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The Compressed Word Problem for Groups

- Monograph -

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Dedicated to Lynda, Andrew, and Ewan.

Preface

The study of computational problems in combinatorial group theory goes back more than 100 years. In a seminal paper from 1911, Max Dehn posed three decision problems [46]: The word problem (called Identitätsproblem by Dehn), the conjugacy problem (called Transformationsproblem by Dehn), and the isomorphism problem. The first two problems assume a finitely generated group G (although Dehn in his paper requires a finitely presented group). For the word problem, the input consists of a finite sequence w of generators of G (also known as a finite word), and the goal is to check whether w represents the identity element of G. For the conjugacy problem, the input consists of two finite words u and v over the generators and the question is whether the group elements represented by u and v are conjugated. Finally, the isomorphism problem asks, whether two given finitely presented groups are isomorphic.¹ Dehns motivation for studying these abstract group theoretical problems came from topology. In a previous paper from 1910, Dehn studied the problem of deciding whether two knots are equivalent [45], and he realized that this problem is a special case of the isomorphism problem (whereas the question of whether a given knot can be unknotted is a special case of the word problem). In his paper from 1912 [47], Dehn gave an algorithm that solves the word problem for fundamental groups of orientable closed 2-dimensional manifolds. His algorithm is nowadays known as Dehn's algorithm and can be applied to a larger class of groups (so called hyperbolic groups). But Dehn also realized that his three problems seem to be very hard in general. In [46], he wrote "Die drei Fundamentalprobleme für alle Gruppen mit zwei Erzeugenden ... zu lösen, scheint einstweilen noch sehr schwierig zu sein." (Solving the three fundamental problems for all groups with two generators seems to be very difficult at the moment.) When Dehn wrote this sentence, a formal definition of computability was still missing. Only in the first half of the 1930's, the foundations of the modern theory of computability where laid by Alonzo Church, Kurt Gödel, Emil Post, and Alan Turing, see e.g. Chapter 1 in the textbook [40] for a brief historial outline. Another 20 years later, Pyotr Sergeyevich Novikov [136] and independently William Werner Boone [22] proved that Dehn's intuition concerning

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¹ Implicitly, the isomorphism problem can be also found in Tietze's paper [161] from 1908.

the difficulty of his problems was true: There exist finitely presented groups with an undecidable word problem (and hence an undecidable conjugacy problem). The isomorphism problem turned out to be undecidable around the same time [1, 145]. More details on the history around Dehn's three decision problems can be found in [158].

Despite these negative results, for many groups the word problem is decidable. Dehn's result for fundamental groups of orientable closed 2-dimensional manifolds was extended to one-relator groups by his student Wilhelm Magnus [121]. Other important classes of groups with a decidable word problem are automatic groups [57] (including important classes like braid groups [8], Coxeter groups, right-angled Artin groups, hyperbolic groups [68]) and finitely generated linear groups, i.e., groups of matrices over a field [144] (including polycyclic groups). This makes it interesting to study the complexity of the word problem. Computational complexity theory is a part of computer science that emerged in the mid 1960's and investigates the relation between (i) the time and memory of a computer necessary to solve a computational problem and (ii) the size of the input. For a word problem, the input size is simply the length of the finite sequence of generators. Early papers on the complexity of word problems for groups are [27, 28, 29, 144]. One of the early results in this context was that for every given $n \ge 0$ there exist groups for which the word problem is decidable but does not belong to the *n*-th level of the Grzegorczyk hierarchy (a hierarchy of decidable problems) [27]. On the other hand, for many prominent classes of groups the complexity of the word problem is quite low. For finitely generated linear groups Richard Jay Lipton and Yechezkel Zalcstein [108] proved that logarithmic working space (and hence polynomial time) suffices to solve the word problem. The class of automatic groups is another quite large class of groups including many classical group classes for which the word problem can be solved in quadratic time [57]. In contrast, groups with a difficult word problem seem to be quite exotic objects. The vague statement that for most groups the word problem is easy can be even made precise: Mikhail Gromov stated in [68] that a randomly chosen (according to a certain probabilistic process) finitely presented group is hyperbolic with probability 1, a proof was given by Alexander Olśhanskiĭ in [137]. Moreover, for every hyperbolic group the word problem can be solved in linear time. Hence, for most groups the word problem can be solved in linear time.

One of the starting points for the work in this book was a question from the 2003 paper [94] by Ilya Kapovich, Alexei Myasnikov, Paul Eugene Schupp, and Vladimir Shpilrain: Is there a polynomial time algorithm for the word problem for the automorphism group of a finitely generated free group F? For every group G the set of all automorphisms of G together with the composition operation is a group, the automorphism group Aut(G) of G. Clearly, if G is finite, then also Aut(G) is finite. But if G is only finitely generated, then Aut(G) is not necessarily finitely generated, see [105] for a counterexample. In a seminal paper [135] from 1924, Jakob Nielsen proved that the automorphism group of a finitely generated free group F is finitely generated (and in fact finitely presented). This makes it interesting to study the word problem for Aut(F). The straightforward algorithm for this problem has an exponential running time. Saul Schleimer [151] realized in 2006 that one can easily

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monoid.²

reduce the word problem for Aut(F) to a variant for the word problem for F, where the input sequence is given in a succinct form by a so called straight-line program. A straight-line program can be seen as a hierarchical description of a string. From a formal language theory point of view it is a context-free grammar G that generates exactly one string that we denote with $val(\mathbb{G})$. The length of this string can be exponential in the size of the grammar \mathbb{G} . In this sense, G can be seen as a succinct description of val(\mathbb{G}). The variant of the word problem for a group G, where the input sequence is given by a straight-line program is the compressed word problem for G, which is the main topic of this book. Explicitly this problem was first studied in my paper [110] (a long version appeared as [112]). My motivation for this work came from two other papers: In 1994, Wojciech Plandowski [139] proved that one can decide in polynomial time whether two straight-line programs produce the same words; implicitly this result can be also found in papers by Kurt Mehlhorn, Rajamani Sundar, and Christian Uhrig [127, 128] and Yoram Hirshfeld, Mark Jerrum and Faron Moller [79, 80] that were both published the same year as Plandowski's work. One could also rephrase this result by saying that the compressed word problem for a free monoid can be solved in polynomial time. My second motivation for studying the compressed word problem is the paper [15] by Martin Beaudry, Pierre McKenzie, Pierre Péladeau and Denis Thérien, where the authors studied the problem whether a given circuit over a finite monoid evaluates to a given monoid

Let me come back to the word problem for the automorphism group of a free group. In my paper [110] I proved that the compressed word problem for a finitely generated free group can be solved in polynomial time; the proof builds on the above mentioned result by Plandowski. Using this result, Schleimer was able to show that the word problem for Aut(F) (with *F* a finitely generated free group) can be solved in polynomial time [151], which answered the question from [94] positively.

element. This problem can be seen as the compressed word problem for a finite

After Schleimer's work, it turned out that the compressed word problem has applications not only for the word problem of automorphism groups, but also for semidirect products and certain group extensions. This motivated the study of the compressed word problem as a topic of its own interest. The aim of this book is to give an extensive overview of known results on the compressed word problem. Some of the results in this book can be found in published articles while others appear to be new. As a computer scientist with a strong interest in group theory, I tried to make this book accessible to both mathematicians and computer scientists. In particular, I tried to explain all necessary concepts from computer science (mainly computational complexity theory) and group theory. On the other hand, to keep the book focused on the compressed word problem I had to stop at a certain point. I hope that I could find the right balance.

I want to thank my former supervisor Volker Diekert for his scientific influence. During my time in Stuttgart, he drew my interest to group theoretical decision prob-

 $^{^{2}}$ At this point the reader might wonder why this book is about the compressed word problems for groups only and not monoids. This is more a matter of personal taste, and the fact that so far there exist more results for groups than for monoids

lems and the work of Plandowski on compression. This was the starting point for my work on the compressed word problem. Many results from this book were discovered with my collaborators Niko Haubold, Christian Mathissen, and Saul Schleimer. Without their contributions, this work would not exist in its present form. I have to thank Daniel König for his thorough proof reading. Many thanks to the referees for their numerous useful comments that helped to improve this book. Finally, I am grateful to Benjamin Steinberg for encouraging me to write this book.

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Chapter 1 Preliminaries from Theoretical Computer Science

In this chapter, we briefly recall basic definitions from theoretical computer science. We start with several general notations from formal language theory (words, finite automata, word rewriting systems). The main part of the chapter is a brief introduction into basic concepts from complexity theory. The goal is to enable readers that are not familiar with complexity theory to understand the results and proofs in this book. But this chapter cannot replace a thorough introduction into the broad field of complexity theory. For this, we refer the reader to the text books [7, 138].

1.1 Preliminaries from Formal Language Theory

Let Γ be a set, called an *alphabet* in the following. We do not assume that Γ is finite, although most of the time it will be finite. Elements of Γ will be called *symbols*.

Definition 1.1 (finite words, length and alphabet of a word, factor, empty word). A *finite word* over Γ is just a sequence of alphabet symbols $s = a_1 a_2 \cdots a_n$ with $n \ge 0$ and $a_1, a_2, \ldots, a_n \in \Gamma$. We can have $a_i = a_j$ for $i \ne j$. The length of this word *s* is |s| = n. For $a \in \Gamma$ let $|s|_a = |\{i \mid 1 \le i \le n, a_i = a\}|$ be the number of occurrences of *a* in *s*. With $alph(s) = \{a \in \Gamma \mid |s|_a > 0\}$ we denote the set of symbols that occur in *s*, also called the *alphabet of s*. For $1 \le i \le n$ we write $s[i] = a_i$. For $1 \le i \le j \le n$ let $s[i:j] = a_i \cdots a_j$. If $1 \le i \le j \le n$ does not hold, then we set $s[i:j] = \varepsilon$. Any word of the form s[i:j] is called a *factor* of *s*. We also use the abbreviations s[:j] = s[1:j]and s[i:] = s[i:|s|]. The unique word of length 0 is denoted by ε (the *empty word*).

Definition 1.2 (Γ^* , Γ^+ , **concatenation of words, free monoid, languages).** The set of all finite words over Γ is denoted with Γ^* . Moreover, let $\Gamma^+ = \Gamma^* \setminus \{\varepsilon\}$. The *concatenation* of words $s = a_1 \cdots a_n$ and $t = b_1 \cdots b_m$ is the word $st = a_1 \cdots a_n b_1 \cdots b_m$. This is an associative operation with identity element ε . Hence, Γ^* has the structure of a monoid, called the *free monoid* generated by Γ . A *language* is a subset of Γ^* for some finite alphabet Γ .

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An important class of languages are regular languages which are defined by finite automata:

Definition 1.3 (nondeterministic finite automaton). A *nondeterministic finite automaton* (briefly *NFA*), is a tuple $\mathscr{A} = (Q, \Sigma, \delta, q_0, F)$, where

- Q is a finite set of states,
- Σ is the (finite) input alphabet,
- $\delta \subseteq Q \times \Sigma \times Q$ is the set of transitions
- $q_0 \in Q$ is the initial state, and
- $F \subseteq Q$ is the set of final states.

We define $\widehat{\delta}$ as the smallest subset of $Q \times \Sigma^* \times Q$ such that:

- $(q, \varepsilon, q) \in \widehat{\delta}$ for all $q \in Q$,
- $\delta \subseteq \widehat{\delta}$, and
- If $(q, u, p), (p, v, r) \in \widehat{\delta}$, then also $(q, uv, r) \in \widehat{\delta}$.

The language accepted by \mathscr{A} is $L(\mathscr{A}) = \{w \in \Sigma^* \mid \exists q \in F : (q_0, w, q) \in \delta\}$; it is the set of all words that label a path from the initial state q_0 to a final state. A *deterministic finite automaton* (briefly *DFA*), is an $\mathscr{A} = (Q, \Sigma, \delta, q_0, F)$ such that for every pair $(q, a) \in Q \times \Sigma$ there is at most one state $p \in Q$ such that $(q, a, p) \in \delta$.

By a famous theorem of Rabin and Scott, for every NFA \mathscr{A} there exists a DFA \mathscr{A}' such that $L(\mathscr{A}) = L(\mathscr{A}')$. There is family of NFA \mathscr{A}_n such that \mathscr{A}_n has *n* states but the smallest DFA accepting $L(\mathscr{A}_n)$ has 2^n states. When we only talk about finite automata, we refer to nondeterministic finite automaton. A language $L \subseteq \Sigma^*$ is *regular* if there is a finite automaton with $L(\mathscr{A}) = L$. The book [82] is an excellent introduction into the wide area of automata theory.

1.2 Rewriting Systems

Rewriting systems are a formalism for manipulating words or other data structures. Before we formally define word rewriting systems, we first introduce some abstract properties of binary relations, see [21, Chapter 1] for more details.

Let \rightarrow be a binary relation on a set *A*. With \rightarrow^* we denote the reflexive and transitive closure of \rightarrow , and \leftrightarrow^* denotes the smallest equivalence relation containing \rightarrow . Formally, we have $a \leftrightarrow^* b$, if there exist $i \ge 1$ and elements $a_1, a_2, \ldots, a_n \in A$ such that $a_1 = a$, $a_n = b$, and $(a_i \rightarrow a_{i+1} \text{ or } a_{i+1} \rightarrow a_i)$ for all $1 \le i \le n-1$.

Definition 1.4 (Noetherian/locally confluent/confluent relation). We say that \rightarrow is *Noetherian* (or *terminating*) if there does not exist an infinite sequence $a_0 \rightarrow a_1 \rightarrow a_2 \rightarrow \cdots$ in *A*. The relation \rightarrow is *confluent* if for all $a, b, c \in A$ with $a \rightarrow^* b$ and $a \rightarrow^* c$ there exists $d \in A$ such that $b \rightarrow^* d$ and $c \rightarrow^* d$. The relation \rightarrow is *locally confluent* if for all $a, b, c \in A$ with $a \rightarrow b$ and $a \rightarrow c$ there exists $d \in A$ such that $b \rightarrow^* d$ and $c \rightarrow^* d$.

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1.2 Rewriting Systems

Clearly, every confluent relation is also locally confluent. Moreover, Newman's Lemma [134] states that a Noetherian and locally confluent relation is also confluent. Furthermore, if \rightarrow is confluent then for all $a, b \in A$, $a \leftrightarrow^* b$ if and only if there exists $d \in A$ with $a \rightarrow^* d$ and $b \rightarrow^* d$.

Definition 1.5 (set of irreducible words $\mathsf{IRR}(\rightarrow)$, **normal form** $\mathsf{NF}_{\rightarrow}(a)$). Let $\mathsf{IRR}(\rightarrow)$ be the set of all $a \in A$ such that there does not exist $b \in A$ with $a \rightarrow b$ ("IRR" stands for "irreducible"). Assume that \rightarrow is Noetherian and confluent. Then for every word $a \in A$ there exists a unique element $\mathsf{NF}_{\rightarrow}(a) \in \mathsf{IRR}(\rightarrow)$ with $a \rightarrow^* \mathsf{NF}_{\rightarrow}(a)$ ("NF" stands for "normal form"). Moreover, $a \leftrightarrow^* b$ if and only if $\mathsf{NF}_{\rightarrow}(a) = \mathsf{NF}_{\rightarrow}(b)$.

Definition 1.6 (semi-Thue system). A *semi-Thue system*¹ (or *word rewriting system*) over the alphabet Γ is just a (possibly infinite) set $R \subseteq \Gamma^* \times \Gamma^*$, see [21] for more details. We associate with R a binary relation \rightarrow_R on Γ^* , also called the, as follows: For all $u, v \in \Gamma^*$, $u \rightarrow_R v$ if and only if there exist $x, y \in \Gamma^*$ and $(\ell, r) \in R$ such that $u = x\ell y$ and v = xry. Elements (ℓ, r) are called *rules* and usually written as $\ell \rightarrow r$.

Definition 1.7 (Noetherian/confluent/locally confluent semi-Thue system, irreducible words). The semi-Thue system *R* is Noetherian (confluent, locally confluent) if \rightarrow_R is Noetherian (confluent, locally confluent). Let $IRR(R) = IRR(\rightarrow_R)$ (the set of *irreducible words* with respect to *R*) and $NF_R(w) = NF_{\rightarrow_R}(w)$ (if *R* is Noetherian and confluent). Thus, we have

$$\mathsf{IRR}(R) = \Gamma^* \setminus \bigcup_{(\ell,r) \in R} \Gamma^* \ell \Gamma^*.$$

Definition 1.8 (quotient monoid Γ^*/R **).** Let $[u]_R = \{v \in \Gamma^* \mid u \leftrightarrow_R^* v\}$ be the equivalence class with respect to \leftrightarrow_R^* containing u. Note that \leftrightarrow_R^* is a congruence relation on the free monoid Γ^* : If $u_1 \leftrightarrow_R^* v_1$ and $u_2 \leftrightarrow_R^* v_2$, then $u_1 u_2 \leftrightarrow_R^* v_1 v_2$. Hence, we can define the quotient monoid Γ^*/R as follows: The set of elements of Γ^*/R is the set of equivalence classes $[u]_R (u \in \Gamma^*)$ and the monoid multiplication is defined by $[u]_R[v]_R = [uv]_R$.

If *R* is Noetherian and confluent, then every equivalence class $[u]_R$ contains a unique irreducible word NF_{*R*}(*u*). Hence, one can identify Γ^*/R with the set of irreducible words IRR(*R*), where the product of $u, v \in IRR(R)$ is defined by NF_{*R*}(uv).

Example 1.9. The semi-Thue system $R = \{ba \rightarrow ab, ca \rightarrow ac\}$ is Noetherian and confluent. We have $IRR(R) = a^*\{b,c\}^*$. The monoid $\{a,b,c\}^*/R$ is isomorphic to $\mathbb{N} \times \{a,b\}^*$ (where we take the monoid operation + on \mathbb{N}).

For a finite Noetherian semi-Thue system R one can check whether R is locally confluent (and hence confluent by Newman's Lemma) by verifying confluence of so called critical pairs that result from overlapping left-hand sides of R, see [21] for more details. A survey on string rewriting systems emphasizing applications in group theory can be found in [37].

¹ Named by Axel Thue, who introduced semi-Thue systems in his paper [160] from 1914.

We assume some familiarity with algorithms and the very basic concepts of computability, see e.g. [7, 138] for an introduction. In this section we will only outline the basic concepts from computational complexity theory that are needed for this book.

This book is concerned with algorithmic problems in combinatorial group theory, and their inherent computational difficulty. In order to make precise statements about the computational difficulty (or computational complexity) of problems, we need an abstract mathematical model of a computer. The basic computational model in computability theory and complexity theory is the Turing machine. Turing machines were introduced in Turing's seminal work [162] as an abstract model of a universal computer. There are several variants for the definition of a Turing machine. All these variants lead to the same definition of complexity classes. Here, we choose the variant of (nondeterministic and deterministic) Turing machines with a read-only input tape, a read-write working tape, and optionally a write-only output tape.

1.3.1 Turing Machines

Definition 1.10 (nondeterministic Turing machine). A *nondeterministic Turing machine* is a tuple $M = (Q, \Sigma, \Gamma, \delta, q_0, q_f, \Box)$ where

- Q is a finite set of states,
- $q_0 \in Q$ is the initial state,
- $q_f \in Q$ is the final state,
- Γ is a finite tape alphabet,
- Σ is the finite input alphabet with $\Sigma \cap \{\triangleleft, \triangleright\} = \emptyset$,
- $\Box \in \Gamma$ is the blank symbol, and
- δ ⊆ (Q \ {q_f}) × (Σ ∪ {⊲,▷}) × Γ × Q × (Γ \ {□}) × {−1,0,1}² is the transition relation. We call its elements instructions, and require that (q,▷,a, p,b,d₁,d₂) ∈ δ implies d₁ ≥ 0 and (q,⊲,a,p,b,d₁,d₂) ∈ δ implies d₁ ≤ 0.

The nondeterministic Turing machine M is *deterministic*, if for all intructions $(q, a, b, p, c, d_1, d_2), (q, a, b, p', c', d'_1, d'_2) \in \delta$ we have $p = p', c = c', d_1 = d'_1$, and $d_2 = d'_2$.

The idea is that the machine *M* has an input tape, where the input word $w = a_1a_2\cdots a_n \in \Sigma^*$ is stored in cell 1 to cell *n*. Moreover, cell 0 (respectively, n + 1) of the input tape contains the left (respectively, right) end marker \triangleright (respectively, \triangleleft). The content of the input tape is not modified by *M*. Moreover, the machine has a *work tape*, whose cells are indexed by the integers \mathbb{Z} . Each of these cells contains a symbol from Γ . At the beginning all cells contain the blank symbol \Box , and at every step, all but finitely many cells contain the blank symbol. The machine

has two heads: An input head, which is scanning a cell of the input tape, and a work head, which is scanning a cell of the work tape. Finally, the Turing machine is equipped with a finite state unit, whose current state is from Q. An instruction $(q, a, b, p, c, d_1, d_2) \in \delta$ has the following intuitive meaning: If the M is currently in state q, the input head is scanning a cell containing the symbol a, and the work tape is scanning a cell containing the symbol b, then the machine M can do the following action: Overwrite the b in the current cell on the work tape with the non-blank symbol c (we may have b = c), move the input head one cell in direction d_1 (where "-1" means "one cell to the left", "0" means "stay at the same cell", and "1" means "one cell to the right"), move the work head one cell in direction d_2 , and enter state q. Let us now define formally configurations and transitions of Turing machines. The following definitions all refer to the Turing machine $M = (Q, \Sigma, \Gamma, \delta, q_0, q_f, \Box)$.

Definition 1.11 (configuration). A *configuration* α of the Turing machine *M* is a 5-tuple $\alpha = (x, q, i, w, j)$, where:

- $x \in \Sigma^*$ is the input word,
- $q \in Q$ is the current state of the Turing machine,
- $0 \le i \le |x| + 1$ is the cell scanned by the input head,
- w: Z → Γ is the current content of the work tape, and there exist only finitely many k ∈ Z with w(k) ≠ □,
- $j \in \mathbb{Z}$ is the current cell scanned by the work head.

The *length* $|\alpha|$ of the configuration $\alpha = (x, q, i, w, j)$ is $|\alpha| = |\{k \in \mathbb{Z} \mid w(k) \neq \Box\}|$. Let init $(x) = (x, q_0, 0, w_{\Box}, 0)$ be the *initial configuration* of M for input x, where $w_{\Box}(k) = \Box$ for all $k \in \mathbb{Z}$. With accept (the set of all *accepting configurations*) we denote the set of all configurations of the form (x, q_f, i, w, j) .

Hence, the length $|\alpha|$ is the number of non-blank cells on the work tape. Note that the length of the input word *x* does not count for the length of α . This is crucial for our later definition of logspace computations. Note that |init(x)| = 0.

For an instruction $t \in \delta$ and configurations α, β of M, we write $\alpha \vdash_t \beta$, if instruction t can be applied to configuration α and yields configuration β . Here is the formal definition:

Definition 1.12 (relation \vdash_M). For configurations α, β of M we write $\alpha \vdash_t \beta$ if and only if the following conditions are satisfied: $\alpha = (x, q, i_1, v, i_2), \beta = (x, p, j_1, w, j_2)$ $t = (q, a_1, a_2, p, b, d_1, d_2), (\triangleright x \triangleleft)[i_1 + 1] = a_1, v(i_2) = a_2, v(j) = w(j)$ for all $j \neq i_2, w(i_2) = b, j_1 = i_1 + d_1$, and $j_2 = i_2 + d_2$. We write $\alpha \vdash_M \beta$ if there exists an instruction $t \in \delta$ with $\alpha \vdash_t \beta$.

Clearly, for a nondeterministic Turing machine M, there may exist several (or no) configurations β with $\alpha \vdash_t \beta$, but the number of successor configurations of α is bounded by a constant that only depends on M. If M is deterministic, then every configuration has at most one successor configuration.

Note that if $\alpha \in \text{accept}$, then there is no configuration β with $\alpha \vdash_M \beta$. Moreover, $\alpha \vdash_M \beta$ implies that $|\beta| - |\alpha| \in \{0, 1\}$ for all configurations α and β (since *M* cannot write \Box into a work tape cell).

Definition 1.13 (computation, L(M)**, computably enumerable language).** A *computation of* M *on input* x is a sequence of configurations $(\alpha_0, \alpha_1, \ldots, \alpha_m)$ with $init(x) = \alpha_0$ and $\alpha_{i-1} \vdash_M \alpha_i$ for all $1 \le i \le m$. The computation is *successful* if $\alpha_m \in$ accept. The set

$$L(M) = \{x \in \Sigma^* \mid \exists \text{ successful computation of } M \text{ on input } x\}$$

is the language accepted (or solved) by M. A language L is called *computably* enumerable (or recursively enumerable) if there exists a Turing machine M with L = L(M).

In the above definition of computably enumerable languages, we can restrict the Turing machine M to be deterministic. In other words: Nondeterministic and deterministic Turing machines recognize the same class of languages, namely the computably enumerable languages.

Example 1.14. Consider the deterministic Turing machine

$$M = (Q, \Sigma, \Gamma, \delta, q_0, q_f, \Box),$$

where $Q = \{q_0, q_1, q_2, q_3, q_f\}$, $\Sigma = \{a, b\}$, $\Gamma = \{a, b, \#\}$, and δ contains the following tuples:

 $\begin{array}{l} (1) \ (q_0, \triangleright, \Box, q_1, \#, 1, 1) \\ (2) \ (q_1, x, \Box, q_1, x, 1, 1) \ \text{for} \ x \in \{a, b\} \\ (3) \ (q_1, \triangleleft, \Box, q_2, \#, 0, -1) \\ (4) \ (q_2, \triangleleft, x, q_2, x, 0, -1) \ \text{for} \ x \in \{a, b\} \\ (5) \ (q_2, \triangleleft, \#, q_3, \#, -1, +1) \\ (6) \ (q_3, x, x, q_3, \#, -1, +1) \\ (7) \ (q_3, \triangleright, \#, q_f, \#, 0, 0) \end{array}$

This machine accepts the set of all palindromes over the alphabet $\{a, b\}$, i.e., the set of words $w \in \{a, b\}^*$ such that w[i] = w[|w| - i + 1] for all $1 \le i \le |w|$. With the first two types of instructions, we copy the input word onto the work tape. At the end of this first stage, the input head scans the right end marker \triangleleft . Then, with the instructions of type (3) and (4), we move the work tape head back to the beginning of the copy of the input word. The input head stays on the right end marker \triangleleft . The main work is done with the instructions of type (6), which compare for every $1 \le i \le n$ the symbols w[i] and w[|w| - i + 1] of the input word w.

So far, we used Turing machines only as language acceptors, similar to finite automata in automata theory. But in many contexts we want to use Turing machines to compute some possibly complex output word from the input word. For instance, we might want to output the sum or product of two input numbers. For this, we need Turing machines with output. Since such a machine should produce a single output word for a given input word, the machine should be deterministic.

Definition 1.15 (Turing machine with output). A *deterministic Turing machine with output* (also called a *transducer*) is a tuple $M = (Q, \Sigma, \Gamma, \Delta, \delta, q_0, q_f, \Box)$ where

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- $Q, \Sigma, \Gamma, q_0, q_f$, and \Box have the same meaning as for ordinary Turing machines,
- Δ is the output alphabet, and
- $\delta \subseteq (Q \setminus \{q_f\}) \times (\Sigma \cup \{\triangleleft, \triangleright\}) \times \Gamma \times Q \times \Gamma \times \{-1, 0, 1\}^2 \times (\Delta \cup \{\varepsilon\})$ is the transition relation. We require that $(q, \triangleright, a, p, b, d_1, d_2, c) \in \delta$ implies $d_1 \ge 0$ and $(q, \triangleleft, a, p, b, d_1, d_2, c) \in \delta$ implies $d_1 \le 0$. Moreover, we require that for all instructions $(q, a, b, p, c, d_1, d_2, o), (q, a, b, p', c', d'_1, d'_2, o') \in \delta$ we have p = p', $c = c', d_1 = d'_1, d_2 = d'_2$, and o = o' (i.e., *M* is deterministic).

