Advanced Logic

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Summer 2025

General comments

Informations concerning the lecture can be found at

https://www.eti.uni-siegen.de/ti/lehre/sommer_2025/advancedlogic/advancedlogic.html

- current version of the slides
- exercise sheets

Literature:

- Schöning: Logik für Informatiker, Spektrum Akademischer Verlag 2013
 - (English Edition: Logic for Computer Scientists, Birkhäuser 2008)
- Ebbinghaus, Flum, Thomas: Einführung in the mathematische Logik, Spektrum Akademischer Verlag (English Edition: Mathematical Logic, Springer 1994)

The tutorials will be organized by Rahul Jain.

Requirements

We assume some knowledge in

- logic, in particular predicate logic; see my lecture Berechenbarkeit und Logik (BuL)
- computability; see again my lecture BuL
- automata theory; see my lecture Formale Sprachen und Automaten (FSA)

Definition (recursively enumerable)

A language $L\subseteq \Sigma^*$ is recursively enumerable, if there is an algorithm with the following properties:

For $x \in \Sigma^*$ we have:

- ▶ If $x \in L$, then the algorithm terminates with input x.
- ▶ If $x \notin L$, then the algorithm does not terminate with input x.

German term: semi-entscheidbar.

Lemma 1

A language $L \subseteq \Sigma^*$ is recursively enumerable if and only if there is a computable total function $f : \mathbb{N} \to \Sigma^*$ with $L = \{f(i) \mid i \in \mathbb{N}\}$.

Definition (decidable and undecidable)

A language $L \subseteq \Sigma^*$ is decidable, if there is an algorithm with the following properties: for all $x \in \Sigma^*$ we have:

- ▶ If $x \in L$, then the algorithm terminates on input x with output "Yes".
- ▶ If $x \notin L$, then the algorithm terminates on input x with output "No".

A language $L \subseteq \Sigma^*$ is undecidable, if L is not decidable.

Theorem

A language $L \subseteq \Sigma^*$ is decidable if and only if L and $\Sigma^* \setminus L$ are both recursively enumerable.

We assume the following notions/definitions:

- Formulas of predicate logic (Formel der Prädikatenlogik) Example: $G = \forall x \exists y (P(x, f(y)) \land \neg Q(g(z, x)))$
- ▶ sentence = formulas without free variable (Aussagen) Example: $F = \forall x \exists y (P(x, y) \land \neg P(f(x), x))$
- ▶ structure (Struktur) $\mathcal{A} = (U_{\mathcal{A}}, I_{\mathcal{A}})$, where $U_{\mathcal{A}}$ is the universe of the structure and $I_{\mathcal{A}}$ is the interpretation function (we write $f^{\mathcal{A}} = I_{\mathcal{A}}(f)$). Example: $U_{\mathcal{A}} = \mathbb{N}$, $f^{\mathcal{A}}(n) = n^2$, $P^{\mathcal{A}} = \{(n, m) \mid n < m\}$.
- Structure A is suitable (passend) for a formula F. Example: A is suitable for F, but not suitable for G.
- $A \models F : F$ evaluates to 1 (= true) in the structure A. Whenever we write $A \models F$, we implicitly assume that A is suitable for F.

A formula F of predicate logic is:

- ▶ satisfiable, if there is a structure A such that $A \models F$ (F is true in the structure A).
- ▶ valid, if $A \models F$ holds for every structure A.

Corollary of Gilmore's theorem

The set of all unsatisfiable formulas of predicate logic is recursively enumerable.

Corollary

The set of all valid formulas of predicate logic is recursively enumerable.

Proof: F is valid if and only if $\neg F$ is unsatisfiable.

Undecidability in predicate logic

We want to prove the following important result:

Church's theorem

The set of valid formulas of predicate logic is undecidable.

Corollary

The set of satisfiable formulas of predicate logic is not recursively enumerable.

Proof: The set of unsatisfiable formulas of predicate logic is recursively enumerable.

If the set of satisfiable formulas of predicate logic would be recursively enumerable, then it would be decidable.

Hence, also the set of unsatisfiable (and hence the set of valid) formulas would be decidable.

We prove Church's theorem by a reduction from the halting problem for register machine programs.

Let R_1, R_2, \ldots be (names for) registers.

Intuition: Every register stores a natural number.

A register machine program (RMP for short) P is a sequence of instructions $A_1; A_2; ...; A_l$, where A_l is the STOP instruction, and for all $1 \le i \le l-1$ the instruction A_i is of one of the following types:

- $ightharpoonup R_i := R_i + 1$ for some $1 \le j \le I$
- $ightharpoonup R_j := R_j 1$ for some $1 \le j \le I$
- ▶ IF $R_i = 0$ THEN k_1 ELSE k_2 for some $1 \le j, k_1, k_2 \le l$.

Note: We assume that only the registers R_1, \ldots, R_l are used in an RMP with l instructions. This is no restriction.

A configuration of P is a tuple $(i, n_1, \dots, n_l) \in \mathbb{N}^{l+1}$ with $1 \le i \le l$.

Intuition: i is the number of the instruction that is executed next and n_j is the current content of register R_j .

For configurations (i, n_1, \ldots, n_l) and (i', n'_1, \ldots, n'_l) we write

$$(i, n_1, \ldots, n_l) \rightarrow_P (i', n'_1, \ldots, n'_l)$$

if and only if $1 \le i \le l-1$ and one of the following cases holds:

- ▶ $A_i = (R_j := R_j + 1)$ for some $1 \le j \le l$, i' = i + 1, $n'_j = n_j + 1$, $n'_k = n_k$ for $k \ne j$.
- ▶ $A_i = (R_j := R_j 1)$ for some $1 \le j \le l$, i' = i + 1, $n_j = n'_j = 0$ or $(n_j > 0, n'_i = n_j 1)$, and $n'_k = n_k$ for $k \ne j$.
- ▶ $A_i = (\text{IF } R_j = 0 \text{ THEN } k_1 \text{ ELSE } k_2) \text{ for some } 1 \leq j, k_1, k_2 \leq l, n'_k = n_k \text{ for all } 1 \leq k \leq l, i' = k_1 \text{ if } n_j = 0, i' = k_2 \text{ if } n_j > 0.$

Example: The following RMP P simulates $R_1 := R_1 + R_2$:

- 1: IF $R_2 = 0$ THEN 5 ELSE 2;
- 2: $R_1 := R_1 + 1$;
- 3: $R_2 := R_2 1$;
- 4: IF $R_1 = 0$ THEN 1 ELSE 1;
- 5: STOP

More precisely: For all numbers n_1 , n_2 we have

$$(1, n_1, n_2, 0, 0, 0) \rightarrow_P^* (5, n_1 + n_2, 0, 0, 0, 0).$$

The configuration is $(1,0,\ldots,0)$ (all registers contain 0, first instruction is executed) is also called starting configuration.

We define

HALT =
$$\{P \mid P = A_1; A_2; ...; A_l \text{ is a RMP with } l \text{ instructions,}$$

 $(1,0,...,0) \rightarrow_P^* (l, n_1,...,n_l) \text{ for } n_1,...,n_l \ge 0\}.$

Register machine programs exactly correspond to GOTO-programs from the lecture BuL.

In BuL we proved that Turing machines and GOTO-programs can simulate each other.

Since the halting problem for Turing machines starting with the empty tape (does a given Turing machine finally terminate when it is started with a tape where every cell contains the blank symbol?) is undecidable, we get:

Theorem (undecidability of the halting problem for RMPs)

The set HALT is undecidable.

Remark: HALT is recursively enumerable: Simulate a given RMP on the starting configuration $(1,0,\ldots,0)$ and stop, if the RMP reaches the STOP-instruction.

We prove Church's theorem by constructing from a given RMP P a formula F_P such that:

$$F_P$$
 is valid $\iff P \in \mathsf{HALT}$

Let $P = A_1; A_2; ...; A_l$ be an RMP.

We fix the following symbols:

- <: binary predicate symbol</p>
- c: constant
- ightharpoonup f, g: unary function symbols
- ightharpoonup R: (I+2)-ary predicate symbol

We define a structure A_P by case distinction:

Case 1:
$$P \notin \mathsf{HALT}$$
:

- ▶ Universe $U_{A_P} = \mathbb{N}$
- \triangleright $<^{\mathcal{A}_P} = \{(n, m) \mid n < m\}$ (the standard order on \mathbb{N})
- $ightharpoonup c^{\mathcal{A}_P}=0$
- $f^{A_P}(n) = n+1, g^{A_P}(n+1) = n, g^{A_P}(0) = 0$
- $R^{A_P} = \{ (s, i, n_1, \dots, n_I) \mid (1, 0, \dots, 0) \to_P^s (i, n_1, \dots, n_I) \}$

Case 2: $P \in \mathsf{HALT}$:

Let t such that $(1,0,\ldots,0) \to_P^t (I,n_1,\ldots,n_I)$ and $e = \max\{t,I\}$.

- ▶ Universe $U_{A_{R}} = \{0, 1, ..., e\}$
- $ightharpoonup < \mathcal{A}_P = \{(n, m) \mid n < m\} \text{ (the standard order on } \{0, 1, \dots, e\})$
- $ightharpoonup c^{\mathcal{A}_P}=0$
- $f^{A_P}(n) = n+1$ for 0 < n < e-1 and $f^{A_P}(e) = e$.
- $g^{A_P}(n+1) = n \text{ for } 0 < n < e-1 \text{ and } g^{A_P}(0) = 0.$
- $R^{A_P} = \{(s, i, n_1, \dots, n_l) \mid 0 \le s \le t, (1, 0, \dots, 0) \to_P^s (i, n_1, \dots, n_l)\}$

In the following we write \overline{m} for the term $f^m(c) = \underbrace{f(f(\cdots f(c)\cdots))}_{m \text{ many}}$.

We define a sentence G_P (in which <, c, f, g and R are used) with the following properties:

- (A) $A_P \models G_P$
- (B) For every model \mathcal{A} of G_P the following holds: If $(1,0,\ldots,0) \to_P^s (i,n_1,\ldots,n_l)$, then:

$$\mathcal{A} \models R(\overline{s}, \overline{i}, \overline{n_1}, \dots, \overline{n_l}) \land \bigwedge_{q=0}^{s-1} \overline{q} < \overline{q+1}.$$

We define $G_P = G_0 \wedge R(\overline{0}, \overline{1}, \overline{0}, \dots, \overline{0}) \wedge G_1 \wedge \dots \wedge G_{l-1}$.

The sentences $G_0, G_1, \ldots, G_{l-1}$ are defined as follows.

G_0 expresses that

- \triangleright < is a strict linear order with smallest element c,
- $\triangleright x < f(x)$ and $g(x) \le x$ for all x,
- for every x, which is not the largest element with respect to <, f(x) is the direct successor of x, and
- for every x with $x \neq c$, g(x) is the direct predecessor of x.

$$\forall x, y, z \ (\neg x < x) \land (x = y \lor x < y \lor y < x) \land ((x < y \land y < z) \rightarrow x < z)$$

$$\land (x = c \lor c < x)$$

$$\land (x = f(x) \lor x < f(x))$$

$$\land (x = g(x) \lor g(x) < x)$$

$$\land (\exists u(x < u) \rightarrow (x < f(x) \land \forall u(x < u \rightarrow (u = f(x) \lor f(x) < u))))$$

 $\wedge \left(\exists u(u < x) \rightarrow (g(x) < x \land \forall u(u < x \rightarrow (u = g(x) \lor u < g(x)))) \right)$

Remark: For every model A of G_0 we have:

- $ightharpoonup \mathcal{A} \models g(c) = c$
- $A \models \forall x \ (\exists u(x < u) \rightarrow g(f(x)) = x)$

$$\mathcal{A} \models g(c) = c$$
: We have $g(c) = c \lor c < g(c)$ and $c = g(c) \lor g(c) < c$.

Hence, if $g(c) \neq c$ then we would obtain $c < g(c) \land g(c) < c$ and hence c < c, which is a contradiction.

$$\mathcal{A} \models \forall x \ (\exists u(x < u) \rightarrow g(f(x)) = x)$$
: Assume that $\exists u(x < u)$.

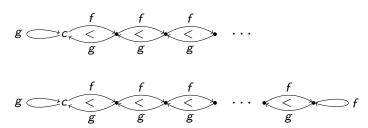
We get $x < f(x) \land \forall u(x < u \rightarrow (u = f(x) \lor f(x) < u)).$

Thus,
$$g(f(x)) < f(x) \land \forall u(u < f(x) \rightarrow (u = g(f(x)) \lor u < g(f(x)))).$$

Since x < f(x) we obtain $x = g(f(x)) \lor x < g(f(x))$.

But x < g(f(x)) < f(x) is not possible (f(x)) = direct successor of x.

Typical models of G_0 :



In particular: A_P is a model of G_0 .

 G_i for $1 \le i \le l-1$ describes the effect of instruction A_i .

Case 1:
$$A_i = (R_j := R_j + 1)$$
. Define

$$G_{i} = \forall x \forall x_{1} \cdots \forall x_{l} \left(R(x, \overline{i}, x_{1}, \dots, x_{l}) \rightarrow (x < f(x) \land R(f(x), \overline{i+1}, x_{1}, \dots, x_{j-1}, f(x_{j}), x_{j+1}, \dots, x_{l})) \right)$$

Case 2:
$$A_i = (R_j := R_j - 1)$$
. Define

$$G_{i} = \forall x \forall x_{1} \cdots \forall x_{l} \left(R(x, \overline{i}, x_{1}, \dots, x_{l}) \rightarrow (x < f(x) \land R(f(x), \overline{i+1}, x_{1}, \dots, x_{j-1}, g(x_{j}), x_{j+1}, \dots, x_{l})) \right)$$

Case 3: $A_i = (IF R_j = 0 THEN k_1 ELSE k_2)$ for a $1 \le j, k_1, k_2 \le l$. Define

$$G_{i} = \forall x \forall x_{1} \cdots \forall x_{l} \left(R(x, \overline{i}, x_{1}, \dots, x_{l}) \rightarrow (x < f(x)) \wedge \left((x_{j} = c \land R(f(x), \overline{k_{1}}, x_{1}, \dots, x_{l})) \vee \left(x_{j} > c \land R(f(x), \overline{k_{2}}, x_{1}, \dots, x_{l})) \right) \right)$$

Statement (A) follows directly from the definition of A_P and G_P :

- $ightharpoonup \mathcal{A}_P$ is a model of G_0 (slide 19).
- ► Since $(1,0,\ldots,0) \to_P^0 (1,0,\ldots,0)$ we have $(0,1,0,\ldots,0) \in R^{A_P}$.

▶ To see that A_P is a model of G_i $(1 \le i \le l-1)$, assume that for instance $A_i = (R_j := R_j + 1)$.

Then for all $s, n_1, \ldots n_l \in U_{\mathcal{A}_P}$ with $(1, 0, \ldots, 0) \rightarrow_P^s (i, n_1, \ldots, n_l)$, i.e., $(s, i, n_1, \ldots, n_l) \in R^{\mathcal{A}_P}$, we have:

- $ightharpoonup s+1, i+1, n_i+1 \in U_{A_P}$
- $(1,0,\ldots,0) \to_P^{s+1} (i+1,n_1,\ldots,n_{j-1},n_j+1,n_{j+1},\ldots,n_l) \text{ and thus } (s+1,i+1,n_1,\ldots,n_{j-1},n_j+1,n_{j+1},\ldots,n_l) \in R^{\mathcal{A}_P}.$

Statement (B) is shown by induction on s.

Induction base: s = 0. Let $(1, 0, ..., 0) \to_P^0 (i, n_1, ..., n_l)$, i.e., i = 1 and $n_1 = n_2 = \cdots = n_l = 0$.

 $\mathcal{A} \models G_P \text{ implies } \mathcal{A} \models R(\overline{0}, \overline{1}, \overline{0}, \dots, \overline{0}), \text{ i.e., } \mathcal{A} \models R(\overline{s}, \overline{i}, \overline{n_1}, \dots, \overline{n_l}).$

Induction step: Let s > 0 and assume that statement (B) holds for s - 1.

Let
$$(1,0,\ldots,0) \to_P^s (i, n_1,\ldots,n_l)$$
.

There are $j \leq l-1, m_1, \ldots, m_l$ with

$$(1,0,\ldots,0)\to_P^{s-1}(j,m_1,\ldots,m_l)\to_P(i,n_1,\ldots,n_l)$$

The induction hypothesis implies

$$\mathcal{A} \models R(\overline{s-1},\overline{j},\overline{m_1},\ldots,\overline{m_l}) \land \bigwedge_{q=0}^{s-2} \overline{q} < \overline{q+1}.$$

We continue with a case distinction with respect to the instruction A_j . We only consider the case that A_j is of the form $R_k := R_k - 1$.

We then have
$$i = j + 1$$
, $n_1 = m_1, \ldots, n_{k-1} = m_{k-1}$, $n_{k+1} = m_{k+1}, \ldots, n_l = m_l$, $(n_k = m_k = 0 \text{ or } m_k > 0 \text{ and } n_k = m_k - 1)$.

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Because of $A \models G_i$ we have:

$$\mathcal{A} \models \forall y, y_1, \dots, y_l \left(R(y, \overline{j}, y_1, \dots, y_l) \rightarrow (y < f(y) \land R(f(y), \overline{j+1}, y_1, \dots, y_{k-1}, g(y_k), y_{k+1}, \dots, y_l)) \right)$$

Since $A \models R(\overline{s-1}, \overline{j}, \overline{m_1}, \dots, \overline{m_l})$, we get

$$\mathcal{A} \models \overline{s-1} < f(\overline{s-1}) \land R(f(\overline{s-1}), \overline{j+1}, \overline{m_1}, \dots, \overline{m_{k-1}}, g(\overline{m_k}), \overline{m_{k+1}}, \dots, \overline{m_l})$$

i.e.,
$$\mathcal{A} \models \overline{s-1} < \overline{s} \land R(\overline{s}, \overline{i}, \overline{n_1}, \dots, \overline{n_{k-1}}, g(\overline{m_k}), \overline{n_{k+1}}, \dots, \overline{n_l}).$$

Because of $A \models \overline{s-1} < \overline{s}$, we have

$$\mathcal{A} \models \bigwedge_{q=0}^{s-1} \overline{q} < \overline{q+1}. \tag{1}$$

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Moreover, $A \models G_0$ implies $A \models g(\overline{m_k}) = \overline{n_k}$:

- ▶ If $n_k = m_k = 0$ then $\overline{m_k} = \overline{n_k} = c$.
 - Since every model of G_0 satisfies g(c) = c (slide 18) we get $A \models g(\overline{m_k}) = \overline{n_k}$.
- ▶ If $m_k > 0$ and $n_k = m_k 1$ then $\overline{m_k} = f(\overline{n_k})$.

Since every model of G_0 satisfies $\forall x \ (\exists u(x < u) \to g(f(x)) = x)$ (slide 18) and $\mathcal{A} \models \overline{n_k} < \overline{n_k + 1} = \overline{m_k}$ by (1), we get

$$A \models g(\overline{m_k}) = g(f(\overline{n_k})) = \overline{n_k}.$$

Therefore we have $\mathcal{A} \models R(\overline{s}, \overline{i}, \overline{n_1}, \dots, \overline{n_l})$.

This shows (A) and (B).

Proof of Church's theorem:

Define
$$F_P = (G_P \rightarrow \exists x \exists x_1 \cdots \exists x_l R(x, \overline{l}, x_1, \dots, x_l)).$$

Claim: F_P is valid $\iff P \in \mathsf{HALT}$.

If F_P is valid, then $A_P \models F_P$.

(A) yields
$$A_P \models \exists x \exists x_1 \cdots \exists x_l R(x, \overline{l}, x_1, \dots, x_l)$$
.

Hence, there are
$$s, n_1, \ldots, n_l \geq 0$$
 with $(s, l, n_1, \ldots, n_l) \in R^{\mathcal{A}_P}$.

We obtain $P \in \mathsf{HALT}$.

Now assume that $P \in HALT$.

Assume that
$$(1,0,\ldots,0) \rightarrow_P^s (I,n_1,\ldots,n_I)$$
.

Let \mathcal{A} be a structure with $\mathcal{A} \models G_P$.

(B) implies
$$\mathcal{A} \models R(\overline{s}, \overline{l}, \overline{n_1}, \dots, \overline{n_l})$$
.

Hence, F_P is valid.

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A formula F is finitely satisfiable if F has a model with a finite universe. If such a model does not exist then F is called finitely unsatisfiable.

Lemma

The set of finitely satisfiable formulas of predicate logic is recursively enumerable.

Proof:

Let A_1, A_2, A_3, \ldots be a systematic enumeration of all finite structures (we assume that the interpretation function I_{A_i} is only defined on those predicate and function symbols that appear in F).

The following algorithm terminates if and only if ${\it F}$ is finitely satisfiable:

$$i := 1$$
;

while true do

if
$$A_i \models F$$
 then STOP else $i := i + 1$

end

A formula F is finitely valid if every finite structure is a model of F.

Example: The formula

$$\forall x \forall y (f(x) = f(y) \rightarrow x = y) \leftrightarrow \forall y \exists x (f(x) = y)$$

is finitely valid but not valid.

Trachtenbrot's theorem

The set of finitely satisfiable formulas is undecidable.

Corollary

The set of finitely unsatisfiable formulas and the set of finitely valid formulas are not recursively enumerable.

Proof of Trachtenbrot's theorem:

We use the construction from the proof of Church's theorem.

Claim: G_P is finitely satisfiable $\iff P \in \mathsf{HALT}$.

(1) Assume that $P \in \mathsf{HALT}$.

Then A_P is finite and $A_P \models G_P$ by statement (A).

Hence, G_P is finitely satisfiable.

(2) Let G_P be finitely satisfiable.

Let A be a finite structure with $A \models G_P$.

Assume that $P \notin HALT$.

Hence, for every $s \ge 0$ there exist i, n_1, \ldots, n_l with $(1, 0, \ldots, 0) \rightarrow_P^s (i, n_1, \ldots, n_l)$.

Statement (B) implies that $A \models \overline{q} < \overline{q+1}$ for all $q \ge 0$.

