, the division remainder must be finally 0.
- $h_n(x) = \gcd(f, g)$ (greatest common divisor of f and g)
- For all $0 \le i \le n$, the polynom $h_n(x)$ divides $h_i(x)$.

We define $[f,g] = (h_0(x), h_1(x), \dots, h_n(x))$ as the Sturm sequence of f and g.

The reduced Sturm sequence of f and g is

$$\left(\frac{h_0(x)}{h_n(x)}, \frac{h_1(x)}{h_n(x)}, \dots, \frac{h_{n-1}(x)}{h_n(x)}, \frac{h_n(x)}{h_n(x)}\right) = \left(\frac{h_0(x)}{h_n(x)}, \frac{h_1(x)}{h_n(x)}, \dots, \frac{h_{n-1}(x)}{h_n(x)}, 1\right)$$

Example: We compute the Sturm sequence $[x^5 + x, x^2 + 2]$. Successive polynomial division yields:

$$x^{5} + x = (x^{2} + 2) \cdot (x^{3} - 2x) + 5x = (x^{2} + 2) \cdot (x^{3} - 2x) - (-5x)$$

$$x^{2} + 2 = (-5x) \cdot (-\frac{1}{5}x) + 2 = (-5x) \cdot (-\frac{1}{5}x) - (-2)$$

$$-5x = (-2) \cdot \frac{5}{2}x$$

We therefore obtain

$$[x^{5} + x, x^{2} + 2] = (x^{5} + x, x^{2} + 2, -5x, -2).$$

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For a polynomial $f(x) \in \mathbb{R}[x]$ we denote with f' the formal derivative of the polynomial f.

It is computed using the well-known rules for derivates.

Let $f, g \in \mathbb{R}[x]$, $a \in \mathbb{R}$: • a' = 0• $(a \cdot f)' = a \cdot f'$ • (f + g)' = f' + g'• $(x^n)' = n \cdot x^{n-1}$ for $n \ge 1$

Also the product rule holds: $(f \cdot g)' = f' \cdot g + f \cdot g'$.

Example: For $f(x) = 4x^3 - 2x^2 + 5x - 3$ we have $f' = 12x^2 - 4x + 5$.

Let $f \in \mathbb{R}[x]$ be a polynomial with $f \neq 0$.

A real number $a \in \mathbb{R}$ is a root of f (i.e. f(a) = 0) if and only if (x - a) divides f (i.e. $f = (x - a) \cdot g$ for some polynomial g).

Proof: If $f = (x - a) \cdot g$, then $f(a) = (a - a) \cdot g(a) = 0$.

Now assume that f(a) = 0.

Polynomial division of f by x - a: $f = (x - a) \cdot q + r$ with $\deg(r) < \deg(x - a) = 1$, i.e., $r \in \mathbb{R}$.

Because of $0 = f(a) = (a - a) \cdot q(a) + r = r$ we get $f = (x - a) \cdot q$.

This observation yields:

Lemma

Let $f, g \in \mathbb{R}[x] \setminus \{0\}$. If gcd(f, g) = 1, then f and g have no common root.

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A root *a* of a polynomial *f* is a multiple root of *f*, if $(x - a)^2$ divides *f*. The following lemmas can be shown as simple exercises:

Lemma

A root a of f is a multiple root of f if and only if f'(a) = 0.

Lemma

If gcd(f, f') = 1, then the polynomial f has no multiple root.

For a quantifier-free formula H with the only free variable x and $a, b \in \mathbb{R}$ with a < b let

$$(\#x:H)^b_a = |\{c \in (a,b) \mid \mathbb{R}_{[x/c]} \models H\}|.$$

Here, $(a, b) = \{c \in \mathbb{R} \mid a < c < b\}$ is the open interval between a and b. Hence, $(\#x : H)_a^b$ is the number of real values $c \in (a, b)$ for which H holds.

Example: $(\#x : x^2 - 2 = 0)_{-2}^2 = 2$, because there are two real roots of the polynomial $x^2 - 2$ $(-\sqrt{2} \text{ and } \sqrt{2})$ and both belong to (-2, 2). Moreover, $(\#x : x^2 - 2 = 0 \land x > 0)_{-2}^2 = 1$.

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We now come to the central theorem for our further considerations:

Theorem of Sturm and Tarski Let $f, g \in \mathbb{R}[x] \setminus \{0\}, f' \neq 0, \operatorname{gcd}(f, g) = \operatorname{gcd}(f, f') = 1, a, b \in \mathbb{R}, a < b, f(a) \neq 0 \neq f(b)$. Then the following identity holds:

$$(\#x: f(x) = 0 \land g(x) > 0)_a^b - (\#x: f(x) = 0 \land g(x) < 0)_a^b =$$

Var_a([f, f'g]) - Var_b([f, f'g]).

For the proof of the theorem of Sturm and Tarski we need two lemmas (Lemma A and Lemma B).

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Lemma A Let $f, g \in \mathbb{R}[x] \setminus \{0\}$, $a, b \in \mathbb{R}$, a < b, and $\forall c \in [a, b] : f(c) \neq 0$. We have $\operatorname{Var}_a([f, g]) = \operatorname{Var}_b([f, g])$.

Proof of Lemma A: Let

$$[f,g]=S=(h_0,h_1,\ldots,h_s)$$

and let

$$\tilde{S} = (\tilde{h}_0, \tilde{h}_1, \ldots, \tilde{h}_s)$$

be the reduced Sturm sequence, i.e., $\tilde{h}_s = 1$ and $\tilde{h}_i = \frac{h_i}{h_s}$.

Let $N = \{c \in [a, b] \mid \exists 0 \leq i \leq s : \tilde{h}_i(c) = 0\}.$

The set N is finite (a polynomial $\neq 0$ has only finitely many roots). Let $[a', b'] \subseteq [a, b]$ be an interval with $|N \cap [a', b']| \leq 1$.

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It suffices to show: $\operatorname{Var}_{a'}(S) = \operatorname{Var}_{b'}(S)$.