The intuition behind an instruction $(q, a, b, p, c, d_1, d_2, o) \in \delta$ is the same as for ordinary Turing machines, where in addition $o \in \Delta \cup \{\varepsilon\}$ is the output symbol. The idea is that the output is generated sequentially from left to right. If $o \in \Delta$ then o is appended to the prefix of the output that has been already produced. If $o = \varepsilon$, then the output is not extended in the current computation step. Formally, a configuration of M is a 6-tuple $\alpha = (x,q,i,w,j,y)$, where x,q,i,w,j have the same meaning as in Definition 1.11 and $y \in \Delta^*$ is the partial output that has been produced so far. For configurations α , β and an instruction $t \in \delta$ we write $\alpha \vdash_t \beta$ if and only if $\alpha = (x,q,i_1,v,i_2,y), \beta = (x,p,j_1,w,j_2,y_0) t = (q,a_1,a_2,p,b,d_1,d_2,o)$, and all conditions from Definition 1.12 hold. Computations are defined analogously to ordinary Turing machines.

A Turing machine with output $M = (Q, \Sigma, \Gamma, \Delta, \delta, q_0, q_f, \Box)$ computes a partial function $f_M : \Sigma^* \to \Delta^*$ in the natural way:

Definition 1.16 (function f_M **computed by** M**).** For a word $x \in \Sigma^*$ we have $f_M(x) = y$ if and only if there exists an accepting configuration $\alpha = (x, q_f, i, w, j, y)$ such that $init(x) \vdash_M^* \alpha$.

In general, the function f_M is only partially defined, since M is not guranteed to finally reach an accepting configuration from init(x).

Recall that a language *L* is computably enumerable if there exists a (deterministic or nondeterministic) Turing machine *M* with L = L(M). Alternatively, one can say that *L* is recursively enumerable if there exists a Turing machine with output *M* such that *L* is the domain of f_M .

Definition 1.17 (computable language). A language *L* is *computable* (or *recursive* or *decidable*) if and only if there exists a Turing machine with output *M* such that for all inputs *x*: If $x \in L$, then $f_M(x) = 1$ and if $x \notin L$, then $f_M(x) = 0$ (in particular, f_M is total). A language, which is not computable is called *undecidable*.

Intuitively, a language L is computable, if there exists an algorithm such that for every input word x, the algorithm either terminates with the answer "yes, x belongs to L" or "no, x does not belong to L". It is well-known that L is computable if and only if L and the complement of L are both computably enumerable.

In the following, we use the term *computational problem* or just *problem* as a synonym for language. Hence, Turing machines are devices for solving computational problems. When describing a computational problem that corresponds to a language $L \subseteq \Sigma^*$ we use a description of the following form:

input: A word *x* over the alphabet Σ .

question: Does *x* belong to *L*?

1.3.2 Time and Space Classes

In this section, we define several important complexity classes.

Definition 1.18 (time and space needed by a Turing machine). Let *M* be a Turing machine and let $c = (\alpha_0, \alpha_1, ..., \alpha_m)$ be a computation of *M* (for a certain input *x*). We say that *c* needs *time m*, and we say that *c* needs *space* max{ $|\alpha_i| | 0 \le i \le m$ }. The Turing machine *M* needs time (respectively, space) at most $N \in \mathbb{N}$ on input *x* if every computation (not only accepting ones) of *M* on input *x* needs time (respectively, space) at most *N*.

Definition 1.19 (*f*-time bounded, *f*-space bounded). Let $f : \mathbb{N} \to \mathbb{N}$ be a monotonically increasing function. We say that *M* is *f*-time bounded, if for every input *x*, *M* needs time at most f(|x|). We say that *M* is *f*-space bounded, if for every input *x*, *M* needs space at most f(|x|).

For example, the Turing machine from Example 1.14 is (3n + 4)-time bounded.

Of course, the above definitions can be also used for Turing machines with output.

Definition 1.20 (DTIME, NTIME, DSPACE, NSPACE). We define the following complexity classes:

 $DTIME(f) = \{L(M) \mid M \text{ is deterministic and } f\text{-time bounded}\}$ $NTIME(f) = \{L(M) \mid M \text{ is nondeterministic and } f\text{-time bounded}\}$ $DSPACE(f) = \{L(M) \mid M \text{ is deterministic and } f\text{-space bounded}\}$ $NSPACE(f) = \{L(M) \mid M \text{ is nondeterministic and } f\text{-space bounded}\}$

For a class \mathscr{C} of monotonically increasing functions on \mathbb{N} we write $\mathsf{DTIME}(\mathscr{C})$ for $\bigcup_{f \in \mathscr{C}} \mathsf{DTIME}(f)$ and similarly for NTIME, DSPACE, and NSPACE.

Trivially, $\mathsf{DTIME}(f) \subseteq \mathsf{NTIME}(f)$ and $\mathsf{DSPACE}(f) \subseteq \mathsf{NSPACE}(f)$. Some other inclusions are:

- $\mathsf{DSPACE}(\mathscr{O}(f)) = \mathsf{DSPACE}(f)$ and $\mathsf{NSPACE}(\mathscr{O}(f)) = \mathsf{NSPACE}(f)$
- $\mathsf{NTIME}(f) \subseteq \mathsf{DSPACE}(f)$
- NSPACE $(f) \subseteq \mathsf{DTIME}(2^{\mathscr{O}(f)})$ if $f \in \Omega(\log n)$.

Moreover, a famous theorem of Savitch states that NSPACE $(f) \subseteq DSPACE(f^2)$ if $f \in \Omega(\log n)$. Hence, nondeterministic Turing machines can be simulated by deterministic Turing machines with a quadratic blow up in space.

Definition 1.21 (L, P, NP, PSPACE). Some important abbreviations are the following, where as usual $\mathbb{N}[x]$ denotes the class of all polynomials with coefficients from \mathbb{N} :

$$\mathbf{L} = \mathsf{DSPACE}(\log(n)) \tag{1.1}$$

$$\mathbf{NL} = \mathsf{NSPACE}(\log(n)) \tag{1.2}$$

$$\mathbf{P} = \bigcup_{f \in \mathbb{N}[n]} \mathsf{DTIME}(f) \tag{1.3}$$

$$\mathbf{NP} = \bigcup_{f \in \mathbb{N}[n]} \mathsf{NTIME}(f) \tag{1.4}$$

$$\mathbf{PSPACE} = \bigcup_{f \in \mathbb{N}[n]} \mathsf{DSPACE}(f) \stackrel{*}{=} \bigcup_{f \in \mathbb{N}[n]} \mathsf{NSPACE}(f) \tag{1.5}$$

The identity (*) in (1.5) is a consequence of Savitch's theorem. In (1.1) and (1.2) we do not have to specify the base of the logarithm, since changing the base only involves a multiplicative factor. So, \mathbf{L} (respectively, \mathbf{NL}) is the class of all problems that can be decided by a deterministic (respectively, nondeterministic) Turing machine in logarithmic space, \mathbf{P} (respectively, \mathbf{NP}) is the class of all problems that can be decided by a deterministic (respectively, nondeterministic) Turing machine in polynomial time, and **PSPACE** is the class of all problems that can be decided by a (deterministic) Turing machine in polynomial time, and **PSPACE** is the class of all problems that can be decided by a (deterministic) Turing machine in polynomial space. The class \mathbf{P} is often identified with the class of those problems that can be solved efficiently. The following inclusions hold:

$$\mathbf{L} \subseteq \mathbf{N}\mathbf{L} \subseteq \mathbf{P} \subseteq \mathbf{N}\mathbf{P} \subseteq \mathbf{P}\mathbf{S}\mathbf{P}\mathbf{A}\mathbf{C}\mathbf{E}.$$
 (1.6)

But none of these inclusions is known to be strict (and the strictness of each inclusion is a major open problem in complexity theory), although the so called space hierarchy theorem implies $NL \subsetneq PSPACE$; hence one of the inclusions must be proper.

Definition 1.22 (coC). For a complexity class **C** we denote with **coC** the set of all complements of languages from **C**.

Hence, C = coC means that C is closed under complement. It is easy to show that deterministic time and space classes (like L, P, PSPACE) are closed under complement. A famous result shown independently by Immerman and Szelepcsényi in 1985 states that NL = coNL. Whether NP = coNP is a major open problem in complexity theory.

1.3.3 Reductions and Completeness

In this section we will introduce the important notions of reductions and completeness for a complexity class. Via completeness, one can identify the most difficult problems within a complexity class. First we have to introduce some resource bounded classes of transducers: **Definition 1.23 (polynomial time transducer, logspace transducer).** A *polynomial time transducer* is a Turing machine M with output that computes a total function f_M and that is p(n)-time bounded for a polynomial p(n). A *logspace transducer* is a Turing machine M with output that computes a total function f_M and that is log(n)-space bounded.

Example 1.24. The binary representation of the sum of two natural numbers that are given in binary representation can be computed with a logspace transducer that follows the standard school method for addition. If u and v are the binary representations of the two input numbers (let us assume that the least significant bit is left), then the machine has to store a position $1 \le p \le \max\{|u|, |v|\}$. This position can be stored in binary representation and hence needs only logarithmically many bits. Moreover, a carry bit is stored. In each step, the bits at position p in u and v and the carry bit is added, a new output bit is produced and a new carry bit is stored. Moreover, the position p is incremented. Incrementing a number in binary representation is possible in logarithmic space.

Also the product of two binary encoded natural numbers can be computed by a logspace transducer; this requires a little bit more work than for sum. Finally, also the integer part of the quotient of two binary encoded natural numbers can be computed in logspace [35, 76]. This solved a long standing open problem.

Example 1.25. Another class of functions that can be computed with logspace transducers are free monoid morphisms. Let $f : \Sigma^* \to \Gamma^*$ be a morphism between free monoids. A logspace transducer that computes f simply reads the input word x from left to right, and for every symbol a in x it appends f(a) to the output.

Using polynomial time transducers and logspace transducers we can refine the classical many-one reducibility from computability theory.

Definition 1.26 $(\leq_m^P, \leq_m^{\log})$. Let $K \subseteq \Sigma^*$ and $L \subseteq \Delta^*$ be languages. We write $K \leq_m^P L$ (*K* is polynomial time many-one reducible to *L*) if there exists a polynomial time transducer *M* such that for all $x \in \Sigma^*$ we have: $x \in K$ if and only if $f_M(x) \in L$. We write $K \leq_m^{\log} L$ (*K* is logspace many-one reducible to *L*) if there exists a logspace transducer *M* such that for all $x \in \Sigma^*$ we have: $x \in K$ if and only if $f_M(x) \in L$.

Since a logspace transducer works in polynomial time (this follows from the same argument that shows $\mathbf{L} \subseteq \mathbf{P}$), $K \leq_m^{\log} L$ implies $K \leq_m^P L$. Moreover, $L_1 \leq_m^P L_2 \leq_m^P L_3$ implies $L_1 \leq_m^P L_3$, i.e., \leq_m^P is transitive: Simply compose two polynomial time transducers. This simple approach does not work for logspace transducers: If M_1 and M_2 are logspace transducers, then for an input x, the length of $f_{M_1}(x)$ can be polynomial in the length of x. Hence, we cannot store the word $f_{M_1}(x)$ as an intermediate result. Nevertheless, \leq_m^{\log} is a transitive relation. The proof is neither obvious nor very difficult. Transitivity of \leq_m^{\log} is very useful. In order to construct a logspace transducer for a certain task, it allows to split this task into several (constantly many) subtasks and to design a logspace transducer for each subtask.

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The class **L** is closed under \leq_m^{\log} : If $L \in \mathbf{L}$ and $K \leq_m^{\log} L$ then also $K \in \mathbf{L}$. The same holds for all comlexity classes in (1.6). Similarly, **P** and all complexity class above **P** in (1.6) are closed under \leq_m^P .

The following two types of reducibilities are weaker than \leq_m^{\log} and \leq_m^P , respectively:

Definition 1.27 $(\leq_{\mathbf{bc}}^{P}, \leq_{\mathbf{bc}}^{\log})$. Let $K \subseteq \Sigma^*$ and $L \subseteq \Delta^*$ be languages. We write $K \leq_{\mathbf{bc}}^{P}$ L (K is polynomial time bounded conjunctively reducible to L) if there exist a constant $c \in \mathbb{N}$ and a polynomial time transducer M such that $f_M(\Sigma^*) \subseteq (\#\Delta^*)^c$ (where $\# \notin \Delta$) and for all $x \in \Sigma^*$ we have: $x \in K$ if and only if $\bigwedge_{i=1}^{c} y_i \in L$, where $f_M(x) = \#y_1 \# y_2 \cdots \# y_c$. We write $K \leq_{\mathbf{bc}}^{\log} L$ (K is logspace bounded conjunctively reducible to L) if there exist a constant $c \in \mathbb{N}$ and a logspace transducer M such that $f_M(\Sigma^*) \subseteq (\#\Delta^*)^c$ (where $\# \notin \Delta$) and for all $x \in \Sigma^*$ we have: $x \in K$ if and only if $\bigwedge_{i=1}^{c} y_i \in L$, where $f_M(x) = \#y_1 \# y_2 \cdots \# y_c$.

The relation \leq_{bc}^{P} (respectively, \leq_{bc}^{\log}) has the same closure properties that we mentioned for \leq_{m}^{P} (respectively, \leq_{m}^{\log}) above.

In this book, we will also need a fifth type of reducibility that is weaker than \leq_{bc}^{P} . It is called *polynomial time Turing-reducibility* and is defined via *oracle Turing machines*.

Definition 1.28 (oracle Turing machine). Let us fix a language $L \in \Delta^*$. An *oracle Turing machine with oracle access to L* is a tuple $M = (Q, \Sigma, \Gamma, \Delta, \delta, q_0, q_f, \Box)$ that satisfies all the conditions of a Turing machine with output (Definition 1.15). In addition, Q constains three distinguished states $q_{?}, q_{Y}$, and q_{N} such that δ contains no outgoing transitions from state $q_{?}$. Instead, we enforce that for a configuration $\alpha = (q_{?}, i, w, j, y)$ (hence, $y \in \Delta^*$ is the output produced so far) the next configuration is $(q_{Y}, i, w, j, \varepsilon)$ if $y \in L$ and $(q_{N}, i, w, j, \varepsilon)$ if $y \notin L$.

Intuitively this means that M can compute words over Δ (so called oracle queries). When it enters the state $q_{?}$ (the query state), the computed oracle query is send to an L-oracle. This oracle answers instantaneously, whether the oracle query belongs to L or not. Hence, membership in the set L can be tested for free. One could also say that we enhance the machine M with a black-box procedure that tests membership in the set L.

In Definition 1.28, we do not care whether L is computable or not. Oracle Turing machines can be deterministic or nondeterministic, but we will only use deterministic ones. All definitions that we gave for ordinary Turing machines (e.g., the accepted language L(M), f(n)-time bounded, f(n)-space bounded) are defined analogously to ordinary Turing machines. Now we can define polynomial time Turing-reducibility:

Definition 1.29 (\leq_T^P). For languages *L* and *K* we write $K \leq_T^P L$ (*K* is polynomial time Turing-reducible to *K*) if there exists a deterministic polynomially timebounded oracle Turing machine *M* with oracle access to *L* such that K = L(M). In other words: *K* can be decided in polynomial time using an oracle for the language *L*. Clearly, $K \leq_m^P L$ implies $K \leq_T^P L$. The converse is false: For every language $L \subseteq \{0,1\}^*$ we have $L \leq_T^P (\{0,1\}^* \setminus L)$, but there are languages such that $L \leq_m^P (\{0,1\}^* \setminus L)$ does not hold (e.g. the halting problem).

Let \leq be one of our reducibility notions, and let K, L_1, \dots, L_n be languages. When writing $K \leq \{L_1, \dots, L_n\}$ we mean that $K \leq \#L_1 \#L_2 \# \cdots L_n$.

Using our reducibility relations we can finally define complete problems for complexity classes. Complete problems for a complexity class \mathscr{C} are the most difficult problems for the class \mathscr{C} . In some sense they completely capture the class \mathscr{C} .

Definition 1.30 (\mathscr{C} -hard language, \mathscr{C} -complete language). Let \mathscr{C} be a complexity class and let \leq be one of the above reducibility relations $(\leq_m^{\log}, \leq_p^m, \leq_{bc}^{\log}, \leq_{bc}^p, or \leq_p^T)$. A language *L* is \mathscr{C} -hard with respect to \leq if $K \leq L$ for every $K \in \mathscr{C}$ (*L* is at least as difficult as any problem in \mathscr{C}). The language *L* is \mathscr{C} -complete with respect to \leq if $L \in \mathscr{C}$ and *L* is \mathscr{C} -hard with respect to \leq . Whenever we say that *L* is \mathscr{C} -complete, we implicitly refer to logspace many-one reducibility \leq_m^{\log} .

Complete problems for \mathscr{C} are in a sense the most difficult problems from \mathscr{C} . For this, it is important that the reducibility used for the definition of completeness is not too weak. For instance, any language $L \subseteq \{0,1\}^*$ with $\emptyset \neq L \neq \{0,1\}^*$ is **P**-complete with respect to \leq_P^m .

For many complexity classes, very natural complete problems are known, Section 1.3.6 below mentions some of them. The book [58] contains a list of several hundred **NP**-complete problems, and [67] contains a similar list of **P**-complete problems. **NP**-complete problems are often called intractable, because of the following observation: If *L* is **NP**-complete, then $L \in \mathbf{P}$ if and only if $\mathbf{P} = \mathbf{NP}$. Analogous equivalences hold for other complexity classes too: For instance, if *L* is **P**-complete, then $L \in \mathbf{NL}$ if and only if $\mathbf{NL} = \mathbf{P}$.

1.3.4 How to Represent Input Structures

We should say a few words about the input representation. The input for a Turing machine is a word over some alphabet Σ . But quite often, we want to solve algorithmic problems, where the input is not a word, but for instance a finite graph, or a finite relational structure, or even another Turing machine. If we want to solve such a problem with a Turing machine, we have to encode the input data types by words. This is certainly possible. For instance a directed graph on *n* nodes can be represented by its adjacency matrix. This matrix can be encoded by a word over the alphabet $\{0, 1, \#\}$ by listing all matrix rows separated by #. Of course, there are other reasonable represented by concatenating for $1 \le i \le n$ all words $0^i \# 0^{j_1} \# 0^{j_2} \dots \# 0^{j_k}$ where j_1, \dots, j_k is a list of all successor nodes of node *i*. This encoding is based on adjacency lists. Strictly speaking the precise word encoding of the input data has to be fixed for a computational problem. Quite often this is not done explicitly, but some

canonical encoding is assumed. If two different input encodings can be transformed into each other efficiently, say by a logspace transducer, then the complexity of the problem does not depend on which of the two encodings is chosen (at least if we only consider classes containing **L**). For instance, the word encodings of directed graphs based on adjacency matrices and adjacency lists can be converted into each other by a logspace transducer.

Two important representations of numbers, which cannot be transformed into each other by logspace transducers are the unary and binary representation of numbers. The unary representation of the number $n \in \mathbb{N}$ is just the word 0^n . A polynomial time transducer cannot convert the binary encoding of the number n into its unary encoding, simply because the latter is exponentially longer than the former, but in polynomial time only polynomially many output symbols can be produced. Hence, for computational problems, where the input consists of numbers, it is important to specify the encoding of numbers (unary or binary encoding). One also says that the binary encoding of numbers is more succinct than the unary encoding. The topic of succinctness is central for this book. In the next section, we will see a general framework for succinct representations based on circuits.

A final remark in this context: For most natural encodings, it is very easy to check for a Turing machine, whether a given input word is a valid encoding. For instance, whether a word over the alphabet $\{0, 1, \#\}$ is the word encoding of a graph as described above can be verified by a deterministic Turing machine in logarithmic space.

1.3.5 Circuits

Circuits are a central topic in this book. They allow to represent large objects in a succinct way. In this section, we introduce a general definition of circuits. Later, we will see several concrete instantiations of circuits.

Let us fix a countable (possibly finite) set \mathscr{F} of function symbols, where every $f \in \mathscr{F}$ has a certain arity $n_f \in \mathbb{N}$. In case $n_f = 0$, f is a constant symbol. We assume that \mathscr{F} contains at least one constant symbol.

Definition 1.31 (\mathscr{F} -expressions with variables). Let *V* be a finite set of *variables*. The set $\mathscr{E}(\mathscr{F}, V)$ of \mathscr{F} -expressions with variables from *V* is the smallest set with respect to inclusion such that:

- $V \subseteq \mathscr{E}(\mathscr{F}, V)$
- If $f \in \mathscr{F}$ and $e_1, \ldots, e_{n_f} \in \mathscr{E}(\mathscr{F}, V)$, then also $f(e_1, \ldots, e_{n_f}) \in \mathscr{E}(\mathscr{F}, V)$.

The set Var(e) of variables that occur in the expression e is defined as follows:

- $\operatorname{Var}(v) = \{v\}$ for $v \in V$.
- $\operatorname{Var}(f(e_1,\ldots,e_{n_f})) = \bigcup_{1 \leq i \leq n_f} \operatorname{Var}(e_i).$

Circuits are a succinct representation of expressions without variables. The idea is to represent a subexpression that appears several times only once.

Definition 1.32 (circuit). An \mathscr{F} -*circuit* is a triple $\mathscr{C} = (V, S, \text{rhs})$ such that:

- V is a finite set of variables (or circuit gates).
- $S \in V$ is the start variable.
- rhs: $V \to \mathscr{E}(\mathscr{F}, V)$ (rhs stands for "right-hand side") assigns to each variable an expression such that the relation

$$graph(\mathscr{C}) = \{(A,B) \in V \times V \mid A \in Var(rhs(B))\}$$
(1.7)

is acyclic. The reflexive and transitive closure of the relation graph(\mathscr{C}) (which is a partial order on V) is the *hierarchical order* of C. The length (number of edges) of a longest path in the graph $(V, graph(\mathcal{C}))$ is the *height* of \mathcal{C} .

In order to evaluate a circuit we need an interpretation for the function symbols from \mathscr{F} . This leads to the notion of an \mathscr{F} -algebra:

Definition 1.33 (\mathscr{F} -algebra). An \mathscr{F} -algebra is a pair $\mathscr{A} = (A, I)$, where A is a set and I maps every $f \in \mathscr{F}$ to a function $I(f) : A^{n_f} \to A$. We usually suppress the mapping I and simply write $(A, (f)_{f \in \mathscr{F}})$ for (A, I). Here, f is identified with the function I(f).

Definition 1.34 (evaluation of an \mathscr{F} -circuit in an \mathscr{F} -algebra). Fix an \mathscr{F} -algebra $\mathscr{A} = (A, I)$ and an \mathscr{F} -circuit $\mathscr{C} = (V, S, rhs)$. We define the evaluation mapping $\mathsf{val}_{\mathscr{C}}^{\mathscr{A}}: \mathscr{E}(\mathscr{F}, V) \to A$ inductively as follows:

- If $e = X \in V$, then $\operatorname{val}_{\mathscr{C}}^{\mathscr{A}}(e) = \operatorname{val}_{\mathscr{C}}^{\mathscr{A}}(\operatorname{rhs}(X))$. If $e = f(e_1, \dots, e_{n_f})$, then $\operatorname{val}_{\mathscr{C}}^{\mathscr{A}}(e) = f(\operatorname{val}_{\mathscr{C}}^{\mathscr{A}}(e_1), \dots, \operatorname{val}_{\mathscr{C}}^{\mathscr{A}}(e_{n_f})) \in A$

The fact that $(V, graph(\mathscr{C}))$ is acyclic ensures that the mapping $val_{\mathscr{C}}^{\mathscr{A}}$ is well-defined. Finally, we define $\operatorname{val}^{\mathscr{A}}(\mathscr{C}) = \operatorname{val}_{\mathscr{C}}^{\mathscr{A}}(S)$.

The \mathscr{F} -algebra \mathscr{A} will be always clear from the context. Hence, we will omit the superscript \mathscr{A} in the mappings $\mathsf{val}_{\mathscr{C}}^{\mathscr{A}}$ and $\mathsf{val}^{\mathscr{A}}$. We will also talk about \mathscr{A} -expressions and \mathscr{A} -circuits (or circuits over \mathscr{A}) instead of \mathscr{F} -expressions and \mathscr{F} -circuits. Finally, if also the circuit $\mathscr C$ is clear from the context, we will also omit the index $\mathscr C$ in the mapping $\operatorname{val}_{\mathscr{C}}(e)$.

If a Turing machine wants to receive a circuit $\mathscr{C} = (V, S, \text{rhs})$ as input, the circuit has to be encoded by a word. One can identify the variables with numbers from $\{1,\ldots,n\}$ and each of these numbers can be binary encoded. Moreover, one can assume S = 1. Then, to encode the whole circuit, we first specify the number n (number of variables) and then list all right-hand sides $rhs(1), \ldots, rhs(n)$. In order to encode an expression $e \in \mathscr{E}(\mathscr{A}, V)$ we have to specify how to encode the operation symbols $f \in \mathscr{F}$. If \mathscr{F} is finite, we can simply include the set \mathscr{F} into the set of input symbols for the Turing machine. If \mathscr{F} is countably infinite, we can assume that $\mathscr{F} = \mathbb{N}$ and take the binary encoding of f as the code for the function symbol f. In order to be flexible, let us fix a function size : $\mathscr{F} \to \mathbb{N}$. In case \mathscr{F} is finite, we assume that size(f) = 1 for every $f \in \mathscr{F}$. This is reasonable, since a symbol from \mathscr{F} can be specified in constant space.

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1.3 Preliminaries from Complexity Theory



Fig. 1.1 The graph of the circuit from Example 1.37.

Definition 1.35 (size of a circuit). Having fixed a size function, we define the size |e| of an expression $e \in \mathscr{E}(\mathscr{F}, V)$ inductively as follows:

- If $e \in V$, then |e| = 1.
- If $e = f(e_1, ..., e_{n_f})$, then $|e| = \text{size}(f) + \sum_{i=1}^{n_f} |e_i|$.

Finally, we define the *size* $|\mathscr{C}|$ of the \mathscr{F} -circuit $\mathscr{C} = (V, S, \text{rhs})$ as

$$|\mathscr{C}| = \sum_{X \in V} |\mathsf{rhs}(X)|.$$

Definition 1.36 (circuit in normal form). A circuit $\mathscr{C} = (V, S, \text{rhs})$ is in normal form, if for every $X \in V$ we have $\text{rhs}(X) = f(X_1, \ldots, X_{n_f})$ for some $f \in \mathscr{F}$ and $X_1, \ldots, X_{n_f} \in V$.

By introducing additional variables we can transform in polynomial time a given circuit \mathscr{C} into a circuit \mathscr{D} in normal form such that $val(\mathscr{C}) = val(\mathscr{D})$.