Since $<^{\mathcal{A}}$ is a strict linear order (because $\mathcal{A} \models G_0$), the set $\{\mathcal{A}(\overline{i}) \mid i \geq 0\}$ must be infinite, which is a contradiction.

Let A be a structure such that the domain of I_A is finite and contains no variables.

Let the domain of I_A consist of $f_1, \ldots, f_n, R_1, \ldots, R_m$.

We identify \mathcal{A} with the tuple $(U_{\mathcal{A}}, f_1^{\mathcal{A}}, \dots, f_n^{\mathcal{A}}, R_1^{\mathcal{A}}, \dots, R_m^{\mathcal{A}})$ for which we also write $(U_{\mathcal{A}}, f_1, \dots, f_n, R_1, \dots, R_m)$.

Definition

The theory of A is the set of formulas

$$\mathsf{Th}(\mathcal{A}) = \{ F \mid F \text{ is a sentence and } \mathcal{A} \models F \}.$$

We are interested in the question whether a given structure has a decidable theory.

Theorem 2

Let A be an arbitrary structure. Then, $\mathsf{Th}(A)$ is decidable if and only if $\mathsf{Th}(A)$ is recursively enumerable.

Proof: Let $\mathsf{Th}(\mathcal{A})$ be recursively enumerable and let F be an arbitrary sentence.

We either have $F \in \mathsf{Th}(\mathcal{A})$ or $\neg F \in \mathsf{Th}(\mathcal{A})$.

Therefore we can enumerate Th(A) until we either produce F or $\neg F$.

Exactly one of the formulas F or $\neg F$ will be produced after a finite number of steps.

For the question whether a theory is decidable, we can restrict to so-called relational structures.

A structure $\mathcal{A} = (A, f_1, \dots, f_n, R_1, \dots, R_m)$ is relational if n = 0.

For an arbitrary structure $\mathcal{A}=(A,f_1,\ldots,f_n,R_1,\ldots,R_m)$ we define

$$\mathcal{A}_{\mathsf{rel}} = (A, P_1, \dots, P_n, R_1, \dots, R_m),$$

where $P_i = \{(a_1, \dots, a_k, a) \in A^{k+1} \mid f_i(a_1, \dots, a_k) = a\}.$

Lemma 3

 $\mathsf{Th}(\mathcal{A})$ is decidable $\iff \mathsf{Th}(\mathcal{A}_{rel})$ is decidable.

Proof: For \longleftarrow we construct from a sentence F that contains the symbols f_i, R_j a sentence F' that only contains the symbols P_i, R_j and such that:

$$A \models F \iff A_{\mathsf{rel}} \models F'$$

Consider a subformula $R_i(t_1, ..., t_k)$ in F, where $t_1, ..., t_k$ are terms, and replace it by

$$\exists x_1 \cdots \exists x_k \ (R_i(x_1, \ldots, x_k) \land \bigwedge_{i=1}^k x_i = t_i).$$

for new variables x_1, \ldots, x_k .

We now replace equations $y = f_j(s_1, \ldots, s_l)$ with $l \ge 0$ by

$$\exists y_1 \cdots \exists y_l \ (P_j(y_1, \ldots, y_l, y) \land \bigwedge_{i=1}^l y_i = s_i)$$

for new variables y_1, \ldots, y_l until only equations of the form y = y' for variables y, y' remain.

The direction \Longrightarrow from the lemma is very easy (Excercise).

Undecidability of arithmetics

Theorem (Gödel 1931)

 $\mathsf{Th}(\mathbb{N},+,\cdot)$ is undecidable.

Corollary

 $\mathsf{Th}(\mathbb{N},+,\cdot)$ is not recursively enumerable.

For the proof we reduce the set HALT of terminating RMPs to $\mathsf{Th}(\mathbb{N},+,\cdot)$.

We follow the proof from the book of Ebbinghaus, Flum and Thomas.

In order make the proof less technical we consider $\mathsf{Th}(\mathbb{N},+,\cdot,s,0)$ with s(n)=n+1.

Undecidability of arithmetics

We then have: $\mathsf{Th}(\mathbb{N},+,\cdot,s,0)$ decidable $\iff \mathsf{Th}(\mathbb{N},+,\cdot)$ decidable:

- ▶ If $Th(\mathbb{N}, +, \cdot, s, 0)$ is decidable, then clearly $Th(\mathbb{N}, +, \cdot)$ is decidable.
- Assume that $\mathsf{Th}(\mathbb{N},+,\cdot)$ is decidable.

We transform a sentence F that contains $+, \cdot, s, 0$ into a sentence F' that only contains $+, \cdot$ and such that $F \in \mathsf{Th}(\mathbb{N}, +, \cdot, s, 0)$ if and only if $F' \in \mathsf{Th}(\mathbb{N}, +, \cdot)$.

Step 1: Replace F by

$$\exists x_0 \ \exists x_1 (x_0 + x_0 = x_0 \land x_1 \cdot x_1 = x_1 \land x_1 \neq x_0 \land F)$$

Step 2: Replace in the resulting sentence every occurrence of the constant 0 by x_0 and every term s(t) by $t + x_1$.

Now assume that $P=A_1;A_2;\cdots;A_I$ is an RMP which uses the registers R_1,\ldots,R_I .

We construct an arithmetic formula F_P with the free variables x, x_1, \ldots, x_l such that for all $1 \le i \le l$ and all $n_1, \ldots, n_l \in \mathbb{N}$ the following statements are equivalent:

- \triangleright $(\mathbb{N}, +, \cdot, s, 0)_{[x/i, x_1/n_1, \dots, x_l/n_l]} \models F_P$
- $(1,0,\ldots,0)\to_P^* (i,n_1,\ldots,n_l)$

This implies $P \in \mathsf{HALT} \iff (\mathbb{N}, +, \cdot, s, 0) \models \exists x_1 \cdots \exists x_l \ F_P[x/s^l(0)].$

Intuitively, F_P expresses the following:

There exists $t \ge 0$ and configurations C_0, C_1, \ldots, C_t with:

- $ightharpoonup C_0 = (1, 0, ..., 0)$
- $ightharpoonup C_t = (x, x_1, \dots, x_l)$
- $ightharpoonup C_{i o P} C_{i+1}$ for all 0 < i < t-1

We encode the (I+1)-tuples C_0, C_1, \ldots, C_t by an $(t+1) \cdot (I+1)$ -tuple. It remains to express the following, where k = I+1:

There exist $t \ge 0$ and a tuple

$$(y_0, y_1, \dots, y_{k-1}, y_k, y_{k+1}, \dots, y_{2k-1}, \dots, y_{tk}, y_{tk+1}, \dots, y_{tk+k-1})$$
 with:

- $y_0 = 1, y_1 = 0, \dots, y_{k-1} = 0$
- $\bigvee y_{tk} = x, \ y_{tk+1} = x_1, \dots, y_{tk+k-1} = x_k$
- $(y_{ik}, \dots, y_{ik+k-1}) \to_P (y_{(i+1)k}, \dots, y_{(i+1)+k-1})$ for all $0 \le i \le t-1$

If one tries to express this with an arithmetic formula, one encounters the problem that one cannot quantify over arbitrary sequences of numbers in predicate logic $(\exists y \exists x_1 \exists x_2 \cdots \exists x_y \text{ is not allowed})$.

In order to simulate quantification of sequences of arbitrary length, we need Gödel's β -function.

Lemma

There is a function $\beta: \mathbb{N}^3 \to \mathbb{N}$ with:

- ▶ For every sequence $(a_0, ..., a_q)$ over $\mathbb N$ there exist $p, r \in \mathbb N$ such that $\beta(p, r, i) = a_i$ for all $0 \le i \le q$.
- ► There is an arithmetic formula B with free variables v, x, y, z such that for all $p, r, i, a \in \mathbb{N}$ we have:

$$(\mathbb{N}, +, \cdot, s, 0)_{[v/p, \times/r, v/i, z/a]} \models B \iff \beta(p, r, i) = a$$

One also says that β is arithmetically definable.

Proof of the lemma:

Let (a_0, \ldots, a_q) be an arbitrary sequence over \mathbb{N} .

Let p be a prime number with p > q and $p > a_i$ for all i.

Furthermore, define

$$r = 0p^{0} + a_{0}p^{1} + 1p^{2} + a_{1}p^{3} + \dots + ip^{2i} + a_{i}p^{2i+1} + \dots + qp^{2q} + a_{q}p^{2q+1}.$$

In other words: $(0, a_0, 1, a_1, \dots, i, a_i, \dots, q, a_q)$ is the base-p expansion of r (least significant digit on the left).

Note: since p is prime, we have the following for every $x \in \mathbb{N}$:

There exists $m \in \mathbb{N}$ with $x = p^{2m}$ if and only if:

- \triangleright x is a square $(\exists y : x = y^2)$ and
- ▶ for all $d \ge 2$ with d|x we have p|d.

Here, x|y stands for "x divides y" $(\exists z : x \cdot z = y)$.

Claim 1: For all $a \in \mathbb{N}$ and all $0 \le i \le q$ we have: $a = a_i$ if and only if there exist $b_0, b_1, b_2 \in \mathbb{N}$ with:

- (a) $r = b_0 + b_1(i + ap + b_2p^2)$
- (b) a < p
- (c) $b_0 < b_1$
- (d) b_1 is a square and p|d holds for all $d \ge 2$ with $d|b_1$. (equivalently: $\exists m : b_1 = p^{2m}$)

 \implies : If $a = a_i$ then we can choose b_0, b_1, b_2 as follows:

$$b_0 = 0p^0 + a_0p^1 + 1p^2 + a_1p^3 + \dots + (i-1)p^{2i-2} + a_{i-1}p^{2i-1}$$

$$b_1 = p^{2i}$$

$$b_2 = (i+1) + a_{i+1}p + \dots + qp^{2(q-i-1)} + a_qp^{2(q-i)-1}$$

 \Leftarrow : Assume that (a)-(d) hold, i.e.,

$$r = b_0 + b_1(i + ap + b_2p^2)$$

= $b_0 + ip^{2m} + ap^{2m+1} + p^{2m+2}b_2$.

where $b_0 < b_1 = p^{2m}$, a < p and i < p.

Comparing this with

$$r = 0p^{0} + a_{0}p^{1} + 1p^{2} + a_{1}p^{3} + \dots + ip^{2i} + a_{i}p^{2i+1} + \dots + qp^{2q} + a_{q}p^{2q+1}$$

and using the uniqueness of the base-p expansion of numbers yields m = i and $a = a_i$.

This shows Claim 1.

We can now define Gödel's β -function:

For all $p, r, i \in \mathbb{N}$ we define $\beta(p, r, i)$ as

- (i) the smallest number $a \in \mathbb{N}$ such that there are $b_0, b_1, b_2 \in \mathbb{N}$ with the properties (a)–(d) from Slide 41, respectively
- (ii) 0 if numbers $a,b_0,b_1,b_2\in\mathbb{N}$ with the properties (a)–(d) do not exist.

Remarks:

- ► The choice of 0 in (ii) is not important (any other number would be also fine).
- ▶ Also the choice of the minimum for a in point (i) is not important. It is only important that we select a unique number a having the properties (a)–(d) (one could for instance take the largest number a with these properties).

Claim 2: For every sequence (a_0, \ldots, a_q) over $\mathbb N$ there exist $p, r \in \mathbb N$ such that $\beta(p, r, i) = a_i$ holds for all $0 \le i \le q$.

Let (a_0, \ldots, a_q) be a sequence over \mathbb{N} .

Define p and r as on Slide 40.

Take an arbitrary number $0 \le i \le q$.

Due to Claim 1 (direction \Rightarrow) there are $a, b_0, b_1, b_2 \in \mathbb{N}$ such that (a)–(d) hold (take $a = a_i$ for this).

By definition of the function β there are $b_0, b_1, b_2 \in \mathbb{N}$ such that (a)–(d) also hold with $a = \beta(p, r, i)$.

By Claim 1 (direction \Leftarrow) we must have $\beta(p, r, i) = a_i$.

Claim 3: β is arithmetically definable.

All four properties (a)-(d) on Slide 41 are arithmetically definable.

For instance, property (d) can be expressed by the formula

$$\exists x: b_1 = x^2 \land \forall x: ((\exists y: s(s(x)) \cdot y = b_1) \rightarrow \exists z: (p \cdot z = s(s(x))).$$

Here, s(s(x)) stands for the number d in property (d) (the two applications of the successor function s ensure that $s(s(x)) \ge 2$ holds).

With Claims 2 and 3, the proof of the lemma is complete.

We can now conclude the undecidability proof for arithmetics.

We have to express the following statement (with free variables x, x_1, \dots, x_l) by an arithmetic formula:

There is a number t and a tuple

$$(y_0, y_1, \dots, y_{k-1}, y_k, y_{k+1}, \dots, y_{2k-1}, \dots, y_{tk}, y_{tk+1}, \dots, y_{tk+k-1})$$

such that:

- $y_0 = 1, y_1 = 0, \dots, y_{k-1} = 0$
- $y_{tk} = x$, $y_{tk+1} = x_1, \dots, y_{tk+k-1} = x_l$
- $(y_{ik}, \dots, y_{ik+k-1}) \to_P (y_{(i+1)k}, \dots, y_{(i+1)k+k-1})$ for all $0 \le i \le t-1$

Note: k = l + 1 is a constant that is determined by the RMP P.

This is equivalent to: there are t, p, r with:

- $\beta(p,r,0) = 1$, $\beta(p,r,1) = 0$, ..., $\beta(p,r,k-1) = 0$
- $\beta(p, r, tk) = x, \ \beta(p, r, tk + 1) = x_1, \dots, \beta(p, r, tk + k 1) = x_1$
- ▶ for all $0 \le i \le t 1$ the following holds:

$$\left(\beta(p,r,ik),\ldots,\beta(p,r,ik+k-1)\right)\to_{P}$$
$$\left(\beta(p,r,(i+1)k),\ldots,\beta(p,r,(i+1)k+k-1)\right)$$

It is straightforward to construct an arithmetic formula for

$$(y, y_1, \ldots, y_l) \rightarrow_P (z, z_1, \ldots, z_l)$$

as a disjunction over all instructions A_i of the RMP P (excercise).

Automatic structures

In this section we will introduce automatic structures.

Our main results concerning automatic structures are:

- ▶ Every automatic structure has a decidable theory.
- \triangleright (\mathbb{N} , +) is automatic.
- \blacktriangleright (\mathbb{Q}, \leq) is automatic.

Convolution of words

Let $n \geq 1$, let Σ be a finite alphabet and let $\# \not\in \Sigma$ be a dummy symbol.

Let $\Sigma_{\#} = \Sigma \cup \{\#\}$ in the following.

For $n \geq 1$ we consider the alphabet $\Sigma^n_\#$ that contains all n-tuples over $\Sigma_\#.$

For words $w_1, w_2 \dots, w_n \in \Sigma^*$ we define the convolution

$$w_1 \otimes w_2 \otimes \cdots \otimes w_n \in \left(\Sigma_\#^n\right)^*$$

as follows:

- ▶ Let $w_i = a_{i,1}a_{i,2}\cdots a_{i,\ell_i}$, (thus, $\ell_i = |w_i|$).
- $\blacktriangleright \text{ Let } \ell = \max\{\ell_1, \dots, \ell_n\}.$
- ▶ For all $1 \le i \le n$ and $\ell_i < j \le \ell$ let $a_{i,j} = \#$.
- $w_1 \otimes w_2 \otimes \cdots \otimes w_n := (a_{1,1}, \ldots, a_{n,1})(a_{1,2}, \ldots, a_{n,2}) \cdots (a_{1,\ell}, \ldots, a_{n,\ell}).$

Convolution of words

Using the convolution, we encode an *n*-tuple $(w_1, w_2 \dots, w_n)$ of words by the single word $w_1 \otimes w_2 \otimes \cdots \otimes w_n$.

Examples:

$$abba \otimes babaaa = (a, b)(b, a)(b, b)(a, a)(\#, a)(\#, a)$$

 $abcd \otimes bcdab \otimes a = (a, b, a)(b, c, \#)(c, d, \#)(d, a, \#)(\#, b, \#)$

Note: The tuple $(\#, \#, \dots, \#)$ does not appear in a convolution.

In particular: $\varepsilon \otimes \varepsilon \otimes \cdots \otimes \varepsilon = \varepsilon$ (multiple convolution of the empty word yields the empty word)

A synchronous *n*-tape automaton A over the alphabet Σ is an arbitrary finite automaton over the alphabet $\Sigma_{\#}^{n}$.

Hence, A accepts a language $L(A) \subseteq (\Sigma_{\#}^{n})^{*}$.

Note: for an automaton A we denote the accepted language with L(A) whereas in my lecture FSA I use T(A).

The synchronous n-tape automaton accepts the n-ary relation

$$K(A) := \{(w_1, \ldots, w_n) \mid w_1, \ldots, w_n \in \Sigma^*, w_1 \otimes \cdots \otimes w_n \in L(A)\}.$$

An *n*-ary relation R over Σ^* is synchronously rational if there is a synchronous n-tape automaton A with K(A) = R.

Words in L(A) that do not belong to $\{w_1 \otimes \cdots \otimes w_n \mid w_1, \ldots, w_n \in \Sigma^*\}$ have no influence on the relation K(A) (they are garbage in some sense).

On the other hand, from A one can easily construct a synchronous n-tape automaton B with $L(B) = L(A) \cap \{w_1 \otimes \cdots \otimes w_n \mid w_1, \ldots, w_n \in \Sigma^*\}.$

Note: $\{w_1 \otimes \cdots \otimes w_n \mid w_1, \dots, w_n \in \Sigma^*\} \subseteq (\Sigma^n_\#)^*$ is regular.

Illustration of a synchronous 2-tape automaton:

V	b_0	b_1	<i>b</i> ₂	•••	b_{m-1}	b _m	#		#	
и	<i>a</i> ₀	a_1	a ₂	• • •	a_{m-1}	a _m	a_{m+1}	• • •	a _n	

Words in L(A) that do not belong to $\{w_1 \otimes \cdots \otimes w_n \mid w_1, \ldots, w_n \in \Sigma^*\}$ have no influence on the relation K(A) (they are garbage in some sense).

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Note: $\{w_1 \otimes \cdots \otimes w_n \mid w_1, \ldots, w_n \in \Sigma^*\} \subseteq (\Sigma^n_\#)^*$ is regular.

Illustration of a synchronous 2-tape automaton:

	90	_							
V	<i>b</i> ₀	b_1	<i>b</i> ₂		b_{m-1}	b _m	#		#
и	<i>a</i> ₀	a ₁	a ₂	•••	a_{m-1}	a _m	a_{m+1}	• • • •	a _n

a

Words in L(A) that do not belong to $\{w_1 \otimes \cdots \otimes w_n \mid w_1, \ldots, w_n \in \Sigma^*\}$ have no influence on the relation K(A) (they are garbage in some sense).

On the other hand, from A one can easily construct a synchronous n-tape automaton B with $L(B) = L(A) \cap \{w_1 \otimes \cdots \otimes w_n \mid w_1, \ldots, w_n \in \Sigma^*\}.$

Note: $\{w_1 \otimes \cdots \otimes w_n \mid w_1, \ldots, w_n \in \Sigma^*\} \subseteq (\Sigma^n_\#)^*$ is regular.

Illustration of a synchronous 2-tape automaton:

		q_1						
V	b_0	b_1	<i>b</i> ₂	 b_{m-1}	b _m	#		#
и	a ₀	a_1	a ₂	 a_{m-1}	a _m	$\overline{a_{m+1}}$	• • • •	a _n

Words in L(A) that do not belong to $\{w_1 \otimes \cdots \otimes w_n \mid w_1, \ldots, w_n \in \Sigma^*\}$ have no influence on the relation K(A) (they are garbage in some sense).

On the other hand, from A one can easily construct a synchronous n-tape automaton B with $L(B) = L(A) \cap \{w_1 \otimes \cdots \otimes w_n \mid w_1, \ldots, w_n \in \Sigma^*\}.$

Note: $\{w_1 \otimes \cdots \otimes w_n \mid w_1, \ldots, w_n \in \Sigma^*\} \subseteq (\Sigma^n_\#)^*$ is regular.

Illustration of a synchronous 2-tape automaton:

			42				
V	b_0	b_1	<i>b</i> ₂	 b_{m-1}	b _m	#	 #
и	a ₀	a ₁	<i>a</i> ₂	 a_{m-1}	a _m	a_{m+1}	 a _n

Words in L(A) that do not belong to $\{w_1 \otimes \cdots \otimes w_n \mid w_1, \ldots, w_n \in \Sigma^*\}$ have no influence on the relation K(A) (they are garbage in some sense).

On the other hand, from A one can easily construct a synchronous n-tape automaton B with $L(B) = L(A) \cap \{w_1 \otimes \cdots \otimes w_n \mid w_1, \ldots, w_n \in \Sigma^*\}.$

Note: $\{w_1 \otimes \cdots \otimes w_n \mid w_1, \dots, w_n \in \Sigma^*\} \subseteq (\Sigma^n_\#)^*$ is regular.

Illustration of a synchronous 2-tape automaton:

						Чт	_		
V	b_0	b_1	<i>b</i> ₂	•••	b_{m-1}	b _m	#	 #	
и	a ₀	a_1	a ₂	•••	a_{m-1}	a _m	a_{m+1}	 a _n	

a

Words in L(A) that do not belong to $\{w_1 \otimes \cdots \otimes w_n \mid w_1, \ldots, w_n \in \Sigma^*\}$ have no influence on the relation K(A) (they are garbage in some sense).

On the other hand, from A one can easily construct a synchronous n-tape automaton B with $L(B) = L(A) \cap \{w_1 \otimes \cdots \otimes w_n \mid w_1, \ldots, w_n \in \Sigma^*\}.$

Note: $\{w_1 \otimes \cdots \otimes w_n \mid w_1, \dots, w_n \in \Sigma^*\} \subseteq (\Sigma^n_\#)^*$ is regular.

Illustration of a synchronous 2-tape automaton:

	<u>9m+1</u>								
V	b_0	b_1	<i>b</i> ₂	• • •	b_{m-1}	b _m	#		#
и	a ₀	a_1	a ₂	•••	a_{m-1}	a _m	a_{m+1}		a _n

Words in L(A) that do not belong to $\{w_1 \otimes \cdots \otimes w_n \mid w_1, \ldots, w_n \in \Sigma^*\}$ have no influence on the relation K(A) (they are garbage in some sense).

