# Logical Aspects of Cayley-Graphs: The Monoid Case

Dietrich Kuske $^{1\star}$  and Markus Lohrey $^2$ 

<sup>1</sup> Martin-Luther-Universität Halle-Wittenberg
Institut für Informatik
D-06099 Halle/Saale, Germany
<sup>2</sup> Universität Stuttgart,
Institut für Formale Methoden der Informatik (FMI)
Universitätsstr. 38, D-70569 Stuttgart, Germany
kuske@math.tu-dresden.de, lohrey@informatik.uni-stuttgart.de

#### 1 Introduction

Cayley-graphs of groups are a fundamental tool in combinatorial group theory [28, 29] and serve as link between other fields like toplogy, graph theory, and automata theory, see, e.g., the results in [34, 35]. The concept of Cayley-graphs can be easily generalized from groups to monoids: the monoid elements are the vertices and edges result from right-multiplication with generators of the monoid. So far, Cayley-graphs of monoids received less attention than Cayley-graphs of groups; their combinatorial properties were studied in [20–22, 51] and in [44, 45], Cayley-graphs of automatic monoids are investigated.

In a previous a paper [25] we have investigated the logical aspects of Cayley-graphs of groups. Building on the seminal results of Muller and Schupp [34, 35], we have shown that the Cayley-graph of a group G has a decidable MSO-theory if and only if G is context-free (or equivalently, virtually-free). We have shown furthermore that the Cayley-graph of a group G has a decidable first-order theory if and only if G has a decidable word problem.

The results mentioned in the previous paragraph do not carry over to monoids, see, e.g., Proposition 3.3. Our main results about the monoid case state the preservation of the decidability of the first-order (resp. monadic second-order) theory under some well-known algebraic constructions. In order to obtain these results, we use a construction that works for arbitrary relational structures: In [50], Walukiewicz proved that the MSO-theory of the tree-like unfolding (see Section 5.1) of a structure can be reduced to the MSO-theory of the original structure; the original statement goes back to [42, 43, 46]. Using this deep result, we prove in Section 6 that the class of finitely generated monoids, whose Cayley-graphs have decidable MSO-theories, is closed under finite free products (Theorem 4.1(2)). The same result also holds for first-order theories, in fact we will prove a more general preservation theorem in this case. For this, we generalize tree-like unfoldings. This leads us to the notion of a factorized unfolding: the tree-like unfolding of a structure  $\mathcal A$  consists of the set of words over the set of elements of  $\mathcal A$ . This set of words is equipped with the natural tree structure. Hence the successors of any element of the tree can be identified with the

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elements of  $\mathcal{A}$  and can therefore naturally be endowed with the structure of  $\mathcal{A}$ . Basically, a factorized unfolding is the quotient of this structure with respect to Mazurkiewicz's trace equivalence, in fact, it is a generalization of this quotient (see Section 5.2). In general, the MSO-theory of a factorized unfolding may be undecidable, even in case the underlying structure has a decidable MSO-theory. On the other hand, the first-order theory of a factorized unfolding can be reduced to the first-order theory of the underlying structure (Theorem 5.6). Section 7 is devoted to the proof of this result. It uses a technique of Ferrante and Rackoff [15] and a thorough analysis of factorized unfoldings using ideas from the theory of Mazurkiewicz traces. Based on this result, we will prove in Section 6 that the class of finitely generated monoids, whose Cayley-graphs have decidable first-order theories, is closed under finite graph products (Theorem 4.1(1)). The graph product is a well-known construction in mathematics, see, e.g., [17, 18, 48].

Our results on first-order theories of Cayley-graphs should be also compared with the classical results about first-order theories of monoids: the first-order theory of a monoid  $\mathcal{M}$  contains all true first-order statements about  $\mathcal{M}$  that are built over the signature containing the monoid operation and all monoid elements as constants. The first-order theory of the Cayley-graph of  $\mathcal{M}$  can be seen as a fragment of the whole first-order theory of  $\mathcal{M}$  in the sense that only equations of the form xa = y, with x and y variables and  $a \in \mathcal{M}$  are allowed. In this context we should mention the classical results of Makanin, stating that the existential first-order theory of a free monoid [30] or free group [31] is decidable. In [11] it was shown that under some algebraic restrictions, the decidability of the existential first-order theory is preserved under graph products.

Some of the results of this paper can be also found in the extended abstract [26].

### 2 Preliminaries

For a binary relation  $\to$  on some set, we denote by  $\stackrel{*}{\to}$  the reflexive and transitive closure of  $\to$ . Let A be an alphabet (finite or infinite). The empty word over A is denoted by  $\varepsilon$ . For  $s \in A^*$  let |s| denote the length of the word s. The set of all  $a \in A$  that occur in s is alph(s). For  $s, t \in A^*$  we write  $s \leq t$  if s is a prefix of t.

Relational structures and logic The notion of a structure (or model) is defined as usual in logic, see, e.g., [19]. Here we only consider relational structures. Sometimes, we will also use constants, but a constant c can be always replaced by the unary relation  $\{c\}$ . Let us fix a relational structure  $\mathcal{A} = (A, (R_i)_{i \in J})$ , where  $R_i \subseteq A^{n_i}$ ,  $i \in J$ . The signature of  $\mathcal{A}$  contains the equality symbol =, and for every  $i \in J$  it contains a relation symbol of arity  $n_i$  that we denote without risk of confusion by  $R_i$  as well. For  $B \subseteq A$  we define the restriction  $\mathcal{A} \upharpoonright B = (B, (R_i \cap B^{n_i})_{i \in J})$ , it is a structure over the same signature as  $\mathcal{A}$ . Let  $\mathcal{A} \backslash B = \mathcal{A} \upharpoonright (A \backslash B)$ . Given further relations  $R_j$ ,  $j \in K$ ,  $J \cap K = \emptyset$ , we also write  $(\mathcal{A}, (R_i)_{i \in K})$  for the structure  $(A, (R_i)_{i \in J \cup K})$ .

Next, let us introduce monadic second-order logic (MSO-logic). Let  $\mathbb{V}_1$  be a countably infinite set of first-order variables which range over elements of the universe A. First-order variables are denoted x, y, z, x', etc. Let  $\mathbb{V}_2$  be a countably infinite set of second-

order variables which range over subsets of A. Variables from  $\mathbb{V}_2$  are denoted X,Y,Z,X', etc. MSO-formulas over the signature of  $\mathcal{A}$  are constructed from the atomic formulas  $R_i(x_1,\ldots,x_{n_i}), \ x=y, \ \text{and} \ x\in X \ (\text{where} \ i\in J,\ x_1,\ldots,x_{n_i},x,y\in\mathbb{V}_1,\ \text{and}\ X\in\mathbb{V}_2)$  using the Boolean connectives  $\neg, \land$ , and  $\lor$ , and quantifications over variables from  $\mathbb{V}_1$  and  $\mathbb{V}_2$ . The notion of a free occurrence of a variable is defined as usual. A formula without free occurrences of variables is called an MSO-sentence. If  $\varphi(x_1,\ldots,x_n,X_1,\ldots,X_m)$  is an MSO-formula such that at most the first-order variables among  $x_1,\ldots,x_n$  and the second-order variables among  $X_1,\ldots,X_m$  occur freely in  $\varphi$ , and  $a_1,\ldots,a_n\in A,\ A_1,\ldots,A_m\subseteq A$ , then  $\mathcal{A}\models\varphi(a_1,\ldots,a_n,A_1,\ldots,A_m)$  means that  $\varphi$  evaluates to true in  $\mathcal{A}$  if the free variable  $x_i$  (resp.  $X_j$ ) evaluates to  $a_i$  (resp.  $A_j$ ). The MSO-theory of  $\mathcal{A}$ , denoted by  $MSOTh(\mathcal{A})$ , is the set of all MSO-sentences  $\varphi$  such that  $\mathcal{A}\models\varphi$ .

A first-order formula over the signature of  $\mathcal{A}$  is an MSO-formula that does not contain any occurrences of second-order variables. In particular, first-order formulas do not contain atomic subformulas of the form  $x \in X$ . The quantifier-depth of a first-order formula  $\varphi$  is the maximal number of nested quantifiers in  $\varphi$ . The first-order theory FOTh( $\mathcal{A}$ ) of  $\mathcal{A}$  is the set of all first-order sentences  $\varphi$  such that  $\mathcal{A} \models \varphi$ . With  $\Sigma_n(\mathcal{A})$  (resp.  $\Pi_n(\mathcal{A})$ ) (where  $n \geq 0$ ) we denote the set of all sentences in FOTh( $\mathcal{A}$ ) of the form  $B_1B_2 \cdots B_n : \varphi$ , where  $\varphi$  is a Boolean formula,  $B_i$  for i odd is a nonempty block of existential (resp. universal) quantifiers and  $B_i$  for i even is a nonempty block of universal (resp. existential) quantifiers.

An important method for proving the decidability of logical theories are interpretations. Let  $\mathcal{B}$  be another relational structure with universe B. Then we say that  $\mathcal{A}$  is MSO-interpretable (resp. first-order interpretable) in  $\mathcal{B}$  if there exist MSO formulas (resp. first-order formulas)  $\psi(x)$  and  $\phi_i(\widetilde{x}_i)$  ( $i \in J$ ,  $\widetilde{x}_i$  is a tuple of first-order variables of length  $n_i$ ) over the signature of  $\mathcal{B}$  such that the structure  $(\psi(x)^{\mathcal{B}}, (\phi_i(\widetilde{x}_i)^{\mathcal{B}})_{i \in J})$  is isomorphic to  $\mathcal{A}$ . Here  $\psi(x)^{\mathcal{B}} = \{b \in \mathcal{B} \mid \mathcal{B} \models \psi(b)\}$  and  $\phi_i(\widetilde{x}_i)^{\mathcal{B}} = \{\widetilde{c} \in \mathcal{B}^{n_i} \mid \mathcal{B} \models \phi_i(\widetilde{c})\}$ . It is easy to see that if  $\mathcal{A}$  is MSO-interpretable (resp. first-order interpretable) in  $\mathcal{B}$  and MSOTh( $\mathcal{B}$ ) (resp. FOTh( $\mathcal{B}$ )) is decidable, then also MSOTh( $\mathcal{A}$ ) (resp. FOTh( $\mathcal{A}$ )) is decidable.

Undirected graphs An undirected graph is a relational structure G = (V, E), where V is called the set of nodes and  $E \subseteq V \times V$  is a symmetric and irreflexive edge relation (thus, undirected graphs do not have self loops). A path of length  $n \geq 0$  in G between  $u \in V$  and  $v \in V$  is a sequence  $[v_0, v_1, \ldots, v_n]$  of nodes such that  $v_0 = u$ ,  $v_n = v$ , and  $(v_i, v_{i+1}) \in E$  for all  $0 \leq i < n$ . We write  $d_G(u, v)$  for the distance between the nodes  $u, v \in V$ , i.e.,  $d_G(u, v)$  is the minimal length of a path between u and v. The r-sphere, centered at  $v \in V$ , is  $S_G(r, v) = \{u \in V \mid d_G(v, u) \leq r\}$ . For a k-tuple  $\widetilde{v} = (v_1, \ldots, v_k) \in V^k$  we define  $S_G(r, \widetilde{v}) = \bigcup_{i=1}^k S_G(r, v_i)$ .

Word problems Let  $\mathcal{M}$  be a finitely generated monoid and let  $\Gamma$  be a finite generating set for  $\mathcal{M}$ , i.e., there exists a surjective monoid homomorphism  $h: \Gamma^* \to \mathcal{M}$ . The word problem for  $\mathcal{M}$  with respect to  $\Gamma$  is the set  $W(\mathcal{M}, \Gamma) = \{(u, v) \in \Gamma^* \times \Gamma^* \mid h(u) = h(v)\}$ . The following fact is well-known:

**Theorem 2.1.** Let  $\mathcal{M}$  be a finitely generated monoid and let  $\Gamma_1$  and  $\Gamma_2$  be two finite generating sets for  $\mathcal{M}$ . Then  $W(\mathcal{M}, \Gamma_1)$  is logspace reducible to  $W(\mathcal{M}, \Gamma_2)$ .

Thus, the computational complexity of the word problem does not depend on the underlying set of generators.

Mazurkiewicz traces A detailed introduction to the theory of Mazurkiewicz traces can be found in [12]. An independence alphabet is a pair (A, I), where A is a possibly infinite set and  $I \subseteq A \times A$  is symmetric and irreflexive (thus, it is an undirected graph). The relation I is known as the independence relation, its complement  $D = (A \times A) \setminus I$  is the dependence relation. The pair (A, D) is called a dependence alphabet. For  $a \in A$ , we let  $I(a) = \{b \in A \mid (a, b) \in I\}$  and  $D(a) = \{b \in A \mid (a, b) \in D\} = A \setminus I(a)$ . Let  $\equiv_I$  be the smallest congruence on  $A^*$  that contains all pairs (ab, ba) with  $(a, b) \in I$ . The trace monoid (free partially commutative monoid)  $\mathbb{M}(A, I)$  associated to (A, I) is the quotient monoid  $A^*/\equiv_I$ ; its elements are called traces. Trace monoids will be one of the few examples of not necessarily finitely generated monoids in this work. Extreme cases are free monoids (if  $D = A \times A$ ) and free commutative monoids (if  $D = \{(a, a) \mid a \in A\}$ ). Trace monoids were first investigated in [8]. Mazurkiewicz [32] introduced them into computer science.

Let us fix a trace monoid  $\mathbb{M} = \mathbb{M}(A, I)$ . The trace represented by the word  $s \in A^*$  is denoted by  $[s]_I$ . The neutral element of  $\mathbb{M}$  is the empty trace  $[\varepsilon]_I$ , briefly  $\varepsilon$ . An element  $a \in A$  will be identified with the trace  $[a]_I$ .

Let  $t = [s]_I \in \mathbb{M}$ . We define |t| = |s| (the length of t) and  $\mathrm{alph}(t) = \mathrm{alph}(s)$ . For two traces  $t, u \in \mathbb{M}$  we write  $(t, u) \in I$  if  $\mathrm{alph}(t) \times \mathrm{alph}(u) \subseteq I$ . The trace  $t \in \mathbb{M}$  can be visualized by its dependence graph  $D_t$ . To define  $D_t$ , choose an arbitrary word  $w = a_1 a_2 \cdots a_n$ ,  $a_i \in A$ , with  $t = [w]_I$  and define  $D_t = (\{1, \ldots, n\}, E, \lambda)$ , where  $E = \{(i, j) \mid i < j, (a_i, a_j) \in D\}$  and  $\lambda(i) = a_i$ . If we identify isomorphic dependence graphs, then this definition is independent of the chosen word representing t. Moreover, the mapping  $t \mapsto D_t$  is injective. As a consequence of the representation of traces by dependence graphs, one obtains Levi's Lemma for traces, see, e.g., [12, p 74], which is one of the fundamental facts in trace theory. The formal statement is as follows.