Then we write [a, b] as

$$[a, b] = [a_0, a_1] \cup [a_1, a_2] \cup [a_2, a_3] \cup \cdots \cup [a_{k-1}, a_k]$$

with $a_0 = a$, $a_k = b$ and $|N \cap [a_i, a_{i+1}]| \le 1$ for all $0 \le i \le k - 1$. We obtain $\operatorname{Var}_{a_i}(S) = \operatorname{Var}_{a_{i+1}}(S)$ for all $0 \le i \le k - 1$ and hence

$$\operatorname{Var}_{a}(S) = \operatorname{Var}_{a_0}(S) = \operatorname{Var}_{a_k}(S) = \operatorname{Var}_{b}(S).$$

So, let us show that $\operatorname{Var}_{a'}(S) = \operatorname{Var}_{b'}(S)$ if $|N \cap [a', b']| \leq 1$. Since $f(a') \neq 0 \neq f(b')$ (because $\forall c \in [a, b] : f(c) \neq 0$) and $h_s = \operatorname{gcd}(f, g)$ divides f, we have $h_s(a') \neq 0 \neq h_s(b')$. This implies $\operatorname{Var}_{a'}(S) = \operatorname{Var}_{a'}(\tilde{S})$ and $\operatorname{Var}_{b'}(\tilde{S}) = \operatorname{Var}_{b'}(S)$. We show that $\operatorname{Var}_{a'}(\tilde{S}) = \operatorname{Var}_{b'}(\tilde{S})$.

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Case 1: No \tilde{h}_i has a root in [a', b'].

Since every polynomial \tilde{h}_i is continuous and, by the intermediate value theorem, $\tilde{h}_i([a', b'])$ contains all values between $\tilde{h}_i(a')$ and $\tilde{h}_i(b')$, we must have

$$ilde{h}_i(a')\cdot ilde{h}_i(b')>0$$

for all $0 \le i \le s$ (\tilde{h}_i does not change its sign on [a', b']).

We obtain $\operatorname{Var}_{a'}(\tilde{S}) = \operatorname{Var}_{b'}(\tilde{S})$.

Case 2: At least one \tilde{h}_i has a root $c \in [a', b']$.

By the choice of [a', b'] we have $N \cap [a', b'] = \{c\}$.

Since $\tilde{h}_s = 1$ and, by the assumption from the lemma, $f = h_0$ has no root in [a, b] (then, also \tilde{h}_0 has no root in [a, b]), we must have $1 \le i \le s - 1$. We have $\tilde{h}_{i-1}(c) = q_i(c)\tilde{h}_i(c) - \tilde{h}_{i+1}(c) = -\tilde{h}_{i+1}(c)$. If $\tilde{h}_{i+1}(c) = 0 = \tilde{h}_i(c)$ would hold, then $\tilde{h}_j(c) = 0$ for all $j \ge i$ (since $\tilde{h}_{j+2}(c) = q_{j+1}(c)\tilde{h}_{j+1}(c) - \tilde{h}_j(c)$), which contradicts $\tilde{h}_s = 1$. Therefore, we have $\tilde{h}_{i+1}(c) \ne 0$ and hence

$$ilde{h}_{i-1}(c) ilde{h}_{i+1}(c) = -(ilde{h}_{i+1}(c))^2 < 0,$$

i.e., $\tilde{h}_{i-1}(c)$ and $\tilde{h}_{i+1}(c)$ have different signs.

Since \tilde{h}_{i-1} and \tilde{h}_{i+1} have no root in [a', b'] (*c* would have been the only possibility), the intermediate value theorem implies

$$ilde{h}_{i-1}(a') ilde{h}_{i+1}(a') < 0 \quad ext{und} \quad ilde{h}_{i-1}(b') ilde{h}_{i+1}(b') < 0.$$

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We obtain:

$$\begin{aligned} \mathsf{Var}_{a'}(\tilde{S}) &= \mathsf{Var}(\tilde{h}_0(a'), \dots, \tilde{h}_{i-1}(a'), \tilde{h}_i(a'), \tilde{h}_{i+1}(a'), \dots, \tilde{h}_s(a')) \\ &= \mathsf{Var}(\tilde{h}_0(a'), \dots, \tilde{h}_{i-1}(a'), \tilde{h}_{i+1}(a'), \dots, \tilde{h}_s(a')) \\ \\ \mathsf{Var}_{b'}(\tilde{S}) &= \mathsf{Var}(\tilde{h}_0(b'), \dots, \tilde{h}_{i-1}(b'), \tilde{h}_i(b'), \tilde{h}_{i+1}(b'), \dots, \tilde{h}_s(b')) \\ &= \mathsf{Var}(\tilde{h}_0(b'), \dots, \tilde{h}_{i-1}(b'), \tilde{h}_{i+1}(b'), \dots, \tilde{h}_s(b')) \end{aligned}$$

In this way we can eliminate for every j with $\tilde{h}_j(c) = 0$ the entries $\tilde{h}_j(a')$ and $\tilde{h}_j(b')$.

We therefore obtain

$$\begin{array}{lll} \mathsf{Var}_{a'}(\tilde{S}) &=& \mathsf{Var}(g_0(a'), \dots, g_t(a')) \\ \mathsf{Var}_{b'}(\tilde{S}) &=& \mathsf{Var}(g_0(b'), \dots, g_t(b')) \end{array}$$

where the polynomials g_0, \ldots, g_t have no root in [a', b'].

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Hence, $g_i(a') \neq 0$ and $g_i(b') \neq 0$ have the same sign for all $0 \le i \le t$, which implies

$$\begin{aligned} \mathsf{Var}_{a'}(\tilde{S}) &= \mathsf{Var}(g_0(a'), \dots, g_t(a')) \\ &= \mathsf{Var}(g_0(b'), \dots, g_t(b')) \\ &= \mathsf{Var}_{b'}(\tilde{S}). \end{aligned}$$

Lemma B
Let
$$f, g \in \mathbb{R}[x] \setminus \{0\}, f' \neq 0, gcd(f, g) = gcd(f, f') = 1, a, b, c \in \mathbb{R}, a < c < b, f(c) = 0, \forall d \in [a, b] \setminus \{c\} : f(d) \neq 0$$
. We have
 $Var_a([f, f'g]) - Var_b([f, f'g]) = \begin{cases} 1 & \text{if } g(c) > 0 \\ -1 & \text{if } g(c) < 0 \end{cases}$

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Proof of Lemma B:

Since gcd(f,g) = gcd(f,f') = 1, f and g have no common root, and f has no multiple root (Slides 104 and 105).

In particular, we have $g(c) \neq 0$ and there is a polynomial h(x) with $f(x) = (x - c) \cdot h(x)$ and $h(c) \neq 0$.

We obtain
$$f f'g = f \cdot (h + (x - c)h') \cdot g = (x - c) \cdot \underbrace{(h^2g + (x - c)hh'g)}_{u(x)}$$
.

Let
$$[f, f'g] = (f, f'g, h_2, \dots, h_s)$$
 with $s \ge 1$.