Example 1.37. Let $\mathscr{F} = \{+, \times, 1\}$, where $n_+ = n_{\times} = 2$ and $n_1 = 0$. Moreover, consider the \mathscr{F} -algebra $\mathscr{A} = (\mathbb{Z}, I)$, where I(+) is the addition operation, $I(\times)$ is the multiplication operation, and I(1) = 1. Finally, define the \mathscr{F} -circuit

$$\mathscr{C} = (\{X_0, X_1, X_2, X_3, X_4, X_5, X_6\}, X_6, \text{rhs}),$$

where the right-hand side mapping rhs is defined as follows (we use infix notation for + and \times):

$$rhs(X_{0}) = 1$$

$$rhs(X_{1}) = X_{0} + X_{0}$$

$$rhs(X_{i}) = X_{i-1} \times X_{i-1} \text{ for } 2 \le i \le 4$$

$$rhs(X_{5}) = X_{2} + X_{0}$$

$$rhs(X_{6}) = X_{5} + X_{4}$$

We obtain

$$\begin{aligned} \operatorname{val}_{\mathscr{C}}(X_0) &= 1, \quad \operatorname{val}_{\mathscr{C}}(X_1) = 2, \quad \operatorname{val}_{\mathscr{C}}(X_2) = 4, \quad \operatorname{val}_{\mathscr{C}}(X_3) = 16, \\ \operatorname{val}_{\mathscr{C}}(X_4) &= 256, \quad \operatorname{val}_{\mathscr{C}}(X_5) = 5, \quad \operatorname{val}_{\mathscr{C}}(X_6) = 261 \end{aligned}$$

and hence $val(\mathscr{C}) = 261$. The circuit \mathscr{C} is in normal form, and has size 19. The graph of \mathscr{C} is shown in Figure 1.1.

1.3.6 Some Important Computational Problems

In this section, we present some important algorithmic problems. In particular, we present complete problems for the complexity classes **L**, **NL**, **P**, **NP**, and **PSPACE**.

Example 1.38 (graph accessibility). The following problem is known as the *graph accessibility problem*:

input: A directed graph *G*, and two nodes *s* and *t*. *question:* Is there a directed path from *s* to *t* in *G*?

The graph accessibility problem belongs to **NL**, and is actually **NL**-complete. The *undirected graph accessibility problem* is the following restriction of the graph accessibility problem:

input: An undirected graph *G*, and two nodes *s* and *t*. *question:* Is there a path from *s* to *t* in *G*.

The undirected graph accessibility problem belongs to **L**. This is a very difficult result which was proved in 2004 bei Reingold [146]. Actually, the undirected graph accessibility problem is **L**-complete. In order to make this statement nontrivial, one has to work with a stronger reducibility than logspace-reducibility (so called DLOGTIME-reducibility).

Example 1.39 (PRIMES). The following problem PRIMES belongs to **P**.

input: A word $w \in \{0, 1\}^*$.

question: Is w the binary representation of a prime number?

This was shown in 2004 by Agrawal, Kayal, and Saxena [4]. Note that is easy to test whether for an input word $w = 0^n$ (unary representation of *n*), *n* is a prime number. This latter problem actually belongs to **L**. It is not known, whether PRIMES is **P**-complete.

Example 1.40 (circuit value problem). A *boolean circuit* is a \mathscr{B} -circuit (in the sense of Definition 1.32), where $\mathscr{B} = (\{0,1\}, \land, \lor, \neg, 0, 1)$ is the boolean algebra (\land denotes the binary boolean AND-function, \lor denotes the binary boolean OR-function, and \neg denotes the unary boolean NOT-function). The *circuit value problem* is the following problem:

input: A boolean circuit C.

question: Does the output gate of *C* evaluate to 1.

Ladner proved that the circuit value problem is **P**-complete [101]. Moreover, the *monotone circuit value problem*, which is the restriction of the circuit value problem to monotone boolean circuits (boolean circuits that do not contain the \neg -operator on right-hand sides), is **P**-complete [63] as well.

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Example 1.41 (SAT). A boolean formula is an expression from $\mathscr{E}(\mathscr{B}, V)$ (in the sense of Definition 1.31), where \mathscr{B} is the boolean algebra from the circuit value problem and *V* is a finite set of variables. Such a boolean formula *F* is satisfiable, if the variables from *V* can be replaced by truth values (0 or 1) in such a way that *F* evaluates to 1. SAT is the following problem:

input: A boolean formula *F*. *question:* Is *F* satisfiable?

SAT was shown to be **NP**-complete by Cook [39] and independently by Levin [104]. SAT was actually the first natural problem that was shown to be **NP**-complete.

Example 1.42 (SUBSETSUM). SUBSETSUM is the following problem: *input:* A finite set $W \subseteq \mathbb{N}$ and $t \in \mathbb{N}$, where all numbers are encoded in binary. *question:* Is there a subset $V \subseteq W$ such that $\sum_{w \in V} w = t$? SUBSETSUM is **NP**-complete as well.

Example 1.43 (universality problem for NFAs). The universality problem for nondeterministic finite automata is the following problem:

input: A nondeterministic finite automaton *A* over the alphabet $\{0,1\}$. *question:* Does $L(A) = \{0,1\}^*$ hold, i.e., does *A* accept all input words? This problem was shown to be **PSPACE**-complete in [5].

1.3.7 Randomized Computation

Let *M* be a nondeterministic Turing machine, and let *x* be an input word for *M*. The machine *M* generates a *computation tree* for input *x*. This is a rooted tree, where every node is labeled with a configuration. The root is labeled with the initial configuration init(*x*), and if a node *v* is labeled with a configuration α , then for every configuration β with $\alpha \vdash_M \beta$, *v* has a β -labeled child. Assume now that this computation tree is finite, which means that *M* does not have an infinite computation on input *x*. We may view the computation tree as a stochastic process, where at each node *v* with children v_1, \ldots, v_k one of the nodes v_1, \ldots, v_k is chosen with probability 1/k. We can now compute the probability Prob[M accepts x] that *M* accepts the input *x*. This new viewpoint allows us to define several randomized complexity classes:

Definition 1.44 (RP). A language L belongs to the class **RP** (*randomized polynomial time*) if there exists a nondeterministic polynomial time bounded Turing machine M such that for every input x we have:

- If $x \notin L$ then Prob[*M* accepts x] = 0.
- If $x \in L$ then Prob[*M* accepts x] $\geq 1/2$.

The choice of the probability 1/2 in the second case is not crucial. If the acceptance probability in case $x \in L$ is 1/p(n) (where n = |x| is the input length), i.e., the error probability is 1 - 1/p(n), then by running the algorithm $n \cdot p(n)$ times, we can reduce the error probability to $(1 - 1/p(n))^{n \cdot p(n)}$, which is smaller than $(1/2)^n$ for *n* large enough. It is important here that the different runs of *M* on input *x* are mutually independent.

Note that a language L belongs to the class **coRP** if there exists a nondeterministic polynomial time bounded Turing machine M such that for every input x we have:

- If $x \in L$ then Prob[M accepts x] = 1.
- If $x \notin L$ then Prob[*M* accepts x] $\leq 1/2$.

The class **RP** \cap **coRP** is also called **ZPP** (*zero-error probabilistic polynomial time*). Note that **P** \subseteq **ZPP**.

Definition 1.45 (BPP). A language *L* belongs to the class **BPP** (*bounded error probabilistic polynomial time*) if there exists a nondeterministic polynomial time bounded Turing machine *M* and a constant ε such that for every input *x* we have:

- if $x \notin L$ then Prob $[M \text{ accepts } x] \leq 1/2 \varepsilon$.
- if $x \in L$ then Prob $[M \text{ accepts } x] \ge 1/2 + \varepsilon$.

The constant ε (the probability gap) can be made larger by probability amplification. For this the machine runs several times (say 2k - 1 times) on input *x* and outputs by majority, i.e., the machine accepts if the machine accepts at least *k* times. Chernoff's bound can used for the analysis of this new machine.

Note that $\mathbf{RP} \cup \mathbf{coRP} \subseteq \mathbf{BPP}$. The classes \mathbf{RP} , \mathbf{coRP} , and \mathbf{BPP} are closed under polynomial time many-one reductions: If $L \in \mathbf{RP}$ and $K \leq_m^P L$, then also $K \in \mathbf{RP}$, and similarly for \mathbf{coRP} and \mathbf{BPP} . Since it is not known, whether \mathbf{RP} is closed under complement, it is not clear whether \mathbf{RP} is closed under polynomial time Turing-reductions. But we will need the following:

Lemma 1.46. Let $L \in \mathbb{RP}$ (respectively, coRP) and $K \leq_{bc}^{P} L$. Then also $K \in \mathbb{RP}$ (respectively, $K \in \text{coRP}$).

Proof. Let $K \subseteq \Sigma^*$ and $L \subseteq \Delta^*$. By the definition of \leq_{bc}^P there exist a constant *c* and a polynomial time transducer *T* such that $f_T(\Sigma^*) \subseteq (\#\Delta^*)^c$ and for all $x \in \Sigma^*$ we have: $x \in K$ if and only if $\bigwedge_{i=1}^c y_i \in L$, where $f_T(x) = \#y_1 \# y_2 \cdots \# y_c$.

First, assume that $L \in \mathbf{RP}$. Hence, there exists a nondeterministic polynomial time Turing machine M such that for all $y \in \Delta^*$, (i) if $y \notin L$ then $\operatorname{Prob}[M \text{ accepts } y] = 0$, and (ii) if $y \in L$ then $\operatorname{Prob}[M \text{ accepts } y] \ge 1/2$. Consider the nondeterministic polynomial time Turing machine M' that behaves for all $x \in \Sigma^*$ as follows:

- From *x*, compute in polynomial time the word $f_T(x) = \#y_1 \# y_2 \cdots \# y_c$.
- Run the machine M on each of the input words y_i . These computations must be mutually independent.
- If each of these *c* many computations is accepting, then *M*' accepts *x*, otherwise *M*' rejects *x*.

Let us compute the probability that M' accepts x. Since the computations are mutually independent, we have

$$\operatorname{Prob}[M' \operatorname{accepts} x] = \prod_{i=1}^{c} \operatorname{Prob}[M \operatorname{accepts} y_i]$$
(1.8)

If $x \notin K$, then there exists at least one y_i $(1 \le i \le c)$ such that $y_i \notin L$. Hence, Prob[*M* accepts y_i] = 0, which implies Prob[*M*' accepts x] = 0 with (1.8). If $x \in K$, then $y_i \in L$ for all $1 \le i \le c$. Hence, Prob[*M* accepts y_i] $\ge 1/2$ for all $1 \le i \le c$. Hence, Prob[*M*' accepts x] $\ge (1/2)^c$, which is a constant (since *c* is a constant). Using probability amplification, we can increase this constant to at least 1/2.

Now, assume that $L \in \mathbf{coRP}$. Hence, there exists a nondeterministic polynomial time Turing machine M such that for all $y \in \Delta^*$, (i) if $y \notin L$ then $\operatorname{Prob}[M \operatorname{accepts} y] \leq 1/2$, and (ii) if $y \in L$ then $\operatorname{Prob}[M \operatorname{accepts} y] = 1$. Consider the nondeterministic polynomial time Turing machine M' constructed above and take an input $x \in \Sigma^*$. Let us compute the probability that M' accepts x. If $x \notin K$, then there exists at least one y_i $(1 \leq i \leq c)$ such that $y_i \notin L$. Hence, $\operatorname{Prob}[M \operatorname{accepts} y_i] \leq 1/2$. With (1.8) we get $\operatorname{Prob}[M' \operatorname{accepts} x] \leq 1/2$. On the other hand, if $x \in K$, then $y_i \in L$ for all $1 \leq i \leq c$. Hence, $\operatorname{Prob}[M \operatorname{accepts} y_i] = 1$ for all $1 \leq i \leq c$. This implies that $\operatorname{Prob}[M' \operatorname{accepts} x] = 1$. \Box

There is some evidence in complexity theory for **BPP** = **P** and hence **RP** = **coRP** = **BPP** = **P** Impagliazzo and Wigderson [85] proved that if there exists a language in $DTIME(2^{\mathcal{O}(n)})$ that has circuit complexity $2^{\Omega(n)}$ (which seems to be plausible) then **BPP** = **P**.

An important computational problem in the context of the class **RP** is *polynomial identity testing (PIT)*. For this, we first have to define arithmetic circuits. Recall that for a ring R, $R[x_1, ..., x_n]$ defines the ring of polynomials with coefficients from R and variables $x_1, ..., x_n$. Also recall the definition of general circuits (Definition 1.32).

Definition 1.47 ((univariate, variable-free) arithmetic circuit). An *arithmetic circuit* over the ring *R* is a $(R[x_1, ..., x_n], +, \cdot, 1, -1, x_1, ..., x_n)$ -circuit for some $n \ge 0$. Hence, an arithmetic circuit defines a polynomial from $R[x_1, ..., x_n]$ using the operations of addition and multiplication of polynomials, starting from the polynomials 1, -1, $x_1, ..., x_n$. A *univariate arithmetic circuit* over the ring *R* is a $(R[x], +, \cdot, 1, -1, x)$ -circuit. A *variable-free arithmetic circuit* over the ring *R* is a $(R, +, \cdot, 1, -1)$ -circuit.

The characteristic char(R) of the ring R, i.e., the smallest number m such that

$$\underbrace{1+\cdots+1}_{m \text{ many}}=0.$$

If no such *m* exists then char(R) = 0. Note that for an arithmetic circuit \mathscr{C} over *R*, all coefficients of the polynomial $val(\mathscr{C})$ are from $\mathbb{Z}_{char(R)}$ (the integers modulo char(R)), where we set $\mathbb{Z}_0 = \mathbb{Z}$.

By iterated squaring, one can easily compute in logspace from a binary encoded natural number *m* an arithmetic circuit \mathscr{C} with $val(\mathscr{C}) = x^m$. For instance, the circuit with $rhs(X_i) = X_{i-1}X_{i-1}$ for $1 \le i \le n$, $rhs(X_0) = x$ and start variable X_n defines the polynomial x^{2^n} , and the size of this circuit is n + 1. In the same way one can define a variable-free arithmetic circuit over the ring \mathbb{Z} of size n + 1 that defines the number 2^{2^n} . Note that the binary encoding of this number has 2^n many bits. Due to this, one may allow in arithmetic circuits right-hand sides of the form x^m for a binary encoded natural number *m*.

In the literature, also the term "straight-line program" is used for arithmetic circuits, see e.g. [6, 84, 93]. Here, we reserve the term "straight-line program" for another class of circuits that will be introduced in Section 3.1.

The main computational problem for arithmetic circuits is polynomial identity testing:

Definition 1.48 (polynomial identity testing, PIT(R)). For a ring *R*, the problem PIT(R) (*polynomial identity testing for the ring R*) is the following computational problem:

input: An arithmetic circuit \mathscr{C} over the ring *R question:* Is val(\mathscr{C}) the zero-polynomial?

Note that asking whether val(\mathscr{C}) is the zero-polynomial is not the same as asking whether val(\mathscr{C}) is zero for all assignments of the variables in val(\mathscr{C}): For instance, $x^2 + x \in \mathbb{Z}_2[x]$ is not the zero polynomial but $0^2 + 0 = 1^2 + 1 = 0$ in \mathbb{Z}_2 .

It suffices to consider polynomial identity testing for the rings \mathbb{Z} and \mathbb{Z}_m for $m \ge 2$: By the remark after Definition 1.47, $\mathsf{PIT}(R)$ is equivalent to $\mathsf{PIT}(\mathbb{Z}_{\mathsf{char}(R)})$. The following important result was shown in [84] for the ring \mathbb{Z} and in [3] for the rings \mathbb{Z}_m ($m \ge 2$).

Theorem 1.49. For every ring $R \in \{\mathbb{Z}\} \cup \{\mathbb{Z}_m \mid m \ge 2\}$, $\mathsf{PIT}(R)$ belongs to **coRP**.

Before we prove Theorem 1.49, let us first present a simple reduction from polynomial identity testing to polynomial identity testing for univariate circuits, see [3]:

Proposition 1.50. For every ring *R* there is a polynomial time many-one reduction from polynomial identity testing to univariate polynomial identity testing.

Proof. For a polynomial $p(x_1, ..., x_n) \in R[x_1, ..., x_n]$ and a variable x_i let $deg(p, x_i) \in \mathbb{N}$ be the maximal number d such that $p(x_1, ..., x_n)$ contains a monomial of the form $r \cdot x_1^{d_1} \cdots x_{i-1}^{d_i} x_i^{d_{i+1}} \cdots x_n^{d_n}$. Assume that $d \in \mathbb{N}$ is such that $deg(p, x_i) < d$ for all $1 \le i \le n$. We define the univariate polynomial $univ(p, d) \in R[x]$ as

univ
$$(p,d) = p(x^d, x^{d^2}, ..., x^{d^n}).$$

The mapping $p \mapsto \operatorname{univ}(p,d)$ is injective, satisfies $\operatorname{univ}(p_1 + p_2,d) = \operatorname{univ}(p_1,d) + \operatorname{univ}(p_2,d)$ and $\operatorname{univ}(p_1 \cdot p_2,d) = \operatorname{univ}(p_1,d) \cdot \operatorname{univ}(p_2,d)$, and maps the zero polynomial to the zero polynomial. Hence, p is the zero-polynomial if and only if $\operatorname{univ}(p,d)$ is the zero-polynomial. Moreover, given an arithmetic circuit \mathscr{C} for

 $p(x_1,...,x_n)$, we can compute in polynomial time the binary encoding of a number *d* such that deg $(p,x_i) < d$ for all $1 \le i \le n$. Then we obtain an arithmetic circuit for univ(p,d) by replacing every right-hand side x_i by x^{d^i} . Note that the binary encoding of the number d^i can be computed in polynomial time. \Box

Proof of Theorem 1.49. We prove the theorem only for the ring \mathbb{Z} and \mathbb{Z}_p for p prime. These are acutally the only cases needed in this book. Let us start with $R = \mathbb{Z}$. Let $\mathscr{C} = (V, A_0, \text{rhs})$ be an arithmetic circuit over \mathbb{Z} . By Proposition 1.50 we can assume that \mathscr{C} is univariate. Moreover, we can assume that \mathscr{C} is in normal form. Hence, every right-hand side of \mathscr{C} is either 1, -1, a variable, X + Y, or $X \cdot Y$ for gates X and Y. Let $p(x) = \text{val}(\mathscr{C})$ and let r be the number of gates of \mathscr{C} and k = r + 1. The following facts follows easily by induction on r:

- The degree deg(p(x)) of the polynomial p(x) is at most $2^r = 2^k/2$.
- For every natural number $a \ge 2$ and every integer b with $|b| \le a$ we have $|p(b)| \le a^{2^r}$.

Let us define

$$A = \{1, 2, \dots, 2^k\}.$$

Since a non-zero polynomial of degree *d* over a field *F* has at most *d* different roots (in our case, we can take the field $F = \mathbb{Q}$), we get: If $p(x) \neq 0$, then the probability that p(a) = 0 for a randomly chosen element $a \in A$ is at most 1/2. Hence, to check whether $p(x) \neq 0$, we can guess an element $a \in A$, and check whether $p(a) \neq 0$. But here, another problem arises: The number p(a) can be very large: By the above consideration, we know that $|p(a)| \leq 2^{k2^r}$ for all $a \in A$, but the binary representation of 2^{k2^r} has exponentially many bits.

To solve this problem, we compute $p(a) \mod m$ for randomly chosen numbers m from the set

$$M = \{1, \dots, 2^{2k}\}.$$

Claim 1: Let *b* be an integer with $1 \le |b| \le 2^{k2^k}$. Then the probability that *b* mod $m \ne 0$ for a randomly chosen number $m \in M$ is at least 1/4k if *k* is sufficiently large.

Proof of the Claim 1: By the prime number theorem, the number of primes in the set M goes to $2^{2k}/\ln(2^{2k})$ for $k \to \infty$. Hence, if k is sufficiently large, then there are more than $2^{2k}/2k$ prime numbers in M. On the other hand, if $1 \le |b| \le 2^{k2^k}$, then the number of different prime divisors of b is at most $\log_2(|b|) \le k2^k$. Hence, there are at least $2^{2k}/2k - k2^k$ prime numbers $q \in M$ such that $b \mod q \ne 0$. If k is sufficiently large, then we get

$$\frac{2^{2k}/2k-k2^k}{2^{2k}} = \frac{1}{2k} - \frac{k}{2^k} \ge \frac{1}{2k} - \frac{1}{4k} = \frac{1}{4k}.$$

This proves Claim 1.

Our algorithm works as follows:

• Randomly choose a pair $(a,m) \in A \times M$.

- Compute $p(a) \mod m$. This can be done in polynomial time using the circuit \mathscr{C} for p(x). One simply replaces every gate with right-hand side x by a mod m. Then we evaluate the circuit in the ring \mathbb{Z}_m of integers modulo m. Note that elements of \mathbb{Z}_m can be represented with 2k = 2r + 2 bits. Hence, all additions and multiplications can be done in polynomial time.
- If $p(a) \mod m \neq 0$ then accept, otherwise reject.

If p(x) is the zero polynomial, then this algorithm accepts with probability zero. On the other hand, if p(x) is not the zero polynomial, then the algorithm accepts with probability at least 1/8k (if k = r + 1 is large enough): With probability at least 1/2the algorithm chooses an element $a \in A$ with $p(a) \neq 0$. Note that $p(a) \leq 2^{k2^k}$. For such an $a \in A$, the probability that the chosen element $m \in M$ satisfies $p(a) \mod m \neq$ 0 is at least 1/4k by Claim 1. Finally, the success probability 1/8k in case p(x) is not the zero polynomial can be increased to 1/2 using probability amplification. This concludes the proof for the ring \mathbb{Z} .

Let us now consider the field \mathbb{F}_q for q a prime number. Let $\mathscr{C} = (V, A_0, \text{rhs})$ be an arithmetic circuit over \mathbb{F}_q in normal form and with r gates. Again, we can assume that the polynomial val $(\mathscr{C}) = p(x)$ is univariate. The degree of p(x) is at most 2^r . Consider the infinite field $\mathbb{F}_q(y)$ of all fractions of polynomials from $\mathbb{F}_q[y]$, which contains \mathbb{F}_q . Hence, we can view p(x) as a polynomial with coefficients from $\mathbb{F}_q(y)$. If A is any subset of $\mathbb{F}_q[y] \subseteq \mathbb{F}_q(y)$ with $|A| \ge 2^{r+1}$, then assuming p(x) is not the zero polynomial, the probability that p(a) = 0 for a randomly chosen polynomial $a = a(y) \in A$ is at most 1/2. Let $d \ge 1$ be the smallest number with $q^d \ge 2^{r+1}$ (clearly, $d \le r+1$) and define

$$A = \{a(y) \in \mathbb{F}_q[y] \mid \text{degree}(a(y)) < d\}$$

Note that $|A| = q^d \ge 2^{r+1}$. Similar to the case of characteristic 0, we will compute p(a) (for $a = a(y) \in A$ chosen randomly) modulo a randomly chosen polynomial of small degree. Recall that a polynomial $c_n y^n + c_{n-1} y^{n-1} + \cdots + c_1 y + c_0$ is *monic*, if $c_n = 1$. Let

$$M = \{m(y) \in \mathbb{F}_q[y] \mid m(y) \text{ is monic and degree}(m(y)) = 2(d+r)\}$$

We can assume that $r \ge 1$ and hence $e := d + r \ge 2$. Note that $|M| = q^{2e}$. We need the following claim:

Claim 2: Let $b(y) \in \mathbb{F}_q[y]$ be a polynomial with degree $(b(y)) < 2^e$. Then the probability that $b(y) \mod m(y) \neq 0$ for a randomly chosen polynomial $m(y) \in M$ is at least 1/8e.

Proof of the Claim 2: The number of irreducible polynomials in *M* that divide b(y) can be at most $2^e/2e$, because the product of all these irreducible polynomials has degree at most 2^e and every polynomial in *M* has degree 2e. Since $q, e \ge 2$, we have $2^e/2e \le q^{2e}/8e$. By [17, Eq. 3.37], the set *M* contains more than $q^{2e}(1-q^{1-e})/2e \ge q^{2e}/4e$ irreducible polynomials (note that $q \ge 2$ and $e \ge 2$). Hence, the probability that $b(y) \mod m(y) \ne 0$ for a randomly chosen polynomial $m(y) \in M$ is at least

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$$\frac{q^{2e}/4e - q^{2e}/8e}{|M|} = \frac{q^{2e}/8e}{q^{2e}} = \frac{1}{8e}.$$

This proves Claim 2.

Our probabilistic algorithm for testing whether p(x) is not the zero polynomial is now very similar to the case of characteristic 0:

- Randomly choose a pair $(a(y), m(y)) \times A \times M$.
- Compute *p*(*a*(*y*)) mod *m*(*y*). This can be done in polynomial time by evaluating the circuit *C* in the quotient ring F_q[*y*]/(*m*(*y*)). Every element of this ring can be represented by a polynomial over F_q of degree at most 2(*d*+*r*) − 1 ≤ 4*r* + 1 and can be therefore stored in polynomial space (the prime *q* is a constant in our consideration). Moreover, arithmetic operations in F_q[*y*]/(*m*(*y*)) can be be also performed in polynomial time.
- If $p(a(y)) \mod m(y) \neq 0$ then accept, otherwise reject.

If p(x) is the zero polynomial, then this algorithm accepts with probability zero. On the other hand, if p(x) is not the zero polynomial, then the algorithm accepts with probability at least 1/16(d+r): With probability at least 1/2 the algorithm chooses a polynomial $a(y) \in A$ with $p(a(y)) \neq 0$. Note that the degree of p(a(y)) is at most $d2^r < 2^{d+r}$. For such a polynomial $a(y) \in A$, the probability that the chosen polynomial $m(y) \in M$ satisfies $p(a(y)) \mod m(y) \neq 0$ is at least 1/8(d+r) by Claim 2. Again, the success probability can be amplified to 1/2. This concludes the proof for the ring \mathbb{Z}_q . \Box

Let us remark that usually Theorem 1.49 is proven without a reduction to the univariate case (Proposition 1.50). In this case, one has to apply the so called Schwartz-Zippel-DeMillo-Lipton Lemma [48, 153, 168] for multivariate polynomials. Except for this detail, the above proof follows [84].

Theorem 1.49 and the above mentioned results from [85] imply that if there exists a language in $\mathsf{DTIME}(2^{\mathscr{O}(n)})$ that has circuit complexity $2^{\Omega(n)}$ then polynomial identity testing belongs to **P**. There is also an implication that goes the other way round: Kabanets and Impagliazzo [92] have shown that if polynomial identity testing over the integers belongs to **P**, then one of the following conclusions holds:

- There is a language in NEXPTIME = NTIME $(2^{n^{\mathcal{O}(1)}})$ that does not have polynomial size circuits.
- The permanent is not computable by polynomial size arithmetic circuits.

Both conclusions represent major open problem in complexity theory. Hence, although it is quite plausible that polynomial identity testing belongs to \mathbf{P} (by [85]), it will be probably very hard to prove (by [92]).

We conclude this section with the following result from [6], stating that for the ring \mathbb{Z} , polynomial identity testing is equivalent to the problem, whether a given variable- free circuit evaluates to 0.

Theorem 1.51. *There is a logspace many-one reduction from* $PIT(\mathbb{Z})$ *to the follow-ing problem:*

input: A variable-free arithmetic circuit \mathscr{C} over the ring \mathbb{Z} . question: Is $val(\mathscr{C}) = 0$?