**Lemma 2.2.** Let  $u_1, \ldots, u_m, v_1, \ldots, v_n \in \mathbb{M}$ . Then  $u_1 u_2 \cdots u_m = v_1 v_2 \cdots v_n$  if and only if there exist  $w_{i,j} \in \mathbb{M}$   $(1 \le i \le m, 1 \le j \le n)$  such that

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-u_i = w_{i,1}w_{i,2}\cdots w_{i,n} for every 1 \le i \le m,

-v_j = w_{1,j}w_{2,j}\cdots w_{m,j} for every 1 \le j \le n, and

-(w_{i,j}, w_{k,\ell}) \in I if 1 \le i < k \le m and n \ge j > \ell \ge 1.
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The situation in the lemma will be visualized by a diagram of the following kind. The i-th column corresponds to  $u_i$ , the j-th row corresponds to  $v_j$ , and the intersection of the i-th column and the j-th row represents  $w_{i,j}$ . Furthermore  $w_{i,j}$  and  $w_{k,\ell}$  are independent if one of them is left-above the other one.

See, e.g., [40] for the notion of logspace reducibility.

$v_n$	$w_{1,n}$	$w_{2,n}$	$w_{3,n}$	 $w_{m,n}$
:	• • •	:	• • •	 • • •
$v_3$	$w_{1,3}$	$w_{2,3}$	$w_{3,3}$	 $w_{m,3}$
$v_2$	$w_{1,2}$	$w_{2,2}$	$w_{3,2}$	 $w_{m,2}$
$v_1$	$w_{1,1}$	$w_{2,1}$	$w_{3,1}$	 $w_{m,1}$
	$u_1$	$u_2$	$u_3$	 $u_m$

A consequence of Levi's Lemma is that trace monoids are cancellative, i.e., usv = utv implies s = t for all traces  $s, t, u, v \in M$ .

A subset  $L \subseteq \mathbb{M}$  is recognizable if there exists a finite monoid S and a monoid homomorphism  $h: \mathbb{M} \to S$ , which may be assumed to be surjective, such that  $L = h^{-1}(h(L))$ . The class of recognizable subsets of  $\mathbb{M}$  is a Boolean algebra. In case A is finite, it is easy to see that L is recognizable if and only if the language  $\{u \in A^* \mid [u]_I \in L\}$  is a regular subset of  $A^*$ . Thus, every finite subset of  $\mathbb{M}$  is recognizable. Moreover, the recognizable subsets of  $\mathbb{M}$  are closed under products [39].

We end this section with a brief discussion of trace rewriting systems, which generalize semi-Thue systems [5] from words to traces. Formally, a trace rewriting system over M is a subset  $R \subseteq \mathbb{M} \times \mathbb{M}$ . Its domain is the set dom $(R) = \{s \in \mathbb{M} \mid \exists t \in \mathbb{M} : (s,t) \in R\}$  and its range is defined dually by  $\operatorname{ran}(R) = \{t \in \mathbb{M} \mid \exists s \in \mathbb{M} : (s,t) \in R\}$ . We define the one-step rewrite relation  $\to_R$  on M as follows:  $s \to_R t$  if there exist  $u, v \in \mathbb{M}$  and  $(\ell, r) \in R$  with  $s = u\ell v$  and t = urv. The Thue congurence  $\stackrel{*}{\leftrightarrow}_R$  is the smallest equivalence relation on M that contains  $\to_R$ ; it is easily seen to be a congurence on the trace monoid M. Thus, we can define the quotient monoid  $\mathbb{M}/_{\stackrel{*}{\leftrightarrow}_R}$ , briefly  $\mathbb{M}/_R$ . In case  $I = \emptyset$ , i.e.,  $\mathbb{M} = A^*$ , R is called a semi-Thue system over A.

The set RED(R) is the set of all traces  $t \in \mathbb{M}$  such that  $t \to_R s$  for some s. The set of irreducible traces (with respect to R) is  $IRR(R) = \mathbb{M} \backslash RED(R)$ . The sytem R is terminating if there does not exist an infinite chain  $s_1 \to_R s_2 \to_R s_3 \to_R \cdots$  in  $\mathbb{M}$ , it is length-reducing if |s| > |t| for all  $(s, t) \in R$  and, finally, it is confluent if for all  $s, t, u \in \mathbb{M}$  with  $t \overset{*}{\underset{R}{\leftarrow}} s \overset{*}{\underset{R}{\rightarrow}} u$  there exists  $v \in \mathbb{M}$  with  $t \overset{*}{\underset{R}{\rightarrow}} v \overset{*}{\underset{R}{\leftarrow}} u$ . It is well-known that R is confluent if and only if R is Church-Rosser, i.e., for all  $s, t \in \mathbb{M}$ , if  $s \overset{*}{\underset{R}{\rightarrow}} t$ , then  $s \overset{*}{\underset{R}{\rightarrow}} u \overset{*}{\underset{R}{\leftarrow}} t$  for some  $u \in \mathbb{M}$ , see [5, p 12]. Moreover, if R is terminating and confluent, then for every  $s \in \mathbb{M}$  there exists a unique normal form  $NF_R(s) \in IRR(R)$  such that  $s \overset{*}{\underset{R}{\rightarrow}} NF_R(s)$  and  $s \overset{*}{\underset{R}{\rightarrow}} t$  if and only if  $NF_R(s) = NF_R(t)$ . Thus, if A and R are both finite and R is moreover terminating and confluent, then the word problem for  $\mathbb{M}/_R$  is decidable. In general, it is undecidable whether a finite length-reducing trace rewriting system is confluent, see [36]. This is in sharp contrast to semi-Thue systems, and makes confluence proofs challenging.

## 3 Cayley-graphs

In this section we introduce the main concept of this work — Cayley-graphs of monoids, and prove some basic results on these graphs.

Let  $\mathcal{M} = (M, \circ, 1)$  be a finitely generated monoid with identity 1 and let  $\Gamma$  be a finite generating set for  $\mathcal{M}$ . The Cayley-graph of  $\mathcal{M}$  with respect to  $\Gamma$  is the following relational

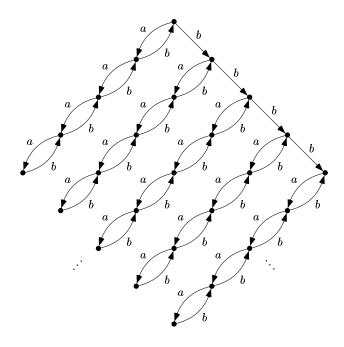


Fig. 1.

structure:

$$\mathcal{C}(\mathcal{M}, \Gamma) = (M, (\{(u, v) \mid u \circ a = v\})_{a \in \Gamma})$$

It is a directed graph, where every edge has a label from  $\Gamma$  and  $\{(u,v) \mid u \circ a = v\}$  is the set of a-labeled edges. We express the fact that there exists an a-labeled edge from x to y by writing  $x \circ a = y$  or briefly xa = y. Since  $\Gamma$  generates  $\mathcal{M}$ ,  $\mathcal{C}(\mathcal{M}, \Gamma)$  is (weakly) connected.

Cayley-graphs of groups play an important role in combinatorial group theory [28], see also the surveys of Babai [1] and Schupp [41]. On the other hand, only a few papers deal with Cayley-graphs for monoids. Combinatorial aspects of Cayley-graphs of monoids are studied in [20–22, 51]. In [44, 45], Cayley-graphs of automatic monoids are investigated. The work of Calbrix and Knapik on Thue-specifications [7, 24] covers Cayley-graphs of monoids  $\Gamma^*/_R$  with R terminating and confluent as a special case.

Figure 1 and 2 depict some typical Cayley-graphs. Figure 1 shows the Cayley-graph of  $\{a,b\}^*/_{\{(ab,\varepsilon)\}}$ , with respect to the generating set  $\{a,b\}$ . Figure 2 shows the Cayley-graph of  $\{a,b\}^*/_{\{(ab,baa)\}}$  with respect to  $\{a,b\}$ . The concrete shape of the Cayley-graph  $\mathcal{C}(\mathcal{M},\Gamma)$  depends heavily on the chosen set of generators  $\Gamma$ . Nevertheless, and similarly to the word problem, the chosen generating set has no influence on the decidability (or complexity) of the first-order (resp. monadic second-order) theory of the Cayley-graph:

**Proposition 3.1.** Let  $\Gamma_1$  and  $\Gamma_2$  be finite generating sets for the monoid  $\mathcal{M}$ . Then  $\mathrm{FOTh}(\mathcal{C}(\mathcal{M}, \Gamma_1))$  is logspace reducible to  $\mathrm{FOTh}(\mathcal{C}(\mathcal{M}, \Gamma_2))$  and the same holds for the  $\Sigma_n$ -,  $\Pi_n$ -, and MSO-theories.

*Proof.* We prove the statement for the first-order theories. The same construction also applies for the other theories mentioned in the proposition. The only difficulty is to find

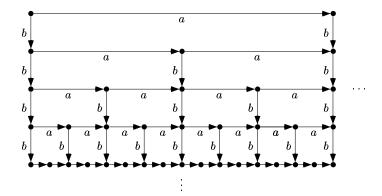


Fig. 2.

a logspace-reduction that preserves the quantifier alternation depth. Given a first-order sentence  $\phi_1$  over the signature of  $\mathcal{C}(\mathcal{M}, \Gamma_1)$  we construct a first-order sentence  $\phi_2$  over the signature of  $\mathcal{C}(\mathcal{M}, \Gamma_2)$  such that  $\mathcal{C}(\mathcal{M}, \Gamma_1) \models \phi_1$  if and only if  $\mathcal{C}(\mathcal{M}, \Gamma_2) \models \phi_2$  as follows: For  $a \in \Gamma_1$ , fix some letters  $b_1^a, \ldots, b_{n_a}^a \in \Gamma_2$  such that a and  $b_1^a, \ldots, b_{n_a}^a$  describe the same element of the monoid  $\mathcal{M}$ . Define the first-order formula  $\theta(x, (x_k^a)_{\substack{a \in \Gamma_1 \\ 1 \le k \le n_a}})$  as

$$\theta(x, (x_k^a)_{\substack{a \in \Gamma_1 \\ 1 \le k \le n_a}}) \equiv \bigwedge_{a \in \Gamma_1} x b_1^a = x_1^a \wedge \bigwedge_{\substack{a \in \Gamma_1 \\ 1 \le k \le n_a}} x_{k-1}^a b_k^a = x_k^a.$$

Then we replace simultaneously in  $\phi_2$  every quantification  $\exists x : \psi$  (resp.  $\forall x : \psi$ ) by

$$\exists x \; \exists_{\substack{a \in \varGamma_1 \\ 1 \le k \le n_a}} \; x_k^a : \theta(x, (x_k^a)_{\substack{a \in \varGamma_1 \\ 1 \le k \le n_a}}) \wedge \psi$$
resp. 
$$\forall x \; \forall_{\substack{a \in \varSigma_1 \\ 1 \le k \le n_a}} \; x_k^a : \theta(x, (x_k^a)_{\substack{a \in \varGamma_1 \\ 1 \le k \le n_a}}) \to \psi.$$

Here, the  $x_k^a$  are new variables that do not appear in  $\phi_1$ . Finally, to obtain  $\phi_2$ , we replace in the resulting sentence every occurrence of an atomic predicate xa = y by  $x_{n_a}^a = y$ . It is easy to see that  $\mathcal{C}(\mathcal{M}, \Gamma_1) \models \phi_1$  if and only if  $\mathcal{C}(\mathcal{M}, \Gamma_2) \models \phi_2$ . Moreover, if  $\phi_1$  is in prenex normal form and we transform  $\phi_2$  into prenex normal form (for which we only have to pull out all quantifiers), then the two sentences have the same quantifier alternation depth. Finally, note that the sentence  $\phi_2$  can be produced using only logarithmic space, an observation that completes the proof of this proposition.

Whenever the specific generating set  $\Gamma$  will be of no importance, we will briefly write  $\mathcal{C}(\mathcal{M})$  instead of  $\mathcal{C}(\mathcal{M}, \Gamma)$ . The next proposition states a simple connection between the word problem and the first-order theory of the Cayley-graph.

**Proposition 3.2.** Let  $\mathcal{M}$  be a finitely generated monoid such that  $\Sigma_1(\mathcal{C}(\mathcal{M}))$  is decidable. Then the word problem for  $\mathcal{M}$  is decidable.

*Proof.* Choose a finite generating set  $\Gamma$  for  $\mathcal{M}$ . Two given words  $u = a_0 a_1 \cdots a_{m-1}$  and  $v = b_0 b_1 \cdots b_{m-1}$ , where  $a_i, b_j \in \Gamma$ , represent different elements in  $\mathcal{M}$  if and only if there exists  $x \in \mathcal{M}$  such that the (unique) paths in  $\mathcal{C}(\mathcal{M}, \Gamma)$  starting in x and labeled by u and v, respectively, end in different nodes. This fact can be easily expressed by an  $\Sigma_1$ -sentence of first-order logic:

$$\exists x_0 \cdots \exists x_m \exists y_0 \cdots \exists y_n \left\{ \bigwedge_{0 \le i < m}^{x_0 = y_0 \land x_m \ne y_n \land \bigwedge_{0 \le i < n}^{x_i a_i = x_{i+1} \land \bigwedge_{0 \le i < n}^{x_i b_i = y_{i+1}} \right\}$$

Note that Book [4] has shown that the word problem for a monoid  $\Gamma^*/_R$ , where  $\Gamma$  and R are finite and R is length-reducing and confluent, can be solved in linear time. Hence the following proposition shows that the converse implication of Proposition 3.2 becomes false.

**Proposition 3.3.** There exists a fixed finite, length-reducing, and confluent semi-Thue system R over a finite alphabet  $\Gamma$  such that  $\Sigma_1(\mathcal{C}(\Gamma^*/_R))$  is undecidable.

*Proof.* By [37, Thm. 2.4] there exists a fixed finite, length-reducing, and confluent semi-Thue system R over  $\Gamma$  such that the common right-multiplier problem is undecidable for  $\Gamma^*/_R$ , which is the following problem:

INPUT: Words  $u, v \in \Gamma^*$ 

QUESTION: Does there exist  $x \in \Gamma^*$  with  $xu \stackrel{*}{\leftrightarrow}_R xv$ ?

But this is a  $\Sigma_1$ -property of the Cayley-graph of  $\Gamma^*/_R$  that can be constructed effectively from u and v. This proves the proposition.

The next result was shown in [10]. A semi-Thue system R over  $\Gamma$  is *left-basic* if it satisfies the following two conditions:

- if  $\ell \in \text{dom}(R)$ ,  $r \in \text{ran}(R)$ , and  $r = u\ell v$ , then  $u = v = \varepsilon$ .
- if  $\ell \in \text{dom}(R)$ ,  $r \in \text{ran}(R)$ ,  $ur = \ell v$ , and  $|\ell| > |u|$ , then  $v = \varepsilon$ .

A semi-Thue system R over a finite alphabet  $\Gamma$  is regular if R can be written as  $R = \bigcup_{i=1}^{n} L_i \times R_i$  where both  $L_i \subseteq \Gamma^*$  and  $R_i \subseteq \Gamma^*$  are regular for  $1 \leq i \leq n$ .