Assume that g(c) > 0 (the case g(c) < 0 can be analyzed analogously). We have $u(c) = (h(c))^2 g(c) > 0$ and $f'(c)g(c) \neq 0$.

Since u(x) is continuous and a < c < b, there are a' < b' with $a \le a' < c < b' \le b$ and $\forall x \in [a', b'] : u(x) > 0$ and $f'(x)g(x) \neq 0$. With $f f'g = (x-c) \cdot u(x)$ we get f(a')f'(a')g(a') < 0 < f(b')f'(b')g(b'). Markus Lohrey (Universität Siegen) Advanced Logic Summer 2022 114/161

Decidability of real arithmetic If $s \ge 2$ (in which case h_2 exists) we obtain:

$$\begin{aligned} \mathsf{Var}_{a}([f, f'g]) & \stackrel{\mathsf{Lemma } \mathsf{A}}{=} & \mathsf{Var}_{a'}([f, f'g]) \\ & = & 1 + \mathsf{Var}_{a'}([f'g, h_2]) \\ \stackrel{\mathsf{Lemma } \mathsf{A}}{=} & 1 + \mathsf{Var}_{b'}([f'g, h_2]) \\ & = & 1 + \mathsf{Var}_{b'}([f, f'g]) \\ \stackrel{\mathsf{Lemma } \mathsf{A}}{=} & 1 + \mathsf{Var}_{b}([f, f'g]) \end{aligned}$$

If
$$s = 1$$
 (i.e., $[f, f'g] = (f, f'g)$) we get

$$Var_a([f, f'g]) \stackrel{\text{Lemma A}}{=} Var_{a'}([f, f'g])$$

$$= 1$$

$$= 1 + Var_{b'}([f, f'g])$$

$$\stackrel{\text{Lemma A}}{=} 1 + Var_b([f, f'g])$$

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Proof of the theorem of Tarski and Sturm:

Assume that $f, g \in \mathbb{R}[x] \setminus \{0\}$, $f' \neq 0$, gcd(f, g) = gcd(f, f') = 1, $a, b \in \mathbb{R}$, a < b, $f(a) \neq 0 \neq f(b)$.

Let
$$N = \{c \in (a, b) \mid f(c) = 0\}$$
 (a finite set).

If $N = \emptyset$ we obtain with Lemma A:

$$(\#x:f(x) = 0 \land g(x) > 0)_a^b - (\#x:f(x) = 0 \land g(x) < 0)_a^b = 0 =$$
$$Var_a([f, f'g]) - Var_b([f, f'g]).$$

Now assume that $N = \{c_1, c_2, \ldots, c_n\}$ with $n \ge 1$.

Choose points $a = a_0 < c_1 < a_1 < c_2 < a_2 < \cdots < a_{n-1} < c_n < a_n = b$.

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With Lemma B we obtain for all $1 \le i \le n$:

$$\operatorname{Var}_{a_{i-1}}([f, f'g]) - \operatorname{Var}_{a_{i}}([f, f'g]) = \begin{cases} 1 & \text{if } g(c_{i}) > 0 \\ -1 & \text{if } g(c_{i}) < 0 \end{cases}$$

Summing over all *i* yields:

$$Var_{a}([f, f'g]) - Var_{b}([f, f'g]) = (\#x : f(x) = 0 \land g(x) > 0)_{a}^{b} - (\#x : f(x) = 0 \land g(x) < 0)_{a}^{b}$$

This concludes the proof of the theorem of Tarski and Sturm.

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Corollary of the theorem of Tarski and Sturm Let $f, g \in \mathbb{R}[x] \setminus \{0\}, f' \neq 0, \operatorname{gcd}(f, g) = \operatorname{gcd}(f, f') = 1, a, b \in \mathbb{R}, a < b, f(a) \neq 0 \neq f(b)$. We then have

$$\#x(f(x) = 0 \land g(x) > 0)_a^b$$

= $\frac{1}{2}(Var_a([f, f'g]) - Var_b([f, f'g]) + Var_a([f, f']) - Var_b([f, f'])).$

Proof: The theorem of of Tarski and Sturm yields

$$(\#x: f(x) = 0 \land g(x) > 0)_a^b - (\#x: f(x) = 0 \land g(x) < 0)_a^b$$

= Var_a([f, f'g]) - Var_b([f, f'g]).

as well as (since f and g have no common root due to gcd(f,g) = 1)

$$(\#x:f(x) = 0 \land g(x) > 0)_a^b + (\#x:f(x) = 0 \land g(x) < 0)_a^b$$

= $(\#x:f(x) = 0)_a^b =$
= $(\#x:f(x) = 0 \land 1 > 0)_a^b - (\#x:f(x) = 0 \land 1 < 0)_a^b$
= $Var_a([f, f']) - Var_b([f, f']).$

Adding both equalities gives:

$$\begin{aligned} &2 \cdot (\#x:f(x)=0 \wedge g(x)>0)_a^b \\ &= \mathsf{Var}_a([f,f'g]) - \mathsf{Var}_b([f,f'g]) + \mathsf{Var}_a([f,f']) - \mathsf{Var}_b([f,f']) \end{aligned}$$

We also need Cauchy's bound for the roots of a polynomial:

Lemma (Cauchy's bound)

Let $f(x) = a_m x^m + \cdots + a_1 x + a_0 \in \mathbb{R}[x]$, $a_m \neq 0$. All real roots of the polynomial f belong to the interval (-c, c) with

$$c = 1 + rac{\max\{|a_0|, \dots, |a_{m-1}|\}}{|a_m|}.$$

Proof of the Cauchy bound:

Assume that we have already proved the Cauchy bound for the case $a_m = 1$.

Then we get the general statement as follows:

Let α be a root of $f(x) = a_m x^m + a_{m-1} x^{m-1} + \cdots + a_1 x + a_0$ with $a_m \neq 0$.

Then α is also a root of the polynomial $x^m + \frac{a_{m-1}}{a_m}x^{m-1} + \cdots + \frac{a_1}{a_m}x + \frac{a_0}{a_m}$.