On the other hand, from A one can easily construct a synchronous n-tape automaton B with $L(B) = L(A) \cap \{w_1 \otimes \cdots \otimes w_n \mid w_1, \ldots, w_n \in \Sigma^*\}.$

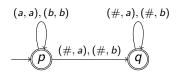
Note: $\{w_1 \otimes \cdots \otimes w_n \mid w_1, \dots, w_n \in \Sigma^*\} \subseteq (\Sigma^n_\#)^*$ is regular.

Illustration of a synchronous 2-tape automaton:

								7111
V	b_0	b_1	<i>b</i> ₂	•••	b_{m-1}	b _m	#	 #
и	a_0	a_1	a ₂	•••	a_{m-1}	a _m	a_{m+1}	 a _n

 a_n

Example: Let *A* be the following synchronous 2-tape automaton:



We have $K(A) = \{(u, v) \mid u, v \in \{a, b\}^*, \exists w \in \{a, b\}^* : v = uw\}$ (the prefix relation).

On the other hand, the suffix relation $\{(u,v) \mid \exists w \in \{a,b\}^* : v = wu\}$ is not synchronously rational.

Automatic structures

Definition

A relational structure $\mathcal{A}=(A,R_1,\ldots,R_m)$ (with R_i an n_i -ary relation) is automatic if there exist a finite alphabet Σ , a finite automaton B over the alphabet Σ , and synchronous n_i -tape automata B_i over the alphabet Σ $(1 \leq i \leq m)$ such that:

- ightharpoonup L(B) = A
- $ightharpoonup K(B_i) = R_i \text{ for } 1 \leq i \leq m$

Definition

A structure $\mathcal A$ is automatically presentable if $\mathcal A$ is isomorphic to an automatic structure.

Automatic structures

Excursion: isomorphic structures

Let $\mathcal{A}=(A,R_1,\ldots,R_m)$ and $\mathcal{B}=(B,P_1,\ldots,P_m)$ be relational structures, where R_i and P_i are both n_i -ary (for all $1\leq i\leq m$).

We say that A and B are isomorphic if there is a bijection $h: A \to B$ such that for all $1 \le i \le m$ and all tuples $(a_1, \ldots, a_{n_i}) \in A^{n_i}$ we have:

$$(a_1,\ldots,a_{n_i})\in R_i\iff (h(a_1),\ldots,h(a_{n_i}))\in P_i.$$

Intuitively: \mathcal{B} can be obtained from \mathcal{A} by renaming the elements from the universe of \mathcal{A} .

If \mathcal{A} and \mathcal{B} are isomorph then $\mathsf{Th}(\mathcal{A})$ is decidable if and only if $\mathsf{Th}(\mathcal{B})$ is decidable (predicate logic cannot refer to the names of elements in the universe).

Theorem

$$(\mathbb{N},+)$$
 with $+=\{(a,b,c)\mid a+b=c\}$ is automatically presentable.

Proof: Let A be a finite automaton with $L(A) = \{0\} \cup \{0,1\}^*1$.

Then, the following function $h: L(A) \to \mathbb{N}$ is a bijection:

$$h(0) = 0$$

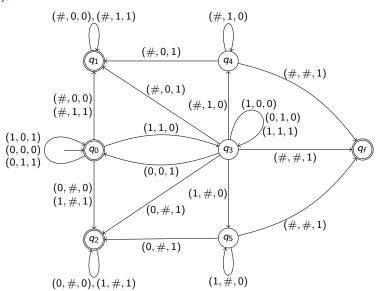
 $h(a_0a_1\cdots a_{n-1}1) = \sum_{i=0}^{n-1} a_i 2^i + 2^n$

Let B_+ be the synchronous 3-tape automaton from the next slide.

B₊ "almost" recognizes the relation

$$\{(u, v, w) \in L(A)^3 \mid h(u) + h(v) = h(w)\}.$$

We have for instance $(00,0000,0000) \in K(B_+)$.



Let A_+ be a synchronous 3-tape automaton with

$$L(A_+) = L(B_+) \cap \{u \otimes v \otimes w \mid u, v, w \in L(A)\}.$$

We then get
$$K(A_+) = \{(u, v, w) \in L(A)^3 \mid h(u) + h(v) = h(w)\}.$$

Intuition: The automaton from Slide 57 checks with the school method for addition whether the number on tape 3 is the sum of the numbers on tapes 1 and 2.

For this, the automaton stores the current carry in its state.

States q_0, q_1, q_2 correspond to carry 0 whereas states q_3, q_4, q_5 correspond to carry 1.

Three states are needed since the numbers on tapes 1 and 2 may have a different bit lengths.

States q_1, q_4 (q_2, q_5) are needed for the situation where the number on tape 1 (2) is shorter than the number on tape 2 (1).

State q_f is a failure state.

One can slightly extend the theorem on Slide 56: For every p>1 the structure $(\mathbb{N},+,|_p)$ with

$$x \mid_{p} y \iff \exists n, k \in \mathbb{N} : x = p^{n} \land y = k \cdot x$$

is automatically presentable.

Linear orders

Our second example for an automatic structure is a linear order.

Recall (from the lecture DMI): a linear order is a structure (A, R), where R is a binary relation with the following properties:

- $\forall a \in A : (a, a) \in R (R \text{ is reflexive})$
- $ightharpoonup \forall a,b \in A: (a,b) \in R \land (b,a) \in R \rightarrow a = b \ (R \ \text{is anti-symmetric})$
- ▶ $\forall a, b, c \in A : (a, b) \in R \land (b, c) \in R \rightarrow (a, c) \in R \ (R \text{ is transitive})$
- $\forall a, b \in A : (a, b) \in R \lor (b, a) \in R (R \text{ is linear})$

Instead of R we denote the binary relation of a linear order always with \leq (possibly with an index).

An element $a \in A$ is a smallest (resp., largest) element of the linear order (A, \leq) if: $\forall b \in A : a \leq b$ (resp., $\forall b \in A : b \leq a$).

Linear orders

Theorem

The linear order (\mathbb{Q}, \leq) (where \leq is the standard order on \mathbb{Q}) is automatically presentable.

For the proof we use a famous theorem of Cantor.

It uses another property of linear orders (we write x < y for $x \le y \land x \ne y$): A linear order (A, \le) is dense if:

$$\forall x \forall y (x < y \rightarrow \exists z (x < z < y)).$$

Intuitively: between two different elements of *A* there is always a third element.

Cantor's theorem

Let (A, \leq_A) and (B, \leq_B) be countable dense linear orders without a smallest and largest element. Then (A, \leq_A) and (B, \leq_B) are isomorphic.

Proof of Cantor's theorem:

We construct enumerations

$$a_1, a_2, a_3, a_4, \ldots$$
 and $b_1, b_2, b_3, b_4, \ldots$

with the following properties:

- $ightharpoonup a_i
 eq a_i$ and $b_i
 eq b_i$ for i
 eq j
- ► $A = \{a_i \mid i \ge 1\}$ and $B = \{b_i \mid i \ge 1\}$
- $ightharpoonup a_i <_A a_i$ if and only if $b_i <_B b_i$ for all i, j.

Then, $f: A \to B$ with $f(a_i) = b_i$ is an isomorphism.

Since A and B are countable and infinite, we can enumerate these sets:

$$A = \{x_1, x_2, x_3, \ldots\}$$
 and $B = \{y_1, y_2, y_3, \ldots\}$

The following "algorithm" constructs enumerations with the above properties:

$$L_A := [x_1, x_2, x_3, \ldots]; \ L_B := [y_1, y_2, y_3, \ldots]$$
 for all $i \ge 1$ do $(a_1, \ldots a_{i-1}, b_1, \ldots b_{i-1})$ are already defined) if i is odd then

let x be the first element from L_A

remove x from the list L_A

let y be an element from L_B with the following properties:

$$\forall 1 \leq j \leq i-1: a_j <_A x \longleftrightarrow b_j <_B y$$
 remove y from the list L_B

$$a_i := x; \ b_i := y$$

else

let y be the first element from L_B

remove y from the list L_B

let x be an element from L_A with the following properties:

$$\forall 1 \le j \le i - 1 : a_j <_A x \longleftrightarrow b_j <_B y \tag{\ddagger}$$

remove x from the list L_A

$$a_i := x$$
; $b_i := y$

endt

Markus Lohrey (Universität Siegen)

Remarks:

- ▶ The element y with the property (\dagger) exists, since (B, \leq_B) is dense and neither has a smallest nor largest element.
 - This ensures that we find for x an element y that has the same position relative to b_1, \ldots, b_{i-1} as x to a_1, \ldots, a_{i-1} .
 - For the same reason, the element x with the property (\ddagger) exists.
- Since the correspondence $a_i \mapsto b_i$ must be bijective, we have to pair every element from the list L_A with exactly one element from the list L_B . Thereby, we also have to ensure that every element from the list L_B is paired.

This will be enforced by the case distinction between i odd and i even.

Illustration of the proof of Cantor's theorem:

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$$L_A := [x_1, x_2, x_3, x_4, x_5, x_6, x_7, \ldots]; \ L_B := [y_1, y_2, y_3, y_4, y_5, y_6, y_7, \ldots]$$

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 x_1

$$L_A := [x_1, x_2, x_3, x_4, x_5, x_6, x_7, \ldots]; \ L_B := [y_1, y_2, y_3, y_4, y_5, y_6, y_7, \ldots]$$



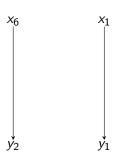
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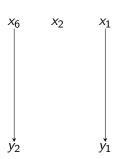


*y*₂

$$L_A := [x_1, x_2, x_3, x_4, x_5, x_6, x_7, \ldots]; \ L_B := [y_1, y_2, y_3, y_4, y_5, y_6, y_7, \ldots]$$



$$L_A := [x_1, x_2, x_3, x_4, x_5, x_6, x_7, \ldots]; \ L_B := [y_1, y_2, y_3, y_4, y_5, y_6, y_7, \ldots]$$



$$L_A := [x_1, x_2, x_3, x_4, x_5, x_6, x_7, \ldots]; \ L_B := [y_1, y_2, y_3, y_4, y_5, y_6, y_7, \ldots]$$

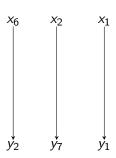
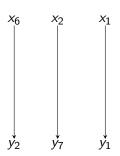


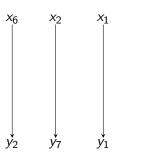
Illustration of the proof of Cantor's theorem:

$$L_A := [x_1, x_2, x_3, x_4, x_5, x_6, x_7, \ldots]; \ L_B := [y_1, y_2, y_3, y_4, y_5, y_6, y_7, \ldots]$$



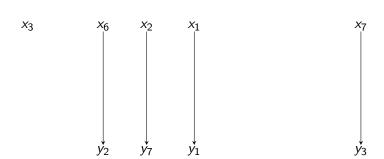
*У*3

$$L_A := [x_1, x_2, x_3, x_4, x_5, x_6, x_7, \ldots]; \ L_B := [y_1, y_2, y_3, y_4, y_5, y_6, y_7, \ldots]$$

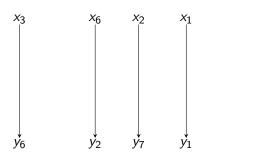




$$L_A := [x_1, x_2, x_3, x_4, x_5, x_6, x_7, \ldots]; \ L_B := [y_1, y_2, y_3, y_4, y_5, y_6, y_7, \ldots]$$



$$L_A := [x_1, x_2, x_3, x_4, x_5, x_6, x_7, \ldots]; \ L_B := [y_1, y_2, y_3, y_4, y_5, y_6, y_7, \ldots]$$





(\mathbb{Q}, \leq) is automatically presentable

Proof that (\mathbb{Q}, \leq) is automatically presentable:

Due to Cantor's theorem, it suffices to construct a countable dense automatic linear order which neither has a smallest nor a largest element.

Let
$$L = \{0, 1\}^*1$$
.

Let \leq be the lexicographic order on L. That means, for $x, y \in L$ we have $x \leq y$ if and only if one of the following cases holds:

- ▶ There exists $u \in \{0,1\}^*$ with y = xu (x is a prefix of y)
- ▶ There exist $z, u, v \in \{0, 1\}^*$ with x = z0u and y = z1v.

Then (L, \leq) is a linear order (easy to check).

 \blacktriangleright (L, \leq) has no largest element:

Let $x \in L$ be arbitrary. Then $x < x1 \in L$.

(\mathbb{Q}, \leq) is automatically presentable

- ▶ (L, \leq) has no smallest element: Let $x = u1 \in L$ be arbitrary. Then u01 < u1 = x
- \blacktriangleright (L, \leq) is dense:

Let $x, y \in L$ with x < y be arbitrary.

Case 1: x = u1, y = u1v1:

Then we have $x = u1 < u10^{|v|+1}1 < u1v1 = y$.

Case 2: x = u0v1, y = u1w:

Then we have $x = u0v1 < u01^{|v|+2} < u1w = y$.

 \blacktriangleright (L, \leq) is automatic: easy excercise

Structures that are not automatically presentable

For the following structures one can show that they are not automatically presentable:

- $ightharpoonup (\mathbb{R},+)$ (because every automatic structure is countable)
- every structure with an undecidable theory (see next slide).
 Examples for this:
 - \blacktriangleright (N, +, ·) (Gödel's theorem)
 - (Σ^*, \circ) (the free monoid over Σ) for $|\Sigma| > 1$ (Quine 1946)
- \blacktriangleright (N,·) and (N,|)
- $ightharpoonup (\mathbb{Q},+)$ (Tsankov 2009)

Our main result on automatic structures is:

Theorem 4 (Khoussainov, Nerode 1994)

For every automatically presentable structure A, Th(A) is decidable.

Corollary (Presburger 1929)

 $\mathsf{Th}(\mathbb{N},+)$ is decidable.

Corollary

 $\mathsf{Th}(\mathbb{Q},\leq)$ is decidable.

For the proof of the theorem of Khoussainov and Nerode we need some facts on regular languages.

From FSA we know that the regular languages are closed under all boolean operations (complement, union, intersection).

Moreover: From finite automata A and B over an input alphabet Γ one can construct finite automata for the languages $\Gamma^* \setminus L(A)$, $L(A) \cap L(B)$ and $L(A) \cup L(B)$.

We need two further closure properties for the regular languages.

A homomorphism is a function $h: \Gamma^* \to \Sigma^*$ such that:

- ightharpoonup Γ and Σ are finite alphabets.
- $h(\varepsilon) = \varepsilon$ (the empty word is mapped to the empty word)
- ▶ For all words $u, v \in \Gamma^*$ we have h(uv) = h(u)h(v).

In particular, for every word $u = a_1 a_2 \cdots a_n \ (a_1, \dots, a_n \in \Gamma)$:

$$h(a_1a_2\cdots a_n)=h(a_1)h(a_2)\cdots h(a_n).$$

In order to specify a homomorphism $h: \Gamma^* \to \Sigma^*$, it suffices to specify all words h(a) for $a \in \Gamma$.

Example: Let $h: \{a, b\}^* \to \{b, c\}^*$ be the homomorphism with h(a) = bcc and h(b) = cbc.

Then we have h(abba) = bcc cbc cbc bcc.

Lemma 5 (closure regular languages under homomorphisms)

From a finite automaton A with input alphabet Γ and a homomorphism $h:\Gamma^*\to\Sigma^*$ one can construct a finite automaton B with

$$L(B) = h(L(A)) = \{h(w) \mid w \in L(A)\}.$$

Proof: Every transition $p \xrightarrow{a} q$ in the automaton A with $a \in \Gamma$ and $h(a) = b_1 b_2 \cdots b_n \ (b_1, \dots, b_n \in \Sigma)$ is replaced by the sequence of transitions

$$p \xrightarrow{b_1} r_1 \xrightarrow{b_2} r_2 \cdots \xrightarrow{b_{n-1}} r_{n-1} \xrightarrow{b_n} q.$$

Here, r_1, \ldots, r_{n-1} are new states that do not appear in other transitions.

For all $v \in \Sigma^*$ we have:

$$v \in L(B) \iff \exists w \in L(A) : v = h(w) \iff v \in h(L(A)).$$

But: What happens when if n = 0 and hence $h(a) = \varepsilon$ holds?

Then we replace the transition $p \xrightarrow{a} q$ by the ε -transition $p \xrightarrow{\varepsilon} q$.

 ε -transitions do not increase the power of finite automata:

From a finite automaton with ε -transitions one can construct an equivalent finite automaton without ε -transitions.

See e.g. slides 74 & 75 from my FSA lecture in summer semester 2024 (https://www.eti.uni-siegen.de/ti/lehre/sommer_2024/fsa/folien-fsa.pdf) or slides 31 & 32 from my Compiler Construction lecture in summer semester 2020 (https://www.eti.uni-siegen.de/ti/lehre/ss20/compilerbau/cb.pdf).

Lemma 6 (closure regular languages under inverse homomorphisms)

From a finite automaton B over the input alphabet Σ and a homomorphism $h: \Gamma^* \to \Sigma^*$ one can construct a finite automaton A with

$$L(A) = h^{-1}(L(B)) = \{ w \in \Gamma^* \mid h(w) \in L(B) \}.$$

Proof: The automaton A has the same set of states and the same initial/final states as B.

In the automaton A there is a transition $p \xrightarrow{a} q$ if and only if in the automaton B one can go with the word $h(a) \in \Sigma^*$ from state p to state q.

For all $w \in \Gamma^*$ we have:

$$w \in L(A) \iff h(w) \in L(B) \iff w \in h^{-1}(L(B)).$$



Now we come to the

Proof of the theorem of Khoussainov and Nerode:

Let $\mathcal{A} = (L, R_1, \dots, R_m)$ be an automatic structure with $L \subseteq \Sigma^*$.

Goal: For every formula F which contains only free variables from the set $\{x_1, \ldots, x_n\}$ (not all variables x_1, \ldots, x_n have to be free in F) we construct by induction on the structure of F a synchronous n-tape automaton B_F such that

$$L(B_F) = \{ w_1 \otimes w_2 \otimes \cdots \otimes w_n \in L^{\otimes n} \mid \mathcal{A}_{[x_1/w_1]\cdots[x_n/w_n]} \models F \}.$$

where

$$L^{\otimes n} = \{ w_1 \otimes w_2 \otimes \cdots \otimes w_n \mid w_1, \ldots, w_n \in L \}$$

(the latter is a regular language).

Case 1: $F = R_i(x_{i_1}, ..., x_{i_k})$, where $1 \le i_1, ..., i_k \le n$:

Define the homomorphism $f: (\Sigma_{\#}^n)^* \to (\Sigma_{\#}^k)^*$ as follows, where $a_1, \ldots, a_n \in \Sigma_{\#}$:

$$f(a_1,\ldots,a_n)=egin{cases} arepsilon & ext{if } a_{i_1}=\cdots=a_{i_k}=\# \ (a_{i_1},\ldots,a_{i_k}) & ext{otherwise} \end{cases}$$

Note: $f(w_1 \otimes \cdots \otimes w_n) = w_{i_1} \otimes \cdots \otimes w_{i_k}$ for all $w_1, \ldots, w_n \in \Sigma^*$.

Let B_i be the synchronous k-tape automaton for R_i .

From B_i we construct, using the lemma from slide 74, an n-tape automaton B_F with

$$L(B_F) = f^{-1}(L(B_i)) \cap L^{\otimes n}.$$

We have for all $w_1, \ldots, w_n \in \Sigma^*$:

$$w_{1} \otimes \cdots \otimes w_{n} \in L(B_{F})$$

$$\iff w_{1} \otimes \cdots \otimes w_{n} \in L^{\otimes n} \cap f^{-1}(L(B_{i}))$$

$$\iff w_{1} \otimes \cdots \otimes w_{n} \in L^{\otimes n} \text{ and } f(w_{1} \otimes \cdots \otimes w_{n}) \in L(B_{i})$$

$$\iff w_{1} \otimes \cdots \otimes w_{n} \in L^{\otimes n} \text{ and } w_{i_{1}} \otimes \cdots \otimes w_{i_{k}} \in L(B_{i})$$

$$\iff w_{1} \otimes \cdots \otimes w_{n} \in L^{\otimes n} \text{ and } (w_{i_{1}}, \dots, w_{i_{k}}) \in K(B_{i})$$

$$\iff w_{1} \otimes \cdots \otimes w_{n} \in L^{\otimes n} \text{ and } (w_{i_{1}}, \dots, w_{i_{k}}) \in R_{i}^{A}$$

$$\iff w_{1} \otimes \cdots \otimes w_{n} \in L^{\otimes n} \text{ and } A_{[x_{1}/w_{1}] \cdots [x_{n}/w_{n}]} \models R_{i}(x_{i_{1}}, \dots, x_{i_{k}})$$

Case 2: $F = (x_i = x_j)$, where $1 \le i, j \le n$:

Analogously to Case 1, since $\{(v, v) \mid v \in L\}$ is synchronously rational.

Case 3: $F = \neg G$:

By induction hypothesis there exists an n-tape automaton B_G for G.

We construct B_F such that:

$$L(B_F) = \{w_1 \otimes \cdots \otimes w_n \mid w_1, \ldots, w_n \in L\} \setminus L(B_G)$$

Case 4: $F = G \vee H$, where F contains only free variables from x_1, \ldots, x_n :

By the induction hypothesis there exist n-tape automata B_G and B_H for G and H, respectively.

We construct B_F such that $L(B_F) = L(B_G) \cup L(B_H)$.

Case 5:
$$F = \exists x_{n+1} : G(x_1, \dots, x_n, x_{n+1})$$
:

By the induction hypothesis there exists an (n+1)-tape automaton B_G for G.

Define the homomorphism $f: (\Sigma_\#^{n+1})^* \to (\Sigma_\#^n)^*$ as follows, where $a_1, \ldots, a_n, a_{n+1} \in \Sigma_\#$:

$$f(a_1,\ldots,a_n,a_{n+1})=egin{cases} arepsilon & ext{if } a_1=\cdots=a_n=\# \ (a_1,\ldots,a_n) & ext{otherwise} \end{cases}$$

Note:
$$f(w_1 \otimes \cdots \otimes w_n \otimes w_{n+1}) = w_1 \otimes \cdots \otimes w_n$$
 for all $w_1, \ldots, w_{n+1} \in \Sigma^*$.