**Proposition 3.4.** Let R be a terminating, confluent, left-basic, and regular semi-Thue system R over a finite alphabet  $\Gamma$ . Then  $MSOTh(\mathcal{C}(\Gamma^*/_R))$  is decidable.

## 4 Graph products

In this section we will introduce graph products of monoids. The graph product construction generalizes both the free product and the direct product. Graph products were

<sup>&</sup>lt;sup>2</sup> In [37, Thm. 2.4] undecidability is stated for the common left-multiplier problem, but by reversing the words in R, undecidability is also obtained for the common right-multiplier problem.

introduced in [17]. Our main result will state that the decidability of the first-order theory (resp. MSO-theory) of the Cayley-graph is preserved under graph products (resp. free products). Other closure results for graph products can be found for instance in [18, 27, 48, 49].

Let  $(\Sigma, I_{\Sigma})$  be a finite independence alphabet, i.e.,  $\Sigma$  is finite, and let  $\mathcal{M}_{\sigma} = (M_{\sigma}, \circ_{\sigma}, 1_{\sigma})$  be a finitely generated monoid for every  $\sigma \in \Sigma$ . Let  $A_{\sigma} = M_{\sigma} \setminus \{1_{\sigma}\}$ , where w.l.o.g.  $A_{\sigma} \cap A_{\tau}$  for  $\sigma \neq \tau$ . Define an independence alphabet (A, I) by

$$A = \bigcup_{\sigma \in \Sigma} A_{\sigma}$$
 and  $I = \bigcup_{(\sigma, \tau) \in I_{\Sigma}} A_{\sigma} \times A_{\tau}$ .

Let  $R_{\sigma}$  for  $\sigma \in \Sigma$  and R be the following trace rewriting systems over  $\mathbb{M}(A, I)$ :

$$R_{\sigma} = \{(ab, c) \mid a, b, c \in A_{\sigma}, a \circ_{\sigma} b = c\} \cup \{(ab, \varepsilon) \mid a, b \in A_{\sigma}, a \circ_{\sigma} b = 1_{\sigma}\}$$

$$R = \bigcup_{\sigma \in \Sigma} R_{\sigma}.$$

Then the graph product  $\mathbb{P}(\Sigma, I_{\Sigma}, (\mathcal{M}_{\sigma})_{\sigma \in \Sigma})$  is the quotient monoid  $\mathbb{M}(A, I)/_R$ . Special cases are the free product  $*_{\sigma \in \Sigma} \mathcal{M}_{\sigma}$  (if  $I_{\Sigma} = \emptyset$ ) and the direct product  $\prod_{\sigma \in \Sigma} \mathcal{M}_{\sigma}$  (if  $I_{\Sigma} = (\Sigma \times \Sigma) \setminus \{(\sigma, \sigma) \mid \sigma \in \Sigma\}$ ). If every  $\mathcal{M}_{\sigma}$  is generated by  $\Gamma_{\sigma}$ , then from the definition of  $\mathbb{P}$  it is obvious that  $\mathbb{P}$  is generated by  $\Gamma = \bigcup_{\sigma \in \Sigma} \Gamma_{\sigma}$ . In fact, if the monoid  $\mathcal{M}_{\sigma}$  is isomorphic to  $\Gamma^*/_{S_{\sigma}}$ , then, using Tietze transformations, it is easy to see that  $\mathbb{P}$  is isomorphic to  $\Gamma^*/_{S}$ , where  $S = \bigcup_{\sigma \in \Sigma} S_{\sigma} \cup \{(ab, ba) \mid a \in \Gamma_{\sigma}, b \in \Gamma_{\tau}, (\sigma, \tau) \in I_{\Sigma}\}$ .

The following theorem is the main result of this section. For technical reasons, we will add in the further discussion the neutral element of a monoid as a constant to the Cayley-graph. Thus, define the *rooted Cayley-graph* of a finitely generated monoid  $\mathcal{M}$  as the rooted graph  $(\mathcal{C}(\mathcal{M}), 1)$ , where 1 is the neutral element of  $\mathcal{M}$ .

**Theorem 4.1.** Let  $\mathbb{P} = \mathbb{P}(\Sigma, I_{\Sigma}, (\mathcal{M}_{\sigma})_{\sigma \in \Sigma})$ , where  $\mathcal{M}_{\sigma}$  is finitely generated.

- (1) If  $FOTh(\mathcal{C}(\mathcal{M}_{\sigma}), 1_{\sigma})$  is decidable for all  $\sigma \in \Sigma$ , then also  $FOTh(\mathcal{C}(\mathbb{P}), 1)$  is decidable.
- (2) If  $I_{\Sigma} = \emptyset$  and  $MSOTh(\mathcal{C}(\mathcal{M}_{\sigma}), 1_{\sigma})$  is decidable for all  $\sigma \in \Sigma$ , then also  $MSOTh(\mathcal{C}(\mathbb{P}), 1)$  is decidable.

Before we go into the details of the proof of Theorem 4.1 (that can be found in Section 6) let us first state some consequences and limitations.

In [25] the authors have shown that for a finitely generated group  $\mathcal{G}$ , FOTh( $\mathcal{C}(\mathcal{G})$ ) is decidable if and only if the word problem of  $\mathcal{G}$  is decidable. Together with Statement (1) in Theorem 4.1 we obtain the following result:

**Corollary 4.2.** Let  $\mathcal{M}$  be a graph product of automatic monoids and groups with decidable word problems. Then  $FOTh(\mathcal{C}(\mathcal{M}))$  is decidable.

Statement (1) in Theorem 4.1 does not generalize to MSO-theories:

**Proposition 4.3.** Let  $\mathbb{P} = \mathbb{P}(\Sigma, I_{\Sigma}, (\mathcal{M}_{\sigma})_{\sigma \in \Sigma})$ , where  $\mathcal{M}_{\sigma}$  is nontrivial and finitely generated by  $\Gamma_{\sigma}$ . If  $MSOTh(\mathcal{C}(\mathbb{P}), 1)$  is decidable, then:

- $-(\Sigma, I_{\Sigma})$  does not contain an induced cycle of length 4 (also called C4),
- $-if(\sigma,\tau) \in I_{\Sigma}$  and  $\mathcal{M}_{\sigma}$  is infinite, then  $\mathcal{M}_{\tau}$  is finite,
- $-if(\sigma,\sigma_1),(\sigma,\sigma_2)\in I_{\Sigma}, \ \sigma_1\neq\sigma_2, \ and \ \mathcal{M}_{\sigma} \ is \ infinite, \ then \ (\sigma_1,\sigma_2)\in I_{\Sigma}, \ and \ \mathcal{M}_{\sigma}$
- $MSOTh(\mathcal{C}(\mathcal{M}_{\sigma}), 1_{\sigma})$  is decidable for every  $\sigma \in \Sigma$ .

*Proof.* If one of the first three conditions is not satisfied, then  $\mathbb{P}$  contains a submonoid of the form  $\mathcal{M}_1 \times \mathcal{M}_2$ , where both  $\mathcal{M}_1$  and  $\mathcal{M}_2$  are infinite (note that we assume that every  $\mathcal{M}_{\sigma}$  is nontrivial). Since  $\mathcal{C}(\mathcal{M}_i)$  is infinite and every node has finite outdegree, we find an infinite path  $a_{i,1} \to a_{i,2} \to \cdots$  in  $\mathcal{C}(\mathcal{M}_i)$ . In  $\mathcal{M}_1 \times \mathcal{M}_2 \subseteq \mathbb{P}$ , these two paths generate an infinite grid. Hence the MSO-theory of  $\mathcal{C}(\mathbb{P})$  is undecidable, see, e.g., [16].

Next we show that  $MSOTh(\mathcal{C}(\mathcal{M}_{\sigma}), 1_{\sigma})$  is decidable for every  $\sigma \in \Sigma$  in case  $MSOTh(\mathcal{C}(\mathbb{P}), 1)$  is decidable. Note that  $\mathcal{M}_{\sigma}$  is the least subset of  $(\mathcal{C}(\mathbb{P}), 1)$  containing 1 that is closed under a-successors for  $a \in \Gamma_{\sigma}$ ; hence  $M_{\sigma}$  is MSO-definable in  $(\mathcal{C}(\mathbb{P}), 1)$ . Since an MSO sentence  $\varphi$  holds in  $(\mathcal{C}(\mathcal{M}_{\sigma}), 1_{\sigma})$  if and only if its restriction to  $\mathcal{M}_{\sigma} \subseteq \mathbb{P}$  holds in  $(\mathcal{C}(\mathbb{P}), 1)$ , the result follows.

In order to prove Theorem 4.1, we will introduce in the next section two general unfolding operations that work for arbitrary relational structures.

### 5 Unfoldings

#### 5.1 Tree-like unfoldings

In [42] Semenov introduced the following construction, which he attributes to An. A. Muchnik and which generalizes a construction from [43, 46].

**Definition 5.1.** Let  $A = (A, (R_i)_{1 \leq i \leq \kappa})$  be a relational structure with finitely many relations, where the relation  $R_i$  has arity  $n_i$ . On the set of finite words  $A^*$ , we define the following relations:

$$\widehat{R}_i = \{ (ua_1, ua_2, \dots, ua_{n_i}) \mid u \in A^*, (a_1, a_2, \dots, a_{n_i}) \in R_i \}$$

$$\text{suc} = \{ (u, ua) \mid u \in A^*, a \in A \}$$

$$\text{cl} = \{ (ua, uaa) \mid u \in A^*, a \in A \}^3$$

The relational structure  $\widehat{\mathcal{A}} = (A^*, (\widehat{R_i})_{1 \le i \le \kappa}, \operatorname{suc}, \operatorname{cl})$  is called the tree-like unfolding of  $\mathcal{A}$ .

One can think of the structure  $\widehat{\mathcal{A}}$  as a tree  $(A^*, \operatorname{suc})$  together with some additional relations. Any tuple of elements of  $A^*$  that appears in one of the additional relations is "local": the distance between any two entries in the tree  $(A^*, \operatorname{suc})$  is at most 2. The term tree-like unfolding comes from the fact that  $\widehat{\mathcal{A}}$  is an extension of the tree  $(A^*, \operatorname{suc})$ .

In [42], Semenov also sketched a proof of the following result, which he attributes to An. A. Muchnik. A complete proof was given by Walukiewicz [50].

<sup>&</sup>lt;sup>3</sup> "cl" stands for "clone".

**Theorem 5.2 (cf. [50]).**  $MSOTh(\widehat{A})$  can be reduced to MSOTh(A).

The relations of the tree-like unfolding are instances of a more general construction, which will be crucial for our notion of factorized unfoldings: Let  $\varphi$  be a first-order formula over the signature of  $\mathcal{A}$  with  $\sum_{i=1}^{n} k_i$  free variables, where  $k_i \in \mathbb{N}$   $(k_i = 0 \text{ is allowed})$ . For words  $u_i = a_{i,1}a_{i,2}\cdots a_{i,k_i}$   $(a_{i,j} \in A)$  of length  $k_i$   $(1 \le i \le n)$  we write  $\mathcal{A} \models \varphi(u_1, u_2, \ldots, u_n)$  if

$$A \models \varphi(a_{1,1},\ldots,a_{1,k_1},a_{2,1},\ldots,a_{2,k_2},\ldots,a_{n,1},\ldots,a_{n,k_n}).$$

An *n*-ary relation R over  $A^*$  is k-suffix definable in  $\mathcal{A}$  if there are  $k_1, \ldots, k_n \leq k$  and a first-order formula  $\varphi$  over the signature of  $\mathcal{A}$  with  $\sum_{i=1}^n k_i$  free variables such that

$$R = \{(uu_1, uu_2, \dots, uu_n) \mid u, u_i \in A^*, |u_i| = k_i, \mathcal{A} \models \varphi(u_1, u_2, \dots, u_n)\}.$$

Note that a formula  $\varphi$  with m free variables defines many different k-suffix definable relations, namely one for each partition of the number m.

All relations of  $\widehat{\mathcal{A}}$  are 2-suffix definable in  $\widehat{\mathcal{A}}$ . On the other hand, there exist 2-suffix definable relations such that adding them to  $\widehat{\mathcal{A}}$  makes Theorem 5.2 fail: To see this, let

$$cp = \{(ua, uba) \mid u \in A^*, a, b \in A\},\$$

which is 2-suffix definable in  $\mathcal{A}$ .<sup>4</sup> Recall that  $\leq$  denotes the prefix order on  $A^*$ ; thus it is the reflexive transitive closure of the relation suc from  $\widehat{\mathcal{A}}$  and therefore MSO definable in  $\widehat{\mathcal{A}}$ .

**Proposition 5.3.** Let  $S = \{(n, n+1) \mid i \in \mathbb{N}\}$  be the successor relation on  $\mathbb{N}$ . Then  $MSOTh(\mathbb{N}, S)$  is decidable but  $FOTh(\mathbb{N}^*, \widehat{S}, \preceq, cp)$  is undecidable.

Proof. The decidability of MSOTh( $\mathbb{N}, S$ ) was shown by Büchi [6]. For the undecidability of FOTh( $\mathbb{N}^*, \widehat{S}, \preceq$ , cp) recall that it is undecidable whether a given two-counter machine (with zero-tests), started with empty counters, finally terminates. Thus, let us fix a two-counter machine  $\mathcal{CM}$  with initial state  $q_0$  and final state  $q_f \neq q_0$ . We will construct a first-order sentence  $\phi_{\mathcal{CM}}$  such that  $(\mathbb{N}^*, \widehat{S}, \preceq, \operatorname{cp}) \models \phi_{\mathcal{CM}}$  if and only if  $\mathcal{CM}$ , started in the configuration  $(q_0, 0, 0)$  terminates. We can assume that the state space Q of  $\mathcal{CM}$  is  $\{1, \ldots, \lambda\}$  for some  $\lambda \in \mathbb{N}$ . Then a computation of  $\mathcal{CM}$  starting in  $(q_0, 0, 0)$  can be encoded by a sequence of the form  $q_0 m_0 n_0 0 q_1 m_1 n_1 0 \cdots q_k m_k n_k \in \mathbb{N}^*$  such that  $q_i \in Q$ ,  $m_i, n_i \geq 1$ ,  $m_0 = n_0 = 1$ , and  $(q_{i+1}, m_{i+1} - 1, n_{i+1} - 1)$  is a successor configuration of  $(q_i, m_i - 1, n_i - 1)$  for  $\mathcal{CM}$ .