The Cauchy bound for the case $a_m = 1$ yields

$$|\alpha| < 1 + \max\{\left|\frac{a_i}{a_m}\right| \mid 0 \le i \le m - 1\} = 1 + \frac{\max\{|a_i| \mid 0 \le i \le m - 1\}}{|a_m|}.$$

It remains to prove the Cauchy bound for a polynomial

$$f(x) = x^m + a_{m-1}x^{m-1} + \cdots + a_1x + a_0.$$

Let $h = \max\{|a_i| \mid 0 \le i \le m - 1\}.$

Assume that $f(\alpha) = \alpha^m + a_{m-1}\alpha^{m-1} + \cdots + a_1\alpha + a_0 = 0$, i.e.,

$$\alpha^{m} = -a_{m-1}\alpha^{m-1} - \dots - a_{1}\alpha - a_{0}. \tag{3}$$

We show that $|\alpha| < 1 + h$.

If $|\alpha| \leq 1$, we have $|\alpha| < 1 + h$ (if h = 0 then we have $\alpha^m = 0$, i.e., $\alpha = 0$).

Now assume that $|\alpha| > 1$.

Using (3) and the laws $|a + b| \le |a| + |b|$, $|a \cdot b| = |a| \cdot |b|$ for all $a, b \in \mathbb{R}$, we get

$$\begin{aligned} |\alpha|^m &\leq |a_{m-1}| \cdot |\alpha|^{m-1} + \dots + |a_1| \cdot |\alpha| + |a_0| \\ &\leq h \cdot (|\alpha|^{m-1} + \dots + |\alpha| + 1) \\ &= h \cdot \frac{|\alpha|^m - 1}{|\alpha| - 1}. \end{aligned}$$

Since $|\alpha| > 1$, we obtain:

$$|\alpha| - 1 \le h \cdot \frac{|\alpha|^m - 1}{|\alpha|^m} < h$$

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We now come back to Case 1 (see Slide 95):

Recall: We want to find a quantifier-free arithmetic formula for $(\#x : s = 0 \land t > 0) = k$, where

$$s = z_0 + z_1 x + \dots + z_m x^m$$

 $t = z_{m+1} + z_{m+2} x + \dots + z_n x^{n-m-1}$

and $1 \leq m < n$ (if m = n then t = 0 and $(\#x : s = 0 \land t > 0) = 0$).

The desired quantifier-free formula has the free variables z_0, \ldots, z_n . Moreover we can restrict to the case that all z_i only take values $\neq 0$.

Let y and z be two new variables.

By Cauchy's bound it suffices to find for $(\#x : s = 0 \land t > 0)_y^z = k$ (see Slide 106) a quantifier-free formula with free variables y, z, z_0, \ldots, z_m .

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In this formula we can replace the interval borders y and z by

$$-\frac{|z_m| + \max\{|z_0|, \dots, |z_{m-1}|\}}{|z_m|}, \text{ resp. } \frac{|z_m| + \max\{|z_0|, \dots, |z_{m-1}|\}}{|z_m|}.$$

Applications of $|\cdot|$ and max can be eliminated by case distinctions (similar to Slide 92).

Examples:

 $|z_i| + y = z$ becomes $(z_i \ge 0 \rightarrow z_i + y = z \land z_i < 0 \rightarrow y = z + z_i)$. max $\{z_i, z_j\} = x$ becomes $(z_i \ge z_j \rightarrow x = z_i \land z_i < z_j \rightarrow x = z_j)$.

Applications of $\frac{\cdot}{|z_m|}$ (in case $z_m \neq 0$) can be eliminated by multiplication with sufficiently large powers of z_m .

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Using the corollary of the Sturm-Tarski theorem from Slide 118 we construct a quantifier-free formula for

$$(\#x:s=0\wedge t>0)_y^z=k$$

with free variables y, z, z_0 , ..., z_n .

But: Are all the assumptions for f = s and g = t from Slide 118 satisfied?

- ▶ $s \neq 0$ and $s' \neq 0$, since $m \ge 1$ on Slide 124 and all z_i are $\neq 0$.
- ▶ $t \neq 0$, since all z_i are $\neq 0$ and the case m < n on Slide 124.
- ▶ gcd(s, t) = gcd(s, s') = 1: does not hold for all $z_i \neq 0$!

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How do we ensure the assumption gcd(s, t) = gcd(s, s') = 1?

We have:

•
$$(\#x:s=0 \land t>0)_y^z = (\#x:s/\gcd(s,t)=0 \land t>0)_y^z$$
:

By replacing s by s/gcd(s, t) we eliminate for s only common roots of s and t (for which t > 0 does not hold).

•
$$(\#x:s=0 \land t>0)_y^z = (\#x:s/\gcd(s,s')=0 \land t>0)_y^z$$
:

s and $s/\gcd(s, s')$ have the same roots (only the multiplicity of the roots of s is reduced to one when dividing by $\gcd(s, s')$).

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In this way we can reduce the degree of s until finally gcd(s, t) = gcd(s, s') = 1 holds.

The gcd-computations have to be done symbolically, since the coefficients of *s* and *t* are parameters $z_i \neq 0$.

Example: m = 2, n = 4, i.e.,

$$s(x) = z_0 + z_1 x + z_2 x^2$$
 and $t(x) = z_3 + z_4 x$

We first compute symbolically

$$gcd(s, t) = gcd(z_0 + z_1x + z_2x^2, z_3 + z_4x).$$

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In order to make the computation more convenient, we multiply s with $z_4^2 \neq 0.$

We have
$$(\#x: s = 0 \land t > 0)_y^z = (\#x: z_4^2 \cdot s = 0 \land t > 0)_y^z.$$

Division with remainder:

$$(z_{2}z_{4}^{2}x^{2} + z_{1}z_{4}^{2}x + z_{0}z_{4}^{2}) : (z_{4}x + z_{3}) = z_{2}z_{4}x + (z_{1}z_{4} - z_{2}z_{3})$$

$$- (z_{2}z_{4}^{2}x^{2} + z_{2}z_{4}z_{3}x)$$

$$((z_{1}z_{4}^{2} - z_{2}z_{4}z_{3})x + z_{0}z_{4}^{2})$$

$$- ((z_{1}z_{4}^{2} - z_{2}z_{4}z_{3})x + (z_{1}z_{4}z_{3} - z_{2}z_{3}^{2}))$$

$$z_{0}z_{4}^{2} - z_{1}z_{4}z_{3} + z_{2}z_{3}^{2}$$
 (remainder)

Therefore:

Moreover:

$$(\#x:s=0 \land t>0)_y^z = (\#x:z_2z_4x + z_1z_4 - z_2z_3 = 0 \land t>0)_y^z$$

At this point we do not necessarily have $gcd(z_2z_4x + z_1z_4 - z_2z_3, t) = 1$, but the x-degree of $z_2z_4x + z_1z_4 - z_2z_3$ is smaller than the x-degree of s.