Proof. Let \mathscr{C} be an arithmetic circuit in normal form over \mathbb{Z} , and let $n \ge 1$ be the number of gates of \mathscr{C} . We construct in polynomial time a variable-free arithmetic circuit \mathscr{C}' such that $\operatorname{val}(\mathscr{C}) = 0$ if and only if $\operatorname{val}(\mathscr{C}') = 0$. By Proposition 1.50 we can assume that \mathscr{C} is univariate. Let $\operatorname{val}(\mathscr{C}) = p(x)$ and $a = 2^{2^{2n}} \ge 16$. By iterated squaring, one can easily construct in logspace a variable-free circuit that computes a. By plugging in this circuit into \mathscr{C} , we obtain a variable-free circuit \mathscr{C}' that computes p(a). Clearly, if p(x) = 0 then also p(a) = 0. It remains to show that $p(x) \neq 0$ implies $p(a) \neq 0$. Assume that $p(x) = \alpha x^m + \sum_{i=0}^{m-1} \alpha_i x^i$ with $\alpha \neq 0$. We have $|\alpha_i| \le 2^{2^n}$ for $0 \le i \le m-1$ and $m \le 2^n$. To show that $p(a) \neq 0$ it suffices to show

$$|\sum_{i=0}^{m-1} \alpha_i a^i| < a^m \le |\alpha a^m|.$$
(1.9)

We have

$$|\sum_{i=0}^{m-1} \alpha_i a^i| \le 2^{2^n} \sum_{i=0}^{m-1} a^i = 2^{2^n} \cdot \frac{a^m - 1}{a - 1} \le 2^{2^n} \cdot \frac{2a^m}{a} = a^m \cdot \frac{2^{1 + 2^n}}{a}$$

Hence, (1.9) follows from $a = 2^{2^{2n}} > 2^{1+2^n}$. \Box

1.3.8 The RAM Model of Computation

Efficient algorithms are not the main concern of this work (see the text books [5, 42] for background on efficient alogorithms). When we state that a problem belongs to **P** we do not care about the actual polynomial: $\mathcal{O}(n)$ is as good as $\mathcal{O}(n^{100})$. Nevertheless, we make occasionally more exact statements on the running time of algorithms. In these statements we implicitly assume a more powerful computational model than Turing machines. Time $\mathcal{O}(n)$ on a Turing machine with a single work tape is very restrictive. A more realistic model that is much closer to a real computer is the *random access machine*, briefly *RAM*.

A RAM has registers r_0, r_1, \ldots that store integers of arbitrary size. The input is a tuple of (i_1, \ldots, i_l) of integers. There are elementary instructions (that all need constant time) for the following tasks:

- loading input values into registers,
- doing arithmetic operations (addition, subtraction, multiplication) on register contents,
- doing bitwise AND and OR on register contents,
- conditional jumps (if the content of a certain register is 0 then jump to the *k*-th instruction, otherwise proceed with the next instruction),

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- indirect addressing (copy the content of register r_c into register r_i , where c is the content of register r_j . Here i and j are the arguments of the instruction.

A problem with this model is that one may produce with a sequence of n + 1 instructions numbers of size 2^{2^n} (which need 2^n bits): $r_0 := 2$; $r_0 := r_0 \cdot r_0$; ... $r_0 := r_0 \cdot r_0$; where we do *n* multiplications. In particular, one can evaluate a variable-free arithmetic circuit in linear time. On the other hand, in all our examples the bit length of all registers will be linearly bounded in the input length, which for an input tuple (i_1, \ldots, i_l) can be defined as $\sum_{j=1}^l \log |i_j|$. Under this restriction, a RAM can be easily simulated on a Turing machine with only a polynomial blow-up.
Chapter 2 Preliminaries from Combinatorial Group Theory

In this chapter, we recall basic definitions from combinatorial group theory. We assume some basic knowledge of group theory, see for instance [149]. More back-ground on combinatorial group theory can be found in [119, 159]. Groups will be written multiplicatively throughout this work and the group identity will be denoted with 1.

2.1 Free Groups

For an alphabet Γ let $\Gamma^{-1} = \{a^{-1} \mid a \in \Gamma\}$ be a disjoint copy of the alphabet Γ . We define $(a^{-1})^{-1} = a$, and for a word $w = a_1 a_2 \cdots a_n$ with $n \ge 0$ and $a_1, a_2, \dots, a_n \in \Gamma \cup \Gamma^{-1}$ we define $(a_1 a_2 \cdots a_n)^{-1} = a_n^{-1} \cdots a_2^{-1} a_1^{-1}$; this defines an involution on $(\Gamma \cup \Gamma^{-1})^*$. We define the semi-Thue system

$$R_{\Gamma} = \{ (aa^{-1}, \varepsilon) \mid a \in \Gamma \cup \Gamma^{-1} \}.$$

$$(2.1)$$

This system is clearly Noetherian and also locally confluent and hence confluent. The latter can be checked by considering overlapping left-hand sides. The only possible overlapping of two left-hand sides is $aa^{-1}a$ for $a \in \Gamma \cup \Gamma^{-1}$. But regardless whether we replace aa^{-1} or $a^{-1}a$ by ε , we obtain from $aa^{-1}a$ the word a. This shows local confluence.

Definition 2.1. The *free group generated by* Γ is the quotient monoid

$$F(\Gamma) = (\Gamma \cup \Gamma^{-1})^* / R_{\Gamma}.$$

Hence, we obtain $F(\Gamma)$ by taking the set $IRR(R_{\Gamma})$ of words that do not contain a factor of the form aa^{-1} for $a \in \Gamma \cup \Gamma^{-1}$. We simply call these words *irreducible* in the following. If *u* and *v* are irreducible words, then the product of *u* and *v* in the free group is the unique irreducible word that is obtained from the concatenation *uv* by cancelling factors of the form aa^{-1} for $a \in \Gamma \cup \Gamma^{-1}$ as long as possible.

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Clearly, the identity element of $F(\Gamma)$ is the empty word ε and the inverse of the irreducible word w is w^{-1} . For $w \in (\Gamma \cup \Gamma^{-1})^*$ we denote the unique irreducible word NF_{*R*_Γ}(*w*) with NF(*w*). The word NF(*w*) is obtained from *w* by cancelling factors of the form aa^{-1} for $a \in \Gamma \cup \Gamma^{-1}$ as long as possible in any order. For example, we have NF($a^{-1}aa^{-1}bb^{-1}b$) = $a^{-1}b$.

2.2 Finitely Generated Groups and Finitely Presented Groups

Definition 2.2 (finitely generated group). A group *G* is *finitely generated*, if there exists a finite set $A \subseteq G$ such that every $g \in G$ can be written as a product $a_1a_2 \cdots a_n$ with $a_1, a_2, \ldots, a_n \in A \cup A^{-1}$. The set *A* is also called a *finite generating set* for *G*.

Equivalently, *G* is finitely generated, if there exists a finite set Γ and a surjective group homomorphism $h: F(\Gamma) \to G$.

For a subset $B \subseteq G$ we denote with $\langle B \rangle$ the subgroup of *G* generated by *B*, it contains all products $b_1b_2 \cdots b_n$ with $b_1, b_2, \ldots, b_n \in B \cup B^{-1}$. The *normal closure* of $B \subseteq G$, denoted by $\langle B \rangle^G$ is the subgroup generated by all conjugates of elements from *B*, i.e.,

$$\langle B
angle^G = \langle \{ g b g^{-1} \mid g \in G, b \in B \}
angle.$$

Following common notation, the quotient group $G/\langle B \rangle^G$ is also denoted with $\langle G | B \rangle$.

Definition 2.3 (presentation of a group, relator, finitely presented group). For a set Γ and $R \subseteq F(\Gamma)$ we write $\langle \Gamma | R \rangle$ for the group $\langle F(\Gamma) | R \rangle$. The set R is called a set of *relators* of the group $\langle \Gamma | R \rangle$ and the pair (Γ, R) is a *presentation* of the group $\langle G | R \rangle$. Here, Γ and R can be infinite. If $\Gamma = \{a_1, \ldots, a_n\}$ and $R = \{r_1, \ldots, r_m\}$ are finite we also write $\langle a_1, \ldots, a_n | r_1, \ldots, r_m \rangle$ for $\langle \Gamma | R \rangle$. If G is finitely generated by $\{a_1, \ldots, a_n\}$ then G can be written in the form $\langle a_1, \ldots, a_n | R \rangle$ for a set $R \subseteq F(\Gamma)$, which in general is infinite. A group G is *finitely presented* if G is isomorphic to a group $\langle a_1, \ldots, a_n | r_1, \ldots, r_m \rangle$.

Example 2.4. Consider the presentation $(\{a, b\}, \{[a, b], a^4, b^2\})$. Here,

$$[a,b] = aba^{-1}b^{-1}$$

is the *commutator* of *a* and *b*. The relator [a,b] specifies that *a* and *b* commute. Moreover, *a* (resp., *b*) generates a copy of the cyclic group \mathbb{Z}_4 (resp., \mathbb{Z}_2). Hence, we have $\langle a, b, | [a,b], a^4, b^2 \rangle \cong \mathbb{Z}_4 \times \mathbb{Z}_2$.

Let us introduce some important classes of finitely presented groups that will reoccur later.

Example 2.5 (graph groups). Let (A, I) be a finite undirected graph, where $I \subseteq A \times A$ is the irreflexive and symmetric edge relation. With (A, I) we associate the *graph group*

2.2 Finitely Generated Groups and Finitely Presented Groups

$$G(A,I) = \langle A \mid [a,b] \text{ for } (a,b) \in I \rangle$$

In other words: Two generators are allowed to commute if and only if they are adjacent in the graph. Graph groups are also known as *right-angled Artin groups* or *free partially commutative groups*. For a survey on graph groups see [32].

Example 2.6 (Coxeter groups). Let $M = (m_{i,j})_{1 \le i,j \le n}$ be a symmetric $(n \times n)$ -matrix over \mathbb{N} such that $m_{i,j} = 1$ if and only if i = j. The corresponding *Coxeter group* is

$$C(M) = \langle a_1, \ldots, a_n \mid (a_i a_j)^{m_{i,j}} \text{ for } 1 \leq i, j \leq n \rangle.$$

In particular, $a_i^2 = 1$ in C(M) for $1 \le i \le n$. Traditionally, one writes the entry ∞ instead 0 in the *Coxeter matrix M* and then $m_{i,j}$ becomes the order of the element $a_i a_j$. If $m_{i,j} \in \{0, 1, 2\}$ for all $1 \le i, j \le n$, then C(M) is called a *right-angled Coxeter group*. In this case we can define C(M) also as $\langle G(A,I) | a_i^2$ for $1 \le i \le n \rangle$, where (A,I) is the graph with $A = \{a_1, \ldots, a_n\}$ and $(a_i, a_j) \in I$ if and only if $m_{i,j} = 2$. The book [20] provides a detailed introduction into Coxeter groups.

Example 2.7 (automatic groups). To define automatic groups, let us first define the convolution of words. For an alphabet *A* and two words $u = a_1a_2 \cdots a_m$ and $v = b_1b_2 \cdots b_n$ (with $a_1, \ldots, a_m, b_1, \ldots, b_n \in A$) the *convolution* $u \otimes v$ is the following word over the alphabet $(A \cup \{\#\}) \times (A \cup \{\#\}) \setminus \{(\#, \#)\}$, where $\# \notin A, k = \max\{m, n\}$, $a_i = \#$ for $m < i \le k$, and $b_i = \#$ for $n < i \le k$:

$$u \otimes v = (a_1, b_1)(a_2, b_2) \cdots (a_k, b_k).$$

For a finitely generated group *G*, an *automatic structure* for *G* consists of a triple $(\Gamma, A, (A_a)_{a \in \Gamma \cup \{1\}})$, where Γ is a finite generating set for *G*, *A* is a finite automaton over $\Gamma \cup \Gamma^{-1}$ such that the canonical homomorphism $h : F(\Gamma) \to G$ is surjective on L(A) (where L(A) is viewed as a subset of $F(\Gamma)$), and for every $a \in \Gamma \cup \{1\}, A_a$ is a finite automaton over the alphabet $(\Gamma \cup \Gamma^{-1} \cup \{\#\}) \times (\Gamma \cup \Gamma^{-1} \cup \{\#\}) \setminus \{(\#, \#)\}$ such that for all $u, v \in L(A), u \otimes v \in L(A_a)$ if and only if h(ua) = h(v). Then, a group *G* is *automatic* if it has an automatic structure. The book [57] provides a detailed introduction into automatic groups. Every automatic group is finitely presented. Graph groups as well as Coxeter groups are automatic, see [75] and [24, 30], respectively.

Sometimes, we will write an identity u = v instead of the relator uv^{-1} in a group presentation. For instance, the graph group $G(A, I) = \langle A \mid [a, b]$ for $(a, b) \in I \rangle$ could be also written as $\langle A \mid ab = ba$ for $(a, b) \in I \rangle$. Moreover, for words $u, v \in (\Gamma \cup \Gamma^{-1})^*$ we say that "u = v in $\langle \Gamma \mid R \rangle$ if $uv^{-1} \in \langle R \rangle^{F(\Gamma)}$. This means that u and v represent the same group element of $\langle \Gamma \mid R \rangle$.

We can also obtain the group $\langle \Gamma | R \rangle$ as a quotient monoid by taking the semi-Thue system $S = R_{\Gamma} \cup \{(r, \varepsilon) | r \in R \cup R^{-1}\}$, where R_{Γ} was defined in (2.1). Then

$$\langle \Gamma \mid R \rangle \cong (\Gamma \cup \Gamma^{-1})^* / S.$$

Clearly, every group *G* can be written in the form $\langle \Gamma | R \rangle$. Simply take $\Gamma = G$ and *R* as the kernel of the canonical homomorphism $h : F(G) \to G$. The notation $\langle \Gamma | R \rangle$ allows to define the free product of two groups in the following way:

Definition 2.8 (free product). Let $G_1 = \langle \Gamma_1 | R_1 \rangle$ and $G_1 = \langle \Gamma_2 | R_2 \rangle$ be groups with $\Gamma_1 \cap \Gamma_2 = \emptyset$. Then the *free product* $G_1 * G_2$ is $\langle \Gamma_1 \cup \Gamma_2 | R_1 \cup R_2 \rangle$.

One can think about the free product $G_1 * G_2$ (where we assume $G_1 \cap G_2 = \{1\}$) as the set of all alternating sequences $g_1g_2...g_n$, where every g_i belongs to either $G_1 \setminus \{1\}$ or $G_2 \setminus \{1\}$, and $g_i \in G_1 \setminus \{1\}$ if and only if $g_{i+1} \in G_2 \setminus \{1\}$ for all $1 \le i \le n-1$. The product of two such sequences is computed in the natural way by multiplying elements from the same group (G_1 or G_2) as long as possible. Formally, let $g = g_1g_2\cdots g_m$ and $h = h_1h_2\cdots h_n$ be alternating sequences as described above. If m = 0, then gh = h and if n = 0, then gh = g. Now, assume that n, m > 0. If g_m and h_1 are from different groups, i.e., $g_m \in G_1 \setminus \{1\}$ if and only if $h_1 \in G_2 \setminus \{1\}$, then gh is the alternating sequence $g_1g_2\cdots g_mh_1h_2\cdots h_n$. Finally, assume that g_m and h_1 are from the same group. Let k be the maximal index $0 \le k \le \min\{n,m\}$ such that for all $1 \le i \le k$, $g_{m-i+1} = h_i^{-1}$. If k = m, then $gh = h_{i+1}\cdots h_n$, and if k = n, then $gh = g_1\cdots g_{m-k}$ (this includes the case k = m = n with gh = 1). Finally, if $k < \min\{m, n\}$, then $gh = g_1\cdots g_{m-k-1}(g_{m-k}h_{i+1})h_{i+2}\cdots h_n$.

If *G* is a group, and *R* is a subset of $G * F(\Gamma)$, then we write $\langle G, \Gamma | R \rangle$ (or $\langle G, a_1, \ldots, a_n | R \rangle$ if $\Gamma = \{a_1, \ldots, a_n\}$) for the group $\langle G * F(\Gamma) | R \rangle$.

2.3 Tietze Transformations

Already in 1908, Tietze came up with a semi-decision procedure for checking whether two group presentations yield isomorphic groups [161]. His procedure consists of four elementary transformation steps:

Definition 2.9 (Tietze transformations). Let (Γ, R) be a finite presentation of a group.

- If r ∈ ⟨R⟩^{F(Γ)}, then we say that the presentation (Γ, R ∪ {r}) is obtained from a *Tietze-type-1 transformation* from (Γ, R). Intuitively, we add a redundant relator to the presentation.
- If $r \in R$ is such that $r \in \langle R \setminus \{r\} \rangle^{F(\Gamma)}$, then we say that the presentation $(\Gamma, R \setminus \{r\})$ is obtained from a *Tietze-type-2 transformation* from (Γ, R) . Intuitively, we remove a redundant relator from the presentation.
- If $a \notin \Gamma \cup \Gamma^{-1}$ and $w \in (\Gamma \cup \Gamma^{-1})^*$, then we say that the presentation $(\Gamma \cup \{a\}, R \cup \{a^{-1}w\})$ is obtained from a *Tietze-type-3 transformation* from (Γ, R) . Intuitively, we add a redundant generator to the presentation. Note that the new relator $a^{-1}w$ defines the new generator *a* as *w* (a word over the old generators).
- If a ∈ Γ and w ∈ ((Γ ∪ Γ⁻¹) \ {a,a⁻¹})* such that a⁻¹w ∈ R, then we say that the presentation (Γ \ {a}, φ(R)) is obtained from a *Tietze-type-4 transformation* from (Γ, R). Here, φ is the homomorphism with φ(a) = w, φ(a⁻¹) = w⁻¹ and

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 $\varphi(c) = c$ for $c \in (\Gamma \cup \Gamma^{-1}) \setminus \{a, a^{-1}\}$. Intuitively, a = w holds in the group $\langle \Gamma \mid R \rangle$, hence *a* is redundant an can be removed from the presentation.

Any of the above four transformations is called a Tietze transformation.

It is not hard to see that if the finite group presentation (Σ, S) is obtained by a finite sequence of Tietze transformations from (Γ, R) , then $\langle \Gamma | R \rangle \cong \langle \Sigma | S \rangle$. Tietze [161] proved that also the converse holds:

Theorem 2.10. Let (Γ, R) and (Σ, S) be finite group presentations. Then $\langle \Gamma | R \rangle \cong \langle \Sigma | S \rangle$ if and only if (Σ, S) can be obtained by a finite sequence of Tietze transformations from (Γ, R) .

This result implies that the isomorphism problem for finitely generated groups (i.e., the question, whether two given finite group presentations yield isomorphic groups) is computably enumerable. We will use Tietze transformations in Chapter 6.

Example 2.11. Consider the group $\langle a, b \mid [a,b], a^3, b^2 \rangle \cong \mathbb{Z}_3 \times \mathbb{Z}_2 \cong \mathbb{Z}_6 \cong \langle c \mid c^6 \rangle$. Hence, we should be able to derive the presentation ($\{c\}, \{c^6\}$) from the presentation ($\{a,b\}, \{[a,b], a^3, b^2\}$) using Tietze transformations. Here is a derivation:

- 1. A Tietze-type-3 transformation allows to go from $(\{a,b\},\{[a,b],a^3,b^2\})$ to $(\{a,b,c\},\{[a,b],a^3,b^2,c^{-1}ab\})$. In the following, we only list the current set of relators. Moreover, we write the relators $[a,b],a^3,b^2,c^{-1}ab$ in the more readable form $ab = ba, a^3 = 1, b^2 = 1, c = ab$.
- 2. Using a Tietze-type-1 transformation (adding the consequence c = ba) followed by a Tietze-type-2 transformation (removing the redundant relator ab = ba), we get c = ba, $a^3 = 1$, $b^2 = 1$, c = ab
- 3. The relator c = ab can be written as $a = cb^{-1}$. This allows to eliminate the generator *a* with a Tietze-type-4 transformation. We get $c = bcb^{-1}$, $(cb^{-1})^3 = 1$, $b^2 = 1$.
- 4. Since $b = b^{-1}$ follows from $b^2 = 1$, we get c = bcb, $(cb)^3 = 1$, $b^2 = 1$ using a Tietze-type-1 and Tietze-type-2 transformations.
- 5. Next, cbcbcb = 1 can be replaced by $c^3b = 1$ (since bcb = c). We now have c = bcb, $c^3b = 1$, $b^2 = 1$, or equivalently, c = bcb, $c^3 = b$, $b^2 = 1$.
- 6. A Tietze-type-4 transformation (eliminating *b*) yields $c = c^7$, $c^3 = 1$.
- 7. Finally, a Tietze-type-2 transformation allows to remove the relator $c = c^7$, and we arrive at the presentation ({c}, { c^6 }).

2.4 The Word Problem

Now that we have defined basic concepts from combinatorial group theory and complexity theory, it is time to introduce the word problem, which is the fundamental computational problem in combinatorial group theory. Basically, the word problem for a finitely generated group G asks whether a given word over the generators of Gand their inverses represents the group identity. Here is the formal definition: **Definition 2.12.** Let *G* be a finitely generated group with a finite generating set Γ ; hence *G* is isomorphic to $\langle \Gamma | R \rangle$ for a set of relators $R \subseteq (\Gamma \cup \Gamma^{-1})^*$. The *word problem for G with respect to* Γ , briefly WP(*G*, Γ) is the following problem: *input:* A word $w \in (\Gamma \cup \Gamma^{-1})$

question: Does w = 1 hold in *G* (i.e., does *w* belong to $\langle R \rangle^{F(\Gamma)}$)?

In the way we defined it, the word problem depends on the chosen generating set for G. But if we are only interested in the decidability/complexity of word problems, the actual generating set is not relevant:

Lemma 2.13. Let G be a finitely generated group and let Γ and Σ be two finite generating sets. Then $WP(G,\Gamma) \leq_m^{\log} WP(G,\Sigma)$.

Proof. Let $G \cong \langle \Gamma | R \rangle \cong \langle \Sigma | S \rangle$. There exists a homomorphism $h : (\Gamma \cup \Gamma^{-1})^* \to (\Sigma \cup \Sigma^{-1})^*$ with $h(a^{-1}) = h(a)^{-1}$ for all $a \in \Gamma \cup \Gamma^{-1}$ that induces an isomorphism from $\langle \Gamma | R \rangle$ to $\langle \Sigma | S \rangle$. Hence, for a word $w \in (\Gamma \cup \Gamma^{-1})^*$ we have w = 1 in $\langle \Gamma | R \rangle$ if and only if h(w) = 1 in $\langle \Sigma | S \rangle$. The lemma follows, since the homomorphism h can be computed with a logspace transducer, see Example 1.25. \Box

Because of Lemma 2.13, it is justified to just speak of the word problem for G, briefly WP(G). It is not difficult to come up with a finitely generated group with an undecidable word problem. For finitely presented groups, this is a much harder problem that was finally solved by Novikov [136] and independently by Boone [22] in the 1950's:

Theorem 2.14. *There is a finitely presented group with an undecidable word problem.*

A modern treatment of this result can be found [159]. In this context, we should also mention the following celebrated result by Higman that is known as Higman's embedding theorem [77]:

Theorem 2.15. Let G be a finitely generated group. Then G has a computably enumerable word problem if and only if G can be embedded into a finitely presented group.

An algebraic characterization of groups with a computable word problem exists as well; it goes back to Boone and Higman [23]:

Theorem 2.16. *Let G be a finitely generated group. Then G has a computable word problem if and only if G can be embedded into a simple subgroup of a finitely presented group.*

In this book, we are only interested in groups with a computable word problem. The class of groups with a computable word problem contains many important group classes. Finitely presented groups with undecidable word problem are somehow exotic. The relators of such a group encode the transition relation of a Turing machine with an undecidable halting problem.

If a group G has a computable word problem, the next question adresses the complexity of the word problem. Actually, for many classes of groups, the word problem can be solved in polynomial time. Here are some examples:

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- word hyperbolic groups [68]: Dehn's algorithm (see [119, Chapter V.4]) solves the word problem for these groups in linear time. Actually, the word problem for a hyperbolic group can be solved in real time (i.e., the time bound is the length of the input word) on a Turing machine with several work tapes [81]. In [25], it was shown that the word problem for a hyperbolic group belongs to the circuit complexity class NC². In [111] this upper bound was slightly improved to LogCFL, which is the class of all languages that are logspace many-one reducible to a context-free language. Actually, the argument in [111] shows that every group having a Cannon's algorithm (a generalization of Dehn's algorithm) [64] has a word problem in LogCFL. Besides word hyperbolic groups, every finitely generated nilpotent group has a Cannon's algorithm [64].
- graph groups, see Example 2.5: By [49, 167] the word problem for a graph group can be solved in linear time on a RAM.
- automatic groups, see Example 2.7: The word problem can be solved in quadratic time on a Turing machine.

Concerning space complexity, there is actually a big class of groups, where the word problem can be even solved in logarithmic space.

Definition 2.17. A group *G* is *linear*, if there exist a field *F* and a dimension *d* such that *G* embeds into the *general linear group* $GL_d(F)$ (the group of all invertible $(d \times d)$ -matrices over the field *F*).

The following result is shown in [108] for a field F of characteristic 0 and in [156] for a field of prime characteristic:

Theorem 2.18. *Let G be a finitely generated linear group. Then the word problem for G belongs to* **L***.*

The proof of Theorem 2.18 makes essential use of the following result, which we will use in Section 4.5. Implicitly it appears in [108] for the case of a field of characteristic 0, see also [156]. Recall that for a field F, $F(x_1, \ldots, x_m)$ denotes the field of all fractions of polynomials from $F[x_1, \ldots, x_m]$.

Theorem 2.19. Let G be a finitely generated linear group over a field F and let P be the prime field of F (which is either \mathbb{Q} if F has characteristic 0 or \mathbb{F}_p if F has prime characteristic p). Then, G is isomorphic to a group of matrices over the field $P(x_1, \ldots, x_m)$.

Proof. The proof uses a bit of field theory. Let *G* be a finitely generated subgroup of $GL_n(F)$. Hence, there exists a finite subset $A \subseteq F$ such that every matrix entry from a generator of *G* belongs to *A*. We can therefore replace the field *F* by the subfield *K* generated by *A*. If we choose a maximal algebraically independent subset $\{x_1, \ldots, x_m\} \subseteq A$, then *K* becomes isomorphic to a finite algebraic extension of a field of fractions $P(x_1, \ldots, x_m)$, where *P* is the prime field of *F*, see e.g. [86, p. 156]. Let $[K : P(x_1, \ldots, x_m)] = d$ be the degree of this algebraic extension. The field *K* can be also seen as a *d*-dimensional associative algebra over the base field

 $P(x_1, \ldots, x_m)$ (i.e., a *d*-dimensional vector space over $P(x_1, \ldots, x_m)$ with a multiplication that together with the vector addition yields a ring structure). By the regular representation for associative algebras [87], *K* is isomorphic to a subring of the ring $M_d(P(x_1, \ldots, x_m))$ of $(d \times d)$ -matrices over $P(x_1, \ldots, x_m)$. Since *K* is a field, every non-zero element of *K* is thereby represented by a matrix from $GL_d(P(x_1, \ldots, x_m))$. Hence, by replacing in the generator matrices of *G* every matrix entry by a $(d \times d)$ -matrix over $P(x_1, \ldots, x_m)$, it follows that *G* is isomorphic to a finitely generated subgroup of $GL_{nd}(P(x_1, \ldots, x_m))$. \Box

Let us briefly sketch, how Theorem 2.18 for characteristic 0 can be deduced from Theorem 2.19. By Theorem 2.19 it remains to show that an identity $A_1A_2 \cdots A_n = Id_k$ can be tested in logspace, where $A_1, A_2, \ldots A_n$ are from a fixed set of $(k \times k)$ matrices over $\mathbb{Q}(x_1, \ldots, x_m)$. This identity can be reduced to an identity $B_1 B_2 \cdots B_n =$ $C_1C_2\cdots C_n$, where $B_1, C_1, \ldots, B_n, C_n$ are from a fixed set of $(k \times k)$ -matrices over $\mathbb{Z}[x_1,\ldots,x_m]$. Let d be the maximal degree of a polynomial in this set. Hence, in the product matrices $B_1B_2\cdots B_n$ and $C_1C_2\cdots C_n$ every polynomial has degree at most dn. It follows that $B_1B_2\cdots B_n = C_1C_2\cdots C_n$ if and only if for every mtuple $\overline{a} \in \{0, \dots, dn\}^m$ we have $B_1(\overline{a})B_2(\overline{a})\cdots B_n(\overline{a}) = C_1(\overline{a})C_2(\overline{a})\cdots C_n(\overline{a})$ (we denote with $B_i(\overline{a})$ the integer matrix obtained by replacing every polynomial entry $p(x_1,\ldots,x_m)$ of B_i by $p(\overline{a})$ and similarly for the matrices C_i . Since m is a constant in our consideration, we can consider every tuple $\overline{a} \in \{0, \dots, dn\}^m$ one after the other and thereby reuse the space needed for the previous tuple. Hence, it remains to verify in logspace an identity $B_1B_2 \cdots B_n = C_1C_2 \cdots C_n$, where $B_1, C_1, \dots, B_n, C_n$ are $(k \times k)$ -matrices over \mathbb{Z} with entries bounded in absolute value by $n^{\mathcal{O}(1)}$. One can easily show that every entry in the product matrices $B_1B_2\cdots B_n$ and $C_1C_2\cdots C_n$ has size $n^{\mathcal{O}(n)}$. Using the Chinese remainder theorem, it suffices to the verify the identity modulo the first ℓ prime numbers, where $\ell \in n^{\mathcal{O}(1)}$. Actually, we can check the identity modulo all numbers 2,..., p, where p is the ℓ -th prime number. Note that p has only $\mathcal{O}(\log n)$ many bits. Hence, all computations can be done in logspace.