We then construct for B_F an n-tape automaton with $L(B_F) = f(L(B_G))$

By the lemma from slide 72 we can construct such an automaton B_F .

We have for all $w_1, \ldots, w_n \in \Sigma^*$:

$$w_{1} \otimes \cdots \otimes w_{n} \in L(B_{F})$$

$$\iff w_{1} \otimes \cdots \otimes w_{n} \in f(L(B_{G}))$$

$$\iff \exists w_{n+1} : w_{1} \otimes \cdots \otimes w_{n} \otimes w_{n+1} \in L(B_{G})$$

$$\iff \exists w_{n+1} : w_{1} \otimes \cdots \otimes w_{n+1} \in L^{\otimes n+1} \text{ and } \mathcal{A}_{[x_{1}/w_{1}]\cdots[x_{n+1}/w_{n+1}]} \models G$$

$$\iff w_{1} \otimes \cdots \otimes w_{n} \in L^{\otimes n} \text{ and } \exists w_{n+1} \in L : \mathcal{A}_{[x_{1}/w_{1}]\cdots[x_{n+1}/w_{n+1}]} \models G$$

$$\iff w_{1} \otimes \cdots \otimes w_{n} \in L^{\otimes n} \text{ and } \mathcal{A}_{[x_{1}/w_{1}]\cdots[x_{n}/w_{n}]} \models F$$

This completes the construction of B_F .

Assume now that F is a sentence (no free variables) and set n = 1 in our goal on slide 75.

We then have:

$$L(B_F) = \begin{cases} L \text{ if } \mathcal{A} \models F \\ \emptyset \text{ if } \mathcal{A} \not\models F \end{cases}$$

Note that $L \neq \emptyset$ (the universe of a structure is a non-empty set).

Therefore, it suffices to construct the automaton B_F and check whether it accepts a non-empty language (see lecture FSA).

Remarks on the complexity: Our algorithm for checking $F \in Th(A)$ is not very efficient.

Reason: For every negation \neg we construct an automaton for the complement of the language of a previously constructed automaton. This increases the automaton size exponentially (power set construction)!

The running time of our algorithm is roughly $f_{|F|}(O(1))$, where $f_0(n) = n$ and $f_{i+1}(n) = 2^{f_i(n)}$ for $i \ge 0$ and |F| = length of the formula F.

This is not avoidable:

Let $T_2 = (\{0,1\}^*, S_0, S_1, \leq)$ (the infinite binary tree) where:

- ► $S_0 = \{(w, w0) \mid w \in \{0, 1\}^*\}$
- $S_1 = \{(w, w1) \mid w \in \{0, 1\}^*\}$
- $ightharpoonup \leq = \{(w, wu) \mid w, u \in \{0, 1\}^*\}$

Note: T_2 is an automatic structure.

Meyer 1974

There do not exist an $i \in \mathbb{N}$ and an algorithm that correctly decides $\mathsf{Th}(T_2)$ and whose running time is bounded by $f_i(n)$ (for an input formula of length n).

One also says: there is no elementary algorithm for $Th(T_2)$.

But for many particular automatic structures one can come up with an elementary algorithm for the theory, for instance:

Oppen 1978

There is an algorithm that decides $\mathsf{Th}(\mathbb{N},+)$ in time $2^{2^{2^{O(n)}}}$.

Oppen's algorithm uses the technique of quantifier elimination, which we will apply in the next section for another structure.

We want to prove the following famous theorem of Alfred Tarski:

Satz (Tarski 1948)

 $\mathsf{Th}(\mathbb{R},+,\cdot)$ is decidable.

Note: $(\mathbb{R}, +, \cdot)$ is not an automatic structure, since \mathbb{R} is uncountable.

The proof of Tarski's theorem is quite long.

First, we extend the structure $(\mathbb{R},+,\cdot)$ to $(\mathbb{R},+,\cdot,<,0,1,-1)$.

Note: If $\mathsf{Th}(\mathbb{R},+,\cdot,<,0,1,-1)$ is decidable then also $\mathsf{Th}(\mathbb{R},+,\cdot)$ is decidable.

In fact, also the reverse implication can be shown but this is not important for us.

We will show that $\mathsf{Th}(\mathbb{R},+,\cdot,<,0,1,-1)$ is decidable.

In the following, we will simply write \mathbb{R} for $(\mathbb{R},+,\cdot,<,0,1,-1)$.

For our decidability proof we will apply the method of quantifier elimination:

Let F be a formula with the free variables y_0, \ldots, y_n .

We construct a quantifier-free formula F' (that means, neither \exists nor \forall occurs in F') with the free variables y_0, \ldots, y_n such that

$$\forall a_0,\ldots,a_n \in \mathbb{R} : \mathbb{R}_{[y_0/a_0,\ldots,y_n/a_n]} \models F \iff \mathbb{R}_{[y_0/a_0,\ldots,y_n/a_n]} \models F'$$

We do this by induction over the structure of the formula F.

Since $\forall xG \equiv \neg \exists x \neg G$, the only difficult case is where F has the form $F = \exists x G$.

By induction, we can assume that G is already quantifier-free.

Example: Let $F = \exists x : y = x \cdot x$.

The formula F expressed that y is a square.

A real number is a square if and only if it is not negative.

Hence, for every real number $a \in \mathbb{R}$ we have:

$$\mathbb{R}_{[y/a]} \models \exists x : y = x \cdot x \iff \mathbb{R}_{[y/a]} \models (y = 0 \lor 0 < y)$$

Thus, $F' = (y = 0 \lor 0 < y)$ is the desired quantifier-free formula.

Assume for a moment that we have already proved the quantifier elimination property.

Let F be a sentence (formula without free variables).

We want to check whether $\mathbb{R} \models F$ holds.

We apply quantifier elimination to F and construct a quantifier-free sentence F' such that:

$$\mathbb{R} \models F \iff \mathbb{R} \models F'$$
.

Since F' is quantifier-free, we can easily check whether $\mathbb{R} \models F'$ holds:

- ightharpoonup F' is a boolean combination of formulas a=b and a< b.
- ▶ Here, a and b are terms that are constructed from the constants 0, 1, -1 using the operations \cdot and +.
- We can evaluate these terms a and b in \mathbb{R} and then check whether a = b, resp. a < b, holds.

Back to quantifier elimination for $F = \exists xG$ with G quantifier-free.

Let the free variables of G be x, y_0, \ldots, y_n ; then the free variables of F are y_0, \ldots, y_n .

For variables x_1, \ldots, x_n let $\mathbb{Z}[x_1, \ldots, x_n]$ denote the set of all polynomials in the variables x_1, \ldots, x_n with coefficients from \mathbb{Z} .

Example:
$$-3x_1^4x_2^2x_3 + 7x_1x_2^6x_3^8 - 8x_2^4x_3 + 12x_1 - 17$$

Atomic subformulas of G are of the form s=t and s< t, where s and t are terms that are constructed with + and \cdot from variables (x,y_0,\ldots,y_n) and the constants -1,0,1.

Such terms s and t can be evaluated to polynomials from $\mathbb{Z}[x, y_0, \dots, y_n]$.

In the following, we assume that $s, t \in \mathbb{Z}[x, y_0, \dots, y_n]$.

Finally, we can bring G into the following form:

$$G = s(x, y_0, ..., y_n) = 0 \land \bigwedge_{i=1}^m t_i(x, y_0, ..., y_n) > 0,$$
 (2)

where $s, t_1, \ldots, t_m \in \mathbb{Z}[x, y_0, \ldots, y_n]$.

First we eliminate all negations in G using the following equivalences:

- $ightharpoonup s_1 = s_2 \iff s_1 s_2 = 0$
- $ightharpoonup s_1 < s_2 \iff s_2 s_1 > 0$
- $ightharpoonup \neg (s=0) \iff (s>0 \lor -s>0)$
- $ightharpoonup \neg (s>0) \iff (s=0 \lor -s>0)$

Then we bring G into disjunctive normal form (thereby we do not introduce new negations).

Conjunctions of the form $\bigwedge_{i=1}^k s_i = 0$ can be replaced by a single equation using the following equivalence:

$$\bigwedge_{i=1}^k s_i = 0 \iff \sum_{i=1}^k s_i^2 = 0$$

Then we pull out the outermost disjunction using the following equivalence:

$$\exists x \big(\bigvee_{i=1}^k G_i\big) \equiv \bigvee_{i=1}^k \exists x G_i$$

Every formula $\exists x \ G_i$ has the desired form (2), and it suffices to apply quantifier elimination for each formula $\exists x \ G_i$.

We finally make a simple syntactic simplification.

Every polynomial $s, t_1, \ldots, t_m \in \mathbb{Z}[x, y_0, \ldots, y_n]$ in (2) can be uniquely written as a sum

$$\sum_{i=0}^d p_i \cdot x^{a_i}$$

with $0 \le a_0 < a_1 < \dots < a_d$ and $p_0, \dots, p_d \in \mathbb{Z}[y_0, \dots, y_n]$.

Example:

$$7 - 4y_0y_1^2y_3^4 + x^2 + y_1^5y_3x + 6y_0y_1^2y_3^4 - 2y_0^2y_1y_3^3x + 17y_0^3x^2$$

= $(7 - 4y_0y_1^2y_3^4 + 6y_0y_1^2y_3^4) + (y_1^5y_3 - 2y_0^2y_1y_3^3) \cdot x + (17y_0^3 + 1) \cdot x^2$

We can now replace every coefficient polynomial p_i by a new coefficient variable z_i , which appears in the formula only once.

After transforming the resulting formula into a quantifier-free formula, we can replace each of the new coefficient variables z_i by the original polynomial p_i .

Example: a possible formula $F = \exists x \ G$ that one might obtain in this way is

$$\exists x: z_0 + z_1 x^2 + z_2 x^3 = 0 \land z_3 x + z_4 x^2 > 0 \land z_5 + z_6 x^3 > 0.$$

In the following, let z_0, \ldots, z_n be all coefficient variables in the formula G.

Recall that we want to construct a quantifier-free formula F' with:

$$\forall a_0, \dots, a_n \in \mathbb{R} : \mathbb{R}_{[z_0/a_0, \dots, z_n/a_n]} \models F \iff \mathbb{R}_{[z_0/a_0, \dots, z_n/a_n]} \models F'$$

We show that it suffices to assume that F' satisfies the above equivalence only for all $a_0, \ldots, a_n \in \mathbb{R} \setminus \{0\}$.

For a subset $I \subseteq \{0, ..., n\}$ let G_I be the formula that is obtained from G by replacing for every $i \in I$ the variable z_i (and hence the term $z_i x^a$) by the constant 0.

Example: For our formula

$$G = (z_0 + z_1 x^2 + z_2 x^3 = 0 \land z_3 x + z_4 x^2 > 0 \land z_5 + z_6 x^3 > 0)$$

and $I = \{1, 3, 5\}$ we get

$$G_I = (z_0 + z_2 x^3 = 0 \land z_4 x^2 > 0 \land z_6 x^3 > 0).$$

We then replace the formula $\exists x G$ by the formula

$$\bigwedge_{I\subseteq \{0,\dots,n\}} \bigg(\bigwedge_{i\in I} z_i = 0 \wedge \bigwedge_{i\not\in I} z_i \neq 0 \ \to \ \exists x \ G_I\bigg).$$

Here, the outer conjunction runs over all subsets $I \subseteq \{0, ..., n\}$.

Assume we have constructed for every formula $F_I := \exists x \ G_I$ a quantifier-free formula F_I' with:

$$\forall a_0,\ldots,a_n \in \mathbb{R} \setminus \{0\} : \mathbb{R}_{[z_0/a_0,\ldots,z_n/a_n]} \models F_1 \iff \mathbb{R}_{[z_0/a_0,\ldots,z_n/a_n]} \models F'_1.$$

Then, for all $a_0, \ldots, a_n \in \mathbb{R}$ the following statements are equivalent:

- $\triangleright \mathbb{R}_{[z_0/a_0,...,z_n/a_n]} \models \exists x \ G$
- $\blacktriangleright \mathbb{R}_{[z_0/a_0,...,z_n/a_n]} \models \bigwedge_{I \subseteq \{0,...,n\}} \left(\bigwedge_{i \in I} z_i = 0 \land \bigwedge_{i \notin I} z_i \neq 0 \rightarrow \exists x \ G_I \right)$
- $\blacktriangleright \mathbb{R}_{[z_0/a_0,\ldots,z_n/a_n]} \models \bigwedge_{I \subseteq \{0,\ldots,n\}} \left(\bigwedge_{i \in I} z_i = 0 \land \bigwedge_{i \notin I} z_i \neq 0 \rightarrow F_I' \right)$

Remaining goal: For a formula $F = \exists x : s = 0 \land \bigwedge_{i=1}^{m} t_i > 0$ we have to construct a quantifier-free formula F' such that:

$$\forall a_0,\dots,a_n \in \mathbb{R} \setminus \{0\}: \mathbb{R}_{[z_0/a_0,\dots,z_n/a_n]} \models F \iff \mathbb{R}_{[z_0/a_0,\dots,z_n/a_n]} \models F'.$$

Here, s, t_1, \ldots, t_m are polynomials in the variables x, and the coefficients are parameters z_0, \ldots, z_n that only take values $\neq 0$. Every parameter z_i appears in F only once.

Moreover, we can assume that:

- $ightharpoonup t_i
 eq 0$ for all $1 \le i \le m$ and
- ightharpoonup s = 0 or x appears in s.

For this note that:

- ▶ If e.g. $t_1 = 0$ (the zero polynomial), then F is always wrong (we can therefore output the quantifier-free formula 0 = 1).
- ▶ If $s \neq 0$ and x does not appear in s, then, again, F is always wrong.

We distinguish three cases:

- ▶ Case 1: x appears in s and m = 1.
- ▶ Case 2: x appears in s and m > 1
- Case 3: s = 0.

Case 1: $G = (s = 0 \land t > 0)$, where x appears in the polynomial s.

Notation: For $k \ge 0$ let (#x : G) = k be a new formula with the following semantics:

For all
$$a_0, \ldots, a_n \in \mathbb{R} \setminus \{0\}$$
: $\mathbb{R}_{[z_0/a_0, \ldots, z_n/a_n]} \models (\#x : G) = k$ if and only if $|\{a \in \mathbb{R} \mid \mathbb{R}_{[x/a, z_0/a_0, \ldots, z_n/a_n]} \models G\}| = k$.

Strictly speaking, we extend here predicate logic by a new construct (the so-called counting quantifier #).

Intuition: (#x:G)=k expresses that exactly k many x have the property G (i.e., $s=0 \land t>0$).

Note: if $d \ge 1$ is the x-degree of s (the largest number a such that x^a appears in s), then $\exists x \ G$ is equivalent in $\mathbb R$ to

$$(\#x:G) = 1 \lor (\#x:G) = 2 \lor \cdots \lor (\#x:G) = d,$$

because a polynomial p(x) of degree d has at most d roots.

New goal: Find a quantifier-free formula which is equivalent to (#x:G)=k in \mathbb{R} .

For this we need some tools: polynomial division, Euclid's algorithm, Sturm sequences, formal derivates.

For $\overline{a} = (a_1, \dots, a_n) \in (\mathbb{R} \setminus \{0\})^n$ let $Var(\overline{a}) = |\{i < n \mid a_i a_{i+1} < 0\}|$. (number of sign flips).

For $\overline{a} \in \mathbb{R}^n$ let $Var(\overline{a}) = Var(\overline{b})$, where \overline{b} results from \overline{a} by removing all zeros.

Example: Var(0, 2, 4, 0, -3, 0, 0, 2, 5) = Var(2, 4, -3, 2, 5) = 2. (the red commas mark the sign flips)

For $\overline{f}=(f_1,\ldots,f_n)\in(\mathbb{R}[x])^n$ (an *n*-tuple of polynomials in the variables x) and $a\in\mathbb{R}$ let

$$\operatorname{Var}_a(\overline{f}) = \operatorname{Var}(f_1(a), \dots, f_n(a)).$$

Recall from DMI: polynomial division with remainder

For polynomials $f,g\in\mathbb{R}[x]$ with $g\neq 0$ there exist unique polynomials $q,r\in\mathbb{R}[x]$ with

- $ightharpoonup \deg(r) < \deg(g) \text{ or } r = 0 \text{ and }$
- $ightharpoonup f = q \cdot g + r.$

By replacing the remainder polynomial r by -r, we obtain $f = q \cdot g - r$.

Note: If deg(g) = 0, i.e., $g \in \mathbb{R} \setminus \{0\}$, then r = 0 holds.

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$$-\frac{(x^5 + \frac{1}{2}x^3)}{(-\frac{1}{2}x^3 + x)}$$

Example: We divide $(x^5 + x)$ by $(2x^2 + 1)$:

$$(x^{5} + x) : (2x^{2} + 1) = \frac{1}{2}x^{3} - \frac{1}{4}x$$

$$-\frac{(x^{5} + \frac{1}{2}x^{3})}{(-\frac{1}{2}x^{3} + x)}$$

$$-(-\frac{1}{2}x^{3} - \frac{1}{4}x)$$

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$$- \underbrace{(x^{5} + \frac{1}{2}x^{3})}_{(-\frac{1}{2}x^{3} + x)}$$

$$- \underbrace{(-\frac{1}{2}x^{3} - \frac{1}{4}x)}_{\frac{5}{4}x \text{ (remainder)}}$$

Example: We divide $(x^5 + x)$ by $(2x^2 + 1)$:

$$(x^{5} + x) : (2x^{2} + 1) = \frac{1}{2}x^{3} - \frac{1}{4}x$$

$$- (x^{5} + \frac{1}{2}x^{3})$$

$$(-\frac{1}{2}x^{3} + x)$$

$$- (-\frac{1}{2}x^{3} - \frac{1}{4}x)$$

$$\frac{5}{4}x \text{ (remainder)}$$

We get:

$$(x^5+x)=(2x^2+1)\cdot(\frac{1}{2}x^3-\frac{1}{4}x)+\frac{5}{4}x=(2x^2+1)\cdot(\frac{1}{2}x^3-\frac{1}{4}x)-(-\frac{5}{4}x).$$

Euclid's algorithm for polynomials:

Let $f, g \in \mathbb{R}[x] \setminus \{0\}$ be non-zero polynomials.

Define the polynomials $h_0(x), \ldots, h_n(x) \in \mathbb{R}[x] \setminus \{0\}$ uniquely by:

$$h_0(x) = f(x)$$
 $h_1(x) = g(x)$
 $h_0(x) = q_1(x)h_1(x) - h_2(x)$ $\deg(h_2) < \deg(h_1)$
 $h_1(x) = q_2(x)h_2(x) - h_3(x)$ $\deg(h_3) < \deg(h_2)$
 \vdots \vdots
 $h_{n-2}(x) = q_{n-1}(x)h_{n-1}(x) - h_n(x)$ $\deg(h_n) < \deg(h_{n-1})$
 $h_{n-1}(x) = q_n(x)h_n(x)$

 $h_{i+2} = \text{division remainder if we divide } h_i \text{ by } h_{i+1}.$

Remarks:

- ▶ Since $deg(h_{i+1}) < deg(h_i)$ for all $1 \le i \le n$, the division remainder must be finally 0.
- $h_n(x) = \gcd(f, g)$ (greatest common divisor of f and g)
- ▶ For all $0 \le i \le n$, the polynom $h_n(x)$ divides $h_i(x)$.

We define $[f,g]=(h_0(x),h_1(x),\ldots,h_n(x))$ as the Sturm sequence of f and g.

The reduced Sturm sequence of f and g is

$$\left(\frac{h_0(x)}{h_n(x)}, \frac{h_1(x)}{h_n(x)}, \dots, \frac{h_{n-1}(x)}{h_n(x)}, \frac{h_n(x)}{h_n(x)}\right) = \left(\frac{h_0(x)}{h_n(x)}, \frac{h_1(x)}{h_n(x)}, \dots, \frac{h_{n-1}(x)}{h_n(x)}, 1\right).$$

Example: We compute the Sturm sequence $[x^5 + x, x^2 + 2]$.

Successive polynomial division yields:

$$x^{5} + x = (x^{2} + 2) \cdot (x^{3} - 2x) + 5x = (x^{2} + 2) \cdot (x^{3} - 2x) - (-5x)$$

$$x^{2} + 2 = (-5x) \cdot (-\frac{1}{5}x) + 2 = (-5x) \cdot (-\frac{1}{5}x) - (-2)$$

$$-5x = (-2) \cdot \frac{5}{2}x$$

We therefore obtain

$$[x^5 + x, x^2 + 2] = (x^5 + x, x^2 + 2, -5x, -2).$$

For a polynomial $f(x) \in \mathbb{R}[x]$ we denote with f' the formal derivative of the polynomial f.

It is computed using the well-known rules for derivates.

Let $f, g \in \mathbb{R}[x]$, $a \in \mathbb{R}$:

- a' = 0
- $(a \cdot f)' = a \cdot f'$
- ▶ (f + g)' = f' + g'
- $(x^n)' = n \cdot x^{n-1}$ for $n \ge 1$

Also the product rule holds: $(f \cdot g)' = f' \cdot g + f \cdot g'$.

Example: For $f(x) = 4x^3 - 2x^2 + 5x - 3$ we have $f' = 12x^2 - 4x + 5$.

Let $f \in \mathbb{R}[x]$ be a polynomial with $f \neq 0$.

A real number $a \in \mathbb{R}$ is a root of f (i.e. f(a) = 0) if and only if (x - a) divides f (i.e. $f = (x - a) \cdot g$ for some polynomial g).

Proof: If $f = (x - a) \cdot g$, then $f(a) = (a - a) \cdot g(a) = 0$.

Now assume that f(a) = 0.

Polynomial division of f by x - a: $f = (x - a) \cdot q + r$ with deg(r) < deg(x - a) = 1, i.e., $r \in \mathbb{R}$.

Because of
$$0 = f(a) = (a - a) \cdot q(a) + r = r$$
 we get $f = (x - a) \cdot q$.