First, note that the relation suc from the tree-like unfolding is first-order definable in  $(\mathbb{N}^*, \preceq)$ . For a fixed  $n \in \mathbb{N}$ , it is also easy to write down a formula  $\psi_n(x)$  such that  $(\mathbb{N}^*, \widehat{S}, \preceq, \operatorname{cp}) \models \psi_n(w)$  if and only if w = v n for some  $v \in \mathbb{N}^*$ : We start with  $\psi_0(x) \equiv \neg \exists y : \widehat{S}(y, x) \land \exists z : \operatorname{suc}(z, x)$  and define inductively  $\psi_n(x) \equiv \exists y : \psi_{n-1}(y) \land \widehat{S}(y, x)$ . Next, using the prefix relation  $\preceq$  and the formulas  $\psi_n$  for  $0 \leq n \leq \lambda$ , we can construct a first-order formula  $\phi_0(x)$  such that  $(\mathbb{N}^*, \widehat{S}, \preceq, \operatorname{cp}) \models \phi_0(w)$  if and only if  $w \in \mathbb{N}^*$  has

<sup>&</sup>lt;sup>4</sup> "cp" stands for "copy".

the form  $q_0 m_0 n_0 0 q_1 m_1 n_1 0 \cdots q_k m_k n_k$  with  $q_i \in Q$ ,  $m_i, n_i \geq 1$ ,  $m_0 = n_0 = 1$ , and  $q_k = q_f$ . Furthermore, we claim that there exists a formula  $\phi_1(x)$  such that for every  $w \in \mathbb{N}^*$  we have  $(\mathbb{N}^*, \widehat{S}, \preceq, \operatorname{cp}) \models \phi_1(w)$  if and only if for every prefix  $v p k \ell 0 q m n \preceq w$  with  $p, k, \ell, q, m, n \geq 1$ , the configuration (q, m - 1, n - 1) is a successor configuration of  $(p, k - 1, \ell - 1)$ , i.e., one of the finitely many transition rules of  $\mathcal{CM}$  transforms the configuration  $(p, k - 1, \ell - 1)$  into (q, m - 1, n - 1). Let us consider one such transition rule, saying, e.g., that if  $\mathcal{CM}$  is in state  $q_1 \in Q$ , then  $\mathcal{CM}$  can move into state  $q_2 \in Q$  and add 1 to the first counter. It suffices to construct a formula  $\theta(x)$  such that for every word w of the form  $v p m n 0 q k \ell$  with  $v \in \mathbb{N}^*$ , we have  $(\mathbb{N}^*, \widehat{S}, \preceq, \operatorname{cp}) \models \theta(w)$  if and only if  $p = q_1$ ,  $q = q_2$ ,  $\ell = n$ , and k = m + 1.

It is easy to express  $p=q_1$  and  $q=q_2$  using  $\psi_{q_1}$  and  $\psi_{q_2}$ . Thus, it remains to express k=m+1 (and  $\ell=n$ , which can be done analogously): This is the case if and only if there are  $x_i, y_i \in \mathbb{N}^*$  for  $0 \le i \le 4$  such that

$$\operatorname{suc}(x_4, w) \wedge y_4 = x_4; \wedge \widehat{S}(x_0, y_0) \wedge \bigwedge_{i=1}^4 \left(\operatorname{suc}(x_{i-1}, x_i) \wedge \operatorname{cp}(y_{i-1}, y_i)\right).$$

This formula expresses that

- (1)  $x_0, x_1, x_2, x_3, x_4, w$  is a successor sequence, i.e.,  $x_4 = v p m n 0 q k$ ,  $x_3 = v p m n 0 q$ , ...,  $x_0 = v p m$ ,
- (2)  $y_0 = v p (m+1)$  because of  $\widehat{S}(x_0, y_0)$ ,
- (3)  $y_4 = x_4$ , i.e.,  $y_4 = v p m n 0 q k$ ,
- (4) and  $y_{i-1}$  is obtained from  $y_i$  by deleting the penultimate letter, i.e.,  $y_3 = v p m n 0 k$ ,  $y_2 = v p m n k$ ,  $y_1 = v p m k$ , and  $y_0 = v p k$ .

Since  $v p k = y_0 = v p (m + 1)$  the formula expresses indeed k = m + 1. Other transitions can be dealt with similarly. Hence, we have  $(\mathbb{N}^*, \widehat{S}, \preceq, \operatorname{cp}) \models \exists x : \phi_0(x) \land \phi_1(x)$  if and only if  $\mathcal{CM}$  reaches the final state  $q_f$  from the initial configuration  $(q_0, 0, 0)$ . This proves the theorem.

Since  $\leq$  is MSO-definable in the presence of suc, the previous proposition implies that MSOTh( $\mathbb{N}^*$ ,  $\widehat{S}$ , suc, cp) is undecidable. Thus, the presence of the relation cp makes Walukiewicz's result fail.

Recall that the underlying set of the tree-like unfolding of a structure  $\mathcal{A}$  is the set of all finite words over the carrier set of  $\mathcal{A}$ . In factorized unfoldings that we introduce next, this underlying set consists of Mazurkiewicz traces.

#### 5.2 Factorized unfoldings

Let (A, I) be an independence alphabet. For an *n*-ary relation R over  $A^*$ , we define its I-quotient

$$R/_I = \{([u_1]_I, \dots, [u_n]_I) \mid (u_1, \dots, u_n) \in R\}.$$

For instance,  $\leq I$  is the prefix order on traces.

**Definition 5.4.** Let A be a relational structure with carrier set A. Let furthermore

- $-I \subseteq A \times A$  be an independence relation that is first-order definable in A,
- $-\eta: \mathbb{M}(A,I) \to S$  be a monoid homomorphism into some finite monoid S such that  $\eta^{-1}(q) \cap A$  is first-order definable in  $\mathcal{A}$  for every  $q \in S$ , and
- $R_i$  be a  $k_i$ -suffix definable relation in  $\mathcal{A}$  for  $1 \leq i \leq \kappa$ .

Then the structure  $\mathcal{B} = (\mathbb{M}(A, I), (\eta^{-1}(q))_{q \in S}, (R_i/I)_{1 \leq i \leq \kappa})$  is a factorized unfolding of  $\mathcal{A}$ , it is also called the factorized unfolding of  $\mathcal{A}$  corresponding to I,  $\eta$ , and  $(R_i)_{1 \leq i \leq \kappa}$ .

Note that in contrast to the tree-like unfolding there are many different factorized unfoldings of A.

The notion of a factorized unfolding is a proper generalization of the tree-like unfolding, also in case  $I = \emptyset$  in Definition 5.4: By Proposition 5.3, the relation cp cannot be defined in the tree-like unfolding  $\widehat{\mathcal{A}}$ , but since it is 2-suffix definable it may be part of a factorized unfolding. On the other hand, for the relations  $\eta^{-1}(q)$  in the above definition we have the following:

**Lemma 5.5.** Let MSOTh(A) be decidable and  $\eta: A^* \to S$  be a monoid morphism into a finite monoid S such that  $\eta^{-1}(q) \cap A$  is MSO-definable in A for every  $q \in S$ . Then also  $MSOTh(\widehat{A}, (\eta^{-1}(q))_{q \in S})$  is decidable.

Proof. Since  $P_q := \eta^{-1}(q) \cap A$  is MSO-definable in  $\mathcal{A}$ , the structure  $\mathcal{B} = (\mathcal{A}, (P_q)_{q \in S})$  has a decidable MSO-theory. Hence, by Theorem 5.2, also MSOTh( $\widehat{\mathcal{B}}$ ) is decidable and it suffices to prove that  $\eta^{-1}(q) \subseteq A^*$  is MSO-definable in  $\widehat{B}$ . But  $x \in \eta^{-1}(q)$  if there is a partition  $(X_s)_{s \in S}$  of the universe  $A^*$  with  $\varepsilon \in X_1$  (where 1 is the unit of the monoid S),  $x \in X_q$  and, for all  $(y, z) \in \text{suc}$ : if  $y \in X_{s_1}$  and  $z \in \widehat{P_s}$ , then  $z \in \widehat{P_{s_1}s}$ .

The following theorem is our main result for factorized unfoldings.

**Theorem 5.6.** Let  $\mathcal{A}$  be a relational structure and let  $\mathcal{B}$  be the factorized unfolding of  $\mathcal{A}$  corresponding to I,  $\eta$ , and  $(R_i)_{1 \leq i \leq \kappa}$ , where  $\{I(a) \mid a \in A\} \subseteq 2^A$  is finite. Then any first-order sentence  $\varphi$  of quantifier alternation depth d over the signature of  $\mathcal{B}$  can be transformed effectively into a sentence  $\theta$  of quantifier alternation depth d + O(1) and size  $2^{2^{O(|\varphi|)}}$  over the signature of  $\mathcal{A}$  such that  $\mathcal{B} \models \varphi$  if and only if  $\mathcal{A} \models \theta$ .

Remark 5.7. We postpone the lengthy proof of this theorem to Section 7. It will also show that not only the size of  $\theta$  is bounded doubly exponential in the size of  $\varphi$ , but also the time needed to construct  $\theta$  from  $\varphi$  is bounded doubly exponential in  $|\varphi|$ .

In case A is finite, a much simpler proof using automatic structures is given as Theorem 8.2. By Theorem 8.1 below, the finiteness of  $\{I(a) \mid a \in A\}$  is necessary for Theorem 5.6 to hold.

**Corollary 5.8.** Let  $\mathcal{A}$  be a relational structure with a decidable first-order theory. Let  $\mathcal{B}$  be the factorized unfolding of  $\mathcal{A}$  corresponding to I,  $\eta$ , and  $(R_i)_{1 \leq i \leq \kappa}$ , where  $\{I(a) \mid a \in A\} \subset 2^A$  is finite. Then  $FOTh(\mathcal{B})$  is decidable.

Remark 5.9. Let  $(R_i)_{i\in\mathbb{N}}$  be a list of all relations that are k-suffix definable in  $\mathcal{A}$  for some  $k\in\mathbb{N}$ . Moreover, let  $(L_i)_{i\in\mathbb{N}}$  be a list of all subsets  $\eta^{-1}(q)\subseteq\mathbb{M}(A,I)$  such that  $\eta:\mathbb{M}(A,I)\to S$  is a homomorphism into a finite monoid  $S,\ q\in S$ , and  $\eta^{-1}(p)\cap A$  is first-order definable in  $\mathcal{A}$  for every  $p\in S$ . Note that every  $L_i$  is recognizable. Then also the first-order theory of  $\mathcal{B}=(\mathbb{M}(A,I),(L_i)_{i\in\mathbb{N}},(R_i/I)_{i\in\mathbb{N}})$  is decidable. The important point is that any first-order sentence over the signature of  $\mathcal{B}$  can mention only finitely many relations  $R_i/I$  and  $L_i$ . Thus, it suffices to work in a suitable reduct of  $\mathcal{B}$  with only finitely many relations, which can be handled by Theorem 5.6 provided the lists above are recursive enumerations. This is no problem for the list  $(R_i)_{i\in\mathbb{N}}$  since any such relation is uniquely given by a tuple  $(k_1,k_2,\ldots,k_n)$  of natural numbers and a first-order formula  $\varphi$  with  $k_1+\cdots+k_n$  free variables. For the languages  $L_i$ , we list all finite monoids S with distinguished element  $q\in S$  and all tuples  $(\varphi_p)_{p\in S}$  of first-order formulas with one free variable such that

- (1) the sets  $\{a \in A \mid \mathcal{A} \models \varphi_p(a)\}$  for  $p \in S$  form a partition of A and
- (2) if  $\mathcal{A} \models \varphi_{p_1}(a) \land \varphi_{p_2}(b)$  and  $(a, b) \in I$ , then  $p_1p_2 = p_2p_1$  in S.

These tuples can be enumerated since the first-order theory of  $\mathcal{A}$  is decidable and I is first-order definable in  $\mathcal{A}$ . By the second requirement, any such tuple encodes an homomorphism  $\eta$  from  $\mathbb{M}(A, I)$  into S satisfying  $\eta^{-1}(p) \cap A = \{a \in A \mid \mathcal{A} \models \varphi_p(a)\}$ . Hence from this enumeration of tuples, we obtain an effective enumeration of the sets  $L_i$  as required.

#### 6 Proof of Theorem 4.1

Using Theorem 5.2 and Theorem 5.6, we will give a proof of Theorem 4.1 in this section. Let us fix a graph product  $\mathbb{P} = \mathbb{P}(\Sigma, I_{\Sigma}, (\mathcal{M}_{\sigma})_{\sigma \in \Sigma})$  for the further discussion. Define  $A_{\sigma}$ , A, I,  $R_{\sigma}$ , and R as in Section 4. The crucial fact for our further investigation is the following:

**Lemma 6.1.** The trace rewriting system R over M(A, I) is confluent.

*Proof.* Since R is terminating, it suffices by Newman's Lemma [38] to show that R is *locally confluent*, i.e., for all  $s, s_1, s_2 \in \mathbb{M}(A, I)$  with  $s_1 \underset{R}{\leftarrow} s \to_R s_2$  there exists  $s' \in \mathbb{M}(A, I)$  with  $s_1 \underset{R}{\rightarrow}_R s' \underset{R}{\leftarrow} s_2$ .

Thus, assume that  $s \to_R s_1$  and  $s \to_R s_2$ . Hence,  $s = t_i a_i b_i u_i$  and  $s_i = t_i r_i u_i$  for i = 1, 2, where  $(a_i b_i, r_i) \in R$ . Thus,  $r_i \in A \cup \{\varepsilon\}$ . By applying Levi's Lemma 2.2 to the identity  $t_1 a_1 b_1 u_1 = t_2 a_2 b_2 u_2$ , we obtain the following diagram:

$u_2$	$w_2$	$q_1$	$v_2$
$a_2b_2$	$p_2$	t	$q_2$
$t_2$	$v_1$	$p_1$	$w_1$
	$t_1$	$a_1b_1$	$u_1$

Thus,  $(w_1, w_2) \in I$ . For the further arguments it is easy to see that we may assume  $v_1 = v_2 = \varepsilon$ . Assume that  $a_i, b_i \in A_{\sigma_i}$ . Let us first consider the case  $t \neq \varepsilon$ . Thus,  $\sigma_1 = \sigma_2 = \sigma$ ,  $r_1, r_2 \in A_{\sigma} \cup \{\epsilon\}$ , and  $(c, w_i) \in I$  for all  $c \in A_{\sigma}$  and i = 1, 2. Moreover, since  $(p_1, p_2) \in I$  but both traces only contain symbols from  $A_{\sigma}$ , we have  $p_1 = \varepsilon$  or  $p_2 = \varepsilon$  and similarly  $q_1 = \varepsilon$  or  $q_2 = \varepsilon$ . If  $p_1 = p_2 = q_1 = q_2 = \varepsilon$  then  $s_1 = s_2$ . Otherwise, since  $a_1b_1$  cannot be a proper factor of  $a_2b_2$  and vice versa, we obtain up to symmetry the following diagram:

$u_2$	$w_2$	$b_1$	ε
$a_2b_2$	$a_2$	$b_2 = a_1$	ω
$t_2$	ε	arepsilon	$w_1$
	$t_1$	$a_1b_1$	$u_1$

Thus,  $s_1 = a_2 w_2 r_1 w_1 = w_1 a_2 r_1 w_2$  and  $s_2 = w_1 r_2 w_2 b_1 = w_1 r_2 b_1 w_2$ . Finally, by definition of the system  $R_{\sigma}$  it follows that  $a_2 r_1$  and  $r_2 b_1$  can be reduced to  $a_2 \circ_{\sigma} b_2 \circ_{\sigma} b_1 = a_2 \circ_{\sigma} a_1 \circ_{\sigma} b_1$ . This concludes the case  $t \neq \varepsilon$ .