We therefore can continue in the same way.

In our concrete situation this is quite easy:

The only root of $z_2z_4 \cdot x + z_1z_4 - z_2z_3$ is $\frac{z_2z_3 - z_1z_4}{z_2z_4}$. The only root of $t = z_4 \cdot x + z_3$ is $-\frac{z_3}{z_4}$. Hence, if $\frac{z_2z_3 - z_1z_4}{z_2z_4} \neq -\frac{z_3}{z_4}$ (i.e., $z_1z_4 \neq 2z_2z_3$) then $gcd(z_2z_4x + z_1z_4 - z_2z_3, t) = 1$.

On the other hand, if $z_1 z_4 = 2 z_2 z_3$ then $(\# x : s = 0 \land t > 0)_y^z = 0$.

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To sum up, for
$$s(x) = z_0 + z_1 x + z_2 x^2$$
 and $t(x) = z_3 + z_4 x$ we have:
If $z_0 z_4^2 - z_1 z_4 z_3 + z_2 z_3^2 \neq 0$ then $gcd(s, t) = 1$.
If $z_0 z_4^2 - z_1 z_4 z_3 + z_2 z_3^2 = 0$ and $z_1 z_4 \neq 2 z_2 z_3$ then
 $(\#x : s = 0 \land t > 0)_y^z = (\#x : z_2 z_4 x + z_1 z_4 - z_2 z_3 = 0 \land t > 0)_y^z$
and $gcd(z_2 z_4 x + z_1 z_4 - z_2 z_3, t) = 1$.
If $z_0 z_4^2 - z_1 z_4 z_3 + z_2 z_3^2 = 0$ and $z_1 z_4 = 2 z_2 z_3$ then
 $(\#x : s = 0 \land t > 0)_y^z = 0$.

In the same way we can ensure the assumption gcd(s, s') = 1.

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Under the assumptions gcd(s, t) = gcd(s, s') = 1 and $s(y) \neq 0 \neq s(z)$, $(\#x : s = 0 \land t > 0)_y^z = k$ is equivalent to

$$\mathsf{Var}_y([s,s't]) - \mathsf{Var}_z([s,s't]) + \mathsf{Var}_y([s,s']) - \mathsf{Var}_z([s,s']) = 2k$$

This can be expressed as a boolean combination of statements of the form $\operatorname{Var}_{y}([s, s't]) = i_{1}$, $\operatorname{Var}_{z}([s, s't]) = i_{2}$, $\operatorname{Var}_{y}([s, s']) = i_{3}$, $\operatorname{Var}_{z}([s, s']) = i_{4}$.

Finally, a statement $Var_y([s, s't]) = i$ (analogously for the other polynomials) can be expressed by a quantifier-free formula.

For this we execute the Euclidean algorithm symbolically for s and s't and thereby compute symbolically the Sturm sequence [s, s't] and then replace the variable of the polynomials in the Sturm sequence by y.

This concludes case 1. We continue with case 2 from Slide 95.

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Case 2:
$$G = (s = 0 \land \bigwedge_{i=1}^{m} t_i > 0), m \ge 1$$
, and x appears in s.

Induction over m:

Induction base: m = 1. See case 1.

Induction step: let m > 2. Let $G' = (s = 0 \land \bigwedge_{i=1}^{m-2} t_i > 0)$. We have: $\#_{X}(G' \wedge t_{m-1} > 0 \wedge t_{m} > 0) +$ $\#x(G' \wedge t_{m-1} > 0 \wedge t_m < 0) = \#x(G' \wedge t_{m-1}t_m^2 > 0)$ (4) $\#x(G' \wedge t_{m-1} > 0 \wedge t_m > 0) +$ $\#x(G' \wedge t_{m-1} < 0 \wedge t_m > 0) = \#x(G' \wedge t_{m-1}^2 t_m > 0)$ (5) $\# x(G' \wedge t_{m-1} > 0 \wedge t_m < 0) +$ $\#x(G' \wedge t_{m-1} < 0 \wedge t_m > 0) = \#x(G' \wedge t_{m-1}t_m < 0)$ (6)

(4) + (5) - (6) yields:

$$2 \cdot \# x \ G = 2 \cdot \# x \cdot (G' \wedge t_{m-1} > 0 \wedge t_m > 0) \\ = \# x (G' \wedge t_{m-1} t_m^2 > 0) + \\ \# x (G' \wedge t_{m-1}^2 t_m > 0) - \\ \# x (G' \wedge - t_{m-1} t_m > 0)$$

Case 3 from Slide 95: s = 0, i.e., $G = \bigwedge_{i=1}^{m} t_i > 0$ with $t_i \neq 0$. Let $t = t_1 t_2 \cdots t_m$.

Claim: $\exists x \ G$ is equivalent in \mathbb{R} to

$$\exists x_0 \forall x \leq x_0 : G \lor \exists x_0 \forall x \geq x_0 : G \lor \exists x \ (t'(x) = 0 \land G).$$
(7)

The implication $(7) \Rightarrow \exists x \ G$ is clear.

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Now assume that $\mathbb{R} \models \exists x \ G$.

We obtain

$$\mathbb{R} \models \exists x_0 \forall x \le x_0 : G \lor \exists x_0 \forall x \ge x_0 : G \lor \\ \exists x_1 \exists x \exists x_2 (x_1 < x < x_2 \land \neg G[x/x_1] \land G \land \neg G[x/x_2]).$$

Assume that

$$\mathbb{R} \models \exists x_1 \exists x \exists x_2 (x_1 < x < x_2 \land \neg G[x/x_1] \land G \land \neg G[x/x_2])$$

Then there are $x_1, x, x_2 \in \mathbb{R}$ and $i, j \in \{1, \ldots, m\}$ with

$$x_1 < x < x_2$$
,
 $t_i(x_1) \le 0$,
 $t_j(x_2) \le 0$,
 $t_k(x) > 0$ for alle $1 \le k \le m$

Then there are also $x'_1, x'_2 \in \mathbb{R}$ with $x'_1 < x < x'_2$ and $t_i(x'_1) = t_j(x'_2) = 0$. We get $t(x'_1) = t(x'_2) = 0$.

Since t has only finitely many roots, we can choose for $x'_1(x'_2)$ the greatest (smallest) root of t, which is smaller (greater) than x.

We get $x'_1 < x < x'_2$, $t(x'_1) = 0 = t(x'_2)$ and $t_k(y) > 0$ for all $y \in (x'_1, x'_2)$ and $1 \le k \le m$.