This observation yields:

Lemma 7

Let $f, g \in \mathbb{R}[x] \setminus \{0\}$. If gcd(f, g) = 1, then f and g have no common root.

A root a of a polynomial f is a multiple root of f, if $(x - a)^2$ divides f.

The following lemmas can be shown as simple exercises:

Lemma 8

A root a of f is a multiple root of f if and only if f'(a) = 0.

Lemma 9

If gcd(f, f') = 1, then the polynomial f has no multiple root.

For a quantifier-free formula H with the only free variable x and $a,b\in\mathbb{R}$ with a< b let

$$(\#x:H)_a^b = |\{c \in (a,b) \mid \mathbb{R}_{[x/c]} \models H\}|.$$

Here, $(a, b) = \{c \in \mathbb{R} \mid a < c < b\}$ is the open interval between a and b.

Hence, $(\#x : H)_a^b$ is the number of real values $c \in (a, b)$ for which H holds.

Example: $(\#x: x^2 - 2 = 0)_{-2}^2 = 2$, because there are two real roots of the polynomial $x^2 - 2$ $(-\sqrt{2}$ and $\sqrt{2})$ and both belong to (-2,2).

Moreover, $(\#x : x^2 - 2 = 0 \land x > 0)_{-2}^2 = 1$.

We now come to the central theorem for our further considerations:

Theorem of Sturm and Tarski

Let $f, g \in \mathbb{R}[x] \setminus \{0\}$, $f' \neq 0$, gcd(f, g) = gcd(f, f') = 1, $a, b \in \mathbb{R}$, a < b, $f(a) \neq 0 \neq f(b)$. Then the following identity holds:

$$(\#x: f(x) = 0 \land g(x) > 0)_a^b - (\#x: f(x) = 0 \land g(x) < 0)_a^b = Var_a([f, f'g]) - Var_b([f, f'g]).$$

For the proof of the theorem of Sturm and Tarski we need two lemmas (Lemma A and Lemma B).

Lemma A

Let $f, g \in \mathbb{R}[x] \setminus \{0\}$, $a, b \in \mathbb{R}$, a < b, and $\forall c \in [a, b] : f(c) \neq 0$. We have $\operatorname{Var}_a([f, g]) = \operatorname{Var}_b([f, g])$.

Proof of Lemma A: Let

$$[f,g]=S=(h_0,h_1,\ldots,h_s)$$

and let

$$\tilde{S} = (\tilde{h}_0, \tilde{h}_1, \dots, \tilde{h}_s)$$

be the reduced Sturm sequence, i.e., $ilde{h}_{s}=1$ and $ilde{h}_{i}=rac{h_{i}}{h_{s}}.$

Let
$$N = \{c \in [a, b] \mid \exists 0 \le i \le s : \tilde{h}_i(c) = 0\}.$$

The set N is finite (a polynomial $\neq 0$ has only finitely many roots).

Let $[a', b'] \subseteq [a, b]$ be an interval with $|N \cap [a', b']| \le 1$.

It suffices to show: $Var_{a'}(S) = Var_{b'}(S)$.

Then we write [a, b] as

$$[a,b] = [a_0,a_1] \cup [a_1,a_2] \cup [a_2,a_3] \cup \cdots \cup [a_{k-1},a_k]$$

with $a_0 = a$, $a_k = b$ and $|N \cap [a_i, a_{i+1}]| \le 1$ for all $0 \le i \le k - 1$.

We obtain $\operatorname{Var}_{a_i}(S) = \operatorname{Var}_{a_{i+1}}(S)$ for all $0 \le i \le k-1$ and hence

$$\operatorname{Var}_a(S) = \operatorname{Var}_{a_0}(S) = \operatorname{Var}_{a_k}(S) = \operatorname{Var}_b(S).$$

So, let us show that $Var_{a'}(S) = Var_{b'}(S)$ if $|N \cap [a', b']| \le 1$.

Since $f(a') \neq 0 \neq f(b')$ (because $\forall c \in [a, b] : f(c) \neq 0$) and $h_s = \gcd(f, g)$ divides f, we have $h_s(a') \neq 0 \neq h_s(b')$.

This implies $\operatorname{Var}_{a'}(S) = \operatorname{Var}_{a'}(\tilde{S})$ and $\operatorname{Var}_{b'}(\tilde{S}) = \operatorname{Var}_{b'}(S)$.

We show that $Var_{a'}(\tilde{S}) = Var_{b'}(\tilde{S})$.

Case 1: No \tilde{h}_i has a root in [a', b'].

Since every polynomial \tilde{h}_i is continuous and, by the intermediate value theorem, $\tilde{h}_i([a',b'])$ contains all values between $\tilde{h}_i(a')$ and $\tilde{h}_i(b')$, we must have

$$\tilde{h}_i(a') \cdot \tilde{h}_i(b') > 0$$

for all $0 \le i \le s$ (\tilde{h}_i does not change its sign on [a', b']).

We obtain $Var_{a'}(\tilde{S}) = Var_{b'}(\tilde{S})$.

Case 2: At least one \tilde{h}_i has a root $c \in [a', b']$.

By the choice of [a', b'] we have $N \cap [a', b'] = \{c\}$.

Since $\tilde{h}_s=1$ and, by the assumption from the lemma, $f=h_0$ has no root in [a,b] (then, also \tilde{h}_0 has no root in [a,b]), we must have $1 \leq i \leq s-1$.

We have
$$\tilde{h}_{i-1}(c) = q_i(c)\tilde{h}_i(c) - \tilde{h}_{i+1}(c) = -\tilde{h}_{i+1}(c)$$
.

If $\tilde{h}_{i+1}(c) = 0 = \tilde{h}_i(c)$ would hold, then $\tilde{h}_j(c) = 0$ for all $j \geq i$ (since $\tilde{h}_{j+2}(c) = q_{j+1}(c)\tilde{h}_{j+1}(c) - \tilde{h}_j(c)$), which contradicts $\tilde{h}_s = 1$.

Therefore, we have $\tilde{h}_{i+1}(c) \neq 0$ and hence

$$\tilde{h}_{i-1}(c)\tilde{h}_{i+1}(c) = -(\tilde{h}_{i+1}(c))^2 < 0,$$

i.e., $\tilde{h}_{i-1}(c)$ and $\tilde{h}_{i+1}(c)$ have different signs.

Since \tilde{h}_{i-1} and \tilde{h}_{i+1} have no root in [a',b'] (c would have been the only possibility), the intermediate value theorem implies

$$\tilde{h}_{i-1}(a')\tilde{h}_{i+1}(a')<0$$
 und $\tilde{h}_{i-1}(b')\tilde{h}_{i+1}(b')<0.$

We obtain:

$$\begin{aligned} \mathsf{Var}_{a'}(\tilde{S}) &= \mathsf{Var}(\tilde{h}_{0}(a'), \dots, \tilde{h}_{i-1}(a'), \tilde{h}_{i}(a'), \tilde{h}_{i+1}(a'), \dots, \tilde{h}_{s}(a')) \\ &= \mathsf{Var}(\tilde{h}_{0}(a'), \dots, \tilde{h}_{i-1}(a'), \tilde{h}_{i+1}(a'), \dots, \tilde{h}_{s}(a')) \end{aligned}$$
$$\mathsf{Var}_{b'}(\tilde{S}) &= \mathsf{Var}(\tilde{h}_{0}(b'), \dots, \tilde{h}_{i-1}(b'), \tilde{h}_{i}(b'), \tilde{h}_{i+1}(b'), \dots, \tilde{h}_{s}(b')) \\ &= \mathsf{Var}(\tilde{h}_{0}(b'), \dots, \tilde{h}_{i-1}(b'), \tilde{h}_{i+1}(b'), \dots, \tilde{h}_{s}(b')) \end{aligned}$$

In this way we can eliminate for every j with $\tilde{h}_j(c) = 0$ the entries $\tilde{h}_j(a')$ and $\tilde{h}_i(b')$.

We therefore obtain

$$Var_{a'}(\tilde{S}) = Var(g_0(a'), \dots, g_t(a'))$$
$$Var_{b'}(\tilde{S}) = Var(g_0(b'), \dots, g_t(b'))$$

where the polynomials g_0, \ldots, g_t have no root in [a', b'].

Hence, $g_i(a') \neq 0$ and $g_i(b') \neq 0$ have the same sign for all $0 \leq i \leq t$, which implies

$$Var_{a'}(\tilde{S}) = Var(g_0(a'), \dots, g_t(a'))$$

$$= Var(g_0(b'), \dots, g_t(b'))$$

$$= Var_{b'}(\tilde{S}).$$

Lemma B

Let $f, g \in \mathbb{R}[x] \setminus \{0\}$, $f' \neq 0$, gcd(f, g) = gcd(f, f') = 1, $a, b, c \in \mathbb{R}$, a < c < b, f(c) = 0, $\forall d \in [a, b] \setminus \{c\} : f(d) \neq 0$. We have

$$\mathsf{Var}_{a}([f,f'g]) - \mathsf{Var}_{b}([f,f'g]) = egin{cases} 1 & \mathsf{if}\ g(c) > 0 \ -1 & \mathsf{if}\ g(c) < 0 \end{cases}$$

Proof of Lemma B:

Since gcd(f,g) = gcd(f,f') = 1, f and g have no common root, and f has no multiple root (Slides 105 and 106).

In particular, we have $g(c) \neq 0$ and there is a polynomial h(x) with $f(x) = (x - c) \cdot h(x)$ and $h(c) \neq 0$.

We obtain
$$f f' g = f \cdot (h + (x - c)h') \cdot g = (x - c) \cdot \underbrace{(h^2 g + (x - c)hh' g)}_{u(x)}$$
.

Let $[f, f'g] = (f, f'g, h_2, ..., h_s)$ with $s \ge 1$.

Assume that g(c) > 0 (the case g(c) < 0 can be analyzed analogously).

We have
$$u(c) = (h(c))^2 g(c) > 0$$
 and $f'(c)g(c) \neq 0$.

Since u(x) is continuous and a < c < b, there are a' < b' with a < a' < c < b' < b and $\forall x \in [a', b'] : u(x) > 0$ and $f'(x)g(x) \neq 0$.

With
$$f f' g = (x - c) \cdot u(x)$$
 we get $f(a')f'(a')g(a') < 0 < f(b')f'(b')g(b')$.

If $s \ge 2$ (in which case h_2 exists) we obtain:

$$\begin{aligned} \mathsf{Var}_{a}([f,f'g]) &\stackrel{\mathsf{Lemma}\ \mathsf{A}}{=} & \mathsf{Var}_{a'}([f,f'g]) \\ &= & 1 + \mathsf{Var}_{a'}([f'g,h_2]) \\ &\stackrel{\mathsf{Lemma}\ \mathsf{A}}{=} & 1 + \mathsf{Var}_{b'}([f'g,h_2]) \\ &= & 1 + \mathsf{Var}_{b'}([f,f'g]) \\ &\stackrel{\mathsf{Lemma}\ \mathsf{A}}{=} & 1 + \mathsf{Var}_{b}([f,f'g]) \end{aligned}$$

Proof of the theorem of Tarski and Sturm:

Assume that $f, g \in \mathbb{R}[x] \setminus \{0\}$, $f' \neq 0$, gcd(f, g) = gcd(f, f') = 1, $a, b \in \mathbb{R}$, a < b, $f(a) \neq 0 \neq f(b)$.

Let $N = \{c \in (a, b) \mid f(c) = 0\}$ (a finite set).

If $N = \emptyset$ we obtain with Lemma A:

$$(\#x: f(x) = 0 \land g(x) > 0)_a^b - (\#x: f(x) = 0 \land g(x) < 0)_a^b = 0 = Var_a([f, f'g]) - Var_b([f, f'g]).$$

Now assume that $N = \{c_1, c_2, \dots, c_n\}$ with $n \ge 1$.

Choose points $a = a_0 < c_1 < a_1 < c_2 < a_2 < \cdots < a_{n-1} < c_n < a_n = b$.

With Lemma B we obtain for all $1 \le i \le n$:

$$Var_{a_{i-1}}([f, f'g]) - Var_{a_{i}}([f, f'g]) = \begin{cases} 1 & \text{if } g(c_{i}) > 0 \\ -1 & \text{if } g(c_{i}) < 0 \end{cases}$$

Summing over all *i* yields:

$$Var_{a}([f, f'g]) - Var_{b}([f, f'g]) =$$

$$(\#x : f(x) = 0 \land g(x) > 0)_{a}^{b} - (\#x : f(x) = 0 \land g(x) < 0)_{a}^{b}$$

This concludes the proof of the theorem of Tarski and Sturm.



Corollary of the theorem of Tarski and Sturm

Let $f,g \in \mathbb{R}[x] \setminus \{0\}$, $f' \neq 0$, gcd(f,g) = gcd(f,f') = 1, $a,b \in \mathbb{R}$, a < b, $f(a) \neq 0 \neq f(b)$. We then have

$$\#x(f(x) = 0 \land g(x) > 0)_a^b$$

$$= \frac{1}{2}(\mathsf{Var}_a([f, f'g]) - \mathsf{Var}_b([f, f'g]) + \mathsf{Var}_a([f, f']) - \mathsf{Var}_b([f, f'])).$$

Proof: The theorem of of Tarski and Sturm yields

$$(\#x : f(x) = 0 \land g(x) > 0)_a^b - (\#x : f(x) = 0 \land g(x) < 0)_a^b$$

= $Var_a([f, f'g]) - Var_b([f, f'g]).$

as well as (since f and g have no common root due to $\gcd(f,g)=1$)

$$(\#x: f(x) = 0 \land g(x) > 0)_a^b + (\#x: f(x) = 0 \land g(x) < 0)_a^b$$

$$= (\#x: f(x) = 0)_a^b =$$

$$= (\#x: f(x) = 0 \land 1 > 0)_a^b - (\#x: f(x) = 0 \land 1 < 0)_a^b$$

$$= \mathsf{Var}_a([f, f']) - \mathsf{Var}_b([f, f']).$$

Adding both equalities gives:

$$\begin{aligned} 2 \cdot (\#x : f(x) &= 0 \land g(x) > 0)_a^b \\ &= \mathsf{Var}_a([f, f'g]) - \mathsf{Var}_b([f, f'g]) + \mathsf{Var}_a([f, f']) - \mathsf{Var}_b([f, f']) \end{aligned}$$



We also need Cauchy's bound for the roots of a polynomial:

Lemma (Cauchy's bound)

Let $f(x) = a_m x^m + \cdots + a_1 x + a_0 \in \mathbb{R}[x]$, $a_m \neq 0$. All real roots of the polynomial f belong to the interval (-c, c) with

$$c=1+rac{\max\{|a_0|,\ldots,|a_{m-1}|\}}{|a_m|}.$$

Proof of the Cauchy bound:

Assume that we have already proved the Cauchy bound for the case $a_m = 1$.

Then we get the general statement as follows:

Let
$$\alpha$$
 be a root of $f(x) = a_m x^m + a_{m-1} x^{m-1} + \cdots + a_1 x + a_0$ with $a_m \neq 0$.

Then
$$\alpha$$
 is also a root of the polynomial $x^m + \frac{a_{m-1}}{a_m} x^{m-1} + \cdots + \frac{a_1}{a_m} x + \frac{a_0}{a_m}$.

The Cauchy bound for the case $a_m = 1$ yields

$$|\alpha| < 1 + \max\{\left|\frac{a_i}{a_m}\right| \mid 0 \le i \le m-1\} = 1 + \frac{\max\{|a_i| \mid 0 \le i \le m-1\}}{|a_m|}.$$

It remains to prove the Cauchy bound for a polynomial

$$f(x) = x^m + a_{m-1}x^{m-1} + \cdots + a_1x + a_0.$$

Let $h = \max\{|a_i| \mid 0 \le i \le m-1\}.$

Assume that
$$f(\alpha) = \alpha^m + a_{m-1}\alpha^{m-1} + \dots + a_1\alpha + a_0 = 0$$
, i.e.,
$$\alpha^m = -a_{m-1}\alpha^{m-1} - \dots - a_1\alpha - a_0. \tag{3}$$

We show that $|\alpha| < 1 + h$.

If $|\alpha| \leq 1$, we have $|\alpha| < 1 + h$ (if h = 0 then we have $\alpha^m = 0$, i.e., $\alpha = 0$).

Now assume that $|\alpha| > 1$.

Using (3) and the laws $|a+b| \le |a| + |b|$, $|a \cdot b| = |a| \cdot |b|$ for all $a, b \in \mathbb{R}$, we get

$$|\alpha|^{m} \leq |a_{m-1}| \cdot |\alpha|^{m-1} + \dots + |a_{1}| \cdot |\alpha| + |a_{0}|$$

$$\leq h \cdot (|\alpha|^{m-1} + \dots + |\alpha| + 1)$$

$$= h \cdot \frac{|\alpha|^{m} - 1}{|\alpha| - 1}.$$

Since $|\alpha| > 1$, we obtain:

$$|\alpha| - 1 \le h \cdot \frac{|\alpha|^m - 1}{|\alpha|^m} < h$$



We now come back to Case 1 (see Slide 96):

Recall: We want to find a quantifier-free arithmetic formula for $(\#x: s=0 \land t>0)=k$, where

$$s = z_0 + z_1 x + \dots + z_m x^m$$

 $t = z_{m+1} + z_{m+2} x + \dots + z_n x^{n-m-1}$

and $1 \le m < n$ (if m = n then t = 0 and $(\#x : s = 0 \land t > 0) = 0$).

The desired quantifier-free formula has the free variables z_0, \ldots, z_n . Moreover we can restrict to the case that all z_i only take values $\neq 0$.

Let y and z be two new variables.

By Cauchy's bound it suffices to find for $(\#x: s=0 \land t>0)_y^z=k$ (see Slide 107) a quantifier-free formula with free variables y,z,z_0,\ldots,z_m .

In this formula we can replace the interval borders y and z by

$$-\frac{|z_m|+\max\{|z_0|,\ldots,|z_{m-1}|\}}{|z_m|}, \text{ resp. } \frac{|z_m|+\max\{|z_0|,\ldots,|z_{m-1}|\}}{|z_m|}.$$

Applications of $|\cdot|$ and max can be eliminated by case distinctions (similar to Slide 93).

Examples:

$$|z_i|+y=z$$
 becomes $(z_i \ge 0 \to z_i+y=z \land z_i < 0 \to y=z+z_i)$. $\max\{z_i,z_j\}=x$ becomes $(z_i \ge z_j \to x=z_i \land z_i < z_j \to x=z_j)$.

Applications of $\frac{\cdot}{|z_m|}$ (in case $z_m \neq 0$) can be eliminated by multiplication with sufficiently large powers of z_m .

Using the corollary of the Sturm-Tarski theorem from Slide 119 we construct a quantifier-free formula for

$$(\#x:s=0 \land t>0)_y^z=k$$

with free variables y, z, z_0, \ldots, z_n .

But: Are all the assumptions for f = s and g = t from Slide 119 satisfied?

- ▶ $s \neq 0$ and $s' \neq 0$, since $m \geq 1$ on Slide 125 and all z_i are $\neq 0$.
- ▶ $t \neq 0$, since all z_i are $\neq 0$ and the case m < n on Slide 125.
- $ightharpoonup \gcd(s,t)=\gcd(s,s')=1$: does not hold for all $z_i\neq 0$!

How do we ensure the assumption gcd(s, t) = gcd(s, s') = 1?

We have:

- $(\#x: s = 0 \land t > 0)_y^z = (\#x: s/\gcd(s,t) = 0 \land t > 0)_y^z$: By replacing s by $s/\gcd(s,t)$ we eliminate for s only common roots of s and t (for which t > 0 does not hold).
- $(\#x: s = 0 \land t > 0)_y^z = (\#x: s/\gcd(s, s') = 0 \land t > 0)_y^z$: s and $s/\gcd(s, s')$ have the same roots (only the multiplicity of the roots of s is reduced to one when dividing by $\gcd(s, s')$).

In this way we can reduce the degree of s until finally $\gcd(s,t)=\gcd(s,s')=1$ holds.

The gcd-computations have to be done symbolically, since the coefficients of s and t are parameters $z_i \neq 0$.

Example: m = 2, n = 4, i.e.,

$$s(x) = z_0 + z_1 x + z_2 x^2$$
 and $t(x) = z_3 + z_4 x$

We first compute symbolically

$$gcd(s, t) = gcd(z_0 + z_1x + z_2x^2, z_3 + z_4x).$$

In order to make the computation more convenient, we multiply s with $z_4^2 \neq 0$.

We have
$$(\#x : s = 0 \land t > 0)_y^z = (\#x : z_4^2 \cdot s = 0 \land t > 0)_y^z$$
.

Division with remainder:

$$(z_2z_4^2x^2 + z_1z_4^2x + z_0z_4^2) : (z_4x + z_3) = z_2z_4x + (z_1z_4 - z_2z_3)$$

$$-(z_2z_4^2x^2 + z_2z_4z_3x)$$

$$((z_1z_4^2 - z_2z_4z_3)x + z_0z_4^2)$$

$$-((z_1z_4^2 - z_2z_4z_3)x + (z_1z_4z_3 - z_2z_3^2))$$

$$z_0z_4^2 - z_1z_4z_3 + z_2z_3^2 \text{ (remainder)}$$

Therefore:

- ▶ If $z_0z_4^2 z_1z_4z_3 + z_2z_3^2 \neq 0$, then $gcd(z_4^2s, t) = gcd(s, t) = 1$.
- ▶ If $z_0z_4^2 z_1z_4z_3 + z_2z_3^2 = 0$, then $gcd(z_4^2s, t) = t = (z_4x + z_3)$ und $\frac{z_4^2s}{t} = z_2z_4x + (z_1z_4 z_2z_3)$.

Moreover:

$$(\#x: s = 0 \land t > 0)_y^z = (\#x: z_2z_4x + z_1z_4 - z_2z_3 = 0 \land t > 0)_y^z$$

At this point we do not necessarily have $\gcd(z_2z_4x+z_1z_4-z_2z_3,t)=1$, but the x-degree of $z_2z_4x+z_1z_4-z_2z_3$ is smaller than the x-degree of s.

We therefore can continue in the same way.