Now assume that  $t = \varepsilon$ . Thus, we have the following diagram:

$u_2$	$w_2$	$q_1$	ε
$a_2b_2$	$p_2$	ω	$q_2$
$t_2$	$\varepsilon$	$p_1$	$w_1$
	$t_1$	$a_1b_1$	$u_1$

If also  $p_1 = \varepsilon$ , i.e.,

$u_2$	$w_2$	$a_1b_1$	ε
$a_2b_2$	$p_2$	ω	$q_2$
$t_2$	$\varepsilon$	ε	$w_1$
	$t_1$	$a_1b_1$	$u_1$

then  $(w_1q_2, a_1) \in I$  implies  $(w_1q_2, r_1) \in I$ . We have to show that  $s_1 = p_2w_2r_1w_1q_2$  and  $s_2 = w_1r_2w_2a_1b_1$  can be reduced to the same trace. We have  $s_2 \to_R w_1r_2w_2r_1$ . Moreover with the independencies listed above, we obtain

$$s_1 = p_2 w_2 r_1 w_1 q_2 = p_2 w_2 w_1 q_2 r_1 = w_1 p_2 q_2 w_2 r_1 \rightarrow_R w_1 r_2 w_2 r_1.$$

If one of the traces  $p_2$ ,  $q_1$ , or  $q_2$  is empty, then we can argue analogously. Thus, we may assume that  $p_1$ ,  $p_2$ ,  $q_1$ , and  $q_2$  are nonempty. It follows  $p_1 = a_1$ ,  $q_1 = b_1$ ,  $p_2 = a_2$ , and  $q_2 = b_2$ . Then all traces from  $\{w_1, w_2, a_1b_1, a_2b_2\}$  are pairwise independent, from which it follows again easily that  $s_1$  and  $s_2$  can be reduced to  $w_1w_2r_1r_2$ .

Since R is also terminating, the previous lemma implies that  $\mathbb{P}$  is in one-to-one correspondence with  $IRR(R) \subseteq \mathbb{M}(A, I)$ , which is the set of all traces that do not contain a factor of the form ab with  $a, b \in A_{\sigma}$  for some  $\sigma \in \Sigma$ .

For the further consideration, assume that  $\mathcal{M}_{\sigma}$  is finitely generated by  $\Gamma_{\sigma} \subseteq A_{\sigma}$ . Then  $\mathbb{P}$  is finitely generated by  $\Gamma = \bigcup_{\sigma \in \Sigma} \Gamma_{\sigma}$ . Our next goal is to define the rooted Cayley-graph  $(\mathcal{C}(\mathbb{P}, \Gamma), 1)$  within the trace monoid  $\mathbb{M}(A, I)$ . For  $a \in \Gamma$ , let us define the edge-relation

$$F_a = \{(s, t) \in IRR(R) \times IRR(R) \mid sa \xrightarrow{*}_R t\}.$$

Since  $\mathbb{P} \cong \mathbb{M}(A, I)/_R$  and R is confluent and terminating, we obtain the following lemma:

**Lemma 6.2.**  $(IRR(R), (F_a)_{a \in \Gamma}), \varepsilon)$  is isomorphic to  $(\mathcal{C}(\mathbb{P}, \Gamma), 1)$ .

For a trace  $t \in \mathbb{M}(A, I)$  let  $\max(t) = \{a \in A \mid \exists u \in A^* : t = [ua]_I\}.$ 

**Lemma 6.3.** For  $s, t \in IRR(R) \subseteq M(A, I)$  and  $a \in \Gamma_{\sigma} \subseteq A_{\sigma}$  we have  $(s, t) \in F_a$  if and only if in M(A, I):

- -t = sa (and thus  $\max(s) \cap A_{\sigma} = \emptyset$ ), or
- -s = tb for  $b \in A_{\sigma}$  and  $b \circ_{\sigma} a = 1_{\sigma}$ , or
- -s = ub for  $u \in IRR(R)$ ,  $b \in A_{\sigma}$ ,  $b \circ_{\sigma} a = c \neq 1_{\sigma}$ , and t = uc.

*Proof.* If one of the three cases above holds, then it is easy to see that indeed  $sa \stackrel{*}{\to}_R t$ , i.e.,  $(s,t) \in F_a$ . Now assume that  $sa \stackrel{*}{\to}_R t \in IRR(R)$ . If  $t \neq sa$ , then  $sa \to_R v \stackrel{*}{\to}_R t$  for some trace v. Thus, there exist  $\tau \in \Sigma$ ,  $(bb', r) \in R_{\tau}$ , and  $s_1, s_2 \in M(A, I)$  such that  $sa = s_1bb's_2$ . By applying Levi's Lemma to this identity and using  $s \in IRR(R)$ , we obtain the following diagram:

$s_2$	$s_2$	ω
bc	b	a = b'
$s_1$	$s_1$	$\varepsilon$
	s	a

Thus,  $\tau = \sigma$  and  $(a, s_2) \in I$ , which implies also  $(b, s_2) \in I$ . Thus, s = ub, for  $u = s_1 s_2$ . If  $r = \varepsilon$ , i.e.,  $b \circ_{\sigma} a = 1_{\sigma}$ , then  $v = u \in IRR(R)$ . Thus, t = u and s = tb, i.e., the second case from the lemma holds. On the other hand, if  $r = b \circ_{\sigma} a = c \neq 1_{\sigma}$ , then v = uc, which again belongs to IRR(R) (otherwise, since  $b, c \in A_{\sigma}$ , also  $s = ub \in RED(R)$ ). Hence t = v = uc.

We now define a structure

$$\mathcal{A} = (A, (A_{\sigma})_{\sigma \in \Sigma}, (E_a)_{a \in \Gamma}, (a)_{a \in \Gamma}), \tag{1}$$

where for  $a \in \Gamma_{\sigma}$ ,  $\sigma \in \Sigma$ ,  $E_a$  consists of all pairs  $(x, y) \in A_{\sigma} \times A_{\sigma}$  such that  $x \circ_{\sigma} a = y$  in  $\mathcal{M}_{\sigma}$ . Thus,  $\mathcal{A}$  is the disjoint union of the restricted Cayley-graphs  $\mathcal{C}(\mathcal{M}_{\sigma}, \Gamma_{\sigma}) \setminus \{1_{\sigma}\}$ , where moreover every generator  $a \in \Gamma_{\sigma}$  is added as a constant, and every  $A_{\sigma} \subseteq A$  is added as a unary predicate. We will apply Theorem 5.2 and 5.6 to the structure  $\mathcal{A}$ . For this, we now define a suitable factorized unfolding of  $\mathcal{A}$ . First, note that the independence relation  $I \subseteq A \times A$  is first-order definable in  $\mathcal{A}$  using the unary predicates  $A_{\sigma}$  and that  $\{I(a) \mid a \in A\}$  is finite: If  $a, b \in A_{\sigma}$ , then I(a) = I(b). In order to define a suitable homomorphism  $\eta : \mathbb{M}(A, I) \to S$  into a finite monoid S, let us consider the finitely generated trace monoid  $\mathbb{M}(\Sigma, I_{\Sigma})$ . The closure properties of recognizable trace languages (see Section 2) imply that

$$L = \mathbb{M}(\Sigma, I_{\Sigma}) \setminus \bigcup_{\sigma \in \Sigma} \mathbb{M}(\Sigma, I_{\Sigma}) \sigma \sigma \mathbb{M}(\Sigma, I_{\Sigma})$$

is recognizable. Hence, there exists a homomorphism  $h: \mathbb{M}(\Sigma, I_{\Sigma}) \to S$  into a finite monoid S and a subset  $F \subseteq S$  such that  $L = h^{-1}(F)$ . Now define  $g: A \to \Sigma$  by  $g(a) = \sigma$  if  $a \in A_{\sigma}$ . We can extend g homomorphically to  $g: \mathbb{M}(A, I) \to \mathbb{M}(\Sigma, I_{\Sigma})$ . Let  $\eta = g \circ h$ . Then  $\eta^{-1}(F) = \operatorname{IRR}(R)$ . Note that for every  $q \in S$ , the set  $\eta^{-1}(q) \cap A_{\sigma}$  is either empty or  $A_{\sigma}$ . Thus, every set  $\eta^{-1}(q) \cap A$  is first-order definable in A.

From the previous discussion it follows that the structure

$$\mathcal{B} = (\mathbb{M}(A, I), (\eta^{-1}(q))_{q \in S}, \operatorname{suc}, (\widehat{A}_{\sigma/I})_{\sigma \in \Sigma}, (\widehat{E}_{a/I})_{a \in \Gamma}, (\widehat{a}/I)_{a \in \Gamma})$$
(2)

(see Section 5.1 for the definition of the operator  $\hat{}$  ) is a factorized unfolding of  $\mathcal{A}$ . We next present a first-order interpretation of the rooted Cayley-graph  $(\mathcal{C}(\mathbb{P}, \Gamma), 1)$  in  $\mathcal{B}$ .

**Lemma 6.4.**  $(\mathcal{C}(\mathbb{P}, \Gamma), 1)$  is first-order interpretable in  $\mathcal{B}$ .

*Proof.* By Lemma 6.2 it suffices to show that  $(IRR(R), (F_a)_{a \in \Gamma}, \varepsilon)$  is first-order interpretable in  $\mathcal{B}$ . First, recall that  $IRR(R) = \eta^{-1}(F)$ . Moreover,  $\varepsilon$  is the only trace t such that there is no s with  $(s,t) \in \text{suc}$ . Finally, by Lemma 6.3 we have  $(s,t) \in F_a$  for  $s,t \in IRR(R)$  and  $a \in \Gamma_{\sigma}$  if and only if in  $\mathcal{B}$ :

- $-(s,t) \in \text{suc}, s \notin \widehat{A_{\sigma}}/I$ , and  $t \in \widehat{a}/I$  (i.e., t = sa) or
- $-(t,s) \in \text{suc}, t \notin \widehat{A_{\sigma}}/I, s \in \widehat{A_{\sigma}}/I, \text{ but there is no } u \text{ with } (s,u) \in \widehat{E_a}/I \text{ (note that if } s \in \widehat{A_{\sigma}}/I, \text{ i.e., } s = vb \text{ with } b \in A_{\sigma}, \text{ but there is no } u \text{ with } (s,u) \in \widehat{E_a}/I, \text{ then } b \circ_{\sigma} a = 1_{\sigma}), \text{ or}$
- $-(s,t)\in \widehat{E_a}/I$ .

This proves the lemma.

Now we can finish the proof of Theorem 4.1. Assume that  $\mathcal{M}_{\sigma}$  is finitely generated by  $\Gamma_{\sigma} \subseteq \mathcal{M}_{\sigma} \setminus \{1_{\sigma}\}$ . Thus,  $\mathbb{P}$  is finitely generated by  $\Gamma = \bigcup_{\sigma \in \Sigma} \Gamma_{\sigma}$ .

Let us first prove (1) from Theorem 4.1. If  $FOTh(\mathcal{C}(\mathcal{M}_{\sigma}, \Gamma_{\sigma}), 1_{\sigma})$  is decidable, then, since every constant  $a \in \Gamma_{\sigma}$  is first-order definable in the rooted Cayley-graph  $(\mathcal{C}(\mathcal{M}_{\sigma}, \Gamma_{\sigma}), 1_{\sigma})$ , also the structure  $(\mathcal{C}(\mathcal{M}_{\sigma}, \Gamma_{\sigma}) \setminus \{1_{\sigma}\}, (a)_{a \in \Gamma_{\sigma}})$  has a decidable first-order theory. By the Feferman-Vaught Theorem [13], the same holds for the disjoint union of these structures with the unary predicates  $A_{\sigma} = \mathcal{M}_{\sigma} \setminus \{1_{\sigma}\}$  added. But this is precisely the structure  $\mathcal{A}$  from (1). We can therefore apply Corollary 5.8 and obtain that  $FOTh(\mathcal{B})$  is decidable. Since  $(\mathcal{C}(\mathbb{P}, \Gamma), 1)$  is first-order interpretable in  $\mathcal{B}$  (Lemma 6.4), it follows that the first-order theory of  $(\mathcal{C}(\mathbb{P}), 1)$  is indeed decidable.

Now assume that  $I_{\Sigma} = \emptyset$ , i.e.,  $\mathbb{M}(A, I) = A^*$ . The argumentation is similar to the first-order case: If  $MSOTh(\mathcal{C}(\mathcal{M}_{\sigma}, \Gamma_{\sigma}), 1_{\sigma})$  is decidable for every  $\sigma \in \Sigma$ , then also  $MSOTh(\mathcal{A})$  is decidable, [43]. Hence, by Lemma 5.5, also  $MSOTh(\widehat{\mathcal{A}}, (\eta^{-1}(q))_{q \in S})$  is decidable. But the structure  $\mathcal{B}$  from (2) (for  $I = \emptyset$ ) is a reduct of this structure. Hence,  $MSOTh(\mathcal{B})$  is decidable, and the result follows again from Lemma 6.4. Note that the cl-predicate from  $\widehat{\mathcal{A}}$  is actually not needed here. This concludes the proof of Theorem 4.1.

Remark 6.5. Concerning the complexity of  $FOTh(\mathcal{C}(\mathbb{P}), 1)$ , note that Theorem 5.6 (more precisely Remark 5.7) allows us to reduce  $FOTh(\mathcal{C}(\mathbb{P}), 1)$  in doubly exponential time to  $FOTh(\mathcal{A})$ . Recall that  $\mathcal{A}$  is essentially the disjoint union of the Cayley-graphs of the monoids  $\mathcal{M}_{\sigma}$ . To the knowledge of the authors, all known proofs for decomposition theorems (in the style of Feferman-Vaught's Theorem) that allow to reduce the theory of a

<sup>&</sup>lt;sup>5</sup> Here we identify the constant a with the unary relation  $\{a\}$ , thus  $\hat{a} = A^*a$ .

disjoint union (or direct product) to the theories of the factors, lead to a nonelementary blow-up in terms of complexity. Therefore, we are only able to give a nonelementary upper bound for  $FOTh(\mathcal{C}(\mathbb{P}), 1)$  even if all the theories  $FOTh(\mathcal{C}(\mathcal{M}_{\sigma}), 1_{\sigma})$  can be decided in elementary time.

For monadic second-order logic the situation is clear: Note that  $\mathcal{C}(\mathbb{Z}/2\mathbb{Z})$  is a graph with two nodes, thus its monadic second-order theory is in PSPACE (it is in fact PSPACE-complete). But in  $\mathcal{C}(\mathbb{Z}/2\mathbb{Z}*\mathbb{Z}/2\mathbb{Z})$  we can define  $\mathbb{Z}$  with the successor relation, which has a nonelementary MSO-theory [33].