Examples of finitely generated linear groups are: finitely generated polycyclic groups, Coxeter groups, braid groups, and graph groups. Hence, for all these groups the word problem can be solved in logspace.

Finitely generated *metabelian group* (a group *G* is metabelian if it is has a normal abelian subgroup *A* such that the quotient *G*/*A* is abelian too) can be embedded into finite direct products of linear groups [165]. Hence, also for finitely generated metabelian groups the word problem can be solved in logspace. An interesting class of groups, for which in general no efficient algorithm for the word problem is known, is the class of *one-relator groups*, i.e., groups of the form $\langle \Gamma | r \rangle$ for $r \in (\Gamma \cup \Gamma^{-1})^*$. By a famous result of Mangus [121] every one-relator group has a computable word problem, which moreover is primitive recursive [10, 29]. No better general complexity bound is known. On the other hand, no example of a onerelator group with a provably hard word problem is known. Let us also mention that by recent results of Wise [166], every one relator group with torsion is linear, and hence has a logspace word problem by Theorem 2.18.

By adapting the Novikov-Boone construction, Cannonito and Gatterdam proved that for every $n \ge 0$, there is a finitely presented group G such that (i) WP(G) is



Fig. 2.1 The starting point for folding

computable but (ii) not within the *n*-th level of the Grzegorczyk hierarchy [27]. Recently, it was even shown that for every computable set *A* there is a finitely presented *residually-finite group G* (recall that *G* is residually-finite if for every $g \in G \setminus 1$ there exists a homomorphism $h : G \to H$ with *H* finite and $h(g) \neq 1$) such that WP(*G*) is at least as hard as *A* [97]. McKinsey [126] has shown that every finitely presented residually-finite group has a computable word problem.

2.5 The Dehn Function and the Word Search Problem

In this section, we will introduce the Dehn function of a group, whose growth is an important geometric invariant of a finitely presented group. A beautiful survey on Dehn functions can be found in [147]. Finally, we will briefly discuss the word search problem for a finitely presented group. This is an extension of the word problem, where we not only ask whether a given word *w* represents the identity 1, but, in the positive case, also want to compute a witness (in form of a van Kampen diagram) for the fact that w = 1.

Assume that we have a finitely presented group $G = \langle \Gamma | R \rangle$ where $R \subseteq (\Gamma \cup \Gamma^{-1})^+$ is a finite set of cyclically reduced words of length at least 2 (an irreducible word *w* is cyclically reduced if *w* is of the form *avb* for $b \neq a^{-1}$). We also say that the finite presentation (Γ, R) is *reduced*, and it is easy to see that a given finite presentation for *G* can be transformed (in polynomial time) into a reduced finite presentation for *G*. If an irreducible word $w \in (\Gamma \cup \Gamma^{-1})^*$ represents the identity of *G*, then in the free group $F(\Gamma)$, *w* belongs to the normal subgroup $\langle R \rangle^{F(\Gamma)}$. Hence, in $F(\Gamma)$ we can write *w* as a product $\prod_{i=1}^{\ell} c_i r_i c_i^{-1}$ with $c_i \in (\Gamma \cup \Gamma^{-1})^*$ irreducible and $r_i \in R \cup R^{-1}$. The smallest number ℓ for which we can write *w* as such a product is also called the *area* of *w* (with respect to the presentation (Γ, R)). The choice of the term "area" can be explained as follows: Given the word $\prod_{i=1}^{\ell} c_i r_i c_i^{-1}$ one obtains a planar diagram as follows: Start with a (planar) bouquet as shown in Figure 2.1. Here, the c_i -labeled edge stands for a path of $(\Gamma \cup \Gamma^{-1})$ -labeled loop. Moreover, for every *a*-labeled edge there is a reversed a^{-1} -labeled edge. If we walk along the

boundary of this bouquet in clockwise orientation, starting in the base point 1 (this is the so called boundary cycle), then we read exactly the word $\prod_{i=1}^{\ell} c_i r_i c_i^{-1}$. The reduction of this word using the rewriting system R_{Γ} for the free group $F(\Gamma)$ (see (2.1)) yields the irreducible word w. This reduction process on words translates into a folding process on planar digrams. As long as the boundary cycle contains two successive edges e and f, such that the label of f is the inverse of the label of e, then we fold these two edges into one edge and thereby identify the initial vertex of e with the target vertex of f. In case the initial vertex of e is already equal to the target vertex of f (this situation can arise for instance, when folding the bouquet for rr^{-1} for a relator r), then e and f enclose a region, and we remove this whole region including all edges and nodes within the region. This is a confluent process, i.e., the completely folded planar diagram obtained this way does not depend from the chosen order of folding steps. Moreover, the boundary cycle of the completely folded planar diagram is labeled with the word w. Such a diagram is called a van Kampen diagram for w and its area is the number of cells (closed regions) [119]. Hence, the area of an irreducible word w with w = 1 in G is the minimal area of a van Kampen diagram for w. The boundary of any cell of a van Kampen diagram is labeled with a relator or the inverse of a relator.

Example 2.20. Let us consider the presentation $(\{a, b\}, \{aba^{-1}b^{-1}\})$ of $\mathbb{Z} \times \mathbb{Z}$. Let us fold the bouquet corresponding to

$$w = a^{-1}(aba^{-1}b^{-1})a ba^{-1}(aba^{-1}b^{-1})ab^{-1}$$

which is (we do not show the inverse edges labeled with a^{-1} or b^{-1}):



The origin is labeled with 1 and the two thick edges are the one's that are folded first. Hence, we get:



Folding the two *b*-labeled edges at the origin 1 yields the following diagram:



Two more folding steps yield the following diagrams:



The right diagram is a van Kampen diagram for $b^2 a^{-1} b^{-2} a$ of area 2.

Definition 2.21 (Dehn function). Let (Γ, R) be a finite group presentation. The *Dehn function* $D_{\Gamma,R} : \mathbb{N} \to \mathbb{N}$ of the group presentation (Γ, R) is defined as

 $D_{\Gamma,R}(n) = \max\{\operatorname{area}(w) \mid w \text{ is irreducible }, w \in \langle R \rangle^{F(\Gamma)}, |w| \le n\}.$

In other words: $D_{\Gamma,R}(n)$ is the maximal area of an irreducible word of length at most *n* that represents the identity of *G*. Clearly, different finite presentations for *G* may yield different Dehn functions. On the other hand, if (Γ_1, R_1) and (Γ_2, R_2) are two finite presentations for the group *G*, then there exists a constant c > 0 such that $D_{\Gamma_1,R_1}(n) \le c \cdot D_{\Gamma_2,R_2}(cn+c) + cn+c$ [61, Proposition 2.4]. Hence, whether the Dehn function is linear, quadratic, cubic, exponential, etc., does not depend on the chosen presentation for a group. For every infinite finitely presented group the Dehn function grows at least linear, and by [68], a group has a linear Dehn function if and only if it is hyperbolic. Moreover, every automatic group has a quadratic Dehn function.

The following relationship between the Dehn function of a group and the complexity of the word problem is folklore:

Proposition 2.22. Let D(n) be a Dehn function for the finitely presented group *G*. Then the word problem for the group *G* can be solved in NTIME($\mathcal{O}(D(n))$).

Proof. Let $G \cong \langle \Gamma | R \rangle$, where (Γ, R) is a reduced presentation. Let *S* the be the set of all cyclic permutations of words from $R \cup R^{-1}$ (a word *s* is a cyclic permutation of

w if there exist words *u* and *v* such that w = uv and s = vu). We define the semi-Thue system

$$T = R_{\Gamma} \cup \{(u, v) \mid uv^{-1} \in R \cup R^{-1}, u \neq \varepsilon\},$$

where R_{Γ} is from (2.1). Here is some intuition: Rules of the form (u, v) with $uv^{-1} \in$ $R \cup R^{-1}$ and $u \neq \varepsilon$ allow to cut off cells from a van Kampen diagram that have a nontrivial intersection with the boundary, where u is the part of the cell that belongs to the boundary. Rules (aa^{-1}, ε) allow to remove boundary edges e, where one endpoint is only adjacent with edge e. Using this intuition, the following fact is not hard to see, see e.g. [147]. For a given irreducible input word w of length n, w = 1in $\langle \Gamma \mid R \rangle$ if and only if w can be rewritten with T to the empty word in at most $(m+1)D_{\Gamma,R}(n) + n$ steps, where m the maximal length of a relator in R (which is a constant in our consideration). A nondeterministic Turing machine simply guesses such a sequence of rewrite steps. Moreover, successive rewrite steps can be applied within bounded distance in the following sense: If the word xuv is rewritten to xvy using the rule $(u, v) \in T$, then (i) either $v = \varepsilon$ and the next rewritten factor covers the last symbol of x or the first symbol of y, or (ii) $v \neq \varepsilon$ and the next rewritten factor covers a position in v. Hence, the whole reduction process can be carried out in time $\mathcal{O}(D_{\Gamma,R}(n)+n)$ on a Turing machine. The proposition follows, since $D_{\Gamma,R}(n)$ grows at least linear if $\langle \Gamma | R \rangle$ is infinite. \Box

Another important and much more difficult result in this context is the following **NP**-analogue of Higman's embedding theorem, which was shown by Birget, Ol'shanskii, and Rips [19]:

Theorem 2.23. For a finitely generated group G, the word problem belongs to **NP** if and only if G can be embedded into a finitely presented group with a polynomial Dehn function.

The Dehn function for a finitely presented group *G* only yields an upper for the complexity of the word problem. For instance, the Baumslag-Solitar group $\langle a, b | bab^{-1} = a^2 \rangle$ has an exponential Dehn function [57], but can be embedded into the linear group $\mathsf{GL}_2(\mathbb{Q})$ using

$$a \mapsto \begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix}, \quad b \mapsto \begin{pmatrix} 1/2 & 0 \\ 0 & 1 \end{pmatrix}$$

Hence, by Theorem 2.18 the word problem for $\langle a, b | bab^{-1} = a^2 \rangle$ can be solved in logarithmic space. An even more extreme example is the Baumslag-Gersten group BG $(1,2) = \langle a,b,t | bab^{-1} = t,tat^{-1} = a^2 \rangle$, which was introduced by Baumslag [13] as the first example of a non-cyclic group, all of whose finite quotients are cyclic. Its Dehn function is roughly a tower of $\log_2(n)$ exponents and hence non-elementary [61, 143]. Nevertheless, using power circuits [133], which are a succinct representation of huge integers, the word problem for BG(1,2) can be solved in polynomial time [53, 132]. In [38] examples of groups with a computable word problem are constructed, for which the gap between the complexity of the word problem and the Dehn function is not bounded by a primitive recursive function. In [97] this result is

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further improved in two aspects: The gap is increased to any recursive function and the group that realizes the gap is finitely presented and residually-finite.

Definition 2.24. Let (Γ, R) be a finite reduced presentation and let $G = \langle \Gamma | R \rangle$. The *word search problem* for (Γ, R) , briefly WSP (Γ, R) , is the following computational problem with output:

input: An irreducible word $w \in (\Gamma \cup \Gamma^{-1})^*$ *output:* "no" if $w \neq 1$ in *G*, otherwise irreducible words $c_1, \ldots, c_\ell \in (\Gamma \cup \Gamma^{-1})^*$ and $r_1, \ldots, r_\ell \in R \cup R^{-1}$ such that $w = \prod_{i=1}^{\ell} c_i r_i c_i^{-1}$ in $F(\Gamma)$.

Hence, instead of just asking whether a given word represents the identity of *G*, one also wants to have a proof for representing the identity in the positive case. Instead of returning irreducible words $c_1, \ldots, c_\ell \in (\Gamma \cup \Gamma^{-1})^*$ and $r_1, \ldots, r_\ell \in R \cup R^{-1}$ such that $w = \prod_{i=1}^{\ell} c_i r_i c_i^{-1}$ in $F(\Gamma)$, one might also return a van Kampen diagram with boundary *w*. Both variants are equivalent with respect to polynomial time computations: From the word $\prod_{i=1}^{\ell} c_i r_i c_i^{-1}$ one can compute in polynomial time a van Kampen diagram with boundary *w*, and from a van Kampen diagram with boundary *w* one can compute in polynomial time a word $\prod_{i=1}^{\ell} c_i r_i c_i^{-1}$ that is equal to *w* in the free group $F(\Gamma)$.

Logspace many-one reductions between computational problems with output are defined as for decision problems. With this in mind, we get:

Lemma 2.25. *Let* (Γ, R) *and* (Σ, S) *be two finite presentations with* $\langle \Gamma | R \rangle \cong \langle \Sigma | S \rangle$ *. Then* WSP (Γ, R) *is logspace many-one reducible to* WSP (Σ, S) *.*

Proof. Let *f* be an isomorphism from $\langle \Gamma | R \rangle$ to $\langle \Sigma | S \rangle$. There exists a homomorphism $g: F(\Gamma) \to F(\Sigma)$ that induces *f* and similarly, there exists a homomorphism $h: F(\Sigma) \to F(\Gamma)$ that induces f^{-1} . Assume we have an algorithm for solving WSP(Σ, S) and we want to use this algorithm for solving WSP(Γ, R). So, let $w = a_1 \cdots a_n \in (\Gamma \cup \Gamma^{-1})^*$. We have w = 1 in $\langle \Gamma | R \rangle$ if and only if g(w) = 1 in $\langle \Sigma | S \rangle$. Hence, if our algorithm for WSP(Σ, R) outputs "no" on input *g*(*w*), then we can output "no" on input *w*. Otherwise, the algorithm for WSP(Σ, S) outputs a representation

$$g(w) = \prod_{i=1}^{\ell} c_i r_i c_i^{-1}$$

in $F(\Sigma)$, where $r_i \in S \cup S^{-1}$. Hence, in $F(\Gamma)$, we have

$$h(g(w)) = h(g(a_1)) \cdots h(g(a_n)) = \prod_{i=1}^{\ell} h(c_i)h(r_i)h(c_i)^{-1}$$
(2.2)

Note that in the group $\langle \Gamma | R \rangle$ we have h(r) = 1 for all $r \in S$. Hence, in $F(\Gamma)$ we can write

$$h(r_i) = \prod_{j=1}^{k_i} d_{i,j} p_{i,j} d_{i,j}^{-1}$$

and thus

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$$h(c_i)h(r_i)h(c_i)^{-1} = \prod_{j=1}^{k_i} h(c_i)d_{i,j}p_{i,j}d_{i,j}^{-1}h(c_i)^{-1}$$

with $p_{i,j} \in R \cup R^{-1}$. Here, the words $d_{i,j}$ and the numbers k_i do not depend on the input *w*. By plugging these identities into (2.2) and renaming the resulting word, we obtain a representation

$$h(g(w)) = h(g(a_1)) \cdots h(g(a_n)) = \prod_{i=1}^k d_i p_i d^{-1}$$
(2.3)

In the group $\langle \Gamma | R \rangle$ we also have h(g(a)) = a for all $a \in \Gamma \cup \Gamma^{-1}$. Hence, we can write in $F(\Gamma)$

$$h(g(a_i))^{-1}a_i = \prod_{j=1}^{\ell_i} e_{i,j}q_{i,j}e_{i,j}^{-1} =: w_i$$

with $q_{i,j} \in R \cup R^{-1}$. Again, the words $e_{i,j}$ and the numbers ℓ_i do not depend on the input *w*. One can easily check that

$$h(g(a_n))^{-1} \cdots h(g(a_1))^{-1} a_1 \cdots a_n = w_n(a_n^{-1} w_{n-1} a_n)(a_n^{-1} a_{n-1}^{-1} w_{n-2} a_{n-1} a_n) \cdots (a_n^{-1} \cdots a_2^{-1} w_1 a_2 \cdots a_n).$$

in $F(\Gamma)$. Finally, we get

$$w = a_1 \cdots a_n = \prod_{i=1}^k d_i p_i d^{-1} w_n (a_n^{-1} w_{n-1} a_n) \cdots (a_n^{-1} \cdots a_2^{-1} w_1 a_2 \cdots a_n),$$

which is the desired representation for w. The above process can be clearly accomplished by a logspace transducer. \Box

By Lemma 2.25, it is justified to speak of the word search problem for the group G, briefly WSP(G).

Further results on the word search problem can be found in [131]. Examples of groups, for which the word search problem can be solved in polynomial time are automatic groups and finitely generated nilpotent groups. For automatic groups, the standard proof that every automatic group is finitely presented and has a quadratic Dehn function [57] yields a polynomial time algorithm for the word search problem. For finitely generated nilpotent groups it has been shown in [62] that a finitely generated nilpotent group of class *c* has a Dehn function of growth $\mathcal{O}(n^{c+1})$. This result is shown in [62] by reducing a word *w* with w = 1 to the empty word by a sequence of rewrite steps with a system of the kind used in the proof of Proposition 2.22. This sequence of rewrite steps is explicitly constructed in [62] and the construction can be carried out in polynomial time. Finally, the constructed sequence of rewrite steps directly translates into a van Kampen diagram for *w*.

Chapter 3 Algorithms on Compressed Words

In this chapter, we will study circuits over a structure whose domain is the set Γ^* of all finite words over a finite alphabet. The operations used in the circuit include the binary concatenation and all symbols from Γ as constants. Such circuits are also called *straight-line programs* (SLPs). A straight-line program can be also viewed as a context-free grammar [82] that produces only a single word. Note that, as remarked in Section 1.3.7, the term "straight-line program" is also used for arithmetic circuits. In this book, we use the term "straight-line program" exclusively for circuits over free monoids. We will also consider extensions of straight-line programs, where some additional operations on words may be used in circuits (so called CSLPs and PCSLPs).

A main topic in this chapter will be algorithms that receive as input a word, which is not given explicitly but as a straight-line program. The main result of this chapter states that for two given straight-line programs one can check in polynomial time whether they produce the same words. For further results on SLPs see [59, 114, 142, 150].

3.1 Straight-Line Programs and Extensions

Let us start with the definition of a PCSLP, which are the most general word circuits that we consider in this book. Here "SLP" abbreviates "straight-line program, and "PC" stands for "projection and cut".

Definition 3.1 (projection). For alphabets $\Delta \subseteq \Gamma$ let us define the projection homomorphism $\pi_{\Delta} : \Gamma^* \to \Delta^*$ by $\pi_{\Delta}(a) = \varepsilon$ for $a \in \Gamma \setminus \Delta$ and $\pi_{\Delta}(a) = a$ for $a \in \Delta$. Strictly speaking, we should denote this homomorphism by $\pi_{\Gamma,\Delta}$, but the alphabet Γ will be always clear from the context.

Definition 3.2 (cut operator). For natural numbers $i, j \in \mathbb{N}$ and an arbitrary alphabet Γ , we define the mapping $c_{i,j} : \Gamma^* \to \Gamma^*$ by $c_{i,j}(w) = w[i : j]$ for all $w \in \Gamma^*$.

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Definition 3.3 (PCSLP, CSLP, SLP, C-expression, PC-expression). Let Γ be a finite alphabet. We define the following structures with domain Γ^* :

$$\begin{aligned} \mathscr{A}_{\Gamma} &= (\Gamma^*, \circ, \varepsilon, (a)_{a \in \Gamma}, (\pi_{\Delta})_{\Delta \subseteq \Gamma}, (c_{i,j})_{i,j \in \mathbb{N}}) \\ \mathscr{B}_{\Gamma} &= (\Gamma^*, \circ, \varepsilon, (a)_{a \in \Gamma}, (c_{i,j})_{i,j \in \mathbb{N}}) \\ \mathscr{C}_{\Gamma} &= (\Gamma^*, \circ, \varepsilon, (a)_{a \in \Gamma}) \end{aligned}$$

Here, \circ denotes the binary concatenation operator on words. A *PCSLP* over the alphabet Γ is a \mathscr{A}_{Γ} -circuit. A *CSLP* over the alphabet Γ is a \mathscr{B}_{Γ} -circuit. An *SLP* over the alphabet Γ is a \mathscr{C}_{Γ} -circuit. A *C-expression* is \mathscr{B}_{Γ} -expression. A *PC-expression* is an \mathscr{A}_{Γ} -expression.

PCSLPs and its restrictions will be denoted with letters $\mathbb{A}, \mathbb{B}, \mathbb{C}, \cdots$. For a (PC)SLP $\mathbb{A} = (V, S, \text{rhs})$ over the alphabet Γ we will also write $(V, \Gamma, S, \text{rhs})$ to make the alphabet explicit. Occasionally, we will consider PCSLPs without a start variable. For such a circuit \mathbb{A} , val (\mathbb{A}) is not defined.

PCSLPs are the only circuits in this book, which are based on a structure with infinitely many operations (due to the cut-operators $c_{i,j}$). Recall that when we defined the size of a circuit we had to fix a size size(f) for each function symbol. In case the underlying structure contains only finitely many operations (which is the case for \mathscr{C}_{Γ}), we can take size(f) = 1 for all f. For the structure \mathscr{A}_{Γ} let us define size($c_{i,j}$) = $\lceil \log_2(i) \rceil + \lceil \log_2(j) \rceil$, which is the number of bits needed to specify the numbers i and j.

We will always write e[i : j] instead of $c_{i,j}(e)$ in right-hand sides of PCSLPs. We will use the abbreviations X[: i] for X[1 : i] and X[i :] for X[i : l], where X is a variable with $l = |va|_A(X)|$, in right-hand sides. One may also allow exponential expressions of the form A^i for $A \in V$ and $i \in \mathbb{N}$ in right-hand sides of PCSLPs. Such an expression can be replaced by $\lceil \log_2(i) \rceil$ many ordinary right-hand sides. For instance the definition $A := a^{10}$ ca be replaced by $A_0 := a, A_1 := A_0^2, A_2 := A_1^2$, $A_3 := A_2^2, A := A_3A_1$. Hence, if we represent exponents in binary notation, then exponential expressions can be eliminated by a logspace transducer.

Example 3.4. We consider the PCSLP $\mathbb{A} = (\{A, B, C, D, E\}, \{a, b, c\}, E, \text{rhs})$ with rhs defined as follows:

$$rhs(A) = ab \qquad rhs(B) = ac \qquad rhs(C) = BA$$

$$rhs(D) = \pi_{\{a,c\}}(C)\pi_{\{b,c\}}(C) \qquad rhs(E) = D[2:4]$$

Then we have:

$$\operatorname{val}(A) = ab$$
 $\operatorname{val}(B) = ac$ $\operatorname{val}(C) = acab$
 $\operatorname{val}(D) = acacb$ $\operatorname{val}(E) = \operatorname{val}(\mathbb{A}) = cac$

The size of the PCSLP is the sum of the sizes of all right-hand sides:

3.1 Straight-Line Programs and Extensions

$$|rhs(A)| = 2$$
 $|rhs(B)| = 2$ $|rhs(C)| = 2$
 $|rhs(D)| = 4$ $|rhs(E)| = 1 + 1 + 2 = 4$

and therefore $|\mathbb{A}| = 14$.

CSLPs were called *composition systems* in [60]¹, *collage systems* in [98], and *interval grammars* in [71]. Here, we prefer the name CSLP in order to be more consistent in our terminology. Readers familiar with context-free grammars will notice that an SLP \mathbb{A} can be seen as a context-free grammar that generates the single word val(\mathbb{A}). If rhs(A) = α we also write (as usual for context-free grammars) $A \rightarrow \alpha$. Some early references on SLPs are [59, 139, 142].

Definition 3.5 (derivation tree). The *derivation tree* of the SLP $\mathbb{A} = (V, \Gamma, S, \text{rhs})$ is a finite rooted ordered tree, where every node is labeled with a symbol from $V \cup \Gamma$. The root is labeled with the start variable *S* and every node that is labeled with a symbol from Γ is a leaf of the derivation tree. A node that is labeled with a variable *A* with $\text{rhs}(A) = \alpha_1 \cdots \alpha_n$ (where $\alpha_1, \ldots, \alpha_n \in V \cup \Gamma$) has *n* children that are labeled from left to right with $\alpha_1, \ldots, \alpha_n$.

Recall the definition of a circuit in normal form (Definition 1.36), which also applies to PCSLPs, CSLPs, and SLPs. In particular, we allow a right-hand side to be ε . For SLPs that evaluate to a non-empty word, we can forbid the empty word as a right-hand side. An SLP in normal form without the empty word on a right-hand side is a context-free grammar in Chomsky normal form:

Definition 3.6 (Chomsky normal form). An SLP $\mathbb{A} = (V, \Gamma, S, \text{rhs})$ is in *Chomsky normal form*, if for all $A \in V$, rhs(A) belongs to Γ or has the form *BC* with $B, C \in V$.

Example 3.7. Consider the SLP \mathbb{A} over the terminal alphabet $\{a, b\}$ with variables A_1, \ldots, A_7 , where rhs $(A_1) = a$, rhs $(A_2) = b$ and rhs $(A_i) = A_{i-1}A_{i-2}$ for $3 \le i \le 7$. The start variable is A_7 . Then val $(\mathbb{A}) = abaababaabaabaaba$. The SLP \mathbb{A} is in Chomsky normal form and $|\mathbb{A}| = 12$.

We will make heavy use of the Chomsky normal form in this book. Therefore, let us outline an efficient algorithm for transforming a given SLP into Chomsky normal form.

Proposition 3.8. For a given SLP $\mathbb{A} = (V, \Gamma, S, \text{rhs})$ with $val(\mathbb{A}) \neq \varepsilon$ one can compute in time $\mathcal{O}(|\mathbb{A}|)$ (on a RAM) an SLP \mathbb{B} in Chomsky normal form such that $val(\mathbb{A}) = val(\mathbb{B})$.

Proof. The proof is similar to the transformation of a context-free grammar into Chomsky normal form, and is divided into 4 steps.

Step 1. First, we compute in linear time an enumeration $A_1, A_2, ..., A_n$ of V such that if A_i is smaller than A_j with respect to the hierarchical order, then i < j, i.e., we compute a topological sorting of V, see e.g. [42].

¹ The formalism in [60] differs in some minor details from CSLPs.

Step 2. Using the toplogical sorting, we can compute the set of variables $E = \{A \in V \mid val_{\mathbb{A}}(A) = \varepsilon\}$ in linear time: We set a bit e(A) to zero for each $A \in V$. Then we go over the sequence A_1, \ldots, A_n . If $rhs(A_i)$ only consists of variables and for each variable A_j in $rhs(A_i)$ we have $e(A_j) = 1$ (this includes the case that $rhs(A_i) = \varepsilon$), then we set $e(A_i) := 1$. At the end, we have $E = \{A \in V \mid e(A) = 1\}$. Then, we set $V := V \setminus E$ and replace every occurrence of a variable from E in a right-hand side by the empty word. The resulting SLP has no empty right-hand sides.