In our concrete situation this is quite easy:

The only root of
$$z_2z_4 \cdot x + z_1z_4 - z_2z_3$$
 is $\frac{z_2z_3 - z_1z_4}{z_2z_4}$.

The only root of $t = z_4 \cdot x + z_3$ is $-\frac{z_3}{z_4}$.

Hence, if
$$\frac{z_2z_3-z_1z_4}{z_2z_4} \neq -\frac{z_3}{z_4}$$
 (i.e., $z_1z_4 \neq 2z_2z_3$) then $\gcd(z_2z_4x+z_1z_4-z_2z_3,t)=1$.

On the other hand, if $z_1z_4 = 2z_2z_3$ then $(\#x : s = 0 \land t > 0)_v^z = 0$.

To sum up, for $s(x) = z_0 + z_1x + z_2x^2$ and $t(x) = z_3 + z_4x$ we have:

- ▶ If $z_0z_4^2 z_1z_4z_3 + z_2z_3^2 \neq 0$ then gcd(s, t) = 1.
- ▶ If $z_0z_4^2 z_1z_4z_3 + z_2z_3^2 = 0$ and $z_1z_4 \neq 2z_2z_3$ then

$$(\#x: s = 0 \land t > 0)_y^z = (\#x: z_2z_4x + z_1z_4 - z_2z_3 = 0 \land t > 0)_y^z$$

and $gcd(z_2z_4x + z_1z_4 - z_2z_3, t) = 1$.

▶ If $z_0z_4^2 - z_1z_4z_3 + z_2z_3^2 = 0$ and $z_1z_4 = 2z_2z_3$ then

$$(\#x : s = 0 \land t > 0)_v^z = 0.$$

In the same way we can ensure the assumption gcd(s, s') = 1.

Under the assumptions $\gcd(s,t)=\gcd(s,s')=1$ and $s(y)\neq 0\neq s(z)$, $(\#x:s=0 \land t>0)_y^z=k$ is equivalent to

$$Var_y([s, s't]) - Var_z([s, s't]) + Var_y([s, s']) - Var_z([s, s']) = 2k$$

This can be expressed as a boolean combination of statements of the form $Var_y([s,s't])=i_1$, $Var_z([s,s't])=i_2$, $Var_y([s,s'])=i_3$, $Var_z([s,s'])=i_4$.

Finally, a statement $Var_y([s, s't]) = i$ (analogously for the other polynomials) can be expressed by a quantifier-free formula.

For this we execute the Euclidean algorithm symbolically for s and s't and thereby compute symbolically the Sturm sequence [s,s't] and then replace the variable of the polynomials in the Sturm sequence by y.

This concludes case 1. We continue with case 2 from Slide 96.

Case 2:
$$G = (s = 0 \land \bigwedge_{i=1}^{n} t_i > 0), m \ge 1$$
, and x appears in s.

Induction over *m*:

Induction base: m = 1. See case 1.

Induction step: let $m \geq 2$.

Let
$$G' = (s = 0 \land \bigwedge_{i=1}^{m-2} t_i > 0)$$
. We have:

$$\#x(G'\wedge t_{m-1}>0\wedge t_m>0)+$$

$$\#x(G' \wedge t_{m-1} > 0 \wedge t_m < 0) = \#x(G' \wedge t_{m-1}t_m^2 > 0)$$

$$\#x(G' \wedge t_{m-1} > 0 \wedge t_m > 0) +$$

$$\#x(G' \land t_{m-1} > 0 \land t_m > 0)$$
 = $\#x(G' \land t_{m-1} < 0 \land t_m > 0)$ = $\#x(G' \land t_{m-1} < 0 \land t_m > 0)$

$$\#_{\mathcal{C}}(C' \wedge t) > 0 \wedge t < 0)$$

$$\#x(G'\wedge t_{m-1}>0\wedge t_m<0)+$$

$$\#x(G' \land t_{m-1} < 0 \land t_m > 0) = \#x(G' \land t_{m-1}t_m < 0)$$

(6)

(4)

(5)

$$(4) + (5) - (6)$$
 yields:

$$2 \cdot \#x G = 2 \cdot \#x \cdot (G' \wedge t_{m-1} > 0 \wedge t_m > 0)$$

$$= \#x(G' \wedge t_{m-1}t_m^2 > 0) +$$

$$\#x(G' \wedge t_{m-1}^2t_m > 0) -$$

$$\#x(G' \wedge -t_{m-1}t_m > 0)$$

Case 3 from Slide 96: s = 0, i.e., $G = \bigwedge_{i=1}^{m} t_i > 0$ with $t_i \neq 0$.

Let
$$t = t_1 t_2 \cdots t_m$$
.

Claim: $\exists x \ G$ is equivalent in \mathbb{R} to

$$\exists x_0 \forall x \leq x_0 : G \lor \exists x_0 \forall x \geq x_0 : G \lor \exists x (t'(x) = 0 \land G). \tag{7}$$

The implication (7) $\Rightarrow \exists x \ G$ is clear.

Now assume that $\mathbb{R} \models \exists x \ G$.

We obtain

$$\mathbb{R} \models \exists x_0 \forall x \leq x_0 : G \lor \exists x_0 \forall x \geq x_0 : G \lor \\ \exists x_1 \exists x \exists x_2 (x_1 < x < x_2 \land \neg G[x/x_1] \land G \land \neg G[x/x_2]).$$

Assume that

$$\mathbb{R} \models \exists x_1 \; \exists x \; \exists x_2 \; (x_1 < x < x_2 \; \land \; \neg G[x/x_1] \land G \land \neg G[x/x_2])$$

Then there are $x_1, x, x_2 \in \mathbb{R}$ and $i, j \in \{1, ..., m\}$ with

- $x_1 < x < x_2,$
- $ightharpoonup t_i(x_1) \leq 0$,
- $t_j(x_2) \leq 0,$
- \blacktriangleright $t_k(x) > 0$ for alle $1 \le k \le m$

Then there are also $x_1', x_2' \in \mathbb{R}$ with $x_1' < x < x_2'$ and $t_i(x_1') = t_j(x_2') = 0$.

We get
$$t(x_1') = t(x_2') = 0$$
.

Since t has only finitely many roots, we can choose for $x'_1(x'_2)$ the greatest (smallest) root of t, which is smaller (greater) than x.

We get $x_1' < x < x_2'$, $t(x_1') = 0 = t(x_2')$ and $t_k(y) > 0$ for all $y \in (x_1', x_2')$ and $1 \le k \le m$.

We obtain t(y) > 0 for all $y \in (x'_1, x'_2)$.

By Rolle's theorem (https://de.wikipedia.org/wiki/Satz_von_Rolle) there exists an x with t'(x) = 0 and $t_i(x) > 0$ for all $1 \le i \le m$, i.e.,

$$\mathbb{R} \models \exists x_0 \forall x \leq x_0 : G \lor \exists x_0 \forall x \geq x_0 : G \lor \exists x \ (t'(x) = 0 \land G).$$

This shows the claim.

It now suffices to find a quantifier-free formula for

$$\exists x_0 \forall x \leq x_0 : G \lor \exists x_0 \forall x \geq x_0 : G \lor \exists x \ (t'(x) = 0 \land G).$$

For the formulas $\exists x_0 \forall x \leq x_0 \ G$ and $\exists x_0 \forall x \geq x_0 \ G$ one can easily find quantifier-free formulas.

To see this, note that for a polynomial $a_n x^n + \cdots + a_1 x + a_0$ with $a_n \neq 0$ we have

$$\exists x_0 \forall x \leq x_0 \ (a_n x^n + \dots + a_1 x + a_0 > 0)$$

if and only if one of the following cases holds:

- ightharpoonup n is even and $a_n > 0$,
- ightharpoonup n is odd and $a_n < 0$.

The formula $\exists x \ (t'(x) = 0 \land G)$ can be made quantifier-free using case 1, respectively case 2, if x appears in t'(x).

If x does not appear in t'(x), then the x-degree of $t(x) = t_1(x) \cdots t_m(x)$ is at most 1.

This means that x appears in at most one of the polynomials t_i , without loss of generality assume that x appears in t_1 .

Moreover, the x-degree of $t_1(x)$ is at most one.

If
$$t_i = z_i$$
 for $1 \le i \le m$, then $\exists x \bigwedge_{i=1}^m t_i > 0$ is equivalent to $\bigwedge_{i=1}^m z_i > 0$.

If
$$t_1 = z_1 \cdot x + z_0$$
 and $t_i = z_i$ for $2 \le i \le m$, then $\exists x \bigwedge_{i=1}^m t_i > 0$ is equivalent to $\bigwedge_{i=2}^m t_i > 0$

This concludes our proof of Tarski's theorem.

Tarski's theorem implies that there is no arithmetical formula F(x) with a single free variable x such that for all $r \in \mathbb{R}$:

$$(\mathbb{R},+,\cdot)_{[x/r]}\models F(x) \Leftrightarrow r\in\mathbb{N}$$

If there would exist such a formula F(x), then together with Gödel's theorem (Th($\mathbb{N}, +, \cdot$) is undecidable) the undecidability of Th($\mathbb{R}, +, \cdot$) would follow.

Surprisingly, Julia Robinsion found in 1949 such a formula for Q instead of \mathbb{R} :

Theorem (Robinson 1949)

There exists an arithmetical formula F(x) with a single free variable x such that for all rational numbers $r \in \mathbb{Q}$:

$$(\mathbb{Q},+,\cdot)_{[x/r]}\models F(x) \Leftrightarrow r\in\mathbb{N}$$

Consequence: Th($\mathbb{Q}, +, \cdot$) is undecidable. Markus Lohrey (Universität Siegen)

Monadic second order logic (MSO for short) is an extension of predicate logic (which is also denoted as first order logic), where quantification over subsets of the universe is allowed.

For this we fix two set of variables:

- first order variables: $Var_0 = \{x_1, x_2, x_3, \ldots\}$
- ▶ second order variables: $Var_1 = \{X_1, X_2, X_3, ...\}$

We have $Var_0 \cap Var_1 = \emptyset$.

Variables from Var₀ are denoted with $x, y, z, x', x_0, ...$, whereas variables from Var₁ are denoted with $X, Y, Z, X', X_0, ...$

As in predicate logic (see Logik I) we have predicate symboles P_i^k (k-ary) and function symbols f_i^k (k-ary).

Terms are defined as in predicate logic using function symbols and variables from Var_0 .

The set MSO of all MSO-formulas is the smallest set with:

- ▶ if t_1, t_2 are terms and $X \in Var_1$, then $(t_1 = t_2), (t_1 \in X) \in MSO$;
- ▶ if $t_1, t_2, ..., t_k$ are terms and P is a k-ary predicate symbol, then $P(t_1, ..., t_k) \in \mathsf{MSO}$;
- ▶ if $F, G \in MSO$, then $\neg F, F \land G, F \lor G \in MSO$.
- ▶ if $F \in MSO$ and $x \in Var_0, X \in Var_1$, then $\exists xF, \exists XF, \forall xF, \forall XF \in MSO$.

The set free(F) \subseteq Var₀ \cup Var₁ of all free variables of $F \in MSO$ is defined as in predicate logic.

For $F \in MSO$ we also write $F(x_1, \ldots, x_n, X_1, \ldots, X_m)$ in order to express $free(F) = \{x_1, \ldots, x_n, X_1, \ldots, X_m\}$.

A formula $F \in MSO$ with free $(F) = \emptyset$ is called an MSO-sentence.

A structure is now a pair $A = (U_A, I_A)$, where U_A is a non-empty set (the universe) and I_A is a partially defined mapping, which assigns

- ▶ to every k-ary predicate symbol P from the domain of I_A a k-ary relation $I_A(P) \subseteq U_A^k$,
- ▶ to every k—ary function symbol f from the domain of $I_{\mathcal{A}}$ a k—ary function $I_{\mathcal{A}}(f): U_{\mathcal{A}}^k \to U_{\mathcal{A}}$,
- ▶ to every variable $x \in \text{Var}_0$ from the domain of I_A an element $I_A(x) \in U_A$, and
- ▶ to every variable $X \in \mathsf{Var}_1$ from the domain of $I_{\mathcal{A}}$ a subset $I_{\mathcal{A}}(X) \subseteq U_{\mathcal{A}}$.

A structure A is suitable for a formula $F \in \mathsf{MSO}$, if I_A is defined for every predicate symbol, function symbol and free variable that appears in F.

Let \mathcal{A} be suitable for F. We write $\mathcal{A} \models F$ if one of the following cases holds (the evaluation $\mathcal{A}(t) \in U_{\mathcal{A}}$ of a term t is defined as in predicate logic):

- $ightharpoonup F = (t_1 = t_2) \text{ and } \mathcal{A}(t_1) = \mathcal{A}(t_2)$
- $ightharpoonup F=(t\in X) ext{ and } \mathcal{A}(t)\in I_{\mathcal{A}}(X)$
- ▶ $F = P(t_1, ..., t_k)$ and $(A(t_1), ..., A(t_k)) \in I_A(P)$
- ▶ $F = \neg G$ and $A \models G$ does not hold.
- ▶ $F = G \land H$ and $(A \models G \text{ and } A \models H)$
- $ightharpoonup F = G \lor H$ and $(A \models G \text{ or } A \models H)$
- ▶ $F = \exists x \ G$ and there exists $a \in U_A$ with $A_{[x/a]} \models G$
- ▶ $F = \forall x \ G$ and for all $a \in U_A$ we have $A_{[x/a]} \models G$
- ▶ $F = \exists X \ G$ and there exists $B \subseteq U_A$ with $A_{[X/B]} \models G$
- ▶ $F = \forall X \ G$ and for all $B \subseteq U_A$ we have $A_{[X/B]} \models G$.

Conventions:

- ▶ In the following we identify a symbol P with its interpretation $I_A(P)$.
- A structure $\mathcal{A} = (U_{\mathcal{A}}, I_{\mathcal{A}})$ with $dom(I_{\mathcal{A}}) = \{P_1, \dots, P_n, f_1, \dots, f_m\}$ is also written as $(U_{\mathcal{A}}, I_{\mathcal{A}}(P_1), \dots, I_{\mathcal{A}}(P_n), I_{\mathcal{A}}(f_1), \dots, I_{\mathcal{A}}(f_m))$ or just $(U_{\mathcal{A}}, P_1, \dots, P_n, f_1, \dots, f_m)$.
- For an MSO-formula $F = F(x_1, \ldots, x_n, X_1, \ldots, X_m)$ and $a_1, \ldots, a_n \in U_A$, $A_1, \ldots, A_m \subseteq U_A$ we also write $A \models F(a_1, \ldots, a_n, A_1, \ldots, A_m)$ for $A_{[x_1/a_1, \ldots, x_n/a_n, X_1/A_1, \ldots, X_m/A_m]} \models F$.

The MSO-theory of a structure A is the set of all MSO-sentences F with $A \models F$.

Monadic second order logic: Example

An example for a useful MSO-formula:

Let $\mathcal{G} = (V, E)$ be a directed graph, which is the structure with universe V and the binary relation $E \subseteq V \times V$.

The following formula reach(x, y) expresses that in \mathcal{G} there is a path from vertex x to vertex y:

$$\mathsf{reach}(x,y) = \forall X \bigg(\big(x \in X \land \forall u \forall v \big(E(u,v) \land u \in X \ \rightarrow v \in X \big) \big) \rightarrow y \in X \bigg)$$

Proof: We say that a subset $U \subseteq V$ of vertices is closed under the edge relation E if for every $(u, v) \in E$ the following holds: if $u \in U$ then $v \in U$.

The formula $\operatorname{reach}(x, y)$ says that every subset $U \subseteq V$ that is closed under the edge relation E and that contains x must also contain y.

Monadic second order logic: Example

This is indeed equivalent to the fact that there is a path from x to y, i.e., $(x,y) \in E^*$:

Assume that there is no such a path from x to y.

Let $U = \{v \in V \mid (x, v) \in E^*\}$ be the set of all vertices that can be reached from x.

Then U is closed under the edge relation E and $x \in U$, $y \notin U$.

Assume that there is a path (u_1, u_2, \dots, u_n) from x to y, i.e., $u_1 = x$, $u_n = y$ and $(u_i, u_{i+1}) \in E$ for all $i \in \{1, \dots, n-1\}$.

Let $U \subseteq V$ be set of vertices that is closed under E with $x \in U$.

Induction along i shows that $u_i \in U$ for all $i \in \{1, ..., n\}$.

Hence, we have $y = u_n \in U$.

MSO-definable languages

We want to use MSO-sentences in order to define (formal) languages.

For this, we first have to represent finite words by structures.

Let Σ be a finite alphabet.

A non-empty word $w=a_1a_2\cdots a_n\ (n\geq 1,\ a_i\in \Sigma)$ is identified with the structure

$$\mathcal{A}_w = (\{1,2,\ldots,n\},<,(P_a)_{a\in\Sigma}),$$

such that:

- ightharpoonup < is the ordinary order on $\{1, 2, \dots, n\}$
- ▶ P_a is the unary relation $P_a = \{i \mid 1 \le i \le n, a_i = a\}$ (the set of all positions in the word w carrying the letter a)

MSO-definable languages

For the following example let the alphabet be $\Sigma = \{a, b\}$.

Example: For the word w = abbaa we have

$$A_w = (\{1, 2, 3, 4, 5\}, <, \underbrace{\{1, 4, 5\}}_{P_a}, \underbrace{\{2, 3\}}_{P_b}).$$

In the following we identify the structure A_w with the word w.

A language $L \subseteq \Sigma^+$ of non-empty words is MSO-definable if there is an MSO-sentence F with $L = \{ w \in \Sigma^+ \mid w \models F \}$.

MSO-definable languages

Example 1: The MSO-sentence

$$\exists x\exists y\exists z(\forall u(x\leq u\wedge u\leq z)\wedge P_{a}(x)\wedge P_{b}(y)\wedge P_{a}(z))$$

defines the language $a\Sigma^*b\Sigma^*a$.

Here, $x \le u$ is an abbreviation for $x < u \lor x = u$.

Example 2: The MSO-sentence

$$\exists X \ (\exists x \exists y (\forall u (x \le u \land u \le y) \land x \in X \land \neg y \in X) \land \\ \forall x \forall y (y = x + 1 \rightarrow (x \in X \leftrightarrow y \notin X)))$$

defines the language $\{w \in \{a, b\}^+ \mid |w| \text{ is even}\}.$

Here, y = x + 1 is an abbreviation for the formula $x < y \land \forall z (x \le z \le y \to (x = z \lor y = z))$.

Theorem 10 (Büchi, Elgot 1958 and Trachtenbrot)

A language $L \subseteq \Sigma^+$ is MSO-definable if and only if L is regular.

Proof:

- 1. Let $L \subseteq \Sigma^+$ be regular. We show that L is MSO-definable.
- Let $A=(Q,\Sigma,\delta,q_0,F)$ be a deterministic finite automaton (DFA) with L(A)=L, where
 - Q is the finite set of states,
 - $\delta: Q \times \Sigma \to Q$ is the transition mapping,
 - $ightharpoonup q_0 \in Q$ is the initial state, and
 - $ightharpoonup F \subseteq Q$ is the set of final states.

Without loss of generality assume that $Q = \{1, ..., n\}$.

Then the following MSO-sentence defines the language L = L(A):

$$\exists X_{1} \exists X_{2} \cdots \exists X_{n}$$

$$\bigwedge_{p \neq q} X_{p} \cap X_{q} = \emptyset \land \forall x \bigvee_{q \in Q} x \in X_{q} \land$$

$$\exists x (\forall y (x \leq y) \land \bigvee_{a \in \Sigma} (P_{a}(x) \land x \in X_{\delta(q_{0},a)})) \land$$

$$\exists x (\forall y (y \leq x) \land \bigvee_{q \in F} x \in X_{q}) \land$$

$$\forall x \forall y (y = x + 1 \rightarrow \bigvee_{q \in Q} \bigvee_{a \in \Sigma} (x \in X_{q} \land P_{a}(y) \land y \in X_{\delta(q,a)}))$$

Here, $X_p \cap X_q = \emptyset$ is an abbreviation for $\neg \exists x (x \in X_p \land x \in X_q)$.

Idea behind this formula: The existentially quantified set X_q is the set of all positions in the word where the DFA A arrives in state $q \in \{1, ..., n\}$.

At every position, the DFA arrives in exactly one state.

$$\exists x (\forall y (x \leq y) \land \bigvee_{a \in \Sigma} (P_a(x) \land x \in X_{\delta(q_0,a)})):$$

If position 1 of the word (x=1 in the above formula) carries the letter a, then the DFA arrives at position 1 in the state $\delta(q_0,a)$ (q_0 is the initial state).

$$\exists x (\forall y (y \leq x) \land \bigvee_{q \in F} x \in X_q):$$

At the last position of the word the DFA arrives in a final state.

$$\forall x \forall y (y = x + 1 \rightarrow \bigvee_{q \in Q} \bigvee_{a \in \Sigma} (x \in X_q \land P_a(y) \land y \in X_{\delta(q,a)})):$$

If x and y = x + 1 are two successive positions in the word, where position y carries the letter a, and the DFA arrives at position x in state q, then the DFA arrives at position y in state $\delta(q, a)$.

2. Let $L \subseteq \Sigma^+$ be MSO-definable. We show that L is regular.

Let $V \subseteq Var_0 \cup Var_1$ be a finite set of variables.

A non-empty word

$$w = (a_1, V_1)(a_2, V_2) \cdots (a_k, V_k) \in (\Sigma \times 2^V)^+$$

 $(k \ge 1, a_i \in \Sigma, V_k \subseteq V)$ is called valid if for every variable $x \in V \cap Var_0$ there is exactly one $1 \le i \le k$ with $x \in V_i$.

For a valid word w we define the mapping $f_w:V \to \{1,\dots,k\} \cup 2^{\{1,\dots,k\}}$ by

- $ightharpoonup f_w(x) = i \text{ if } x \in V_i \cap \text{Var}_0 \text{ and }$
- $f_w(X) = \{i \mid X \in V_i\} \text{ for } X \in V \cap Var_1.$

We identify a valid word $w = (a_1, V_1)(a_2, V_2) \cdots (a_k, V_k)$ with the structure $A_w = (\{1, \dots, k\}, I_w)$ where

- $I_w(x) = f_w(x)$ for $x \in V \cap Var_0$,
- $I_w(X) = f_w(X) \text{ for } X \in V \cap Var_1,$
- ▶ and I_w is defined for the predicate symbols < and P_a ($a \in \Sigma$) in the same way as in the structure A_v for $v = a_1 a_2 \cdots a_k$.