### 7 Proof of Theorem 5.6

We have to translate a first-order sentence  $\varphi$  over the signature of the factorized unfolding  $\mathcal{B}$  into an equivalent one over the basic structure  $\mathcal{A}$ . In a first step, we show how to restrict quantifications in  $\varphi$  to "short traces". This reduction can be found in Section 7.3, it uses a method by Ferrante and Rackoff whose essence is described in Section 7.2. The precise notion of "short trace" uses the concept of Foata's normal form and can be found in Section 7.1. After this reduction to short traces, i.e., after the translation of  $\varphi$  into a local sentence, the local sentence is transformed into an equivalent one over the signature of  $\mathcal{A}$ , see Section 7.4 for the details.

For the remainder of this section, let us fix the factorized unfolding

$$\mathcal{B} = (\mathbb{M}(A, I), (\eta^{-1}(q))_{q \in S}, (R_i/I)_{1 < i < \kappa})$$
(3)

of A. Recall that

- $-I \subseteq A \times A$  is first-order definable in  $\mathcal{A}$ ,
- $-\eta: \mathbb{M}(A,I) \to S$  is a monoid homomorphism into a finite monoid S such that  $\eta^{-1}(q) \cap A$  is first-order definable in A for every  $q \in S$ , and
- $R_i$  is a  $k_i$ -suffix definable relation in  $\mathcal{A}$  for  $1 \leq i \leq \kappa$ .

Assume moreover that there are only finitely many different sets I(a) for  $a \in A$ .

#### 7.1 Foata normalforms

An (A, I)-clique is a subset  $C \subseteq A$  such that  $(a, b) \in I$  for all  $a, b \in C$  with  $a \neq b$ . Since  $\{I(a) \mid a \in \Sigma\}$  is finite, every (A, I)-clique is finite. Thus, for an (A, I)-clique C, we can define a unique trace  $[C] = [a_1 a_2 \cdots a_n]_I$ , where  $a_1, a_2, \ldots, a_n$  is an arbitrary enumeration of C. Let  $\mathcal{F}(A, I)$  denote the set of all (A, I)-cliques. For  $t \in M(A, I)$  let  $\max(t) = \{a \in A \mid \exists u \in A^* : t = [uu]_I\}$  and  $\min(t) = \{a \in A \mid \exists u \in A^* : t = [au]_I\}$ . Note that  $\min(t)$  and  $\max(t)$  are (A, I)-cliques. The set of all traces that have t as a prefix is denoted by  $t M(A, I) = \{tu \mid u \in M(A, I)\}$ . Thus,  $t \in [\min(t)]M(A, I)$ .

The Foata normal form FNF(t) of  $t \in \mathbb{M}(A, I)$  is a word over the set  $\mathcal{F}(A, I)$  of finite (A, I)-cliques. It is defined inductively:

$$\text{FNF}([\varepsilon]_I) = \varepsilon$$
 and  $\text{FNF}(t) = \min(t) \text{ FNF}(s)$ 

where s is the trace satisfying  $t = [\min(t)]s$ . Since  $\mathbb{M}(A, I)$  is cancellative, s is given uniquely by this requirement. The height of t, briefly height(t), is the length of its Foata normal form FNF(t). Alternatively, height(t) can be defined as the number of nodes in a longest directed path in the dependence graph  $D_t$ . Thus,  $height(st) \leq height(s) + height(t)$ . The reversed Foata normal form of  $t \in \mathbb{M}(A, I)$  is defined as follows:

$$rFNF([\varepsilon]_I) = \varepsilon$$
 and  $rFNF(t) = rFNF(s) \max(t)$ 

where s is the trace uniquely given by  $t = s[\max(t)]$ . Then height(t) also equals the length of rFNF(t). If the word  $A_1A_2\cdots A_n$ , where  $A_i \in \mathcal{F}(A,I)$ , is the (reversed) Foata normal form of t, then we say that the factorization  $t = [A_1][A_2]\cdots[A_n]$  is in (reversed) Foata normal form.

#### 7.2 The method of Ferrante and Rackhoff

The major tool from mathematical logic that we use for the proof of Theorem 5.6 is a method of Ferrante and Rackhoff. Let  $\mathcal{B} = (A, (R_i)_{i \in J})$  be a relational structure, where  $R_i$  has arity  $n_i$ . The Gaifman-graph  $G_{\mathcal{B}}$  of the structure  $\mathcal{B}$  is the following undirected graph:

$$G_{\mathcal{B}} = (A, \{(a, b) \in A \times A \mid \bigvee_{i \in J} \exists (c_1, \dots, c_{n_i}) \in R_i \ \exists j, k : c_j = a \neq b = c_k\}).$$

We will mainly be interested in restrictions of the structure  $\mathcal{B}$  to certain spheres in this graph. To ease notations, we will also write  $S_{\mathcal{B}}(r, \tilde{a})$  for  $\mathcal{B} \upharpoonright S_{G_{\mathcal{B}}}(r, \tilde{a})$ , i.e.,  $S_{\mathcal{B}}(r, \tilde{a})$  is the substructure of  $\mathcal{B}$  induced by the r-sphere around the tuple  $\tilde{a}$  in the Gaifman-graph of  $\mathcal{B}$ .

A norm function on  $\mathcal{B}$  is just a function  $\lambda : A \to \mathbb{N}$ . We write  $\mathcal{B} \models \exists x \leq n : \varphi$  in order to express that there exists  $a \in A$  such that  $\lambda(a) \leq n$  and  $\mathcal{B} \models \varphi(a)$ , and similarly for  $\forall x \leq n : \varphi$ . Following Ferrante and Rackoff [15], we define H-bounded structures:

**Definition 7.1.** Let  $\lambda$  be a norm function on the structure  $\mathcal{B}$ . Let furthermore  $H: \{(j,d) \in \mathbb{N} \times \mathbb{N} \mid j \leq d\} \to \mathbb{N}$  be a function such that the following holds: For any  $j \leq d \in \mathbb{N}$ , any  $\widetilde{a} = (a_1, a_2, \dots, a_{j-1}) \in A^{j-1}$  with  $\lambda(a_i) \leq H(i,d)$ , and any  $a \in A$ , there exists  $a_j \in A$  with  $\lambda(a_i) \leq H(j,d)$  and

$$(S_{\mathcal{B}}(7^{d-j}, \widetilde{a}, a), \widetilde{a}, a) \cong (S_{\mathcal{B}}(7^{d-j}, \widetilde{a}, a_i), \widetilde{a}, a_i).^6$$

Then  $\mathcal{B}$  (together with the norm function  $\lambda$ ) is called H-bounded.

The original definition by Ferrante and Rackoff [15] differs slightly from this one in two aspects: firstly, their function H has a third argument that describes a uniform bound for  $\lambda(a_i)$  with i < j; instead, we restrict to the case where the norm of these elements is bounded by appropriate values of the function H. Secondly, Ferrante and Rackoff require the tuples  $(\tilde{a}, a)$  and  $(\tilde{a}, a_i)$  to be indistinguishable by a first-order formula of quantifier

Thus, there is an isomorphism from  $S_{\mathcal{B}}(7^{d-j}, \widetilde{a}, a)$  to  $S_{\mathcal{B}}(7^{d-j}, \widetilde{a}, a_j)$  that fixes every  $a_i$  for i < j and maps a to  $a_j$ .

depth d-j; instead, we require certain spheres around these tuples to be isomorphic. By Gaifman's theorem, this implies that the given tuples are indistinguishable by any first-order formula, i.e., our requirement is more restrictive, but easier to establish. The following result was shown by Ferrante and Rackoff for their version of H-bounded structures. See [25] for a proof.

**Proposition 7.2 (cf. [15]).** Let  $\mathcal{B}$  be a relational structure with norm  $\lambda$  and let H:  $\{(j,d) \in \mathbb{N} \times \mathbb{N} \mid j \leq d\} \to \mathbb{N}$  be a function such that  $\mathcal{B}$  is H-bounded. Then for any first-order formula  $\varphi \equiv Q_1x_1Q_2x_2\cdots Q_dx_d: \psi$  where  $\psi$  is quantifier-free and  $Q_i \in \{\exists, \forall\}$ , we have  $\mathcal{B} \models \varphi$  if and only if

$$\mathcal{B} \models Q_1 x_1 \le n_1 Q_2 x_2 \le n_2 \cdots Q_d x_d \le n_d : \psi(x_1, \dots, x_d). \tag{4}$$

#### 7.3 From properties of $\mathcal{B}$ to local properties of $\mathcal{B}$

In this section, we will reduce an arbitrary first-order sentence over the signature of  $\mathcal{B}$  to a sentence of the form (4) using Corollary 7.2. First of all, this requires the definition of a norm function on  $\mathcal{B}$ : Let  $k = \max\{k_i \mid 1 \leq i \leq \kappa\}$ . On  $\mathbb{M}(A,I)$  we define a norm function  $\lambda : \mathbb{M}(A,I) \to \mathbb{N}$  by  $\lambda(t) = |t|$ . According to Section 7.2,  $\exists x \leq n : \phi(x)$  is an abbreviation for  $\exists x : |x| \leq n \land \phi(x)$ . Now, in order to make Corollary 7.2 applicable, we next investigate the metric on  $\mathbb{M}(A,I)$  that is induced by the structure  $\mathcal{B}$  (more precisely, by its Gaifman-graph, cf. Section 2).

**Lemma 7.3.** Let  $u = s[A_1] \cdots [A_m] y = tv \in \mathbb{M}(A, I)$  with  $s[A_1] \cdots [A_m]$  in reversed Foata normal form and  $|v| \leq m$ . Then  $t = s[A_1] \cdots [A_{m-|v|}] w$  for some  $w \in \mathbb{M}(A, I)$ .

Proof. The lemma is shown by induction on |v|. The case  $v = \varepsilon$  is trivial. Thus, let v = av' for some  $a \in A$ , i.e.,  $u = s[A_1] \cdots [A_m] y = (ta)v'$ . By induction we have  $ta = s[A_1] \cdots [A_{m-|v|+1}] w'$  for some  $w' \in \mathbb{M}(A, I)$ . Then  $a \in \max(s[A_1] \cdots [A_{m-|v|+1}] w')$ . Since  $s[A_1][A_2] \cdots [A_{m-|v|+1}]$  is in reversed Foata normal form, we obtain  $a \in \max([A_{m-|v|+1}] w')$ . Hence, there is a trace w satisfying  $[A_{m-|v|+1}] w' = wa$ , i.e.,  $t = s[A_1] \cdots [A_{m-|v|}] w$ .

Recall that for  $r \in \mathbb{N}$  and  $u \in \mathbb{M}(A, I)$  we denote by  $S_{\mathcal{B}}(r, u)$  the substructure of  $\mathcal{B}$  induced by the r-sphere around u in the Gaifman-graph  $G_{\mathcal{B}}$ . The distance function  $d_{G_{\mathcal{B}}}$  in the Gaifman-graph  $G_{\mathcal{B}}$  will be denoted by d in the following. Recall also that k was chosen such that every relation  $R_i$  is k-suffix definable.

**Lemma 7.4.** Let  $u = s[A_1] \cdots [A_{k \cdot r}]$  be in reversed Foata normal form. Then we have  $S_{\mathcal{B}}(r, u) \subseteq s \, \mathbb{M}(A, I)$ .

Proof. Let us take  $v \in \mathbb{M}(A, I)$  with  $d(u, v) \leq r$ . We have to show that  $v \in s\mathbb{M}(A, I)$ . By assumption there exists a path  $u_0, u_1, \ldots u_m$  in the Gaifman-graph of  $\mathcal{B}$  such that  $u_0 = u$ ,  $u_m = v$ , and  $m \leq r$ . Inductively we will show that  $u_i = s[A_1] \cdots [A_{kr-ki}] y_i$  for some  $y_i$ , thus  $v = s[A_1] \cdots [A_{kr-km}] y_m \in s\mathbb{M}(A, I)$ . The case i = 0 is clear. Now assume that  $u_i = s[A_1] \cdots [A_{kr-ki}] y_i$  and i < m. Since  $(u_i, u_{i+1})$  is an edge in the Gaifman-graph of  $\mathcal{B}$  and all nonunary relations of  $\mathcal{B}$  result from k-suffix definable relations, we have

 $u_i = s[A_1] \cdots [A_{kr-ki}] y_i = zw$  and  $u_{i+1} = zw'$  for some  $z, w, w' \in \mathbb{M}(A, I)$  with  $|w| \leq k$  (and  $|w'| \leq k$ ). Lemma 7.3 implies that  $u_{i+1} = s[A_1] \cdots [A_{kr-ki-k}] y'w'$  for some  $y' \in \mathbb{M}(A, I)$ . Thus, we can set  $y_{i+1} = y'w'$ .

Thus, the r-sphere around  $u = s[A_1][A_2] \cdots [A_{kr}]$  is contained in  $s \, \mathbb{M}(A, I)$ . The next lemma will be used to shorten s, i.e., to find v properly shorter than u that is the center of an isomorphic r-sphere. Let  $s, t \in \mathbb{M}(A, I)$  be two traces. Since  $\mathbb{M}(A, I)$  is cancellative, the mapping  $f = f_{s,t} : s \, \mathbb{M}(A, I) \to t \, \mathbb{M}(A, I)$  defined by f(su) = tu is a bijection. We will show that, under some assumptions on s and t, it is an isomorphism from  $(S_{\mathcal{B}}(r, u), u)$  to  $(S_{\mathcal{B}}(r, v), v)$ .

**Lemma 7.5.** Let  $u = s[A_1] \cdots [A_{kr+k}]$  and  $v = t[A_1] \cdots [A_{kr+k}]$  be in reversed Foata normal form and  $\eta(s) = \eta(t)$ . Then the mapping  $f = f_{s,t}$  is an isomorphism from  $(S_{\mathcal{B}}(r, u), u)$  to  $(S_{\mathcal{B}}(r, v), v)$ .