Step 3. Next, we replace every occurrence of a terminal symbol $a \in \Gamma$ in a righthand side rhs $(A) \neq a$ by a new variable A_a with rhs $(A_a) = a$. At this point, every right-hand side is either a single terminal symbol or a non-empty word over the set of variables V.

Step 4. Right-hand sides of length at least 3 are split into right-hand sides of length 2 by introducing additional variables. For this, we have to go only once over all right-hand sides; hence linear time suffices.

Step 5. Finally, we remove right-hand sides consisting of a single variable (so called chain productions). Let $C := \{A \in V \mid rhs(A) \in V\}$. Then, we go over the set *C* in topological order and thereby redefine rhs(A) := rhs(rhs(A)) for every $A \in C$. The resulting SLP is in Chomsky normal form. \Box

A simple induction shows that for every SLP \mathbb{A} of size *m* one has $|val(\mathbb{A})| \leq \mathcal{O}(3^{m/3})$ [31, proof of Lemma 1]. On the other hand, it is straightforward to define an SLP \mathbb{B} in Chomsky normal form of size 2n such that $|val(\mathbb{B})| \geq 2^n$. Hence, an SLP can be seen as a compressed representation of the word it generates, and exponential compression rates can be achieved in this way.

3.2 Algorithms for Words Represented by SLPs

In this section, we will see some simple polynomial time algorithms for words that are represented by SLPs. In the next section, we will show that CSLPs and under certain restrictions also PCSLPs can be transformed in polynomial time into equivalent SLPs. Hence, all algorithmic problems from this section can be solved in polynomial time for CSLPs and PCSLPs (under some restrictions) as well.

Proposition 3.9. The following time bounds hold for the RAM model:

- (1) Given an SLP $\mathbb{A} = (V, \Sigma, S, \text{rhs})$, one can compute all alphabets $\operatorname{alph}(\operatorname{val}_{\mathbb{A}}(A))$ for $A \in V$ in time $\mathcal{O}(|\mathbb{A}|)$.
- (2) Given an SLP $\mathbb{A} = (V, \Sigma, S, \text{rhs})$, one can compute all lengths $|va|_{\mathbb{A}}(A)|$ for $A \in V$ in time $\mathcal{O}(|\mathbb{A}|)$.
- (3) Given an SLP \mathbb{A} and a number $1 \le i \le |val(\mathbb{A})|$, one compute the symbol $val(\mathbb{A})[i]$ in time $\mathcal{O}(|\mathbb{A}|)$ (this problem is in fact **P**-complete [107]).
- (4) Given an SLP \mathbb{A} over the terminal alphabet Γ and a free monoid homomorphism $\rho: \Gamma^* \to \Sigma^*$, one can compute an SLP \mathbb{B} such that $val(\mathbb{B}) = \rho(val(\mathbb{A}))$ in time

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 $\mathscr{O}(|\mathbb{A}| \cdot \max\{|\rho(a)| \mid a \in \Gamma\})$. Moreover, this computation is also possible by a logspace transducer.

- (5) Given an SLP \mathbb{A} over the terminal alphabet Σ and a symbol $a \in \Sigma$ one can compute the number $\max(\{0\} \cup \{p \mid \mathsf{val}(\mathbb{A})[p] = a\})$ (i.e., the maximal position on which $\mathsf{val}(\mathbb{A})$ contains an a) in time $\mathscr{O}(|\mathbb{A}|)$.
- (6) Given an SLP \mathbb{A} over the terminal alphabet Σ , a subalphabet $\Gamma \subseteq \Sigma$ and a number $1 \leq i \leq |\pi_{\Gamma}(\mathsf{val}(\mathbb{A}))|$, one can compute the minimal position $1 \leq p \leq |\mathsf{val}(\mathbb{A})|$ with $|\pi_{\Gamma}(\mathsf{val}(\mathbb{A})[1:p])| = i$ (i.e., the position of the *i*-th occurrence of a letter from Γ in $\mathsf{val}(\mathbb{A})$) in time $\mathscr{O}(|\mathbb{A}|)$.

Proof. By Proposition 3.8, we can assume that $\mathbb{A} = (V, \Sigma, S, \text{rhs})$ is in Chomsky normal form. First, we compute in linear time an enumeration A_1, A_2, \dots, A_n of V such that if A_i is smaller than A_j with respect to the hierarchical order, then i < j, see also the proof of Proposition 3.8.

For (1), let us assume that $\Sigma = \{a_1, \ldots, a_m\}$. A subset of Σ can be represented by a bit vector of length *m*, and the union of two subsets can be computed as the bitwise OR of the corresponding bit vectors. Note that the bitwise OR is an elementary operation in our RAM model, see Section 1.3.8. Hence, we store for each nonterminal $A_i \in V$ a bit vector b_i of length *m*, which is initially set to the 0-vector. Then we go over all nonterminals in the order A_1, A_2, \ldots, A_n . If $rhs(A_i) = a_j$ then we set the *j*-th bit of b_i to 1. If $rhs(A_i) = A_jA_k$ with j, k < i then we set b_i to the bitwise OR of b_j and b_k .

Basically, the same algorithm works for (2), except that b_i now stores a natural number. If $rhs(A_i) = a_j$ then we set $b_i := 1$. If $rhs(A_i) = A_jA_k$ with j, k < i then we set $b_i := b_j + b_k$. Note that the number of bits of each number b_i is bounded by $\mathcal{O}(\log(|val_A(A)|)) \leq \mathcal{O}(|A|)$.

For (3), the algorithm walks down in the derivation tree for \mathbb{A} to position *i*. By (2), we can assume that for every $A \in V$, the length $|val_{\mathbb{A}}(A)|$ is available. At each stage, the algorithm stores a number *p* and a variable *A* of \mathbb{A} such that $1 \leq p \leq |val_{\mathbb{A}}(A)|$. Initially, p = i, and *A* is the start variable of \mathbb{A} . If rhs(A) = BC, then there are two cases: If $1 \leq p \leq |val_{\mathbb{A}}(B)|$, then we continue with position *p* and the variable *B*. Otherwise, we have $|val_{\mathbb{A}}(B)| + 1 \leq p \leq |val_{\mathbb{A}}(A)|$, and we continue with position $p - |val_{\mathbb{A}}(B)|$ (this number can be computed using the algorithm from the previous point) and variable *C*. Finally, if rhs(A) = a, then we must have p = 1 and we output the terminal symbol *a*.

For (4) we only have to replace in each right-hand side of \mathbb{A} every occurrence of a terminal symbol by $\rho(a)$.

For (5) let $p_{a,i} = \max(\{0\} \cup \{k \mid \mathsf{val}_{\mathbb{A}}(A_i)[k] = a\})$ for each $1 \le i \le n$. We compute all values $p_{a,i}$ for $1 \le i \le n$. First, we compute for each variable A_i the alphabet $\mathsf{alph}(\mathsf{val}_{\mathbb{A}}(A_i))$ (represented by a bit vector according to the proof of (1)) and the length $|\mathsf{val}_{\mathbb{A}}(A_i)|$ (see (2)) in time $\mathcal{O}(|\mathbb{A}|)$. Then, we compute the positions $p_{a,i}$ as follows: If $\mathsf{rhs}(A_i) = b \in \Sigma$ we set $p_{a,i} = 1$ if b = a and $p_{a,i} = 0$ otherwise. For a variable A_i with $\mathsf{rhs}(A_i) = A_i A_k$ (j, k < i) we set:

3 Algorithms on Compressed Words

$$p_{a,i} = \begin{cases} 0 & \text{if } a \notin \mathsf{alph}(\mathsf{val}_{\mathbb{A}}(A_i)) \\ p_{a,j} & \text{if } a \in \mathsf{alph}(\mathsf{val}_{\mathbb{A}}(A_i)) \setminus \mathsf{alph}(\mathsf{val}_{\mathbb{A}}(A_k)) \\ |\mathsf{val}_{\mathbb{A}}(A_j)| + p_{a,k} & \text{if } a \in \mathsf{alph}(\mathsf{val}_{\mathbb{A}}(A_k)). \end{cases}$$

Finally, the proof of (6) is similar to the proof of (3). By (2) and (4) we can assume that for every $A \in V$ the lengths $|va|_{\mathbb{A}}(A)|$ and $|\pi_{\Gamma}(va|_{\mathbb{A}}(A))|$ are available. We start with setting a variable p to 0 and another variable q to i (where i is from (6)). Then we walk down in the derivation tree for \mathbb{A} . If we are currently at a variable $A \in V$ and rhs(A) = BC, then there are two cases: If $1 \leq q \leq |\pi_{\Gamma}(va|_{\mathbb{A}}(B))|$, then we we continue at variable B and do not change the values of p and q. On the other hand, if $|\pi_{\Gamma}(va|_{\mathbb{A}}(B))| < q \leq |\pi_{\Gamma}(va|_{\mathbb{A}}(A))|$, then we set $p := p + |va|_{\mathbb{A}}(B)|$ and $q := q - |\pi_{\Gamma}(va|_{\mathbb{A}}(B))|$ and continue at variable C. Finally, if we arrive at a variable A with rhs $(A) \in \Sigma$, then we terminate and output the current value of p.

This concludes the proof of the proposition. \Box

Point (4) from Proposition 3.9 can be extended to mappings computed by deterministic rational transducers, as long as we only require the output SLP to be computed in polynomial time (and not logspace). A *deterministic rational transducer* \mathcal{T} is a tuple $\mathcal{T} = (Q, \Sigma, \Gamma, \delta, q_0, F)$, where

- Q is a finite set of states,
- Σ is the (finite) input alphabet,
- Γ is the (finite) output alphabet,
- δ ⊆ Q × Σ × Γ* × Q is a finite set of transitions such that for every q ∈ Q and a ∈ Σ there exists at most one transition of the form (q, a, w, p) in δ,
- $q_0 \in Q$ is the initial state, and
- $F \subseteq Q$ is the set of final states.

We define $\hat{\delta}$ as the smallest subset of $Q \times \Sigma^* \times \Gamma^* \times Q$ such that:

- $(q, \varepsilon, \varepsilon, q) \in \widehat{\delta}$ for all $q \in Q$,
- $\delta \subseteq \widehat{\delta}$, and
- If $(q, u, v, p), (p, u', v', r) \in \widehat{\delta}$, then also $(q, uu', vv', r) \in \widehat{\delta}$.

Then, for every state $p \in Q$ and every input word $u \in \Sigma^*$, there is at most one state $q \in Q$ and at most one word $v \in \Gamma^*$ such that $(p, u, v, q) \in \hat{\delta}$. Hence, we can define a partial mapping $[\mathscr{T}]: \Sigma^* \to \Gamma^*$ by (i) $[\mathscr{T}](u) = v$ if there is a final state $q \in F$ such that $(q_0, u, v, q) \in \hat{\delta}$ and (ii) $[\mathscr{T}](u) =$ undefined in all other cases. We define the *size* of the transducer $\mathscr{T} = (Q, \Sigma, \Gamma, \delta, q_0, F)$ as $|\mathscr{T}| = |Q| + \sum_{(q, a, w, p) \in \delta} (|w| + 1)$.

Theorem 3.10. From a given SLP \mathbb{A} over the terminal alphabet Σ and a given deterministic rational transducer \mathcal{T} with input alphabet Σ one can compute in time $\mathcal{O}(|\mathbb{A}| \cdot |\mathcal{T}|)$ an SLP \mathbb{B} such that $val(\mathbb{B}) = [[\mathcal{T}]](val(\mathbb{A}))$.

Proof. Let $\mathbb{A} = (V, \Sigma, S, \text{rhs})$, which is without loss of generality in Chomsky normal form, and $\mathscr{T} = (Q, \Sigma, \Gamma, \delta, q_0, F)$. In a first step we compute inductively over the hierarchical order of \mathbb{A} for every variable $A \in V$ and every state $p \in Q$ the unique

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state $s(p,A) \in Q$ such that $(p, val(A), v, s(p,A)) \in \delta$ for some word $v \in \Gamma^*$. If such a word v does not exist, we set s(p,A) = undefined. If $rhs(A) = a \in \Sigma$ then there is at most one transition $(p, a, w, q) \in \delta$ and we set s(p,A) = q if such a transition exists. If rhs(A) = BC and for every state $q \in Q$ the states s(q,B) and s(q,C) are already defined, then we set s(p,A) = s(s(p,B),C) for all $p \in Q$ (if s(p,B) is undefined, or q = s(p,B) is defined but s(q,C) is undefined, then clearly s(p,A) is undefined too). This first phase needs time $\mathcal{O}(|V| \cdot |Q|)$.

Now we can define the SLP \mathbb{B} . The variables of \mathbb{B} are all pairs $(p,A) \in Q \times V$ such that s(p,A) is defined. The right-hand sides for these variables are defined as follows: Let $A \in V$, $p \in Q$, and s(p,A) = q. If $rhs(A) = a \in \Sigma$, then there is exactly one transition $(p,a,w,q) \in \delta$ and we set rhs((p,A)) = w. If rhs(A) = BC, then s(p,B) = r must be defined. We set rhs((p,A)) = (p,B)(r,C). This second phase needs time $\mathcal{O}(|V| \cdot \sum_{(q,a,w,p) \in \delta} (|w| + 1))$. \Box

We will also need the following simple related result:

Theorem 3.11. For a given SLP \mathbb{A} and a given nondeterministic finite automaton $\mathscr{A} = (Q, \Sigma, \delta, q_0, F)$ we can check in time $\mathscr{O}(|\mathbb{A}| \cdot |Q|^3)$ whether $\mathsf{val}(\mathbb{A}) \in L(\mathscr{A})$.

Proof. We can assume that $Q = \{1, ..., n\}$ and $q_0 = 1$. This allows to represent the set of transitions of the automaton \mathscr{A} by boolean matrices M_a , one for each symbol $a \in \Sigma$. The matrix M_a has a 1 at entry (i, j) if and only if $(i, a, j) \in \delta$. We can now evaluate the SLP $\mathbb{A} = (V, \Sigma, S, \text{rhs})$ (which is without loss of generality in Chomsky normal form) over boolean matrices. Formally, for every variable $A \in V$ of \mathbb{A} we define a boolean matrix M_A as follows: If $\text{rhs}(A) = a \in \Sigma$ then $M_A = M_a$. If rhs(A) = BC, then $M_A = M_B M_C$. Since a multiplication of two boolean $(n \times n)$ matrices can be done in time n^3 , we need time $\mathcal{O}(|V| \cdot n^3)$ to compute all matrices M_A .

Now, $val(\mathbb{A}) \in L(\mathscr{A})$ if and only if there is a final state $i \in F$ such that entry (1, i) of the matrix M_S is 1. \Box

In [15, 124] it was shown that there exists a fixed regular language *L* such that it is **P**-complete to check for a given SLP \mathbb{A} whether val $(\mathbb{A}) \in L$; see also the remark after Theorem 4.10.

The following lemma will be crucial for our applications of compressed word problems. It generalizes point (4) from Proposition 3.9.

Lemma 3.12. For a given sequence $\varphi_1, \ldots, \varphi_n$ of free monoid homomorphisms $\varphi_i : \Gamma^* \to \Gamma^*$ $(1 \le i \le n)$ and an SLP \mathbb{A} over the alphabet Γ one can compute in logarithmic space an SLP \mathbb{B} such that $val(\mathbb{B}) = \varphi_1(\varphi_2(\cdots \varphi_n(val(\mathbb{A}))\cdots))$.

Proof. We compute in logarithmic space SLPs for the words $\varphi_1(\varphi_2(\cdots \varphi_n(a)))$ for all $a \in \Gamma$. Then, one can take the union of all these SLPs (assuming that their variable sets are pairwise disjoint) and replace in the SLP \mathbb{A} every occurrence of a symbol *a* by the start variable of the SLP for $\varphi_1(\varphi_2(\cdots \varphi_n(a)\cdots))$.

Let us take variables $A_{i,a}$, where $0 \le i \le n$ and $a \in \Gamma$, and define

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$$\operatorname{rhs}(A_{i,a}) = \begin{cases} a & \text{if } i = 0\\ A_{i-1,a_1} \cdots A_{i-1,a_m} & \text{if } 0 < i \le n \text{ and } \varphi_i(a) = a_1 \cdots a_m \end{cases}$$

By induction on *i* one can easily show that $val(\mathbb{A}_{i,a}) = \varphi_1(\varphi_2(\cdots \varphi_i(a) \cdots))$. \Box

We conclude this chapter with a simple problem for words, which becomes difficult for SLPs.

Theorem 3.13. *The following problem is* **NP***-complete: input: Two SLPs* \mathbb{A} *and* \mathbb{B} *over the terminal alphabet* $\{a,b\}$ *. output: Is there a position i such that* $val(\mathbb{A})[i] = val(\mathbb{B})[i] = b$?

Proof. It is clear that the problem belongs to **NP**: We can guess a position *i* and then verify $val(\mathbb{A})[i] = val(\mathbb{B})[i]$ in polynomial time.

For **NP**-hardness, we use a construction from [112]. We reduce from SUB-SETSUM, see Example 1.42. Let $\overline{w} = (w_1, \ldots, w_n)$ be a tuple of natural numbers and let $t \in \mathbb{N}$; all numbers are encoded in binary. For a bit vector $\overline{x} \in \{0,1\}^n$ of length *n* let us define $\overline{x} \cdot \overline{w} = x_1w_1 + x_2w_2 + \cdots + x_nw_n$. Note that SUBSETSUM is the question, whether there exists a bit vector $\overline{x} \in \{0,1\}^n$ with $\overline{x} \cdot \overline{w} = t$. Let $\overline{1}_k$ be the constant-1 vector $(1,1,\ldots,1)$ of length *k*, let $\overline{w}_k = (w_1,\ldots,w_k)$, and let $s_k = \overline{1}_k \cdot \overline{w}_k = w_1 + \cdots + w_k$ for $1 \le k \le n$. Finally, let $s = s_n = w_1 + w_2 + \cdots + w_n$ and define the word

$$S(\overline{w}) = \prod_{\overline{x} \in \{0,1\}^n} a^{\overline{x} \cdot \overline{w}} b a^{s - \overline{x} \cdot \overline{w}}.$$

Here, the product $\prod_{\overline{x} \in \{0,1\}^n}$ means that we concatenate all words $a^{\overline{x} \cdot \overline{w}} b a^{s-\overline{x} \cdot \overline{w}}$ for $\overline{x} \in \{0,1\}^n$ and the order of concatenation is the lexicographic order on $\{0,1\}^n$, where the right-most bit has highest significance. For example, we have

$$S(2,3,5) = ba^{10} a^2 ba^8 a^3 ba^7 a^5 ba^5 a^5 ba^5 a^7 ba^3 a^8 ba^2 a^{10} b$$

= $ba^{12} ba^{11} ba^{12} ba^{10} ba^{12} ba^{11} ba^{12} b.$

Let us show that there is an SLP \mathbb{A} of size polynomial in $\sum_{i=1}^{n} \log(w_i)$ for the word $S(\overline{w})$. Note that $\sum_{i=1}^{n} \log(w_i)$ is roughly the length of the binary encoding of the tuple \overline{w} . The SLP \mathbb{A} contains variables A_1, \ldots, A_n with

rhs(A₁) =
$$ba^{s+w_1}b$$

rhs(A_{k+1}) = $A_k a^{s-s_k+w_{k+1}}A_k$ (1 ≤ k ≤ n - 1).

Here we use binary coded numbers as exponents. These powers can be easily removed by ordinary right-hand sides as remarked earlier. To see that \mathbb{A} can be computed by a logspace transducer from w_1, \ldots, w_n it suffices to compute all numbers s_1, \ldots, s_n in logspace. This is an instance of the iterated addition problem (compute the sum of a given tuple of binary encoded numbers), which belongs to the circuit complexity class \mathbf{TC}^0 . Every function in \mathbf{TC}^0 can be computed by a logspace transducer, see [163] for details.

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3.3 Transforming CSLPs and PCSLPs into SLPs

Let A_n be the start variable of \mathbb{A} . We prove by induction on k that

$$\mathsf{val}_{\mathbb{A}}(A_k) = \left(\prod_{\overline{x} \in \{0,1\}^k \setminus \{\overline{1}_k\}} a^{\overline{x} \cdot \overline{w}_k} b a^{s - \overline{x} \cdot \overline{w}_k}\right) a^{s_k} b.$$

The case k = 1 is clear, since $\operatorname{val}_{\mathbb{A}}(A_1) = ba^{s+w_1}b = ba^sa^{s_1}b = a^0ba^{s-0}a^{s_1}b$. For $k+1 \leq n$ we obtain the following:

$$=\underbrace{\left(\prod_{\overline{x}\in\{0,1\}^{k+1}\setminus\{\overline{1}_{k+1}\}}a^{\overline{x}\cdot\overline{w}_{k+1}}ba^{s-\overline{x}\cdot\overline{w}_{k+1}}\right)a^{s_{k+1}}b}_{\mathsf{val}_{\mathbb{A}}(A_{k})a^{s-\overline{x}\cdot\overline{w}_{k}}}\underbrace{\left(\prod_{\overline{x}\in\{0,1\}^{k}\setminus\{\overline{1}_{k}\}}a^{\overline{x}\cdot\overline{w}_{k}+w_{k+1}}ba^{s-\overline{x}\cdot\overline{w}_{k}-w_{k+1}}\right)a^{w_{k+1}}a^{s_{k}}b}_{a^{w_{k+1}}\mathsf{val}_{\mathbb{A}}(A_{k})}$$

$$=\operatorname{val}_{\mathbb{A}}(A_{k})a^{s-s_{k}+w_{k+1}}\operatorname{val}_{\mathbb{A}}(A_{k})=\operatorname{val}_{\mathbb{A}}(A_{k+1}).$$

For k = n we finally get

$$\mathsf{val}(\mathbb{A}) = \mathsf{val}_{\mathbb{A}}(A_n) = \prod_{\overline{x} \in \{0,1\}^n} a^{\overline{x} \cdot \overline{w}} b a^{s - \overline{x} \cdot \overline{w}} = S(\overline{w}).$$

Our second SLP ${\mathbb B}$ satisfies

$$\mathsf{val}(\mathbb{B}) = (a^t b a^{s-t})^{2^n}.$$

It is straightforward to construct such an SLP in logspace from the binary representations of *s* and *t*. Clearly, there exists a bit vector $\overline{x} \in \{0,1\}^n$ with $\overline{x} \cdot \overline{w} = t$ if and only if there is a position *i* with $val(\mathbb{A})[i] = val(\mathbb{B})[i] = b$. This concludes the proof. \Box

3.3 Transforming CSLPs and PCSLPs into SLPs

CSLPs and PCSLPs are sometimes more convenient than SLPs. On the other hand, in this section we will see that CSLPs can be transformed in polynomial time into SLPs. The same holds for PCSLPs if we restrict applications of projection operators suitably.

The following result was shown by Hagenah in his PhD thesis [71] (in German), see also [151].

Theorem 3.14. From a given CSLP $\mathbb{A} = (V_{\mathbb{A}}, \Gamma, \operatorname{rhs}_{\mathbb{A}})$ (without start variable) in normal form with *n* variables one can compute in time $\mathcal{O}(n^2)$ an SLP $\mathbb{B} = (V_{\mathbb{B}}, \Gamma, \operatorname{rhs}_{\mathbb{B}})$ (without start variable) of size $\mathcal{O}(n^2)$ such that $V_{\mathbb{A}} \subseteq V_{\mathbb{B}}$ and $\operatorname{val}_{\mathbb{B}}(X) = \operatorname{val}_{\mathbb{A}}(X)$ for all $X \in V_{\mathbb{A}}$. *Proof.* Let us write *V* and rhs for $V_{\mathbb{A}}$ and rhs_{\mathbb{A}}, respectively, in the following. Let *h* be the height of \mathbb{A} . The idea is to push cut-operators downwards (towards smaller variables in the hierarchical order). First we compute the lengths of all words $val_{\mathbb{A}}(A)$ for $A \in V$. This is possible in time $\mathcal{O}(n)$ as for SLPs, see Proposition 3.9. Choose a variable $A \in V$ such that rhs(A) = B[i : j] but every smaller variable *C* (smaller with respect to the hierarchical order) has no cut-operator in its right-hand side. We show that we can eliminate the cut-operator in rhs(A) and thereby obtain a CSLP $\mathbb{A}' = (V', \Gamma, S, rhs')$ in normal form such that $V \subseteq V'$, $|V' \setminus V| \leq 2h$, $val_{\mathbb{A}}(A) = val_{\mathbb{A}'}(A)$ for all $A \in V$, and the height of \mathbb{A}' is bounded by the height of \mathbb{A} . By iterating this transformation, we can eliminate all cut-operators and transform \mathbb{A} into an equivalent SLP of size $|\mathbb{A}| + \mathcal{O}(h|V|)$ (the elimination of each cut-operator increases the size by $\mathcal{O}(h)$).

If rhs(B) = a for $a \in \Gamma$, then we set rhs(A) = a if i = j = 1 and $rhs(A) = \varepsilon$ otherwise. Now assume that rhs(B) = CD (recall that we assume that \mathbb{A} is in normal form). Let m = |val(C)| and n = |val(D)|. There are three cases:

Case 1. $j \le m$. We redefine rhs(A) = C[i, j].

Case 2. $i \ge n+1$. We redefine rhs(A) = D[i-m, j-m].

Case 3. $i \le m$ and j > m. In this case we introduce two new variables C' and D', redefine rhs(A) = C'D', and set rhs(C') = C[i:] and rhs(D') = D[:i-m].

By iterating this process, we arrive at one of the following two situations:

- (i) After several applications of Case 1 and 2 we have rhs(A) = X[k, l] and $rhs(X) = a \in \Gamma$ for some variable $X \in V$.
- (ii) We arrive at Case 3 for the first time.

In situation (i) we are done (and have not introduced any new variables). So assume that we arrive in situation (ii). We have introduced two new variables C' and D'. Let us deal with C' (with D' we deal analogously). We have set rhs(C') = C[i:]. If rhs(C) = a for $a \in \Gamma$, then we set rhs(C') = a if i = 1 and $rhs(C) = \varepsilon$ otherwise. Now assume that rhs(C) = EF for $E, F \in V$. Let m = |val(E)| and n = |val(F)|. We distinguish two cases:

Case 1. $i \le m$. We introduce a new variable E', redefine rhs(C') = E'F, set rhs(E') = E[i:], and continue with E'.

Case 2. i > m. We redefine rhs(C') = F[: i - m] and continue with C'.