Hence, a valid word w defines an ordinary word $a_1 a_2 \dots a_k$ and in addition a valuation of the variables from V, where

- ▶ to every $x \in V \cap Var_0$ a position $i \in \{1, ..., k\}$ is assigned to and
- ▶ to every variable $X \in V \cap Var_1$ a set of positions is assigned to.

For an MSO-formula F with the free variables free(F) let L(F) be the set of all non-empty valid words w over the alphabet $\Sigma \times 2^{\mathsf{free}(F)}$ such that $w \models F$.

Proof strategy: we construct for every formula F a finite automaton A_F for the language L(F) using induction over the structure of F. At the end, we are only interested in the case free $(F) = \emptyset$.

First, one can construct for every finite set of variables $V \subseteq \mathsf{Var}_0 \cup \mathsf{Var}_1$ an automaton A_V which accepts exactly the valid words from $(\Sigma \times 2^V)^+$.

The automaton A_V only has to check that every variable $x \in V \cap Var_0$ appears at exactly one position of the input word.

For this, A_V stores in its state those variables from $V \cap {\sf Var}_0$ that were already seen.

Now we come to the construction of the automaton A_F :

Case 1: F = (x = y). Construct A_F such that

$$L(A_F) = (\Sigma \times \{\emptyset\})^* (\Sigma \times \{\{x,y\}\}) (\Sigma \times \{\emptyset\})^*.$$

Case 2: F = (x < y). Construct A_F such that

$$L(A_F) = (\Sigma \times \{\emptyset\})^* (\Sigma \times \{\{x\}\}) (\Sigma \times \{\emptyset\})^* (\Sigma \times \{\{y\}\}) (\Sigma \times \{\emptyset\})^*.$$

Case 3: $F = P_a(x)$. Construct A_F such that

$$L(A_F) = (\Sigma \times \{\emptyset\})^* (a, \{x\}) (\Sigma \times \{\emptyset\})^*.$$

Case 4: $F = (x \in X)$. Construct A_F such that

$$L(A_F) = (\Sigma \times \{\emptyset, \{X\}\})^* (\Sigma \times \{x, X\}) (\Sigma \times \{\emptyset, \{X\}\})^*.$$

For the following cases we use the known closure properties for regular languages (closure under boolean operations, homomorphisms and inverse homomorphisms) that we also used in the proof of the theorem of Khoussainov and Nerode (Slides 70–81).

 $L(A_F) = L(A_V) \setminus L(A_G)$.

Case 5:
$$F = \neg G$$
. Let $V = \text{free}(G)$. Construct A_F such that

Case 6:
$$F = G \vee H$$
.

Let
$$V_G = \text{free}(G)$$
, $V_H = \text{free}(H)$ and $V = \text{free}(F) = V_G \cup V_H$.

Define homomorphisms $g: (\Sigma \times 2^V)^* \to (\Sigma \times 2^{V_G})^*$ and $h: (\Sigma \times 2^V)^* \to (\Sigma \times 2^{V_H})^*$ by

$$g(a,S) = (a,S \cap V_G),$$

$$h(a,S) = (a,S \cap V_H).$$

Next, construct the automata A'_G and A'_H such that

$$L(A'_G) = L(A_V) \cap g^{-1}(L(A_G)),$$

 $L(A'_H) = L(A_V) \cap h^{-1}(L(A_H)).$

The automaton A_F is now constructed such that $L(A_F) = L(A'_G) \cup L(A'_H)$.

Case 7: $F = \exists x \ G$.

Let V = free(G) and hence $\text{free}(F) = V \setminus \{x\}$.

Define the homomorphism $f: (\Sigma \times 2^V)^* \to (\Sigma \times 2^{V \setminus \{x\}})^*$ by

$$f(a,S)=(a,S\setminus\{x\}).$$

Construct the automaton A_F such that $L(A_F) = f(L(A_G))$.

Case 8: $F = \exists X G$.

Let V = free(G) and hence $\text{free}(F) = V \setminus \{X\}$.

Define the homomorphism $f: (\Sigma \times 2^V)^* \to (\Sigma \times 2^{V \setminus \{X\}})^*$ by

$$f(a,S)=(a,S\setminus\{X\}).$$

Then, construct the automaton A_F such that $L(A_F) = f(L(A_G))$.

This concludes the proof of Büchi's theorem.



Extensions of Büchi's theorem and applications

Büchi extended his result from finite words to infinite words, also known as ω -words.

An ω -word over the alphabet Σ is an infinite sequence $w=a_0a_1a_2a_3\cdots$ with $a_i\in\Sigma$ for all $i\geq 0$. It can be identified with the function $w:\mathbb{N}\to\Sigma$ with $w(i)=a_i$.

With Σ^{ω} we denote the set of all ω -words over the alphabet Σ .

An ω -language is a subset of Σ^{ω} .

We can identify the ω -word $w = a_0 a_1 a_2 a_3 \cdots$ with the structure

$$A_w = (\mathbb{N}, <, (P_a)_{a \in \Sigma}),$$

where $P_a = \{i \in \mathbb{N} \mid a = a_i\}.$

Büchi automata

Syntactically, a Büchi automaton is exactly the same thing as a nondeterministic finite automaton.

Definition (nondeterministic Büchi automaton, NBA for short)

A nondeterministic Büchi automaton (over the alphabet Σ) is a tuple $B = (S, \Sigma, \delta, s_0, E)$ such that:

- S is a finite set of states.
- \triangleright Σ is a finite alphabet,
- ▶ $\delta \subseteq S \times \Sigma \times S$ is the transition relation,
- s₀ is the initial state, and
- $ightharpoonup E \subseteq S$ is the set of final states.

Büchi automata

Definition (runs and accepting runs)

Let $B=(S,\Sigma,\delta,s_0,E)$ be an NBA and $w=(a_1a_2a_3\cdots)\in\Sigma^\omega$.

A run of B on w is an ω -word $(s_0s_1s_2\cdots)\in S^\omega$ with $(s_i,a_{i+1},s_{i+1})\in \delta$ for all $i\geq 0$.

This runs is an accepting run of B in w, if there are infinitely many $i \geq 0$ with $s_i \in E$ (or equivalently: there is a $q \in E$ such that $s_i = q$ for infinitely many i).

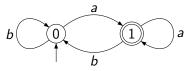
Definition (language accepted by an NBA)

The ω -language accepted by the NBA $B = (S, \Sigma, \delta, s_0, E)$ is

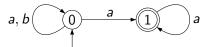
$$L(B) = \{ w \in \Sigma^{\omega} \mid \text{ there is an accepting run of } B \text{ on } w \}.$$

Examples for Büchi automata

Example 1: This NBA accepts the set of all ω -words that contain infinitely many a's.



Example 2: This NBA accepts $\{a, b\}^*a^{\omega}$.



Büchi automata and MSO

Let $L \subseteq \Sigma^{\omega}$ be an ω -language.

- ▶ L is MSO-definable if there exists an MSO-sentence F such that $L = \{ w \in \Sigma^{\omega} \mid \mathcal{A}_w \models F \}$. In the following, we write L(F) for $\{ w \in \Sigma^{\omega} \mid \mathcal{A}_w \models F \}$.
- L is ω-regular if there is an NBA B with L = L(B).

Theorem 11 (Büchi 1960)

An ω -language $L\subseteq \Sigma^{\omega}$ is MSO-definable if and only if L is ω -regular. Moreover, both directions are effective:

- From an MSO-sentence F one can construct effectively a Büchi automaton B such that L(B) = L(F).
- From a Büchi automaton B one can construct effectively an MSO-sentence F such that L(B) = L(F).

The MSO-theory of $(\mathbb{N}, <)$

Before we prove Theorem 11, we first show an important corollary.

The MSO-theory of a structure A is the set of all MSO-sentences F with $A \models F$.

Corollary

The MSO-theory of $(\mathbb{N}, <)$ is decidable.

Proof: Let F be an MSO-sentence with < the only predicate symbol in F.

By Theorem 11 we can construct from F a Büchi automaton B over the unary alphabet $\{a\}$ such that

$$(\mathbb{N},<)\models F\iff a^{\omega}\in L(B)\iff L(B)\neq\emptyset.$$

It is easy to check whether $L(B) \neq \emptyset$ holds: this is the case iff there is a final state q_f that belongs to a cycle and such that q_f can be reached from the initial state q_0 .

Characterization of ω -regular languages

We now want to prove Theorem 11. The 2nd point is easy:

From a Büchi automaton B one can construct an MSO-sentence F with L(B) = L(F) by a simple modification of the construction for finite automata (proof of Theorem 10).

For the other direction we start with a characterization of ω -regular languages. The proof is a simple exercise.

Lemma 12

A language $L \subseteq \Sigma^{\omega}$ is ω -regular if and only if there exist

- $ightharpoonup n \geq 0$ and
- ▶ regular languages $U_1, V_1 \dots, U_n, V_n \subseteq \Sigma^+$

such that

$$L=\bigcup_{i=1}^n U_iV_i^{\omega}.$$

Generalized Büchi automata

Definition (generalized Büchi automaton — GBA)

A generalized Büchi automaton (over the alphabet Σ) is a tuple $B = (S, \Sigma, \delta, I, F_0, \dots F_{k-1})$ such that:

- ▶ S, Σ and δ are as in an ordinary Büchi automaton,
- $I, F_0, \ldots, F_{k-1} \subseteq S$ and
- $k \geq 1$.

Generalized Büchi automata

Definition (runs and accepting run of a GBA)

Let $B=(S,\Sigma,\delta,I,F_0,\ldots,F_{k-1})$ be a GBA and $w=(a_1a_2a_3\cdots)\in\Sigma^\omega.$

A run of B on w is an ω -word $(s_0s_1s_2\cdots)\in S^\omega$ with $s_0\in I$ and $(s_i,a_{i+1},s_{i+1})\in \delta$ for all $i\geq 0$.

This run is an accepting run of B on w iff for all $0 \le j \le k-1$ there are infinitely many $i \ge 0$ with $s_i \in F_j$.

Definition (language accepted by a GBA)

The language accepted by the GBA $B = (S, \Sigma, \delta, I, F_0, \dots, F_{k-1})$ is

$$L(B) = \{ w \in \Sigma^{\omega} \mid \text{ there is an accepting run of } B \text{ on } w \}.$$

$GBA \rightarrow NBA$

Lemma 13

From a GBA $B=(S,\Sigma,\delta,I,F_0,\ldots,F_{k-1})$ one can construct an NBA A with $1+|S|\cdot k$ many states such that L(A)=L(B).

Proof: Assume that $k \geq 2$.

Step 1. We first reduce k to 1.

Define the GBA

$$B' = (S \times \{0, \dots, k-1\}, \Sigma, \delta', I \times \{0\}, F_0 \times \{0\})$$

where $\delta' \subseteq (S \times \{0, \dots, k-1\}) \times \Sigma \times (S \times \{0, \dots, k-1\})$ is defined as follows

$$\delta' = \{ ((s,i), a, (p,i)) \mid (s, a, p) \in \delta, s \notin F_i \} \cup \{ ((s,i), a, (p,i+1 \bmod k)) \mid (s, a, p) \in \delta, s \in F_i \}$$

$\mathsf{GBA} \to \mathsf{NBA}$

Claim 1: $L(B) \subseteq L(B')$.

Let $w \in L(B)$.

Thus, B has an accepting run $r = (s_0 s_1 s_2 \cdots)$ on w.

For all $0 \le j \le k-1$ there are infinitely many $i \ge 0$ with $s_i \in F_j$.

We choose positions $-1 = i_{-1} < i_0 < i_1 < i_2 < \cdots$ as follows:

$$i_p = \min\{j > i_{p-1} \mid s_j \in F_{p \bmod k}\}$$
 for all $p \ge 0$

This implies that the GBA B' can execute the transition $((s_{i_p}, p \mod k), a, (s_{i_p+1}, p+1 \mod k))$ at time i_p .

This implies that B' visits the set $F_0 \times \{0\}$ infinitely many times and thus $w \in L(B')$.

$\mathsf{GBA} \to \mathsf{NBA}$

Claim 2: $L(B') \subseteq L(B)$.

Let $w \in L(B')$.

Thus, B' has an accepting run $r = (s_0, j_0)(s_1, j_1)(s_2, j_2) \cdots$ on w.

Hence, there are infinitely many $i \ge 0$ with $s_i \in F_0$ and $j_i = 0$.

In order to see in the 2nd components j_i of r infinitely many times a 0, the 2nd component of the run must cycle infinitely many times through $0, 1, 2, \ldots, k-1$.

In particular: for every $0 \le j \le k-1$ there are infinitely many $i \ge 0$ with $s_i \in F_j$.

Therefore, $s_0s_1s_2\cdots$ is an accepting run of B on w and thus $w\in L(B)$.

$\mathsf{GBA} \to \mathsf{NBA}$

Step 2: We reduce the set of initial states *I* to a single state.

For this, let $B = (S, \Sigma, \delta, I, F)$ be a GBA with a single set of accepting states.

Let $s_0 \notin S$ be a new state.

Define the NBA

$$A = (S \cup \{s_0\}, \Sigma, \delta', s_0, F)$$

with

$$\delta' = \delta \cup \{(s_0, a, p) \mid \exists s \in I : (s, a, p) \in \delta\}.$$

Then we have L(A) = L(B).

Step 1 and 2 together yield an NBA with $1 + |S| \cdot k$ states.

Recall: A language $L \subseteq \Sigma^{\omega}$ ist ω -regular if there is an NBA such that L(B) = L.

Closure of the $\omega\text{-regular}$ languages under union and intersection is easy to show.

Theorem 14

From NBAs B_1 and B_2 one can construct an NBA B with $L(B) = L(B_1) \cup L(B_2)$.

Proof: Let $B_i = (S_i, \Sigma, \delta_i, s_i, F_i)$ with $S_1 \cap S_2 = \emptyset$.

Let $s_0 \notin S_1 \cup S_2$ and $B = (S_1 \cup S_2 \cup \{s_0\}, \Sigma, \delta, s_0, F_1 \cup F_2)$, where

$$\delta = \delta_1 \cup \delta_2 \cup \{(s_0, a, s) \mid (s_1, a, s) \in \delta_1 \text{ or } (s_2, a, s) \in \delta_2\}.$$

Then we have $L(B) = L(B_1) \cup L(B_2)$.

Theorem 15

From NBAs B_1 and B_2 one can construct an NBA B with $L(B) = L(B_1) \cap L(B_2)$.

Proof: Let $B_i = (S_i, \Sigma, \delta_i, s_i, F_i)$.

Construct the GBA $B=(S_1\times S_2,\Sigma,\delta,\{(s_1,s_2)\},F_1\times S_2,S_1\times F_2)$ with

$$\delta = \{((p_1, p_2), a, (q_1, q_2)) \mid (p_1, a, q_1) \in \delta_1, (p_2, a, q_2) \in \delta_2\}.$$

Then we have $L(B) = L(B_1) \cap L(B_2)$.

By Lemma 13 one can transform B into an equivalent NBA.



Our next goal is to show that one can construct from an NBA B over the alphabet Σ an NBA B' with $L(B') = \Sigma^{\omega} \setminus L(B)$.

In other words: The ω -regular languages are closed under complement.

Recall that the regular languages (of finite words) are also closed under complement.

For the proof of this fact (see my lecture Formale Sprachen und Automaten) one transforms a given nondeterministic finite automaton into an equivalent deterministic finite automaton (power set construction).

Deterministic Büchi automata (DBA) are defined as normal finite automata (δ is a function $\delta: S \times \Sigma \to S$).

But: There is an ω -regular language L, which cannot be accepted by a DBA: $L = \{a, b\}^* a^{\omega}$.

Let $B = (S, \Sigma, \delta, s_0, F)$ be an NBA.

For $s, t \in S$ and $w \in \Sigma^+$ we write

- $ightharpoonup s \xrightarrow{w} t$ if there is a path in B from s to t along which the word w is read and
- ▶ $s \xrightarrow{w}_{F} t$ if there is a path in B from s to t along which the word w is read and in addition the path visits a state from F.

We define an equivalence relation \equiv_B on the set Σ^+ as follows: For $u, v \in \Sigma^+$ we have $u \equiv_B v$ if and only if the following holds:

$$\forall s, t \in S : (s \xrightarrow{u} t) \Leftrightarrow (s \xrightarrow{v} t) \text{ and}$$

 $\forall s, t \in S : (s \xrightarrow{u}_F t) \Leftrightarrow (s \xrightarrow{v}_F t)$

Lemma 16

The relation \equiv_B is an equivalence relation with only finitely many equivalence classes and every equivalence class is a regular language.

From B one can compute a finite list of finite automata A_1, \ldots, A_k such that $L(A_1), \ldots, L(A_k)$ is a list of all equivalence classes of \equiv_B .

Proof: simple exercise

Lemma 17

Let $U, V \subseteq \Sigma^+$ be equivalence classes of \equiv_B . If $UV^{\omega} \cap L(B) \neq \emptyset$ holds then $UV^{\omega} \subseteq L(B)$.

Proof: Assume that $w \in UV^{\omega} \cap L(B)$.

Because $w \in UV^{\omega}$ there are $u \in U$ and $v_1, v_2, v_3, \ldots \in V$ with

$$w = uv_1v_2v_3\cdots$$
.

Because of $w \in L(B)$, there are states $s_1, s_2, s_3, \ldots \in S$ with

$$s_0 \xrightarrow{u} s_1, \forall i \geq 1: s_i \xrightarrow{v_i} s_{i+1}, \text{ and } s_i \xrightarrow{v_i}_F s_{i+1} \text{ for } \infty \text{ many } i \geq 1.$$

Now, let $w' \in UV^{\omega}$ be arbitrary.

Then we can write w' as

$$w' = u'v_1'v_2'v_3'\cdots$$

with $u \equiv_B u'$ and $v_i \equiv_B v'_i$ for all $i \geq 1$.

Therefore, we have

$$s_0 \xrightarrow{u'} s_1, \forall i \geq 1 : s_i \xrightarrow{v'_i} s_{i+1}, \text{ and } s_i \xrightarrow{v'_i}_F s_{i+1} \text{ for } \infty \text{ many } i \geq 1.$$

This implies $w' \in L(B)$.



Lemma 18

For every word $w \in \Sigma^{\omega}$ there are equivalence classes $U, V \subseteq \Sigma^{+}$ of $\equiv_{\mathcal{B}}$ with $w \in UV^{\omega}$.

For the proof of Lemma 18 we use a famous result from combinatorics.

Recall: $\binom{\mathbb{N}}{2}$ is the set of all subsets of \mathbb{N} that consist of two elements.

A coloring of $\binom{\mathbb{N}}{2}$ is a function $\chi:\binom{\mathbb{N}}{2}\to C$, for a finite set C of colors.

Theorem 19 (Ramsey's theorem, 1930)

Let $\chi:\binom{\mathbb{N}}{2}\to C$ be a coloring. Then there is an infinite subset $M\subseteq\mathbb{N}$ such that for all $A,B\in\binom{M}{2}$ we have $\chi(A)=\chi(B)$.

Proof of Lemma 18: Let $w = a_1 a_2 a_3 \cdots$ with $a_1, a_2, a_3, \ldots \in \Sigma$.

For
$$i < j$$
 let $w[i,j] = a_i a_{i+1} \cdots a_{j-1} \in \Sigma^+$.

We define a coloring χ of the set $\binom{\mathbb{N}}{2}$ as follows: For i < j let

$$\chi(\{i,j\}) = \text{ the equivalence class } C \text{ of } \equiv_B \text{ with } w[i,j] \in C.$$

This is a coloring with finitely many colors.

By Ramsey's theorem there is an infinite subset $I \subseteq \mathbb{N}$ such that for all $i,j,k,\ell \in I$ with i < j and $k < \ell$ we have: $\chi(\{i,j\}) = \chi(\{k,\ell\})$.

Let
$$I = \{i_1, i_2, i_3, \ldots\}$$
 with $1 < i_1 < i_2 < i_3 < \cdots$.

Hence, there is an equivalence class V of \equiv_B with $w[i_k,i_{k+1}] \in V$ for all k > 1.

If *U* is the equivalence class of \equiv_B with $w[1, i_1]$ then we get $w \in UV^{\omega}$.

Theorem 20 (Büchi, 1962)

From a given NBA B over Σ one can construct an NBA B' with $L(B') = \Sigma^{\omega} \setminus L(B)$.

Proof: We first show the existence of B' and then prove that B' can be constructed with an algorithm.

Let $(U_1, V_1), \ldots, (U_k, V_k)$ all pairs such that

- $V_1, V_1, \dots, U_k, V_k$ are equivalence classes of \equiv_B and
- ▶ $U_iV_i^{\omega} \cap L(B) = \emptyset$ for all $1 \le i \le k$.

By Lemma 16 there are indeed only finitely many such pairs.

Let
$$L' = \bigcup_{i=1}^k U_i V_i^{\omega}$$
.

By Lemma 12, L' is ω -regular.

Claim 1: $L' = \Sigma^{\omega} \setminus L(B)$.

Since $U_i V_i^{\omega} \cap L(B) = \emptyset$ for all 1 < i < k, we have $L' \subset \Sigma^{\omega} \setminus L(B)$.

Vice versa, assume that $w \in \Sigma^{\omega} \setminus L(B)$.

By Lemma 18 there are equivalence class U and V of \equiv_B with $w \in UV^{\omega}$.

From $UV^{\omega} \cap L(B) \neq \emptyset$, we would obtain $UV^{\omega} \subset L(B)$ by Lemma 17, which contradicts $w \in UV^{\omega} \cap (\Sigma^{\omega} \setminus L(B))$.

Therefore we have $UV^{\omega} \cap L(B) = \emptyset$, i.e., there is $1 \le i \le k$ with $U = U_i$ and $V = V_i$.

Hence, we have $w \in U_i V_i^{\omega} \subseteq L'$.

Claim 2: An NBA B' with L(B') = L' can be constructed with an algorithm.