Proof. Lemma 7.4 implies  $S_{\mathcal{B}}(r,u) \subseteq s[A_1] \cdots [A_k] \mathbb{M}(A,I)$ , thus f is defined on  $S_{\mathcal{B}}(r,u)$ . Since  $\eta(f(su)) = \eta(tu) = \eta(t) \cdot \eta(u) = \eta(s) \cdot \eta(u) = \eta(su)$ , f preserves all unary predicates  $\eta^{-1}(q)$  for  $q \in S$ . Now assume that  $(u_1, \ldots, u_n) \in R/I$ , where  $u_i \in S_{\mathcal{B}}(r,u)$  and R/I is a relation of  $\mathcal{B}$ . Thus, R is k-suffix definable. Hence, there exist  $y, w_1, \ldots, w_n \in \mathbb{M}(A,I)$  such that  $u_i = yw_i$ ,  $|w_i| \leq k$ , and  $(y'w_1, \ldots, y'w_n) \in R/I$  for all  $y' \in \mathbb{M}(A,I)$ . Since  $S_{\mathcal{B}}(r,u) \subseteq s[A_1] \cdots [A_k] \mathbb{M}(A,I)$ , we have  $yw_i = u_i = s[A_1] \cdots [A_k] v_i$  for some  $v_i \in \mathbb{M}(A,I)$ . Thus, Lemma 7.3 and  $|w_i| \leq k$  implies  $y = sy_i$  for some trace  $y_i$ . Since  $\mathbb{M}(A,I)$  is cancellative, it follows  $y_1 = \cdots = y_n =: z$ . Thus,  $f(u_i) = f(szw_i) = tzw_i$  and  $(f(u_1), \ldots, f(u_n)) \in R/I$ . It follows that f maps  $S_{\mathcal{B}}(r,u)$  injectively and structure preserving into  $S_{\mathcal{B}}(r,v)$ . Since we may exchange the roles of s and t, it follows that f maps  $S_{\mathcal{B}}(r,u)$  bijectively to  $S_{\mathcal{B}}(r,v)$ .  $\square$ 

Recall that (A, I) has only finitely many neighborhoods, i.e., that the set  $\{I(a) \mid a \in A\}$  is finite. Thus, also  $\{D(a) \mid a \in A\}$  is finite, where  $D = (A \times A) \setminus I$ .

**Lemma 7.6.** There exists a homomorphism  $h : \mathbb{M}(A, I) \to Q$  into some finite monoid Q such that for all  $s, t \in \mathbb{M}(A, I)$ , we have:

if h(s) = h(t) and  $a \in \max(s)$ , then there exists  $b \in \max(t)$  with D(a) = D(b).

Proof. Let  $\mathcal{D}$  be the powerset of  $\{D(a) \mid a \in A\}$ , thus  $\mathcal{D}$  is finite. For  $s \in \mathbb{M}(A, I)$ , define  $f(s) = \{D(a) \mid a \in \max(s)\} \in \mathcal{D}$ . Let  $s, t \in \mathbb{M}(A, I)$  such that f(s) = f(t). We show that f(sc) = f(tc) for all  $c \in A$ : Clearly,  $c \in \max(sc) \cap \max(tc)$ . Now let  $a \in A \setminus \{c\}$ . Then  $a \in \max(sc)$  if and only if  $(a, c) \in I$  and  $a \in \max(s)$ . Hence  $f(sc) = \{D(c)\} \cup \{D(a) \mid D(a) \in f(s), c \notin D(a)\}$ . Thus, indeed, f(sc) = f(tc).

Now consider the image  $f(\mathcal{D})$  of  $\mathbb{M}(A, I)$  under f. Let Q be the transformation monoid of  $f(\mathcal{D})$ , i.e.,  $Q = (f(\mathcal{D})^{f(\mathcal{D})}, \circ)$  and define a mapping  $h : A \to Q$  such that h(a)(f(s)) = f(sa) which is well defined by the previous paragraph. Clearly  $h(a) \circ h(b) = h(b) \circ h(a)$  for  $(a, b) \in I$ . Thus, we can extend h to a monoid homomorphism  $h : \mathbb{M}(A, I) \to Q$  with h(t)(f(s)) = f(st). Now suppose h(s) = h(t). Then  $a \in \max(s)$  implies  $D(a) \in f(s) = h(s)(f(\varepsilon)) = f(t)$ . Hence, there is  $b \in \max(t)$  with D(a) = D(b).

**Lemma 7.7.** Let h be the homomorphism from Lemma 7.6 and let  $s, s', t, t' \in M(A, I)$  with h(s') = h(t'),  $s = s'[\max(s)]$ , and  $t = t'[\max(s)]$ . Then  $\max(t) = \max(s)$  and height(t) = height(t') + 1.

Proof. Clearly,  $\max(s) \subseteq \max(t)$ . So let  $a \in \max(t) \setminus \max(s)$ . Since  $t = t'[\max(s)]$ , we get  $a \in \max(t')$  and  $(a, c) \in I$  for every  $c \in \max(s)$ . Since h(s') = h(t'), it follows D(a) = D(b), i.e., I(a) = I(b) for some  $b \in \max(s')$ . Thus, also  $(b, c) \in I$  for every  $c \in \max(s)$ . But this implies  $b \in \max(s)$ , i.e.,  $(b, b) \in I$ , a contradiction. Thus, indeed,  $\max(t) = \max(s)$ . This implies height $(t') = \operatorname{height}(t') = \operatorname$ 

By Lemma 7.6 we can find a homomorphism  $\eta'$  from  $\mathbb{M}(A, I)$  into some finite monoid S' (namely  $S \times Q$ ) such that the following implications hold:

- if  $\eta'(s) = \eta'(t)$  and  $a \in \max(s)$ , then there exists  $b \in \max(t)$  with D(a) = D(b).
- If  $\eta'(s) = \eta'(t)$ , then  $\eta(s) = \eta(t)$ .

**Lemma 7.8.** Let  $u \in \mathbb{M}(A, I)$  and  $r, \ell \in \mathbb{N}$  such that  $\ell \geq k(r+1)$ , height $(u) > \max\{k(r+1) + |S'| + 1, \ell\}$ . Then there exists  $v \in \mathbb{M}(A, I)$  with

$$\ell < \operatorname{height}(v) \le \ell + |S'| + 1$$
 and  $(S_{\mathcal{B}}(r, u), u) \cong (S_{\mathcal{B}}(r, v), v).$ 

Proof. If height(u)  $\leq \ell + |S'| + 1$  we can set u = v. Thus, assume that height(u)  $> \ell + |S'| + 1$ . Then there are (A, I)-cliques  $A_i \subseteq A$  and  $s \in \mathbb{M}(A, I)$  such that  $u = s[A_1][A_2] \cdots [A_{k(r+1)}]$  is in reversed Foata normal form and height(s)  $> \ell - k(r+1) + |S'| + 1$ . Let  $s' \in \mathbb{M}(A, I)$  with  $s = s'[\max(s)]$ . Then height(s')  $\geq \ell - k(r+1) + |S'| + 1$ , and we can write  $s' = s_1 s_2$  with height( $s_1$ )  $= \ell - k(r+1)$  and height( $s_2$ ) > |S'|. A simple pigeon hole argument shows that there exists  $s'_2 \in \mathbb{M}(A, I)$  such that  $\eta'(s_2) = \eta'(s'_2)$  and height( $s'_2$ )  $\leq |S'|$ . Define  $t' = s_1 s'_2$  and  $t = t'[\max(s)]$ . Thus,  $\eta'(s') = \eta'(t')$ . Hence, by Lemma 7.7 we get height(t) = height(t') + 1 and  $\max(t) = \max(s)$ . This ensures in particular

$$\operatorname{height}(t) = \operatorname{height}(t') + 1 \le \operatorname{height}(s_1) + \operatorname{height}(s_2') + 1 \le \ell - k(r+1) + |S'| + 1$$

and

$$\operatorname{height}(t) > \operatorname{height}(t') \ge \operatorname{height}(s_1) = \ell - k(r+1).$$

Now set  $v = t[A_1][A_2] \cdots [A_{k(r+1)}]$ . A k(r+1)-fold application of Lemma 7.7 implies height(v) = height(t) + k(r+1) and therefore

$$\ell < \operatorname{height}(v) \le \ell + |S'| + 1.$$

Since  $\eta'(s) = \eta'(t)$ , we can apply Lemma 7.5, implying  $(S_{\mathcal{B}}(r, u), u) \cong (S_{\mathcal{B}}(r, v), v)$ , which finishes the proof.

**Lemma 7.9.** The factorized unfolding  $\mathcal{B}$  from (3) is H-bounded by a function H with  $H(j,d) \leq H(d,d) \in 2^{O(d)}$  for  $j \leq d$ .

*Proof.* Recall that the norm of a trace t was defined as its length |t|. Since  $\{I(a) \mid a \in A\}$  is finite, there is  $\alpha \in \mathbb{N}$  such that any (A, I)-clique contains at most  $\alpha$  elements. We define H(i, d) inductively:  $H(1, d) = \alpha \cdot (k(7^{d-1} + 1) + 2(|S'| + 1))$  and  $H(j, d) = \alpha \cdot (H(j - 1, d) + 4 \cdot 7^{d-j} \cdot k + |S'| + 1)$  for  $1 < j \le d$ . Then  $H(j, d) \le H(d, d)$  is bounded by  $2^{O(d)}$  for  $j \le d$ .

Let  $d \in \mathbb{N}$  and  $t \in \mathbb{M}(A, I)$  with |t| > H(1, d). Let  $\ell = k(7^{d-1} + 1) + |S'| + 1 < H(1, d)/\alpha$  and  $r = 7^{d-1}$ . Then  $\ell \ge k(r+1)$  and  $\ell = k(r+1) + |S'| + 1 < H(1, d)/\alpha < |t|/\alpha \le \text{height}(t)$ . Hence, by Lemma 7.8, there is  $t_1 \in \mathbb{M}(A, I)$  with  $\text{height}(t_1) \le \ell + |S'| + 1 \le H(1, d)$  and  $(S_{\mathcal{B}}(7^{d-1}, t), t) \cong (S_{\mathcal{B}}(7^{d-1}, t_1), t_1)$ . This proves the base case for the H-boundedness of  $\mathcal{B}$ .

Next, let  $1 < j \le d \in \mathbb{N}$ ,  $\widetilde{t} = (t_1, t_2, \dots, t_{j-1}) \in \mathbb{M}(A, I)^{j-1}$  with  $|t_i| \le H(i, d)$  and  $t \in \mathbb{M}(A, I)$  with |t| > H(j, d). In order to apply Lemma 7.8, let  $\ell = H(j-1, d) + 4 \cdot 7^{d-j} \cdot k$  and  $r = 7^{d-j}$ . Thus,  $\ell \ge H(1, d) \ge k(7^{d-1} + 1) \ge k(r+1)$ . Moreover,  $|t| > H(j, d) > H(1, d) \ge \alpha \cdot (k(7^{d-j} + 1) + |S'| + 1)$ . Hence, height $(t) \ge |t|/\alpha > k(r+1) + |S'| + 1$ . Furthermore,  $|t| > H(j, d) > \alpha \cdot \ell$  implies height $(t) > \ell$ . Thus, by Lemma 7.8, there exists  $t_j \in \mathbb{M}(A, I)$  with

$$\ell < \text{height}(t_j) \le \ell + |S'| + 1 \text{ and } (S_{\mathcal{B}}(7^{d-j}, t), t) \cong (S_{\mathcal{B}}(7^{d-j}, t_j), t_j).$$

Thus,  $\ell < |t_j| \le \alpha \cdot (\ell + |S'| + 1)$ . In the Gaifman-graph  $G_{\mathcal{B}}$ , the distance between  $t_i$  and  $t_j$  is at least  $(|t_j| - |t_i|)/k$ . Since  $|t_i| \le H(i,d) \le H(j-1,d)$  for  $1 \le i < j$ , we obtain  $d(t_i,t_j) \ge (|t_j| - |t_i|)/k > (\ell - H(j-1,d))/k = 4 \cdot 7^{d-j}$ . Hence the spheres  $S_{\mathcal{B}}(7^{d-j},\widetilde{t})$  and  $S_{\mathcal{B}}(7^{d-j},t_j)$  are disjoint and no edge in  $G_{\mathcal{B}}$  connects elements from the former to elements from the latter sphere. The same holds for the spheres  $S_{\mathcal{B}}(7^{d-j},\widetilde{t})$  and  $S_{\mathcal{B}}(7^{d-j},t)$ . Thus,

$$(S_{\mathcal{B}}(7^{d-j}, \widetilde{t}, t), \widetilde{t}, t) \cong (S_{\mathcal{B}}(7^{d-j}, \widetilde{t}, t_j), \widetilde{t}, t_j),$$

and the factorized unfolding  $\mathcal{B}$  is indeed H-bounded.

Now let  $\varphi \equiv Q_1 x_1 Q_2 x_2 \cdots Q_d x_d : \psi(x_1, \dots, x_d)$  be a first-order sentence over the signature of  $\mathcal{B}$  with d quantifiers  $Q_i \in \{\exists, \forall\}$ . Since  $\mathcal{B}$  is H bounded by the previous lemma, Proposition 7.2 implies that  $\mathcal{B} \models \varphi$  if and only if

$$\mathcal{B} \models Q_1 x_1 \le H(1, d) Q_2 x_2 \le H(2, d) \cdots Q_d x_d \le H(d, d) : \psi(x_1, \dots, x_d). \tag{5}$$

### 7.4 From local properties of $\mathcal{B}$ to properties of $\mathcal{A}$

It remains to reduce local sentences of the form (5) to sentences that speak about the structure A. This is achieved by the following proposition.

**Proposition 7.10.** Let  $\psi(x_1, \ldots, x_d)$  be a Boolean formula over the signature of  $\mathcal{B}$ . Let  $n_1, \ldots, n_d \in \mathbb{N}$ , and  $Q_1, \ldots, Q_d \in \{\exists, \forall\}$ . Then we can effectively construct a sentence  $\theta$  over the signature of  $\mathcal{A}$  such that

$$\mathcal{B} \models Q_1 x_1 \leq H(1, d) \ Q_2 x_2 \leq H(2, d) \cdots Q_d x_d \leq H(d, d) : \psi.$$

if and only if  $A \models \theta$ . Moreover,  $\theta$  has quantifier alternation depth d+O(1) and size bounded by  $n^d \cdot |\psi| \cdot 2^{O(n)}$  where  $n = \max\{n_1, \ldots, n_d\}$ .

Proof. We will encode a trace  $x \in \mathbb{M}(A, I)$  with  $|x| \leq n$  by a sequence  $y_1 y_2 \cdots y_m$  of first-order variables  $y_i \in A$  of length  $m \leq n$ , with the meaning that  $x = [y_1 y_2 \cdots y_m]_I$ . First, for every  $m \leq n$ , we have to construct a first-order formula in 2m free variables over the signature of A, which expresses that  $[y_1 y_2 \cdots y_m]_I = [z_1 z_2 \cdots z_m]_I$  in  $\mathbb{M}(A, I)$ . This can be done inductively as follows: If m = 0, then this formula is the truth value true. If m > 0, then  $[y_1 y_2 \cdots y_m]_I = [z_1 z_2 \cdots z_m]_I$  if and only if

$$\bigvee_{i=1}^{m} \left( y_1 = z_i \wedge \bigwedge_{j=1}^{i-1} (z_i, z_j) \in I \wedge [y_2 \cdots y_m]_I = [z_1 \cdots z_{i-1} z_{i+1} \cdots z_m]_I \right)$$

(recall that by assumption the independence relation I can be defined by a fixed first-order formula over the signature of  $\mathcal{A}$ ). The above recursive definition would lead to a formula of exponential size for  $[y_1y_2\cdots y_m]_I=[z_1z_2\cdots z_m]_I$  since an equation of the form  $[y_2\ldots y_m]_I=[u_1\ldots u_{m-1}]_I$  appears m times. Using a trick from Ferrante [14, Lem. 2] we can be more space economical: The above formula is equivalent to

$$\exists u_1 \cdots \exists u_{m-1} \left\{ \bigvee_{i=1}^{[y_2 \cdots y_m]_I} \left\{ \begin{matrix} [y_2 \cdots y_m]_I = [u_1 \cdots u_{m-1}]_I \land \\ y_1 = z_i \land \bigwedge_{j=1}^{i-1} (z_j = u_j \land (z_i, u_j) \in I) \land \\ \bigwedge_{j=i+1}^m z_j = u_{j-1} \end{matrix} \right\} \right\}.$$

Let  $s_m$  be the size of this formula with 2m free variables. Then  $s_m$  is bounded by  $s_{m-1} + O(m^2)$ . Thus,  $s_n \in O(n^3)$ . Moreover the quantifier alternation depth in the above formula is 0, since we only use existential quantifiers.