By iterating this process we finally eliminate the cut-operator. Note that in each step at most one new variable is introduced (in Case 1). Therefore, at most *d* variables are introduced. Since we have to do an analogous procedure for *D'*, we introduce at most 2*h* new variables in total. Clearly, our process does not increase the height of the CSLP. Moreover, the resulting CSLP is again in normal form except for variables *X* with $rhs(X) = \varepsilon$. But these variables can be eliminated at the end. This proves the theorem. \Box

3.3 Transforming CSLPs and PCSLPs into SLPs

Theorem 3.14 cannot be generalized to PCSLPs, simply because the size of a smallest SLP that is equivalent to a given PCSLP may be exponential in the size of the PCSLP. Here is an example:

Example 3.15. For $n \ge 1$ let us define the PCSLP

$$\mathbb{A}_n = (\{A_1, \dots, A_n, A_{n+1}\}, \Gamma_n, A_1, \mathrm{rhs})$$

with $\Gamma_n = \{a_1, \ldots, a_n\}$, rhs $(A_i) = \pi_{\Delta_i}(A_{i+1})A_{i+1}$ for $1 \le i \le n$, and rhs $(A_{n+1}) = a_1a_2 \cdots a_n$, where $\Delta_i = \{a_1, \ldots, a_n\} \setminus \{a_i\}$. This PCSLP generates the word

$$\mathsf{val}(\mathbb{A}_n) = \prod_{\Delta \subseteq \Gamma_n} \pi_{\Delta}(a_1 a_2 \cdots a_n), \tag{3.1}$$

where all subsets $\Delta \subseteq \Gamma_n$ are listed in a kind of lexicographic order (the precise order is not important for the following argument). Let \mathbb{B}_n be an SLP with $val(\mathbb{A}_n) = val(\mathbb{B}_n)$. By [31, Lemma 3], $val(\mathbb{B}_n)$ contains at most $k \cdot |\mathbb{B}_n|$ many different factors of length k. But from (3.1) we see that $val(\mathbb{A}_n) = val(\mathbb{B}_n)$ contains at least $\binom{n}{\lfloor n/2 \rfloor}$ many factors of length $\lfloor n/2 \rfloor$. Hence, $|\mathbb{B}_n|$ must be at least $\lfloor n/2 \rfloor^{-1} \cdot \binom{n}{\lfloor n/2 \rfloor}$, which is exponential in n.

Nevertheless, under certain restrictions we can transform a given PCSLP into an equivalent SLP:

Lemma 3.16. *Let p be a constant. Then there exists a polynomial time algorithm for the following problem:*

input: Finite alphabets $\Gamma_1, \ldots, \Gamma_p$ and a PCSLP $\mathbb{A} = (V_{\mathbb{A}}, \Gamma, \operatorname{rhs}_{\mathbb{A}})$ (without start variable) over $\Gamma = \bigcup_{i=1}^p \Gamma_i$ such that $\Delta \in {\Gamma_1, \ldots, \Gamma_p}$ for every subexpression of the form $\pi_{\Delta}(\alpha)$ that appears in a right-hand side of \mathbb{A} .

output: An SLP $\mathbb{B} = (V_{\mathbb{B}}, \Gamma, \operatorname{rhs}_{\mathbb{B}})$ (without start variable) over Γ such that $V_{\mathbb{A}} \subseteq V_{\mathbb{B}}$ and $\operatorname{val}_{\mathbb{A}}(X) = \operatorname{val}_{\mathbb{B}}(X)$ for every $X \in V_{\mathbb{A}}$.

Proof. Since for a CSLP an equivalent SLP can be constructed in polynomial time by Theorem 3.14, it suffices to construct in polynomial time a CSLP \mathbb{B} with the desired properties from the statement of the lemma. Let

$$\mathscr{C} = \Big\{ \bigcap_{i \in K} \Gamma_i \mid K \subseteq \{1, \dots, p\} \Big\} \cup \{\Gamma\}.$$

Note that \mathscr{C} has constant size. Let $V_{\mathbb{B}} = \{X_{\Delta} \mid X \in V_{\mathbb{A}}, \Delta \in \mathscr{C}\}$ be the set of variables of \mathbb{B} . We identify $X \in V_{\mathbb{A}}$ with $X_{\Gamma} \in V_{\mathbb{B}}$. The right-hand side mapping $\operatorname{rhs}_{\mathbb{B}}$ will be defined in such a way that $\operatorname{val}_{\mathbb{B}}(X_{\Delta}) = \pi_{\Delta}(\operatorname{val}_{\mathbb{A}}(X))$.

If $\operatorname{rhs}_{\mathbb{A}}(X) = a \in \Gamma$, then we set $\operatorname{rhs}_{\mathbb{B}}(X_{\Delta}) = \pi_{\Delta}(a) \in \{\varepsilon, a\}$. If $\operatorname{rhs}_{\mathbb{A}}(X) = YZ$, then we set $\operatorname{rhs}_{\mathbb{B}}(X_{\Delta}) = Y_{\Delta}Z_{\Delta}$. If $\operatorname{rhs}_{\mathbb{A}}(X) = \pi_{\Theta}(Y)$ with $\Theta \in \{\Gamma_1, \ldots, \Gamma_p\}$, then we set $\operatorname{rhs}_{\mathbb{B}}(X_{\Delta}) = Y_{\Delta \cap \Theta}$. Note that $\Delta \cap \Theta \in \mathscr{C}$.

Finally, consider the case $\operatorname{rhs}_{\mathbb{A}}(X) = Y[i:j]$. We set $\operatorname{rhs}_{\mathbb{B}}(X_{\Delta}) = Y_{\Delta}[k:\ell]$, where $k = |\pi_{\Delta}(\operatorname{val}(Y)[:i-1])| + 1$ and $\ell = |\pi_{\Delta}(\operatorname{val}(Y)[:j])|$. These lengths can be computed in polynomial time as follows: Implicitly, we have already computed a CSLP,

which generates the word val(Y). Hence, by adding a single definition, we obtain a CSLP for the word val(Y)[:i-1]. Using Theorem 3.14 we can transform this CSLP in polynomial time into an equivalent SLP, which can be transformed in polynomial time into an SLP for the word $\pi_{\Delta}(val(Y)[:i-1])$ by Proposition 3.9(4). From this SLP we can compute the length $|\pi_{\Delta}(val(Y)[:i-1])|$ in polynomial time by Proposition 3.9 (the SLP for the word val(Y)[:i-1] is not used in the further computation). The length $|\pi_{\Delta}(val(Y)[:i])|$ can be computed similarly. Since the size of \mathscr{C} is constant, the above construction works in polynomial time. \Box

In the proof of Lemma 3.16, it is crucial that p is a fixed constant, i.e., not part of the input. Otherwise the construction would lead to an exponential blow-up. Example 3.15 shows that this is unavoidable.

By Theorem 3.14, all algorithmic problems for SLP-represented words considered in Section 3.2 can be solved in polynomial time for CSLP-represented words as well. The same applies to PCSLPs under the restriction for the alphabet from Lemma 3.16.

3.4 Compressed Equality Checking

The most basic task for SLP-compressed words is equality checking: Given two SLPs \mathbb{A} and \mathbb{B} , does val $(\mathbb{A}) =$ val (\mathbb{B}) hold? Clearly, a simple decompress-and-compare strategy is very inefficient. It takes exponential time to compute val (\mathbb{A}) and val (\mathbb{B}) . Nevertheless a polynomial time algorithm exists. This was independently discovered by Hirshfeld, Jerrum, and Moller [80], Mehlhorn, Sundar, and Uhrig [128], and Plandowski [139].

Theorem 3.17 ([80, 128, 139]). The following problem belongs to P:

input: Two SLPs \mathbb{A} and \mathbb{B} question: Does val (\mathbb{A}) = val (\mathbb{B}) hold?

A natural generalization of checking equality of two words is pattern matching. In the classical *pattern matching problem* it is asked for given words p (usually called the pattern) and t (usually called the text), whether p is a factor of t. There are several linear time algorithms for this problem on uncompressed words, most notably the well-known Knuth-Morris-Pratt algorithm [99]. It is therefore natural to ask, whether a polynomial time algorithm for pattern matching on SLP-compressed words exists; this problem is sometimes called *fully compressed pattern matching* and is defined as follows:

input: Two SLPs \mathbb{A} and \mathbb{B} *question:* Is val(\mathbb{A}) a factor of val(\mathbb{B})?

The first polynomial time algorithm for fully compressed pattern matching was presented in [96], further improvements with respect to the running time were achieved in [59, 89, 106, 130]. In this book, we will only need the weaker Theorem 3.17.

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In the rest of this section, we will prove Theorem 3.17. Since the result is so fundamental for the rest of the book, we will also analyze the precise running time of our algorithm (using the RAM model from Section 1.3.8). Our algorithm will use Jeż's recompression technique [89]. This technique was used in [89] to give the currently fastest algorithm for fully compressed pattern matching. Basically, our algorithm can be seen as a simplification of the algorithm from [89].² We start with several definitions.

Let $s \in \Sigma^+$ be a non-empty word over a finite alphabet Σ . We define the word block(*s*) as follows: Assume that $s = a_1^{n_1} a_2^{n_2} \cdots a_k^{n_k}$ with $a_1, \ldots, a_k \in \Sigma$, $a_i \neq a_{i+1}$ for all $1 \le i < k$ and $n_i > 0$ for all $1 \le i \le k$. Then block(s) = $a_1^{(n_1)} a_2^{(n_2)} \cdots a_k^{(n_k)}$, where $a_1^{(n_1)}, a_2^{(n_2)}, \ldots, a_k^{(n_k)}$ are new symbols. For instance, for s = aabbbaccb we have block(s) = $a^{(2)} b^{(3)} a^{(1)} c^{(2)} b^{(1)}$. For the symbol $a^{(1)}$ we will simply write a. Let us set block(ε) = ε .

For a partition $\Sigma = \Sigma_l \uplus \Sigma_r$ we denote with $s[\Sigma_l, \Sigma_r]$ the word that is obtained from *s* by replacing every occurrence of a factor *ab* in *s* with $a \in \Sigma_l$ and $b \in \Sigma_r$ by the new symbol $\langle ab \rangle$. For instance, for s = abcbabcad and $\Sigma_l = \{a, c\}$ and $\Sigma_r = \{b, d\}$ we have $s[\Sigma_l, \Sigma_r] = \langle ab \rangle \langle cb \rangle \langle ab \rangle c \langle ad \rangle$. Since two different occurrences of factors from $\Sigma_l \Sigma_r$ must occupy disjoints sets of positions in *s*, the word $s[\Sigma_l, \Sigma_r]$ is well-defined.³

Obviously, for all words $s, t \in \Sigma^*$ we have

$$(s = t \iff block(s) = block(t))$$
 and $(s = t \iff s[\Sigma_l, \Sigma_r] = t[\Sigma_l, \Sigma_r])$. (3.2)

In the rest of this section, we assume that all SLPs $\mathbb{A} = (V, \Sigma, S, \text{rhs})$ are in a kind of generalized Chomsky normal form: We require that for every variable $A \in V$, rhs(A) is either of the form $u \in \Sigma^+$, uBv with $u, v \in \Sigma^*$ and $B \in V$, or uBvCw with $u, v, w \in \Sigma^*$ and $B, C \in V$. In other words, every right-hand side is non-empty and contains at most two occurrences of variables. In particular, we only consider SLPs that produce non-empty word. This is not a crucial restriction for checking the equality $val(\mathbb{A}) = val(\mathbb{B})$, since we can first check easily in polynomial time, whether $val(\mathbb{A})$ or $val(\mathbb{B})$ produce the empty string.

Following Jeż's recompression technique [89], our strategy for checking an equality val(\mathbb{A}) = val(\mathbb{B}) is to compute from \mathbb{A} and \mathbb{B} two SLPs \mathbb{A}' and \mathbb{B}' such that val(\mathbb{A}') = (block(val(\mathbb{A})))[Σ_l, Σ_r] and val(\mathbb{B}') = (block(val(\mathbb{B})))[Σ_l, Σ_r], where the partition is chosen in such a way that the total length $|val(\mathbb{A}')| + |val(\mathbb{B}')|$ is bounded by $c \cdot (|val(\mathbb{A})| + |val(\mathbb{B})|)$ for some constant c < 1. This process is iterated. After at most log($|val(\mathbb{A})| + |val(\mathbb{B})|$) $\in \mathcal{O}(|\mathbb{A}| + |\mathbb{B}|)$ many iterations it must terminate with two SLPs, one of which produces a string of length one. Checking equality of the two words produced by these SLPs is easy. The main difficulty of this approach is to bound the size of the two SLPs during this process.

 $^{^2}$ Using a refined analysis, Jeż moreover achieves a better running time in [89] compared to our algorithm.

³ More formally, one can define the semi-Thue system $R = \{(ab, \langle ab \rangle) \mid a \in \Sigma_l, b \in \Sigma_r\}$. It is Noetherian and confluent, and we have $s[\Sigma_l, \Sigma_r] = \mathsf{NF}_R(s)$.

Algorithm 1: CompressBlocks(A)

```
input : SLP \mathbb{A} = (V, \Sigma, S, \text{rhs})
output: SLP \mathbb{B} with val(\mathbb{B}) = block(val(\mathbb{A}))
let A_1, A_2, \ldots, A_m be an enumeration of V in hierarchical order
for i := 1 to m do
     if rhs(A_i) = u \in \Sigma^+ then
      rhs(A_i) := block(u)
     else if rhs(A_i) = uBv with u, v \in \Sigma^* and B \in V then
      rhs(A_i) := block(u) B block(v)
     else
          let rhs(A_i) = uBvCw with u, v, w \in \Sigma^* and B, C \in V
          rhs(A_i) := block(u) B block(v) C block(w)
     end
end
for i := 1 to m - 1 do
     if rhs(A_i) is of the form a^{(k)} then
          replace every occurrence of A_i in a right-hand side by a^{(k)}
          remove A_i from the SLP
     else
          let rhs(A_i) be of the form a^{(k)} \alpha b^{(l)}
          if \alpha = \varepsilon then
                replace every occurrence of A_i in a right-hand side by a^{(k)}b^{(l)}
                remove A_i from the SLP
          else
                replace every occurrence of A_i in a right-hand side by a^{(k)}A_ib^{(l)}
                \operatorname{rhs}(A_i) := \alpha
          end
     end
     replace every factor c^{(j)}c^{(k)} (c \in \{a, b\}) in a right-hand side by c^{(j+k)}
end
```

Lemma 3.18. *Given an SLP* \mathbb{A} , alph(block(val(\mathbb{A}))) *contains at most* $|\mathbb{A}|$ *many dif-ferent symbols.*

Proof. A block in $s = val(\mathbb{A})$ is a maximal factor of the form $s[i, j] = a^n$ for $a \in \Sigma$ (maximal in the sense that either i = 1 or $s[i-1] \neq a$, and either j = |s| or $s[j+1] \neq a$). We have to show that *s* contains at most $|\mathbb{A}|$ different blocks. To every block a^n that is a factor of *s* we can assign a unique variable *A* such that a^n is a factor of $val_{\mathbb{A}}(A)$ but a^n is not a factor of any word $val_{\mathbb{A}}(B)$, where *B* is a variable that occurs in rhs(*A*). But there are at most |rhs(A)| such blocks. Summing over all variables yields the lemma. \Box

Lemma 3.19. *Given an SLP* \mathbb{A} *, one can compute in time* $\mathcal{O}(|\mathbb{A}|)$ *an SLP* \mathbb{B} *such that* $\mathsf{val}(\mathbb{B}) = \mathsf{block}(\mathsf{val}(\mathbb{A}))$ *. Moreover, if* \mathbb{A} *has m variables, then* \mathbb{B} *has at most m variables and* $|\mathbb{B}| \leq |\mathbb{A}| + 4m$.

Proof. Let $\mathbb{A} = (V, \Sigma, S, \text{rhs})$ (where every right-hand side is non-empty and contains at most two variables) and let A_1, A_2, \dots, A_m be an enumeration of V that respects

3.4 Compressed Equality Checking

the hierarchical order of \mathbb{A} : If A_i occurs in rhs (A_j) then i < j. Such an enumeration can be produced in time $\mathcal{O}(|\mathbb{A}|)$; it is equivalent to the problem of computing a topological sorting of an acyclic graph, see e.g. [42, Section 22.4]. We can assume that $A_m = S$. Let a_i (respectively, b_i) be the first (respectively, last) symbol of val_{\mathbb{A}} (A_i) . Moreover, let φ be the homomorphism with $\varphi(a^{(k)}) = a^k$ for all $a \in \Sigma$ and $k \ge 1$.

Consider Algorithm 1 (CompressBlock). It gradually modifies the input SLP \mathbb{A} . Let \mathbb{A}_0 be the SLP before the second for-loop is executed for the first time, and let \mathbb{A}_i be the SLP produced after $1 \le i \le m-1$ iterations of the second for-loop. Finally let $\mathbb{B} = \mathbb{A}_{m-1}$ be the output SLP. Hence, $\varphi(val(\mathbb{A}_0)) = \varphi(block(val(\mathbb{A}))) = val(\mathbb{A})$. By induction on $0 \le i \le m-1$ we prove the following invariants:

- (i) For all $1 \le j \le i$ we have: If $block(val_{\mathbb{A}}(A_j))$ has length at most two, then A_j does no longer occur in \mathbb{A}_i . On the other hand, if $block(val_{\mathbb{A}}(A_j)) = a^{(k)}ub^{(l)}$ with $u \ne \varepsilon$, then $val_{\mathbb{A}_i}(A_j) = u$.
- (ii) For all *i* + 1 ≤ *j* ≤ *m*, we have φ(val_{Ai}(A_j)) = val_A(A_j) and rhs_{Ai}(A_j) does not contain a factor of the form *a*^(p)*a*^(q). Moreover, every occurrence of a variable A_k with 1 ≤ k ≤ *i* in rhs_{Ai}(A_j) has a symbol of the from *a*^(p)_k on its left and a symbol of the form *b*^(q)_k on its right.

For i = 0, (i) and (ii) clearly hold. Now assume that (i) and (ii) hold for some $0 \le i \le m-2$ and consider the (i + 1)-th iteration of the for-loop. Only the righthand sides of variables from A_{i+1}, \ldots, A_m are modified. Hence, (i) still holds for all variables A_1, \ldots, A_i after the (i + 1)-th iteration. In order to prove the remaining points, note that all variables in $\operatorname{rhs}_{\mathbb{A}_i}(A_{i+1})$ are among $\{A_1, \ldots, A_i\}$ and hence satisfy point (i) after the *i*-th iteration. Morover, A_{i+1} satisfies (ii) after the *i*-th iteration. We get $\operatorname{val}_{\mathbb{A}_i}(A_{i+1}) = \operatorname{block}(\operatorname{val}_{\mathbb{A}}(A_{i+1}))$ and $\operatorname{rhs}_{\mathbb{A}_i}(A_{i+1})$ either has the form $a^{(p)} = \operatorname{block}(\operatorname{val}_{\mathbb{A}}(A_{i+1}))$ or $a^{(k)} \alpha b^{(l)}$, where $a^{(k)}$ (respectively, $b^{(l)}$) is the first (respectively, last) symbol of $\operatorname{block}(\operatorname{val}_{\mathbb{A}}(A_{i+1}))$. Using this, it is straightforward to verify (i) for A_{i+1} as well as (ii) for all variables A_{i+2}, \ldots, A_m .

Note that \mathbb{B} has at most *m* variables (no new variables are introduced) and that the length of a right-hand side of \mathbb{A} increases by at most 4 in the construction of \mathbb{B} : Every right-hand side of \mathbb{A} contains at most two variables, and for each occurrence of a variable in a right-hand side we add one symbol on the left and one symbol on the right. Hence, we get $|\mathbb{B}| \leq |\mathbb{A}| + 4m$. \Box

Let us now analyze words $s[\Sigma_l, \Sigma_r]$ for a partition $\Sigma = \Sigma_\ell \uplus \Sigma_r$.

Lemma 3.20. For a word $s \in \Sigma^*$ which does not contain factor of the form aa with $a \in \Sigma$ (i.e., block(s) = s) there exists a partition $\Sigma = \Sigma_{\ell} \uplus \Sigma_r$ such that $|s[\Sigma_l, \Sigma_r]| \le (3|s|+1)/4$.

Proof. The following probabilistic argument is given in [90]. Let $s = a_1a_2 \cdots a_n$. We put each symbol $a \in \Sigma$ with probability 1/2 into Σ_l and with probability 1/2 into Σ_r . Hence, for every position $1 \le i \le n-1$, the probability that $a_ia_{i+1} \in \Sigma_l\Sigma_r$ is 1/4 (here, we need $a_i \ne a_{i+1}$). By linearity of expectations (for which we do not need independence), the expected number of positions $1 \le i \le n-1$ with $a_ia_{i+1} \in \Sigma_l\Sigma_r$

is (n-1)/4. Hence, there exists a partition $\Sigma = \Sigma_{\ell} \uplus \Sigma_r$ for which there are at least (n-1)/4 many positions $1 \le i \le n-1$ with $a_i a_{i+1} \in \Sigma_l \Sigma_r$. For this partition, we get $|s[\Sigma_l, \Sigma_r]| \le n - (n-1)/4 = (3n+1)/4$. \Box

Next, we show that for an SLP-represented string one can compute a partition as in Lemma 3.20 in linear time:

Lemma 3.21. Assume that the alphabet Σ is an initial segment of the natural numbers. Given an SLP \mathbb{A} over the terminal alphabet Σ such that $s := \operatorname{val}(\mathbb{A}) = \operatorname{block}(\operatorname{val}(\mathbb{A}))$, one can compute in time $\mathcal{O}(|\mathbb{A}|)$ a partition $\Sigma = \Sigma_l \uplus \Sigma_r$ such that $|s[\Sigma_l, \Sigma_r]| \leq (3|s|+1)/4$.

Proof. Let $n = |\mathbb{A}|$. First note that the word $s = \operatorname{val}(\mathbb{A})$ contains at most n many different digrams (= factors of length 2). The argument is similar to the proof of Lemma 3.18: To each digram ab of s we can assign a unique variable A such that ab is a factor of $\operatorname{val}_{\mathbb{A}}(A)$ but ab is not a factor of any word $\operatorname{val}_{\mathbb{A}}(B)$, where B is a variable that occurs in rhs(A). But there are at most $|\operatorname{rhs}(A)| - 1$ such factors. Summing over all variables yields the statement.

Consider Algorithm 2 (CountingDigrams), which computes for each letter $a \in \Sigma$ a list R(a) that contains all pairs (b, v) such that the digram *ab* occurs in *s* and the number of positions $1 \le i \le |s| - 1$ such that s[i, i+1] = ab is equal to v. By the remark in the preceding paragraph, the total number of entries in all lists R(a) ($a \in$ Σ) is bounded by *n*. The algorithm first computes a topological sorting A_1, \ldots, A_m of the variables with respect to the hierarchical order. Then, it computes for every $A_i \in V$ the number v_i of occurrences of A_i in the derivation tree of A. This part of the algorithm is taken from [65]. Next, an array B of at most m entries is computed. This array contains all triples (a, b, i), where $rhs(A_i) = A_i A_k$ (for some j, k < i), the last symbol of val_A(A_i) is a and the first symbol of val_A(A_k) is b. Note that for each occurrence of *ab* in *s* there exists a unique node *v* in the derivation tree of \mathbb{A} such that the occurrence of ab is below v, but it is neither below the left child of vnor below the right child of v. If v is labeled with A_i and $rhs(A_i) = A_j A_k$, then the last (respectively, first) symbol of A_i (respectively, A_k) must be a (respectively, b). Hence, the total number of occurrences of ab in s is the sum of all numbers v_i such that (a, b, i) occurs in the array R.

In order to compute the lists R(a), the array *B* is sorted using radix sort on the lexicographic order on $\Sigma \times \Sigma$ (the first two components from *B*-entries), where the second Σ -component has higher priority. Radix sort is an algorithm that allows to sort an array of *m* many *k*-ary numbers having *d* digits in time $\mathcal{O}(dm + dk)$ on a RAM, see [42]. To apply radix sort in our situation, we need the assumption that the alphabet Σ is an initial segment of natural numbers, see also [90]. Then, radix sort needs time $\mathcal{O}(m + |\Sigma|) \leq \mathcal{O}(|\mathbb{A}|)$ to sort the array *B*. From the sorted array *C* it is easy to compute the lists R(a) for all $a \in \Sigma$ in a single pass over *C*.

Completely analogous to the lists R(a), one can also compute in linear time lists L(a) ($a \in \Sigma$), where L(a) contains all pairs (b, v) such that the digram *ba* occurs in *s* and the number of positions $1 \le i \le |s| - 1$ such that s[i, i+1] = ab is equal to *v*. Both lists R(a) and L(a) are needed in Algorithm 3 (ComputePartition) (see again

Algorithm 2: CountingDigramms

```
Data: SLP \mathbb{A} = (V, \Sigma, S, \text{rhs}) with val(\mathbb{A}) = block(val(\mathbb{A}))
transform A into Chomsky normal form in time \mathcal{O}(|A|)
let A_1, A_2, \ldots, A_m be an enumeration of V in hierarchical order
for i := 1 to m - 1 do
v_i := 0
end
v_m := 1
for i := m downto 2 do
     if rhs(A_i) = A_j A_k then
         v_j := v_j + v_i
         v_k := v_k + v_i
     end
end
c := 0
for i := 1 to m do
     if rhs(A_i) = a \in \Sigma then
        first(i) := a; last(i) := a
      else
          let rhs(A_i) = A_i A_k with j, k < i
          first(i) := first(j); last(i) := last(k)
          a := \mathsf{last}(j); b := \mathsf{first}(k)
          c := c + 1
          B[c] := (a, b, i)
     end
end
sort array B using radix sort on the lexicographic order on tuples from \Sigma \times \Sigma \times \{1, ..., m\},
ignoring the last component, and let C be the resulting array (of length c \le m)
for a \in \Sigma do
 R(a) := empty list
end
for i := 1 to c do
     \operatorname{let} C[i] = (a, b, i)
     if i = 1 or C[i-1] is not of the form (a,b,j) for some j then
          append to R(a) the entry (b, v_i)
      else
          let the last entry in R(a) be (b, v)
          replace this entry by (b, v + v_i)
     end
end
```

[90]) for computing a partition $\Sigma = \Sigma_l \uplus \Sigma_r$. The two sets Σ_l and Σ_r are stored as bit maps, i.e., arrays of length $|\Sigma|$, where the *a*-th array entry is 0 or 1, depending on whether *a* belongs to Σ_l (respectively, Σ_r). Here, we need again the assumption that $\Sigma = \{1, ..., |\Sigma|\}$.

Compute Partition first computes in a greedy way a partition $\Sigma = \Sigma_l \uplus \Sigma_r$ such that the number of positions $1 \le i \le |s| - 1$ with $s[i, i + 1] \in \Sigma_l \Sigma_r \cup \Sigma_r \Sigma_l$ is at least (|s| - 1)/2. For this the algorithm goes over all symbols from Σ and makes for every $a \in \Sigma$ a greedy choice. If for the current sets Σ_l and Σ_r the number of occurrences of digrams from $a\Sigma_r \cup \Sigma_r a$ is at least as large as the number of occurrences of digrams

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Algorithm 3: ComputePartition(A)

```
Data: SLP \mathbb{A} = (V, \Sigma, S, \text{rhs}) with val(\mathbb{A}) = block(val(\mathbb{A}))
compute list L(a) and R(a) for all a \in \Sigma using Algorithm 2
\Sigma_l := \emptyset; \Sigma_r := \emptyset; \Gamma := \emptyset
for a \in \Sigma do
 l_a := 0; r_a := 0
end
for a \in \Sigma do
      if r_a \ge l_a then
              \Sigma_l := \Sigma_l \cup \{a\}
              for (b, v) \in L(a) do
               l_b := l_b + v
              end
              for (b, v) \in R(a) do
                l_b := l_b + v
              end
       else
              \Sigma_r := \Sigma_r \cup \{a\}
              for (b, v) \in L(a) do
               r_b := r_b + v
              end
              for (b, v) \in R(a) do
               r_b := r_b + v
              end
       end
end
if \sum_{a \in \Sigma_r} \sum_{(b,v) \in (\Sigma_l \times \mathbb{N}) \cap R(a)} v > \sum_{a \in \Sigma_l} \sum_{(b,v) \in (\Sigma_r \times \mathbb{N}) \cap R(a)} v then | (\Sigma_l, \Sigma_r) := (\Sigma_r, \Sigma_l)
end
```

from $a\Sigma_l \cup \Sigma_l a$, then the algorithm puts *a* into Σ_l , otherwise *a* is put into Σ_r . To make this choice, the algorithm stores (and correctly updates) the number of occurrences of digrams from $a\Sigma_r \cup \Sigma_r a$ (resp., $a\Sigma_l \cup \Sigma_l a$) in the variable r_a (resp., l_a). These variables are updated using the lists L(a) and R(a).