We obtain t(y) > 0 for all $y \in (x'_1, x'_2)$.

By Rolle's theorem (https://de.wikipedia.org/wiki/Satz_von_Rolle) there exists an x with t'(x) = 0 and $t_i(x) > 0$ for all $1 \le i \le m$, i.e.,

$$\mathbb{R} \models \exists x_0 \forall x \leq x_0 : G \ \lor \ \exists x_0 \forall x \geq x_0 : G \ \lor \ \exists x \ (t'(x) = 0 \land G).$$

This shows the claim.

It now suffices to find a quantifier-free formula for

$$\exists x_0 \forall x \leq x_0 : G \lor \exists x_0 \forall x \geq x_0 : G \lor \exists x \ (t'(x) = 0 \land G).$$

For the formulas $\exists x_0 \forall x \leq x_0 \ G$ and $\exists x_0 \forall x \geq x_0 \ G$ one can easily find quantifier-free formulas.

To see this, note that for a polynomial $a_n x^n + \cdots + a_1 x + a_0$ with $a_n \neq 0$ we have

$$\exists x_0 \forall x \leq x_0 \ (a_n x^n + \dots + a_1 x + a_0 > 0)$$

if and only if one of the following cases holds:

- \blacktriangleright *n* is even and $a_n > 0$,
- *n* is odd and $a_n < 0$.

The formula $\exists x \ (t'(x) = 0 \land G)$ can be made quantifier-free using case 1, respectively case 2, if x appears in t'(x).

If x does not appear in t'(x), then the x-degree of $t(x) = t_1(x) \cdots t_m(x)$ is at most 1.

This means that x appears in at most one of the polynomials t_i , without loss of generality assume that x appears in t_1 .

Moreover, the x-degree of $t_1(x)$ is at most one.

If $t_i = z_i$ for $1 \le i \le m$, then $\exists x \bigwedge_{i=1}^m t_i > 0$ is equivalent to $\bigwedge_{i=1}^m z_i > 0$.

If $t_1 = z_1 \cdot x + z_0$ and $t_i = z_i$ for $2 \le i \le m$, then $\exists x \bigwedge_{i=1}^m t_i > 0$ is equivalent to $\bigwedge_{i=2}^m t_i > 0$

This concludes our proof of Tarski's theorem.

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Tarski's theorem implies that there is no arithmetical formula F(x) with a single free variable x such that for all $r \in \mathbb{R}$:

$$(\mathbb{R},+,\cdot)_{[x/r]}\models F(x) \Leftrightarrow r\in\mathbb{N}$$

If there would exist such a formula F(x), then together with Gödel's theorem (Th($\mathbb{N}, +, \cdot$) is undecidable) the undecidability of Th($\mathbb{R}, +, \cdot$) would follow.

Surprisingly, Julia Robinsion found in 1949 such a formula for $\mathbb Q$ instead of $\mathbb R$:

Theorem (Robinson 1949)

There exists an arithmetical formula F(x) with a single free variable x such that for all rational numbers $r \in \mathbb{Q}$:

$$(\mathbb{Q},+,\cdot)_{[x/r]}\models F(x) \Leftrightarrow r\in\mathbb{N}$$

Consequence: $\mathsf{Th}(\mathbb{Q},+,\cdot)$ is undecidable.

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Monadic second order logic (MSO for short) is an extension of predicate logic (which is also denoted as first order logic), where quantification over subsets of the universe is allowed.

For this we fix two set of variables:

- first order variables: $Var_1 = \{x_1, x_2, x_3, \ldots\}$
- second order variables: $Var_2 = \{X_1, X_2, X_3, \ldots\}$

We have $Var_1 \cap Var_2 = \emptyset$.

Variables from Var₁ are denoted with x, y, z, x', x_0, \ldots , whereas variables from Var₂ are denoted with X, Y, Z, X', X_0, \ldots

As in predicate logic (see Logik I) we have predicate symboles P_i^k (k-ary) and function symbols f_i^k (k-ary).

Terms are defined as in predicate logic using function symbols and variables from Var_1 .

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The set MSO of all MSO-formulas is the smallest set with:

- ▶ if t_1, t_2 are terms and $X \in Var_2$, then $(t_1 = t_2), (t_1 \in X) \in MSO$;
- ▶ if $t_1, t_2, ..., t_k$ are terms and *P* is a *k*-ary predicate symbol, then $P(t_1, ..., t_k) \in MSO$;
- if $F, G \in MSO$, then $\neg F, F \land G, F \lor G \in MSO$.
- ▶ if $F \in MSO$ and $x \in Var_1, X \in Var_2$, then $\exists xF, \exists XF, \forall xF, \forall XF \in MSO$.

The set $free(F) \subseteq Var_1 \cup Var_2$ of all free variables of $F \in MSO$ is defined as in predicate logic.

For $F \in MSO$ we also write $F(x_1, \ldots, x_n, X_1, \ldots, X_m)$ in order to express free $(F) = \{x_1, \ldots, x_n, X_1, \ldots, X_m\}$.

A formula $F \in MSO$ with free $(F) = \emptyset$ is called an MSO-sentence.

A structure is now a pair $\mathcal{A} = (U_{\mathcal{A}}, I_{\mathcal{A}})$, where $U_{\mathcal{A}}$ is a non-empty set (the universe) and $I_{\mathcal{A}}$ is a partially defined mapping, which assigns

- to every k-ary predicate symbol P from the domain of I_A a k-ary relation I_A(P) ⊆ U^k_A,
- ► to every *k*-ary function symbol *f* from the domain of I_A a *k*-ary function $I_A(f) : U_A^k \to U_A$,
- ▶ to every variable $x \in Var_1$ from the domain of I_A an element $I_A(x) \in U_A$, and

► to every variable $X \in Var_2$ from the domain of I_A a subset $I_A(X) \subseteq U_A$.

A structure A is suitable for a formula $F \in MSO$, if I_A is defined for every predicate symbol, function symbol and free variable that appears in F.