Now a bounded existential quantification  $\exists x_i \leq n_i$  in (4) can be replaced by  $\bigvee_{j=0}^{n_i} \exists y_1 \cdots \exists y_j$ , where x is represented by the sequence  $y_1 \cdots y_j$ , and similarly for a universal quantifier. Since there are only d quantifiers in (4), these replacements increase the size of the formula at most by a factor  $n^d$ . Furthermore, the quantifier alternation depth is unchanged.

Next, consider an atomic formula  $R/I(x_1, \ldots, x_r)$  in  $\psi$ , where R is one of the k-suffix definable relations  $R_i$   $(1 \le i \le \kappa)$ . Since R is k-suffix definable, we can assume that

$$R = \{(uu_1, uu_2, \dots, uu_r) \mid u, u_i \in A^*, |u_i| = \ell_i, \mathcal{A} \models \phi(u_1, u_2, \dots, u_r)\}$$

for some  $\ell_i \leq k$ , where  $\phi$  is a fixed first-order formula over the signature of  $\mathcal{A}$ . Assume that the trace  $x_i \in \mathbb{M}(A,I)$  is represented by the sequence  $y_{i,1} \cdots y_{i,m_i}$   $(m_i \leq n)$ . If for some  $1 \leq i \leq r$ , we have  $m_i < \ell_i$ , then we can replace  $R/I(x_1,\ldots,x_r)$  by the truth value false. The same can be done if  $m_i - \ell_i \neq m_j - \ell_j$  for two different i,j. Thus, assume that  $m_i - \ell_i = \ell \geq 0$  for all  $1 \leq i \leq r$ . Then we can replace  $R/I(x_1,\ldots,x_r)$  by the formula

$$\exists_{\substack{1 \leq i \leq r \\ 1 \leq j \leq \ell_i}} z_{i,j} \exists z_1 \cdots \exists z_\ell \left\{ \bigwedge_{\substack{1 \leq i \leq r \\ \wedge \phi(z_{1,1}, \dots, z_{1,\ell_1}, \dots, z_{r,1}, \dots, z_{r,\ell_r})} [y_{i,1} \cdots y_{i,m_i}]_I = [z_1 \cdots z_\ell z_{i,1} \cdots z_{i,\ell_i}]_I \right\},$$

which has fixed quantifier alternation depth and size bounded by  $O(n^3)$ . Similarly, an atomic formula of the form x = y can be replaced by a formula of size  $s_n \in O(n^3)$  and fixed quantifier alternation depth.

Finally, we want to express  $\eta(x) = q$  for some  $q \in S$ . Assume that  $x \in M(A, I)$  is represented by the sequence  $y_1 \cdots y_m$ , where  $m \leq n$ . Then we can replace  $\eta(x) = q$  by

$$\bigvee_{\substack{(q_1,\ldots,q_m)\in S^m\\q_1,q_2\cdots q_m=q}}\bigwedge_{1\leq i\leq m}\eta(y_i)=q_i.$$

Recall that  $\eta(y_i) = q_i$  can be expressed by a fixed first-order formula over the signature of  $\mathcal{A}$ . Thus, the size of the above formula is bounded by  $O(|S|^n)$  and its quantifier alternation depth is O(1).

Altogether, any of the atomic subformulas in  $\psi$  gets replaced by a formula of quantifier alternation depth O(1) and size bounded by  $2^{O(n)}$ . Hence, the size of the resulting sentence  $\theta$  is bounded by  $n^d \cdot |\psi| \cdot 2^{O(n)}$ , and its quantifier alternation depth is bounded by d + O(1).

Since the function H satisfies  $H(j,d) \leq H(d,d) \in 2^{O(d)}$ , the previous proposition implies that the sentence in (5) is equivalent to a first-order sentence over the signature of  $\mathcal{A}$  of size  $2^{2^{O(|\varphi|)}}$  and quantifier alternation depth d + O(1). This finishes the proof of Theorem 5.6.

### 8 Some results on factorized unfoldings

This final section contains two auxiliary result on factorized unfoldings. The first one shows that the requirement on  $\{I(a) \mid a \in A\}$  in Theorem 5.6 to be finite is necessary for the theorem to hold. The second result of this section gives a much simpler proof of Theorem 5.6 in case the structure  $\mathcal{A}$  is finite.

The structure  $(\mathbb{N}^*, \widehat{S}, \preceq, \operatorname{cp})$  from Proposition 5.3 has an undecidable first-order theory. Thus, allowing the relation  $\preceq/I$ , which is the prefix order on traces, in factorized unfoldings would make Theorem 5.6 fail (already for  $I = \emptyset$ ). In Theorem 5.6, we also assume that there are only finitely many different sets I(a). The reason is again that otherwise the result would fail: Let  $V = \{(m, n) \in \mathbb{N}^2 \mid m \leq n\}$  and  $E = \{(\ell, m, n) \in \mathbb{N}^3 \mid \ell, m \leq n\}$ . On  $A = V \cup E$ , define the relation R by

$$R = \{ ((m, n), (\ell, m, n)) \mid \ell, m \le n \} \cup \{ ((\ell, n), (\ell, m, n)) \mid \ell, m \le n \}.$$

Thus, dom(R) = V and ran(R) = E. Furthermore, let I be the set of pairs of distinct elements from  $V \cup E$  that agree on their last component. Then there are infinitely many sets I(a), but any of these sets is finite. We will consider the structure  $\mathcal{A} = (A, R, I)$ . The decidability of  $FOTh(\mathbb{N}, \leq)$  implies the decidability of  $FOTh(\mathcal{A})$ .

**Theorem 8.1.** Let  $\mathcal{B} = (\mathbb{M}(A, I), \operatorname{cl}/_I, \operatorname{suc}/_I, \widehat{R}/_I)$ , which is a factorized unfolding of  $\mathcal{A}$ . Then  $\operatorname{FOTh}(\mathcal{B})$  is undecidable.

*Proof.* We will reduce the first-order theory of all finite directed graphs (which is undecidable by [47]) to the first-order theory of  $\mathcal{B}$ .

The idea is to represent a finite graph by the finite (A, I)-clique  $\max(s)$  of a trace  $s \in M(A, I)$ , which by the definition of I is a subset of

$$V \cap (\mathbb{N} \times \{n\}) \cup E \cap (\mathbb{N}^2 \times \{n\})$$

for some  $n \in \mathbb{N}$ . Those elements from V (resp. E) in  $\max(s)$  represent the nodes (resp. edges) of G. To represent the set  $\max(s)$  in  $\mathcal{B}$ , we use the  $\operatorname{cl}_{I}$ -relation. More precisely, for  $s \in \mathbb{M}(A,I)$  let G(s) denote the set of traces t such that  $(s,t) \in \operatorname{cl}_{I}$  in  $\mathcal{B}$ . In other words, G(s) is the set of traces sa (with  $a \in A$ ) such that  $a \in \max(s)$ . By  $f_s$  we denote the bijection from G(s) to  $\max(s)$  given by  $sa \mapsto a$  (this is well-defined, since sa = sb implies a = b). Now let  $t \in G(s)$ . Then  $f_s(t) \in V$  if and only if there is  $u \in \mathbb{M}(A,I)$  with  $(s,u) \in \sup_I (recall \text{ that } V = \dim(R))$ . Similarly,  $f_s(t) \in E$  if and only if there is  $u \in \mathbb{M}(A,I)$  with  $(s,u) \in \sup_I (u,t) \in \widehat{R}_{I}$ . Now let  $v,e \in G(s)$  with  $f_s(v) \in V$  and  $f_s(e) \in E$ . Then  $(f_s(v),f_s(e)) \in R$  if and only if  $(v,e) \in \widehat{R}_{I}$ . Thus, we can write a formula graph(x) with one free variable x such that  $\mathcal{B} \models \operatorname{graph}(s)$  if and only if  $\max(s)$  is a directed graph, i.e., any element of  $\max(s) \cap E$  is adjacent with at least one element from  $\max(s) \cap V$ .

Now let  $\varphi$  be a sentence over the signature of directed graphs. Using the ideas explained above, we can construct a formula  $\varphi'(x)$  with one free variable such that for any trace  $s \in \mathbb{M}(A, I)$  satisfying graph(s), the graph of maximal elements of s satisfies  $\varphi$  if and only if  $\mathcal{B} \models \varphi'(s)$ . Thus,  $\varphi$  is true in all finite graphs (i.e., belongs to the theory of all finite graphs) if and only if  $\mathcal{B} \models \forall x : \operatorname{graph}(x) \Rightarrow \varphi'(x)$ .

In order to prove the undecidability results in Proposition 5.3 and Theorem 8.1 we used infinite structures. Infinity is needed as the next theorem shows. See [23, 3] for the definition of an automatic structure.

**Theorem 8.2.** Let A be a finite relational structure with universe A, and let

$$\mathcal{B} = (\mathbb{M}(A, I), (\eta^{-1}(q))_{q \in S}, (R_i/I)_{1 \le i \le \kappa})$$

be any factorized unfolding of A. Then the structure  $(\mathcal{B}, \leq I_I)$  is automatic and has therefore a decidable first-order theory.

Proof. The free monoid  $\mathcal{F}(A,I)^*$  generated by the set of (A,I)-cliques maps naturally onto  $\mathbb{M}(A,I)$ , let h denote the canonical homomorphism defined by h(C) = [C]. Let  $\mathrm{FNF} \subseteq \mathcal{F}(A,I)^*$  denote the set of Foata normal forms. Then a word  $C_1C_2\cdots C_n$  over  $\mathcal{F}(A,I)$  belongs to FNF if and only if for every  $1 \leq i < n$  and every  $a \in C_{i+1}$ , there is  $b \in C_i$  with  $(a,b) \notin I$ . Since A is finite, the set FNF is recognizable. Moreover, h maps FNF bijectively to  $\mathbb{M}(A,I)$ . Let  $\mathrm{suc}_a = \{(t,ta) \mid t \in \mathbb{M}(A,I)\}$  for  $a \in A$ . In a forthcoming paper, we will show that the structure  $(\mathbb{M}(A,I), \preceq/I, (\mathrm{suc}_a)_{a \in A})$  is automatic with respect to FNF and h. Using the closure of automatic structures under first-order interpretations [23], it suffices to show that

- the set  $\{w \in \text{FNF} \mid \eta(h(w)) = q\}$  is regular for every  $q \in S$  and
- every relation  $R_i/I$ ,  $1 \le i \le \kappa$ , is first-order definable in  $(\mathbb{M}(A, I), \preceq/I, (\operatorname{suc}_a)_{a \in A})$ .

Using an automaton with state space S, the first point is easy to check. For the second point we can argue as follows: Since A is finite and  $R_i$  is k-suffix definable for some k, we can write  $R_i/I$  as  $R_i/I = \bigcup_{(s_1,\ldots,s_n)\in F_i} \{(ts_1,\ldots,ts_n) \mid t\in \mathbb{M}(A,I)\}$ , where  $F_i\subseteq \mathbb{M}(A,I)^n$  is a finite relation. Now, for  $s=[a_1a_2\cdots a_m]_I\in \mathbb{M}(A,I)$ ,  $a_k\in A$ , define

$$\operatorname{suc}_{s}(x_{0}, x_{m}) \equiv \exists x_{1} \cdots \exists x_{m-1} \left\{ \bigwedge_{j=1}^{m} \operatorname{suc}_{a_{j}}(x_{j-1}, x_{j}) \right\}.$$

Then  $(y_1, \ldots, y_n) \in R_i/I$  if and only if

$$\bigvee_{(s_1,\ldots,s_n)\in F_i} \exists x \left\{ \bigwedge_{1\leq j\leq n} \operatorname{suc}_{s_j}(x,y_j) \right\}.$$

Thus, the relation  $R_i/I$  is even first-order definable in  $(\mathbb{M}(A,I), (\operatorname{suc}_a)_{a\in A})$ 

Remark 8.3. We can also say something on the complexity of the decision procedure for the first-order theory of  $(\mathcal{B}, \leq/I)$  in the previous theorem: Suppose that any two distinct letters from A are independent. Then one can reduce  $\mathrm{FOTh}(\mathcal{B}, \leq)$  to Presburger's Arithmetic, which is decidable in  $\mathrm{DSPACE}(2^{2^{O(n)}})$  [2] and hence elementary. On the other hand, the theory  $\mathrm{FOTh}(\{a,b\}^*, \mathrm{suc}_a, \mathrm{suc}_b, \leq)$  is not elementarily decidable, see [9, Example 8.3].

Note that Theorem 8.2 implies in particular that the prefix order on finite traces over a finite independence alphabet (A, I) has a decidable first-order theory.

## 9 Open problems

Many open problems remain for Cayley-graphs of finitely generated monoids. The most ambitious goal would be to obtain a complete (algebraic or combinatorial) characterization of those monoids such that the corresponding Cayley-graph has a decidable first-order theory or MSO-theory, respectively. But due to the missing symmetry in Cayley-graphs of monoids this problem might be too difficult. A promising class for further results are cancellative monoid with a decidable word problem such that the corresponding Cayley-graph has an undecidable first-order theory? Is there a cancellative monoid such that its Cayley-graph has finite tree-width but an undecidable MSO-theory?

In [25] we have shown that for Cayley-graphs of finitely generated groups the decidability of the full first-order theory is equivalent to the decidability of the  $\Sigma_1$ -theory. The corresponding problem for monoids is again open.

As already mentioned, in statement (1) from Theorem 4.1 it remains open whether the complexity of  $FOTh(\mathcal{C}(\mathbb{P}), 1)$  is bounded elementarily in the complexity of the theories  $FOTh(\mathcal{C}(\mathcal{M}_{\sigma}), 1_{\sigma})$ , where the  $\mathcal{M}_{\sigma}$  are the factors of the graph product.

For MSO-theories, statements (2) from Theorem 4.1 and Proposition 4.3 leave a gap. A plausible conjecture is that MSOTh( $\mathcal{C}(\mathbb{P})$ , 1) is decidable if and only if the four conditions in Proposition 4.3 are satisfied. One might first try to prove this conjecture for graph products of finite monoids. In particular, if the independence relation ( $\Sigma$ ,  $I_{\Sigma}$ ) is a chain of four nodes (also called P4) and every node is labeled with a finite monoid, then it is not clear whether the corresponding graph product has a Cayley-graph with a decidable MSO-theory.

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