By Lemma 16 one can construct a list A_1, \ldots, A_k of finite automata for the equivalence classes of \equiv_B .

It therefore suffices to check with algorithm whether $L(A_i)L(A_j)^{\omega} \cap L(B) \neq \emptyset$ holds for given $1 \leq i, j \leq k$.

By Lemma 17 it suffices to check for arbitrary words $u \in L(A_i)$ and $v \in L(A_i)$ whether $uv^{\omega} \in L(B)$ holds.

We have $uv^{\omega} \in L(B)$ if and only if there is a state $s \in S$ and $m, n \leq |S|$ with $s_0 \xrightarrow{uv^m} s$ and $s \xrightarrow{v^n}_{F} s$.

From MSO to Büchi automata

We can no easily show the 1st point from Theorem 11.

From an MSO-sentence F one can construct a Büchi automaton B with L(B) = L(F) using the same construction that we used for finite automata in the proof of Theorem 10.

All the closure properties that we used for finite automata also hold for Büchi automata:

- closure under union (and intersection).
- closure under complement

From MSO to Büchi automata

closure under homomorphisms and inverse homomorphisms

Note that we only need this for homomorphisms $h: \Sigma \to \Gamma$ that map letters to letters.

Given a Büchi automaton B over the alphabet Σ one can construct a Büchi automaton for h(L(B)) by replacing every transition (p, a, q) in B by (p, h(a), q).

Given a Büchi automaton B over the alphabet Γ one obtains a Büchi automaton for $h^{-1}(L(B))$ by replacing every transition (p, b, q) in B by all transitions (p, a, q) where h(a) = b.

Tree automata and MSO

The results of Büchi can be extended to infinite trees.

A Σ -labelled (binary) ω -tree is a structure

$$\mathcal{T} = (\{0,1\}^*, S_0, S_1, (P_a)_{a \in \Sigma})$$

where

- lacksquare $S_0 = \{(w, w0) \mid w \in \{0, 1\}^*\}, S_1 = \{(w, w1) \mid w \in \{0, 1\}^*\}, \text{ and }$
- every $P_a \subseteq \{0,1\}^*$ is a unary relation such $(P_a)_{a \in \Sigma}$ is a partition of $\{0,1\}^*$.

One can define a suitable automaton model for running on such trees, which yields the class of ω -regular tree languages.

The class of ω -regular tree languages then coincides with the class of MSO-definable ω -tree languages.

More decidable MSO theories

A corollary is then the following famous (and very difficult) result:

Corollary (Rabin 1969)

The MSO-theory of the infinite binary tree $T_2 = (\{0,1\}^*, S_0, S_1, \leq)$ (see slide 82) is decidable.

From this result one easily obtains:

Corollary

The MSO-theory of (\mathbb{Q}, \leq) is decidable.

Existential Second-Order Logic and NP

We have seen that

finite automata = $(\exists)MSO$ (on words and trees)

The basic message of the rest of the lecture:

 $NP = \exists SO$ (on arbitrary relational structures)

Instead of arbitrary structures, we will restrict to graphs; the generalization to arbitrary relational structures is just a technicality.

Graphs and their encodings

Conventions:

- Graphs will be always finite and directed.
- The set of nodes will be an initial segment of the natural numbers.

Hence, a graph is a pair
$$\mathcal{G}=(\{1,\ldots,n\},E)$$
 with $E\subseteq\{1,\ldots,n\}\times\{1,\ldots,n\}.$

 $\mathcal G$ can be represented by its adjacency matrix $M_{\mathcal G}=(a_{i,j})_{1\leq i,j\leq n}$, where

$$a_{i,j} = \begin{cases} 1 & \text{if } (i,j) \in E \\ 0 & \text{else} \end{cases}$$

We can encode $M_{\mathcal{G}}$ and hence \mathcal{G} by the following bit string of length n^2 :

$$code(G) = a_{1,1}a_{2,1}\cdots a_{n,1}a_{1,2}a_{2,2}\cdots a_{n,2}\cdots a_{1,n}a_{2,n}\cdots a_{n,n}$$

Graph properties

A graph property is a set of graphs ${\cal A}$ that is closed under isomorphism:

$$\mathcal{G}_1 \cong \mathcal{G}_2 \quad \Rightarrow \quad (\mathcal{G}_1 \in \mathcal{A} \Leftrightarrow \mathcal{G}_2 \in \mathcal{A})$$

We will present two formalism for specifying graph properties:

- ► (Existential) second-order logic
- ▶ (Nondeterministic polynomial time) Turing machines.

Second-order logic over graphs

Let us fix countably infinite sets of variables Var₀, Var₁, Var₂,

- ▶ Var₀ is the set of first-order variables $x, y, z, x_1, x_2, ...$, ranging over nodes of a graph.
- ▶ Var_k for $k \ge 1$ is the set of k-ary second-order variables $R, P, Q, R_1, R_2, \ldots$, ranging over k-ary relations on nodes.

The set of second-order formulas (SO-formulas) is inductively defined as follows, where E denotes the edge relation of a graph:

- For all $x, y \in Var_0$, (x = y) and E(x, y) are SO-formulas.
- ▶ For all $R \in Var_k$ and all $x_1, ..., x_k \in Var_0$, $R(x_1, ..., x_k)$ is an SO-formula.
- ▶ If F and G are SO-formulas, then also $\neg F$, $F \land G$, and $F \lor G$ are SO-formulas.
- ▶ If F is an SO-formula and $x \in Var_0$ then also $\exists x : F$ and $\forall x : F$ are SO-formulas.
- ▶ If F is an SO-formula and $R \in \mathsf{Var}_k$ for some $k \ge 1$ then also $\exists R : F$ and $\forall R : F$ are SO-formulas.

Second-order logic over graphs

An SO-sentence is an SO-formula without free (first-order or second-order) variables.

A first-order formula (FO-formula) is an SO-formula without quantifications over second-order variables.

An existential second-order formula (∃SO-formula) is an SO-formula of the form

$$\exists R_1 \exists R_2 \cdots \exists R_k : F,$$

where $R_1, R_2 \dots, R_k$ are second-order variables (of arbitrary arity) and F is an FO-formula.

For an SO-sentence F and a graph \mathcal{G} we write $\mathcal{G} \models F$ if F is true in \mathcal{G} .

Note: $\{\mathcal{G} \mid \mathcal{G} \models F\}$ is a graph property.

Let \mathcal{L} be any logic (e.g. FO, SO, \exists SO). A graph property \mathcal{A} is \mathcal{L} -definable if there exists an \mathcal{L} -sentence F such that $\mathcal{A} = \{\mathcal{G} \mid \mathcal{G} \models F\}$.

Examples

The following \exists SO-sentence states that a graph (with edge relation E) can be colored with 3 colors:

$$\exists C_1 \exists C_2 \exists C_3 :$$

$$\bigwedge_{1 \le i < j \le 3} \neg \exists x (C_i(x) \land C_j(x)) \land$$

$$\forall x \bigvee_{1 \le i \le 3} C_i(x) \land$$

$$\forall x \forall y : E(x, y) \to \bigwedge_{1 \le i \le 3} \neg (C_i(x) \land C_i(y))$$

Examples

The following $\exists SO$ -sentence states that a graph has an even number of nodes:

$$\exists \leq \exists S \; \exists A :$$

$$\forall x, y, z : x \leq x \land (x \leq y \leq x \rightarrow x = y) \land$$

$$(x \leq y \leq z \rightarrow x \leq z) \land (x \leq y \lor y \leq x) \land$$

$$\forall x, y : S(x, y) \leftrightarrow (x < y \land \neg \exists z (x < z < y)) \land$$

$$\forall x : (\forall y : x \leq y) \rightarrow A(x) \land$$

$$\forall x : (\forall y : y \leq x) \rightarrow \neg A(x) \land$$

$$\forall x, y : S(x, y) \rightarrow (A(x) \leftrightarrow \neg A(y))$$

Turing machines: Definition

A nondeterministic 1-tape Turing machine is a 6-tuple

 $M = (Q, \Gamma, \delta, q_0, q_Y, q_N)$, where:

- Q is the finite set of states,
- $ightharpoonup q_0 \in Q$ is the initial state,
- ▶ $q_Y \in Q$ (resp., q_N) is the accepting (resp., rejecting) state,
- ightharpoonup Γ is the finite tape alphabet with $\{0,1,\square\}\subseteq \Gamma$,
- ▶ $\delta: (Q \setminus \{q_Y, q_N\}) \times \Gamma \to 2^{Q \times \Gamma \times \{-1,0,1\}} \setminus \{\emptyset\}$ is the transition function.

M is equipped with an infinite tape, whose cells are indexed with $1, 2, 3, \ldots$

Every cell contains a symbol from Γ .

 \Box is the blank symbol, 0 and 1 are the input symbols.

Turing machines: Definition

That $(q, b, d) \in \delta(p, a)$ means: If current state is p and the current tape cell $k \in \mathbb{N}$ to which the head points contains symbol a, then M:

- 1. changes the symbol of cell k to b,
- 2. moves the tape head to cell $\max\{1, k+d\}$, and
- 3. enters state q.

If the transition function δ is required to be of type

$$\delta: (Q \setminus \{q_Y, q_N\}) \times \Gamma \to Q \times \Gamma \times \{-1, 0, 1\}$$

then M is a deterministic Turing machine.

Turing machines: Configurations

Configurations of M can be represented by words u(q, a)v with $u, v \in \Gamma^*$, $q \in Q$, and $a \in \Gamma$:

▶ If $u = a_1 a_2 \cdots a_n$ and $v = b_1 b_2 \cdots b_m$ $(n, m \ge 0)$ then the current tape content is

$$a_1 a_2 \cdots a_n a b_1 \cdots b_m \square \square \square \cdots$$

- ▶ The tape head points to cell n+1 (which contains a).
- q is the current state.

Note: $u(q, a)v, u(q, a)v\Box, u(q, a)v\Box\Box, ...$ all represent the same configuration of M.

The initial configuration for an input $w = a_1 \cdots a_n \in \{0, 1\}^*$ is:

$$\operatorname{init}(w) = egin{cases} (q_0, a_1)a_2 \cdots a_n & \text{if } n \geq 1 \\ (q_0, \Box) & \text{if } n = 0. \end{cases}$$

Turing machines: Computations

For two configurations α and β we write $\alpha \vdash_M \beta$ if M can transform α into β .

An M-computation of length t on input w is a sequence of configurations

$$init(w) \vdash_M \alpha_1 \vdash_M \alpha_2 \vdash_M \cdots \vdash_M \alpha_t$$
.

This computation is accepting if $\alpha_t = u(q_Y, a)v$.

The input word $w \in \{0,1\}^*$ is accepted by M if there exists an accepting M-computation on input w.

Let $f: \mathbb{N} \to \mathbb{N}$ be monotone. The machine M is f(n)-time bounded if every M-computation on an input w with |w| = n has length at most f(n).

The classes P and NP

The class NP is the set of all languages $L \subseteq \{0,1\}^*$ for which there exists a nondeterministic Turing machine M with:

- ▶ M is p(n)-time bounded for some polynomial p(n).
- ▶ For every word $w \in \{0,1\}^*$: w is accepted by M if and only if $w \in L$.

The class P is the set of all languages $L \subseteq \{0,1\}^*$ for which there exists a deterministic Turing machine M with:

- ▶ M is p(n)-time bouned for some polynomial p(n).
- ▶ For every word $w \in \{0,1\}^*$: w is accepted by M if and only if $w \in L$.

Clearly, $P \subseteq NP$. Whether P = NP holds, is the most important open question in TCS (and one of the most important open problems in Mathematics).

Accepting graph properties by Turing machines

For a graph property A let $code(A) = \{code(G) : G \in A\}$.

We say that a Turing machine M accepts a graph property if there is a graph property \mathcal{A} with $L(M) = \operatorname{code}(\mathcal{A})$.

Note that this implies that $w \notin L(M)$ for every word $w \in \{0,1\}^*$ such that |w| is not a square.

Fagin's Theorem

Theorem 21 (Ronald Fagin, 1974)

Let \mathcal{A} be a graph property. Then $code(\mathcal{A}) \in NP$ if and only if \mathcal{A} is $\exists SO$ -definable.

Proof:

- (1) Assume that $A = \{G \mid G \models F\}$, where F is an $\exists SO$ -sentence.
- Let $F = \exists R_1 \exists R_2 \cdots \exists R_k Q_1 x_1 \cdots Q_\ell x_\ell : G$ where R_i is a k_i -ary second order variable, x_i is a first-order variable, $Q_i \in \{\forall, \exists\}$ and G is quantifier-free.
- For a graph $\mathcal{G} = (V, E)$ with |V| = n, a nondeterministic Turing machine can guess in time $\sum_{i=1}^{k} n^{k_i}$ relations R_i of arity k_i $(1 \le i \le k)$.
- Then, $Q_1x_1\cdots Q_\ell x_\ell$: G can be checked in time $n^\ell \cdot \mathsf{poly}(|G|, n)$.

(2) Assume that code(A) belongs to NP.

+

Let $M = (Q, \Gamma, \delta, q_0, q_Y, q_N)$ be a nondeterministic p(n)-time bounded Turing machine that accepts code(A), where p(n) is a polynomial.

W.l.o.g. we can assume that for all $(q,a) \in (Q \setminus \{q_Y,q_N\}) \times \Gamma$ we have $|\delta(q,a)| = 2$. Let

$$\delta(q, a) = \{ (\rho_0(q, a), \alpha_0(q, a), \delta_0(q, a)), \\ (\rho_1(q, a), \alpha_1(q, a), \delta_1(q, a)) \}.$$

For technical reasons, we set for all $a \in \Gamma$ and $i \in \{0, 1\}$:

$$\rho_i(q_Y, a) = q_Y, \quad \alpha_i(q_Y, a) = a, \quad \delta_i(q_Y, a) = 0$$

It suffices to come up with an $\exists SO$ -sentence F such that:

$$\exists c > 0 \ \forall n \geq c \ \forall \ \text{graphs } \mathcal{G} \ \text{with } n \ \text{nodes} :$$
 $\mathcal{G} \models F \Leftrightarrow M \ \text{accepts code}(\mathcal{G})$

There are constants c, k > 0 such that $\forall n \geq c : p(n^2) \leq n^k - 1$.

Note: $p(n^2)$ bounds the running time of M on an input $code(\mathcal{G})$ for a graph $\mathcal{G} = (V, E)$ with n = |V| nodes.

Let $\mathcal{G} = (V, E)$ be a graph with $n = |V| \ge c$ nodes.

Let
$$w = a_1 a_2 \cdots a_{n^2} = \operatorname{code}(\mathcal{G})$$
.

Hence, every M-computation for input w has length at most $n^k - 1$.

An accepting M computation

$$\mathsf{init}(w) = \gamma_0 \vdash_M \gamma_1 \vdash_M \gamma_2 \vdash_M \cdots \vdash_M \gamma_m$$

 $(m \le n^k - 1)$ on input w can be represented by an $(n^k \times n^k)$ -matrix with entries from $\Gamma \cup (Q \times \Gamma)$:

- ▶ For $1 \le i \le m+1$, the *i*-th row represents the configuration γ_{i-1} .
- ▶ For $m+1 < i \le n^k$, the *i*-th row represents the configuration γ_m .

Our $\exists SO$ -sentence F will express the existence of such a matrix.

Our \exists SO-sentence F will have the form

$$\exists \leq \exists (S_i)_{1 \leq i \leq k} \ \exists (T_x)_{x \in Q \cup \Gamma} \ \exists C_0 \ \exists C_1 \ \exists z_0 \ \exists z_1 : \bigwedge_{i=1}^5 F_i \land \bigwedge_{i=1}^k G_i$$

for first-order formulas $F_1, \ldots, F_5, G_1, \ldots, G_k$.

Formula G_1 expresses that (i) \leq is a linear order on the node set V, (ii) S_1 is the associated successor relation, (iii) z_0 (resp., z_1) is the first (resp., last) element of \leq :

$$\forall x, y, z : x \leq x \land (x \leq y \leq x \rightarrow x = y) \land (x \leq y \leq z \rightarrow x \leq z) \land (x \leq y \lor y \leq x) \land \forall x, y : S_1(x, y) \leftrightarrow (x < y \land \neg \exists z (x < z < y)) \land \forall y : z_0 \leq y \leq z_1$$

Formula G_i ($2 \le i \le k$) expresses that S_i is a successor relation on i-tuples of nodes:

$$\forall x_1, \dots, x_i, y_1, \dots, y_i : S_i(x_1, \dots, x_i, y_1, \dots, y_i) \leftrightarrow$$

$$\left(\left(S_1(x_1, y_1) \land \bigwedge_{j=2}^i x_j = y_j \right) \lor$$

$$\left(x_1 = z_1 \land y_1 = z_0 \land S_{i-1}(x_2, \dots, x_i, y_2, \dots, y_i) \right) \right)$$

Two abbreviations:

$$first(x_1,\ldots,x_k) = \bigwedge_{i=1}^k x_i = z_0$$

The second-order variables C_0 and C_1 are k-ary.

 F_1 expresses that at every "time instance" $\overline{t} = (t_1, \dots, t_k)$ either C_0 or C_1 holds:

$$\forall \overline{t}: \left(C_0(\overline{t}) \vee C_1(\overline{t})\right) \wedge \left(\neg C_0(\overline{t}) \vee \neg C_1(\overline{t})\right)$$

Intuition: If $C_0(\overline{t})$ (resp., $C_1(\overline{t})$) then at time \overline{t} the Turing machine takes choice 0 (resp. 1).

Hence, the predicates C_0 and C_1 encode a certain computation path.

Every second-order variable T_x for $x \in \Gamma \cup Q$ is 2k-ary.

Formula F_2 expresses that

- ▶ every time-position pair $(\overline{t}, \overline{p})$ is labelled (via T_a) with a unique tape symbol $a \in \Gamma$, and
- ▶ that for every time \overline{t} , there exists a unique position \overline{p} such that the time-position pair $(\overline{t}, \overline{p})$ is labelled (via T_q) with a unique state state $q \in Q$.

$$\forall \overline{t} \ \forall \overline{p} : \bigvee_{a \in \Gamma} \left(T_a(\overline{t}, \overline{p}) \land \bigwedge_{b \in \Gamma \setminus \{a\}} \neg T_b(\overline{t}, \overline{p}) \right) \land \\
\forall \overline{t} \ \exists \overline{p} : \bigvee_{q \in Q} \left(T_q(\overline{t}, \overline{p}) \land \bigwedge_{q' \in Q \setminus \{q\}} \neg T_{q'}(\overline{t}, \overline{p}) \right) \land \\
\forall \overline{p}' : \overline{p}' \neq \overline{p} \to \bigwedge_{T \in Q} \neg T_q(\overline{t}, \overline{p}')$$

Formula F_3 expresses that the predicates T_x ($x \in Q \cup \Gamma$) encode a valid computation table of the Turing machine that corresponds to the computation path encoded by C_0 and C_1 .

$$\forall \overline{p} \ \forall \overline{t} : \bigwedge_{(q,a) \in Q \times \Gamma} \bigwedge_{i \in \{0,1\}} (T_a(\overline{t}, \overline{p}) \wedge T_q(\overline{t}, \overline{p}) \wedge C_i(\overline{t}) \wedge \neg \mathsf{last}(\overline{t})) \rightarrow \\ (T_{\alpha_i(q,a)}(\overline{t}+1, \overline{p}) \wedge T_{\rho_i(q,a)}(\overline{t}+1, \overline{p}+\delta_i(q,a)) \wedge \\ \forall \overline{p}' : \overline{p} \neq \overline{p}' \rightarrow \bigwedge_{b \in \Gamma} : T_b(\overline{t}, \overline{p}') \leftrightarrow T_b(\overline{t}+1, \overline{p}'))$$

Here, $\overline{t}+1$ is the unique \overline{t}' such that $S_k(\overline{t},\overline{t}')$ holds (similarly, for $\overline{p}\pm 1$).

Formula F_4 expresses that the first row of the computation table encoded by the predicates T_x ($x \in Q \cup \Gamma$) is the initial configuration for input $w = a_1 a_2 \cdots a_{n^2}$.

$$\begin{split} \forall \overline{t} \ \forall \overline{p} : & (\mathsf{first}(\overline{t}) \land \mathsf{first}(\overline{p})) \to T_{q_0}(\overline{t}, \overline{p}) \land \\ \forall \overline{t} \ \forall \overline{p} : \left(\mathsf{first}(\overline{t}) \land \bigwedge_{i=3}^k p_i = z_0 \right) \to \\ & \left(E(p_1, p_2) \to T_1(\overline{t}, \overline{p}) \land \neg E(p_1, p_2) \to T_0(\overline{t}, \overline{p}) \right) \land \\ \forall \overline{t} \ \forall \overline{p} : \left(\mathsf{first}(\overline{t}) \land \neg \bigwedge_{i=3}^k p_i = z_0 \right) \to T_{\square}(\overline{t}, \overline{p}) \end{split}$$

Formula F_5 expresses that the accepting state q_Y appears in the computation table:

$$\exists \overline{t} \; \exists \overline{p} : \; T_{q_Y}(\overline{t}, \overline{p})$$

This concludes the description of the $\exists SO$ -sentence F.

I hope, you are convinced that it works.

Descriptive Complexity

Fagin's theorem was the first result in descriptive complexity theory. There are many other characterizations:

- ightharpoonup FO = AC⁰
- ► SO = PH (the polynomial time hierarchy).
- ► SO-Horn = P on structures with a successor relation SO-Horn is the set of all SO-formulas of the form

$$Q_1 R_1 \cdots Q_n R_n \forall \overline{x} \bigwedge_{i=1}^k D_i, \tag{8}$$

where every D_i is a disjunction of literals containing at most one occurrence of a positive literal $R_i(\overline{y})$.

▶ SO-Krom = NL on structures with a successor relation: SO-Krom is the set of all SO-formulas of the form (8), where every D_i is a disjunction of literals containing at most two literals of the form $(\neg)R_i(\overline{y})$.

Descriptive Complexity

Why is it good to have logical characterizations of complexity classes?

- ► Machine independent characterizations
- Independent of concrete encoding of input structures

Do these logical characterizations help solving the big open problems of complexity theory?