Let \mathcal{A} be suitable for F. We write $\mathcal{A} \models F$ if one of the following cases holds (the evaluation $\mathcal{A}(t) \in U_{\mathcal{A}}$ of a term t is defined as in predicate logic):

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Conventions:

- ln the following we identify a symbol P with its interpretation $I_A(P)$.
- A structure $\mathcal{A} = (U_{\mathcal{A}}, I_{\mathcal{A}})$ with dom $(I_{\mathcal{A}}) = \{P_1, \dots, P_n, f_1, \dots, f_m\}$ is also written as $(U_{\mathcal{A}}, I_{\mathcal{A}}(P_1), \dots, I_{\mathcal{A}}(P_n), I_{\mathcal{A}}(f_1), \dots, I_{\mathcal{A}}(f_m))$ or just $(U_{\mathcal{A}}, P_1, \dots, P_n, f_1, \dots, f_m)$.
- ► For an MSO-formula $F = F(x_1, ..., x_n, X_1, ..., X_m)$ and $a_1, ..., a_n \in U_A, A_1, ..., A_m \subseteq U_A$ we also write $A \models F(a_1, ..., a_n, A_1, ..., A_m)$ for $A_{[x_1/a_1, ..., x_n/a_n, X_1/A_1, ..., X_m/A_m]} \models F$.

The MSO-theory of a structure A is the set of all MSO-sentences F with $A \models F$.

Monadic second order logic: Example

An example for a useful MSO-formula:

Let $\mathcal{G} = (V, E)$ be a directed graph, which is the structure with universe V and the binary relation $E \subseteq V \times V$.

The following formula reach(x, y) expresses that in \mathcal{G} there is a path from vertex x to vertex y:

$$\mathsf{reach}(x,y) = \forall X \bigg(\big(x \in X \land \forall u \forall v (E(u,v) \land u \in X \ \rightarrow v \in X) \big) \rightarrow y \in X \bigg)$$

Proof: We say that a subset $U \subseteq V$ of vertices is closed under the edge relation *E* if for every $(u, v) \in E$ the following holds: if $u \in U$ then $v \in U$.

The formula reach(x, y) says that every subset $U \subseteq V$ that is closed under the edge relation E and that contains x must also contain y.

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Monadic second order logic: Example

This is indeed equivalent to the fact that there is a path from x to y, i.e., $(x, y) \in E^*$:

Assume that there is no such a path from x to y.

Let $U = \{v \in V \mid (x, v) \in E^*\}$ be the set of all vertices that can be reached from x.

Then U is closed under the edge relation E and $x \in U$, $y \notin U$.

Assume that there is a path (u₁, u₂,..., u_n) from x to y, i.e., u₁ = x, u_n = y and (u_i, u_{i+1}) ∈ E for all i ∈ {1,..., n − 1}.
Let U ⊆ V be set of vertices that is closed under E with x ∈ U.
Induction along i shows that u_i ∈ U for all i ∈ {1,..., n}.
Hence, we have y = u_n ∈ U.

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MSO-definable languages

We want to use MSO-sentences in order to define (formal) languages.

For this, we first have to represent finite words by structures.

Let Σ be a finite alphabet.

A non-empty word $w = a_1 a_2 \cdots a_n$ $(n \ge 1, a_i \in \Sigma)$ is identified with the structure

$$\mathcal{A}_w = (\{1, 2, \ldots, n\}, <, (P_a)_{a \in \Sigma}),$$

such that:

- < is the ordinary order on $\{1, 2, \ldots, n\}$
- P_a is the unary relation P_a = {i | 1 ≤ i ≤ n, a_i = a} (the set of all positions in the word w carrying the letter a)

MSO-definable languages

For the following example let the alphabet be $\Sigma = \{a, b\}$.

Example: For the word w = abbaa we have

$$\mathcal{A}_{w} = (\{1, 2, 3, 4, 5\}, <, \underbrace{\{1, 4, 5\}}_{P_{a}}, \underbrace{\{2, 3\}}_{P_{b}}).$$

In the following we identify the structure A_w with the word w.

A language $L \subseteq \Sigma^+$ of non-empty words is MSO-definable if there is an MSO-sentence F with $L = \{w \in \Sigma^+ \mid w \models F\}$.

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MSO-definable languages

Example 1: The MSO-sentence

 $\exists x \exists y \exists z (\forall u (x \leq u \land u \leq z) \land P_a(x) \land P_b(y) \land P_a(z))$

defines the language $a\Sigma^*b\Sigma^*a$.

Here, $x \le u$ is an abbreviation for $x < u \lor x = u$.

Example 2: The MSO-sentence

$$\exists X \ (\exists x \exists y (\forall u (x \le u \land u \le y) \land x \in X \land \neg y \in X) \land \forall x \forall y (y = x + 1 \rightarrow (x \in X \leftrightarrow y \notin X)))$$

defines the language $\{w \in \{a, b\}^* \mid |w| \text{ is even}\}.$

Here, y = x + 1 is an abbreviation for the formula $x < y \land \forall z (x \le z \le y \rightarrow (x = z \lor y = z)).$

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Theorem (Büchi, Elgot 1958 and Trachtenbrot 1958) A language L is MSO-definable if and only if L is regular.

Proof:

1. Let $L \subseteq \Sigma^*$ be regular. We show that L is MSO-definable.

Let $A = (Q, \Sigma, \delta, q_0, F)$ be a deterministic finite automaton (DFA) with L(A) = L, where

- Q is the finite set of states,
- $\delta: Q \times \Sigma \rightarrow Q$ is the transition mapping,
- $q_0 \in Q$ is the initial state, and
- $F \subseteq Q$ is the set of final states.

Without loss of generality assume that $Q = \{1, ..., n\}$. Then the following MSO-sentence defines the language L = L(A):

$$\exists X_1 \exists X_2 \cdots \exists X_n$$

$$\bigwedge_{p \neq q} X_p \cap X_q = \emptyset \land \forall x \bigvee_{q \in Q} x \in X_q \land$$

$$\exists x (\forall y (x \le y) \land \bigvee_{a \in \Sigma} (P_a(x) \land x \in X_{\delta(q_0, a)})) \land$$

$$\exists x (\forall y (y \le x) \land \bigvee_{q \in F} x \in X_q) \land$$

$$\forall x \forall y (y = x + 1 \rightarrow \bigvee_{q \in Q} \bigvee_{a \in \Sigma} (x \in X_q \land P_a(y) \land y \in X_{\delta(q, a)}))$$

Here, $X_p \cap X_q = \emptyset$ is an abbreviation for $\neg \exists x (x \in X_p \land x \in X_q)$.

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Idea behind this formula: The existentially quantified set X_q is the set of all positions in the word where the DFA A arrives in state $q \in \{1, ..., n\}$.

At every position, the DFA arrives in exactly one state.

$$\blacktriangleright \exists x (\forall y (x \leq y) \land \bigvee_{a \in \Sigma} (P_a(x) \land x \in X_{\delta(q_0,a)})):$$

If position 1 of the word (x = 1 in the above formula) carries the letter *a*, then the DFA arrives at position 1 in the state $\delta(q_0, a)$ (q_0 is the initial state).

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$$\blacksquare \exists x (\forall y (y \leq x) \land \bigvee_{q \in F} x \in X_q):$$

At the last position of the word the DFA arrives in a final state.

$$\blacktriangleright \forall x \forall y (y = x + 1 \rightarrow \bigvee_{q \in Q} \bigvee_{a \in \Sigma} (x \in X_q \land P_a(y) \land y \in X_{\delta(q,a)})):$$

If x and y = x + 1 are two successive positions in the word, where position y carries the letter a, and the DFA arrives at position x in state q, then the DFA arrives at position y in state $\delta(q, a)$.

2. Let $L \subseteq \Sigma^*$ be MSO-definable. We show that L is regular.

Let $V \subseteq Var_1 \cup Var_2$ be a finite set of variables.

A non-empty word

$$w = (a_1, V_1)(a_2, V_2) \cdots (a_k, V_k) \in (\Sigma \times 2^V)^*$$

 $(k \ge 1, a_i \in \Sigma, V_k \subseteq V)$ is called valid if for every variable $x \in V \cap Var_1$ there is exactly one $1 \le i \le k$ with $x \in V_i$.

For a valid word w we define the mapping $f_w : V \to \{1, \ldots, k\} \cup 2^{\{1, \ldots, k\}}$ by

•
$$f_w(x) = i$$
 if $x \in V_i \cap Var_1$ and

▶ $f_w(X) = \{i \mid X \in V_i\}$ for $X \in V \cap Var_2$.

We identify a valid word $w = (a_1, V_1)(a_2, V_2) \cdots (a_k, V_k)$ with the structure $\mathcal{A}_w = (\{1, \ldots, k\}, I_w)$ where

•
$$I_w(x) = f_w(x)$$
 for $x \in V \cap Var_1$,

$$\blacktriangleright \ I_w(X) = f_w(X) \text{ for } X \in V \cap \mathsf{Var}_2,$$

and I_w is defined for the predicate symbols < and P_a (a ∈ Σ) in the same way as in the structure A_v for v = a₁a₂ ··· a_k.

Hence, a valid word w defines an ordinary word $a_1a_2...a_k$ and in addition a valuation of the variables from V, where

- ▶ to every $x \in V \cap Var_1$ a position $i \in \{1, ..., k\}$ is assigned to and
- to every variable $X \in V \cap Var_2$ a set of positions is assigned to.

For an MSO-formula F with the free variables free(F) let L(F) be the set of all non-empty valid words w over the alphabet $\Sigma \times 2^{\text{free}(F)}$ such that $w \models F$.

Proof strategy: we construct for every formula F a with finite automaton A_F for the language L(F) using induction over the structure of F. At the end, we are only interested in the case free $(F) = \emptyset$.

First, one can construct for every finite set of variables $V \subseteq Var_1 \cup Var_2$ an automaton A_V which accepts exactly the valid words from $(\Sigma \times 2^V)^*$.

The automaton A_V only has to check that every variable $x \in V \cap Var_1$ appears at exactly one position of the input word.

For this, A_V stores in its state those variables from $V \cap Var_1$ that were already seen.

Now we come to the construction of the automaton A_F :

Case 1: F = (x = y). Construct A_F such that

$$L(A_F) = (\Sigma \times \{\emptyset\})^* (\Sigma \times \{x, y\}) (\Sigma \times \{\emptyset\})^*.$$

Case 2: F = (x < y). Construct A_F such that

$$L(A_{\mathcal{F}}) = (\Sigma \times \{\emptyset\})^* (\Sigma \times \{x\}) (\Sigma \times \{\emptyset\})^* (\Sigma \times \{y\}) (\Sigma \times \{\emptyset\})^*.$$

Case 3: $F = P_a(x)$. Construct A_F such that

$$L(A_F) = (\Sigma \times \{\emptyset\})^* (a, \{x\}) (\Sigma \times \{\emptyset\})^*.$$

Case 4: $F = (x \in X)$. Construct A_F such that

 $L(A_{\mathcal{F}}) = (\Sigma \times \{\emptyset, \{X\}\})^* (\Sigma \times \{x, X\}) (\Sigma \times \{\emptyset, \{X\}\})^*.$

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For the following cases we use the known closure properties for regular languages (closure under boolean operations, homomorphisms and inverse homomorphisms) that we also used in the proof of the theorem of Khoussainov and Nerode (Slides 69–80).

Case 5: $F = \neg G$. Let V = free(G). Construct A_F such that $L(A_F) = L(A_V) \setminus L(A_G)$.

Case 6: $F = G \lor H$.

Let $V_G = \text{free}(G)$, $V_H = \text{free}(H)$ and $V = \text{free}(F) = V_G \cup V_H$.

Define homomorphisms $g : (\Sigma \times 2^V)^* \to (\Sigma \times 2^{V_G})^*$ and $h : (\Sigma \times 2^V)^* \to (\Sigma \times 2^{V_H})^*$ by

$$g(a,S) = (a,S \cap V_G),$$

 $h(a,S) = (a,S \cap V_H).$

Next, construct the automata A'_G and A'_H such that

$$\begin{array}{lll} L(A'_G) &=& L(A_V) \cap g^{-1}(L(A_G)), \\ L(A'_H) &=& L(A_V) \cap h^{-1}(L(A_H)). \end{array}$$

The automaton A_F is now constructed such that $L(A_F) = L(A'_G) \cup L(A'_H)$.

Case 7: $F = \exists x \ G$.

Let $V = \operatorname{free}(G)$ and hence $\operatorname{free}(F) = V \setminus \{x\}$.

Define the homomorphism $f: (\Sigma \times 2^V)^* \to (\Sigma \times 2^{V \setminus \{x\}})^*$ by

$$f(a,S) = (a,S \setminus \{x\}).$$

Construct the automaton A_F such that $L(A_F) = f(L(A_G))$.

Case 8: $F = \exists X G$.

Let V = free(G) and hence $\text{free}(F) = V \setminus \{X\}$.

Define the homomorphism $f: (\Sigma imes 2^V)^* o (\Sigma imes 2^{V \setminus \{X\}})^*$ by

$$f(a,S) = (a,S \setminus \{X\}).$$

Then, construct the automaton A_F such that $L(A_F) = f(L(A_G))$. This concludes the proof of Büchi's theorem.

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