Since the number of positions $1 \le i \le |s| - 1$ with $s[i, i + 1] \in \Sigma_l \Sigma_r \cup \Sigma_r \Sigma_l$ is at least (|s| - 1)/2, there exist at least (|s| - 1)/4 positions *i* with $s[i, i + 1] \in \Sigma_l \Sigma_r$ or there exist at least (|s| - 1)/4 positions *i* with $s[i, i + 1] \in \Sigma_r \Sigma_l$. The last if-statement in Algorithm 3 selects the partition which yields more digram occurrences. Note that the sum $\sum_{a \in \Sigma_r} \sum_{(b,v) \in (\Sigma_l \times \mathbb{N}) \cap R(a)} v$ can be computed in linear time since the sets Σ_l and Σ_r are stored as bit maps and the total length of all lists R(a) is at most *n*. A similar remark applies to the sum $\sum_{a \in \Sigma_l} \sum_{(b,v) \in (\Sigma_r \times \mathbb{N}) \cap R(a)} v$. \Box

Since we have to deal with two SLPs that have to be checked for equality, we need a simple adaptation of Lemma 3.21 for two SLPs:

Lemma 3.22. There is an algorithm ComputePartition(\mathbb{A}, \mathbb{B}) that computes for given SLPs \mathbb{A} and \mathbb{B} over the terminal alphabet Σ with $s := val(\mathbb{A}) = block(val(\mathbb{A}))$ and $t := val(\mathbb{B}) = block(val(\mathbb{B}))$ in time $\mathcal{O}(|\mathbb{A}| + |\mathbb{B}|)$ a partition such that $|s[\Sigma_l, \Sigma_r]| + |t[\Sigma_l, \Sigma_r]| \leq 3(|s| + |t|)/4 + 5/4$.

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Algorithm 4: CompressPairs($\mathbb{A}, \Sigma_l, \Sigma_r$)

Data: SLP $\mathbb{A} = (V, \Sigma, S, \text{rhs})$ with $val(\mathbb{A}) = block(val(\mathbb{A}))$ and a partition $\Sigma = \Sigma_l \uplus \Sigma_r$. let A_1, A_2, \ldots, A_m be an enumeration of V in hierarchical order for i := 1 to m - 1 do **if** $\operatorname{rhs}(A_i)$ *is of the form* $a\alpha$ *for* $a \in \Sigma_r$ **then** replace every occurrence of A_i in a right-hand side by aA_i $rhs(A_i) := \alpha$ end **if** $rhs(A_i)$ *is of the form* βb *for* $b \in \Sigma_l$ **then** replace every occurrence of A_i in a right-hand side by $A_i b$ $\operatorname{rhs}(A_i) := \beta$ end if $rhs(A_i) = \varepsilon$ then replace every occurrence of A_i in a right-hand side by ε remove A_i from the SLP end end replace every occurrence of a factor $ab \in \Sigma_l \Sigma_r$ in a right-hand side by $\langle ab \rangle$

Proof. By taking the disjoint union of all productions of \mathbb{A} and \mathbb{B} we can easily construct an SLP \mathbb{C} of size $\mathcal{O}(|\mathbb{A}| + |\mathbb{B}|)$ such that $\operatorname{val}(\mathbb{C}) = st =: u$. With Lemma 3.21 we obtain a partition $\Sigma = \Sigma_l \cup \Sigma_r$ such that $|u[\Sigma_l, \Sigma_r]| \le (3|u|+1)/4 = (3(|s|+|t|)+1)/4$. On the other hand, we have $|u[\Sigma_l, \Sigma_r]| \ge |s[\Sigma_l, \Sigma_r]| + |t[\Sigma_l, \Sigma_r]| - 1$. Hence, we get $|s[\Sigma_l, \Sigma_r]| + |t[\Sigma_l, \Sigma_r]| \le 3(|s|+|t|)/4 + 5/4$. \Box

Lemma 3.23. Given an SLP \mathbb{A} over the terminal alphabet Σ such that $val(\mathbb{A}) = block(val(\mathbb{A}))$ and a partition $\Sigma = \Sigma_{\ell} \cup \Sigma_r$ one can compute in time $\mathcal{O}(|\mathbb{A}|)$ an SLP \mathbb{B} such that $val(\mathbb{B}) = val(\mathbb{A})[\Sigma_l, \Sigma_r]$. Moreover, if \mathbb{A} has m variables, then \mathbb{B} has at most m variables and $|\mathbb{B}| \leq |\mathbb{A}| + 4m$.

Proof. Let $\mathbb{A} = (V, \Sigma, S, \text{rhs})$ and let A_1, A_2, \dots, A_m be an enumeration of V that respects the hierarchical order of \mathbb{A} : If A_i occurs in $\text{rhs}(A_j)$ then i < j. We can assume that $S = A_m$. Let a_i (respectively, b_i) be the first (respectively, last) symbol of $\text{val}_{\mathbb{A}}(A_i)$. Consider Algorithm 4 (CompressPairs) and let \mathbb{B} be the output SLP of this algorithm. The proof that $\text{val}(\mathbb{B}) = \text{val}(\mathbb{A})[\Sigma_l, \Sigma_r]$ is similar to the proof of Lemma 3.19.

For a word $w \in \Sigma^*$ define the words $pop_I(w)$ and $pop_r(w)$ as follows:

$pop_l(m{arepsilon}) = m{arepsilon}$	$pop_r(oldsymbol{arepsilon}) = oldsymbol{arepsilon}$
$pop_l(au) = au \text{ for } a \in \Sigma_l, u \in \Sigma^*$	$pop_r(ua) = ua \text{ for } a \in \Sigma_r, u \in \Sigma^*$
$pop_l(au) = u \text{ for } a \in \Sigma_r, u \in \Sigma^*$	$pop_r(ua) = u \text{ for } a \in \Sigma_l, u \in \Sigma^*$

Moreover, let $pop(w) = pop_l(pop_r(w)) = pop_r(pop_l(w))$. Note that for a single symbol *a* we have $pop(a) = \varepsilon$.

Let \mathbb{A}_i be the SLP after *i* iterations of the for-loop $(0 \le i \le m-1)$. Hence, $\mathbb{A}_0 = \mathbb{A}$. By induction on $0 \le i \le m-1$ one can easily prove the following invariants:

Algorithm 5: CheckEquality

```
Data: SLPs \mathbb{A} and \mathbb{B}

while |val(\mathbb{A})| > 1 and |val(\mathbb{B})| > 1 do

\mathbb{A} := \text{CompressBlocks}(\mathbb{A})

\mathbb{B} := \text{CompressBlocks}(\mathbb{B})

let \Gamma be the union of the terminal alphabets of \mathbb{A} and \mathbb{B}

(\Gamma_{l}, \Gamma_{r}) := \text{ComputePartition}(\mathbb{A}, \mathbb{B})

\mathbb{A} := \text{CompressPairs}(\mathbb{A}, \Gamma_{l}, \Gamma_{r})

\mathbb{B} := \text{CompressPairs}(\mathbb{B}, \Gamma_{l}, \Gamma_{r})

end

check whether val(\mathbb{A}) = val(\mathbb{B})
```

- (i) For all 1 ≤ j ≤ i we have: If pop(val_A(A_j)) = ε, then variable A_i does no longer occur in A_i. Otherwise, val_{Ai}(A_j) = pop(val_A(A_j)).
- (ii) For all $i + 1 \le j \le m$ we have $\operatorname{val}_{\mathbb{A}_i}(A_j) = \operatorname{val}_{\mathbb{A}}(A_j)$. Moreover, every occurrence in $\operatorname{rhs}_{\mathbb{A}_i}(A_j)$ of a variable A_k with $1 \le k \le i$ and $a_k \in \Sigma_r$ (respectively, $b_k \in \Sigma_l$) is preceded (respectively, followed) by a_k (respectively, b_k).

Hence, we have $val(\mathbb{A}) = val(\mathbb{A}_{m-1})$. Moreover, for every factorization $\alpha A_i\beta$ of a right-hand side from \mathbb{A}_{m-1} we have:

- Either α does not end with a symbol from Σ_l or $\mathsf{val}_{\mathbb{A}_{m-1}}(A_i)$ does not start with a symbol from Σ_r .
- Either β does not start with a symbol from Σ_r or $\mathsf{val}_{\mathbb{A}_{m-1}}(A_i)$ does not end with a symbol from Σ_l .

This implies that for the final SLP \mathbb{B} , which results from replacing in all righthand sides of \mathbb{A}_m all occurrences of factors $ab \in \Sigma_l \Sigma_r$ by $\langle ab \rangle$, we have $\mathsf{val}(\mathbb{B}) = \mathsf{val}(\mathbb{A})[\Sigma_l, \Sigma_r]$ for every variable.

Note that \mathbb{B} has at most *m* variables (no new variables are introduced) and that the length of a right-hand side of \mathbb{A} increases by at most 4 in the construction of \mathbb{B} : Every right-hand side of \mathbb{A} contains at most two variables, and for each occurrence of a variable in a right-hand side we introduce at most one symbol on the left and right. Hence, we get $|\mathbb{B}| \le |\mathbb{A}| + 4m$. \Box

Proof of Theorem 3.17. Assume that we have two SLPs A and B over the same terminal alphabet Σ and let m := |val(A)| and n := |val(B)|. Moreover, let k (respectively, l) be the number of variables of A (respectively, B). Algorithm 5 (Check-Equality) checks whether val(A) = val(B). Correctness of the algorithm follows from observation (3.2). It remains to analyze the running time of the algorithm. By Lemma 3.22, the number of iterations of the while-loop is bounded by $\mathcal{O}(\log(n + m)) \leq \mathcal{O}(|A| + |B|)$. Let A_i and B_i be the SLPs after i iterations of the while-loop. The number of variables of A_i (respectively, B_i) is at most k (respectively, l). Hence, by Lemma 3.19 and 3.23, the size of A_i (respectively, B_i) can be bounded by $|A| + 4ki \in \mathcal{O}((|A| + |B|)^2)$ (respectively, $|B| + 4li \in \mathcal{O}((|A| + |B|)^2)$). Since the i-th iteration takes time $\mathcal{O}(|A_i| + |B_i|)$, the total running time is $\mathcal{O}((|A| + |B|)^3)$. □

3.5 2-level PCSLPs

For our algorithms in Chapter 5, it is useful to consider PCSLPs, which are divided into two layers.

Definition 3.24 (2-level PCSLP). A 2-level PCSLP is a tuple $\mathbb{A} = (Up, Lo, \Gamma, S, rhs)$ such that the following holds:

- Up, Lo, and Γ are pairwise disjoint finite alphabets, $S \in Up$, and rhs : Up \cup Lo \rightarrow PC(Up \cup Lo, Γ).
- The tuple $(Up, Lo, S, rhs|_{Up})$ is a PCSLP over the terminal alphabet Lo.
- The tuple (Lo, Γ, rhs↾_{Lo}) is an SLP (without start variable) over the terminal alphabet Γ.

The set Up (respectively, Lo) is called the set of *upper level variables* (*lower level variables*) of A. Moreover, we set $V = Up \cup Lo$ and call it the set of variables of A. The PCSLP (Up,Lo,S,rhs \upharpoonright_{Up}) is called the *upper part of* A, briefly up(A), and the SLP (without start variable) (Lo, Γ ,rhs \upharpoonright_{Lo}) is the *lower part of* A, briefly up(A). The upper level evaluation mapping uval_A : PC(Up,Lo) \rightarrow Lo^{*} of A is defined as uval_A = val_{up(A)}. The evaluation mapping val_A is defined by val_A(X) = val_{lo(A)}(val_{up(A)}(X)) for $X \in$ Up and val_A(X) = val_{lo(A)}(X) for $X \in$ Lo. Finally, we set val(A) = val_A(S). We define the size of A as $|A| = \sum_{X \in V} |rhs(X)|$.

Example 3.25. Let $\mathbb{A} = (\{F, G, H\}, \{A, B, C, D, E\}, \{a, b, c\}, H, \text{rhs})$ be a two-level PCSLP with Up = $\{F, G, H\}$ and Lo = $\{A, B, C, D, E\}$, where the mapping rhs defined as follows:

$$\begin{split} \mathrm{rhs}(A) &= a & \mathrm{rhs}(B) = b & \mathrm{rhs}(C) = c \\ \mathrm{rhs}(D) &= AB & \mathrm{rhs}(E) = AC \\ \mathrm{rhs}(F) &= EABCDEA & \\ \mathrm{rhs}(G) &= F[2:6] & \\ \mathrm{rhs}(H) &= \pi_{\{A,C,D\}}(G) \end{split}$$

Then we have

$$\begin{split} \mathsf{up}(\mathbb{A}) &= (\{F,G,H\}, \{A,B,C,D,E\}, H, \mathsf{rhs}\!\upharpoonright_{\mathsf{Up}}) \text{ and } \\ \mathsf{lo}(\mathbb{A}) &= (\{A,B,C,D,E\}, \{a,b,c\}, \mathsf{rhs}\!\upharpoonright_{\mathsf{Lo}}). \end{split}$$

The $uval_A$ -values for the upper level variables are:

$$uval_{\mathbb{A}}(F) = EABCDEA$$

 $uval_{\mathbb{A}}(G) = ABCDE$
 $uval_{\mathbb{A}}(H) = ACD$

The val_A -values for all variables of A are:

3 Algorithms on Compressed Words

$$\begin{split} & \mathsf{val}_{\mathbb{A}}(A) = a \quad \mathsf{val}_{\mathbb{A}}(B) = b \quad \mathsf{val}_{\mathbb{A}}(C) = c \\ & \mathsf{val}_{\mathbb{A}}(D) = ab \quad \mathsf{val}_{\mathbb{A}}(E) = ac \\ & \mathsf{val}_{\mathbb{A}}(F) = \mathsf{val}_{\mathbb{A}}(EABCDEA) = acabcabaca \\ & \mathsf{val}_{\mathbb{A}}(G) = \mathsf{val}_{\mathbb{A}}(ABCDE) = abcabac \\ & \mathsf{val}_{\mathbb{A}}(H) = \mathsf{val}_{\mathbb{A}}(ACD) = acab \end{split}$$

Note that $\mathsf{val}_{\mathbb{A}}(G)$ is different from $\mathsf{val}_{\mathbb{A}}(F)[2:6] = cabca$
Chapter 4 The Compressed Word Problem

In this chapter, we introduce the main topic of this book, namely the compressed word problem for a finitely generated group. This is the variant of the word problem, where the input word is not written down explicitly, but given by an SLP. Since the input word is given in a more succinct way, the compressed word problem for a group G may have a higher computational complexity than the word problem for G, and in Section 4.8 we will see such a group. In Section 4.1 we show that the complexity of the compressed word problem is preserved when going to a finitely generated subgroup or a finite extension. Section 4.2 demonstrates that an efficient algorithm for the compressed word problem for a group G leads to efficient algorithms for (ordinary) word problems for various groups derived from G (automorphism groups, semidirect products, and other group extensions). The remaining Sections 4.3-4.8 study the complexity of the compressed word problem in various classes of groups (finite groups, free groups, finitely generated linear groups, finitely generated nilpotent groups, wreath products).

4.1 The Compressed Word Problem and Basic Closure Properties

Let us start with the definition of the compressed word problem:

Definition 4.1. Let *G* be a finitely generated group and fix a finite generating set Γ for *G*. The *compressed word problem* for *G* with respect to Γ , briefly $CWP(G,\Gamma)$, is the following decision problem:

input: An SLP \mathbb{A} over the terminal alphabet $\Gamma \cup \Gamma^{-1}$. *question:* Does val $(\mathbb{A}) = 1$ hold in *G*?

In $\text{CWP}(G,\Gamma)$, the input size is of course the size $|\mathbb{A}|$ of the SLP \mathbb{A} . As for the (uncompressed) word problem, the complexity of the compressed word problem does not depend on the chosen generating set:

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Lemma 4.2. Let G be a finitely generated group and let Γ and Σ be two generating sets. Then $\text{CWP}(G,\Gamma) \leq_m^{\log} \text{CWP}(G,\Sigma)$.

Proof. Let $G \cong \langle \Gamma | R \rangle \cong \langle \Sigma | S \rangle$. There exists a homomorphism $h : (\Gamma \cup \Gamma^{-1})^* \to (\Sigma \cup \Sigma^{-1})^*$ with $h(a^{-1}) = h(a)^{-1}$ for all $a \in \Gamma \cup \Gamma^{-1}$ that induces an isomorphism from $\langle \Gamma | R \rangle$ to $\langle \Sigma | S \rangle$. Hence, for a word $w \in (\Gamma \cup \Gamma^{-1})^*$ we have w = 1 in $\langle \Gamma | R \rangle$ if and only if h(w) = 1 in $\langle \Sigma | S \rangle$. The lemma follows, since by Proposition 3.9(4) we can compute from a given SLP \mathbb{A} over $\Gamma \cup \Gamma^{-1}$ in logarithmic space an SLP \mathbb{B} over $\Sigma \cup \Sigma^{-1}$ such that $\mathsf{val}(\mathbb{B}) = h(\mathsf{val}(\mathbb{A}))$. This gives a logspace many-one reduction from $\mathsf{CWP}(G, \Gamma)$ to $\mathsf{CWP}(G, \Sigma)$. \Box

By Lemma 4.2, we can just speak about the compressed word problem for G, briefly CWP(G).

Before we consider the compressed word problem in specific groups we prove two preservation results. Recall the reducibility relations from Section 1.3.3. By the following simple proposition, the complexity of the compressed word problem is preserved when going to a finitely generated subgroup:

Proposition 4.3. Assume that *H* is a finitely generated subgroup of the finitely generated group *G*. Then $CWP(H) \leq_m^{\log} CWP(G)$.

Proof. Choose a generating set Γ for G that contains a generating set Σ for H. Then for a word $w \in (\Sigma \cup \Sigma^{-1})^*$ we have w = 1 in H if and only if w = 1 in G. \Box

By the following result from [116], the complexity of the compressed word problem is also preserved when going to a finite extension:

Theorem 4.4. Assume that K is a finitely generated subgroup of the group G such that the index [G:K] is finite (hence, G is finitely generated too). Then $\text{CWP}(G) \leq_m^P \text{CWP}(K)$.

Proof. Let Γ be a finite generating set for K and let Σ be a finite generating set for G. Let $h: (\Sigma \cup \Sigma^{-1})^* \to G$ be the canonical morphism. Let Kg_1, \ldots, Kg_n be a list of the cosets of K, where without loss of generality $g_1 = 1$. Let \mathscr{A} be the coset automaton of K. This is an NFA over the alphabet $\Sigma \cup \Sigma^{-1}$ and with state set $\{Kg_1, \ldots, Kg_n\}$. The initial and final state is $K = Kg_1$ and the triple (Kg_i, a, Kg_j) $(a \in \Sigma \cup \Sigma^{-1})$ is a transition of \mathscr{A} if and only if $Kg_ia = Kg_j$. Note that this automaton accepts a word $w \in (\Sigma \cup \Sigma^{-1})^*$ if and only if $h(w) \in K$. Since by Theorem 3.11 it can be checked in polynomial time whether the word generated by a given SLP is accepted by a given NFA (here, we even have a fixed NFA \mathscr{A}), we can check in polynomial time whether $h(val(\mathbb{A})) \in K$ for a given SLP \mathbb{A} .

Now let $\mathbb{A} = (V, \Sigma \cup \Sigma^{-1}, S, \text{rhs})$ be an SLP in Chomsky normal form over the alphabet $\Sigma \cup \Sigma^{-1}$. We want to check whether $\text{val}(\mathbb{A}) = 1$ in *G*. First, we check in polynomial time, whether $h(\text{val}(\mathbb{A})) \in K$. If not, we reject immediately (formally, since we have to construct a polynomial time many-one reduction from CWP(G) to CWP(K), we should output some fixed SLP over $\Gamma \cup \Gamma^{-1}$ that evaluates to an element of $K \setminus \{1\}$). Otherwise, we will construct in polynomial time an SLP \mathbb{B} over the generating set $\Gamma \cup \Gamma^{-1}$ of *K*, which computes the same group element as \mathbb{A} .

4.2 From the Compressed Word Problem to the Word Problem

The set of variables of \mathbb{B} is the set of triples

$$W = \{ [g_i, A, g_i^{-1}] \mid A \in V, 1 \le i, j \le n, g_i h(\mathsf{val}_A(A)) g_i^{-1} \in K \}.$$

By the above observation, this set can be computed in polynomial time. Now, let us define the right-hand sides for the variables $[g_i, A, g_j^{-1}] \in W$. First, assume that rhs(A) = a, where $a \in \Sigma \cup \Sigma^{-1}$. Hence, $g_i a g_j^{-1} \in K$, and we set $rhs([g_i, A, g_j^{-1}]) = w$, where $w \in (\Gamma \cup \Gamma^{-1})^*$ is such that $h(w) = g_i a g_j^{-1}$ (we do not have to compute this word w; it is a fixed word that does not depend on the input). Now assume that rhs(A) = BC. In polynomial time, we can determine the unique k such that $g_i h(val_A(B))$ belongs to the coset Kg_k . Thus, $g_i h(val_A(B))g_k^{-1} \in K$, i.e., $[g_i, B, g_k^{-1}] \in W$. We set

rhs
$$([g_i, A, g_i^{-1}]) = [g_i, B, g_k^{-1}][g_k, C, g_i^{-1}].$$

Note that

$$g_ih(\mathsf{val}_{\mathbb{A}}(A))g_j^{-1} = g_ih(\mathsf{val}_{\mathbb{A}}(B))g_k^{-1}g_kh(\mathsf{val}_{\mathbb{A}}(C))g_j^{-1}$$

Hence, since $g_ih(val_{\mathbb{A}}(A))g_j^{-1}$ and $g_ih(val_{\mathbb{A}}(B))g_k^{-1}$ both belong to the subgroup K, we also have $g_kh(val_{\mathbb{A}}(C))g_j^{-1} \in K$, i.e., $[g_k, C, g_j^{-1}] \in W$. Finally, let $[g_1, S, g_1^{-1}] = [1, S, 1]$ be the start variable of \mathbb{B} . Since we assume that $h(val(\mathbb{A})) = h(val_{\mathbb{A}}(S)) \in K$, we have $[1, S, 1] \in W$. It is easy to prove that for every variable $[g_i, A, g_j^{-1}] \in W$, $val_{\mathbb{B}}([g_i, A, g_j^{-1}])$ represents the group element $g_ih(val_{\mathbb{A}}(A))g_j^{-1}$. Thus, $val(\mathbb{A}) = 1$ in G if and only if $val(\mathbb{B}) = 1$ in K, which is an instance of CWP(K). This proves the theorem. \Box

The reducibility relation \leq_m^P in Theorem 4.4 cannot be replaced by the stronger relation \leq_m^{\log} (unless $\mathbf{P} = \mathbf{L}$) because there exists a finite group *G* with a **P**-complete compressed word problem, see Theorem 4.10 (take K = 1 in Theorem 4.4).

4.2 From the Compressed Word Problem to the Word Problem

It turns out that an efficient algorithm for the compressed word problem for a group G can be used to solve efficiently the (uncompressed) word problem in certain groups derived from G. Hence, the compressed word problem is useful for the solution of the ordinary word problem. In this section, we present three results of this type. All three results are formulated in terms of certain reducibilities, see Section 1.3.3.

Definition 4.5 (Aut(G)). For a group G, Aut(G) denotes the *automorphism group* of G, which consists of all automorphisms of G with composition of functions as the group operation.

Recall from Definition 1.27 the definition of \leq_{bc}^{log} .

Theorem 4.6 (cf [151]). Let G be a finitely generated group and let H be a finitely generated subgroup of Aut(G). Then $WP(H) \leq_{bc}^{log} CWP(G)$.

Proof. Let Σ be a finite generating set for G, where without loss of generality $a \in \Sigma$ implies $a^{-1} \in \Sigma$. Let H be generated by the finite set $A \subseteq Aut(G)$, where again $\varphi \in A$ implies $\varphi^{-1} \in A$.

For a given input word $\varphi_1 \varphi_2 \cdots \varphi_n$ (with $\varphi_i \in A$ for $1 \le i \le n$ we have to check whether the composition of $\varphi_1, \varphi_2, \ldots, \varphi_n$ (in that order) is the identity isomorphism in order to solve the word problem for *H*. But this is equivalent to $\varphi_n(\varphi_{n-1}(\cdots \varphi_1(a)\cdots)) = a$ in *G* for all $a \in \Sigma$.

Since Σ is closed under inverses, every $\varphi \in A$ can be viewed as a homomorphism on Σ^* . Hence, by Lemma 3.12 we can compute in logarithmic space an SLP \mathbb{A}_a over the alphabet Σ such that $val(\mathbb{A}_a) = \varphi_n(\varphi_{n-1}(\cdots \varphi_1(a) \cdots))a^{-1}$. Thus, the composition of $\varphi_1, \varphi_2, \ldots, \varphi_n$ is the identity if and only if for all $a \in \Sigma$, $val(\mathbb{A}_a) = 1$ in *G*. Since $|\Sigma|$ is a constant in our consideration, we obtain $WP(H) \leq_{bc}^{\log} CWP(G)$. \Box

It should be noted that there are finitely generated (even finitely presented) groups G, where Aut(G) is not finitely generated, see e.g. [105]. Therefore, we restrict in Theorem 4.6 to a finitely generated subgroup of Aut(G).

Definition 4.7 (semidirect product). Let *K* and *Q* be groups and let $\varphi : Q \to \operatorname{Aut}(K)$ be a group homomorphism. Then the *semidirect product* $K \rtimes_{\varphi} Q$ is the group with the domain $K \times Q$ and the following multiplication: $(k,q)(\ell,p) = (k \cdot (\varphi(q)(\ell)), qp)$, where \cdot denotes the multiplication in *K* (note that $\varphi(q) \in \operatorname{Aut}(K)$ and hence $\varphi(q)(\ell) \in K$).

The following result is stated in [116].

Theorem 4.8. Let *K* and *Q* be finitely generated groups and let $\varphi : Q \to \operatorname{Aut}(K)$ be a homomorphism. Then, for the semidirect product $K \rtimes_{\varphi} Q$ we have $\operatorname{WP}(K \rtimes_{\varphi} Q) \leq_m^{\log} \{\operatorname{WP}(Q), \operatorname{CWP}(K)\}$.

Proof. Let us consider a word $(k_1, q_1)(k_2, q_2) \cdots (k_n, q_n)$, where k_i (respectively, q_i) is a generator of K (respectively, Q). In $K \rtimes_{\varphi} Q$ we have

 $(k_1,q_1)(k_2,q_2)\cdots(k_n,q_n) = (\theta_1(k_1)\theta_2(k_2)\cdots\theta_n(k_n),q_1q_2\cdots q_n),$

where $\theta_i \in Aut(K)$ is the automorphism defined by

$$\theta_i = \varphi(q_1 \cdots q_{i-1}) = \varphi(q_1) \cdots \varphi(q_{i-1})$$

for $1 \le i \le n$ (note that $\theta_1 = id_K$). By Lemma 3.12, we can compute in logarithmic space an SLP \mathbb{A} over the generators of K, which produces the word $\theta_1(k_1)\theta_2(k_2)\cdots\theta_n(k_n)$. We have $(k_1,q_1)(k_2,q_2)\cdots(k_n,q_n) = 1$ in $K \rtimes_{\varphi} Q$ if and only if $q_1q_2\cdots q_n = 1$ in Q and $val(\mathbb{A}) = 1$ in K. This proves the proposition. \Box

The semidirect product $G = K \rtimes_{\varphi} Q$ is a an extension of K by Q, i.e., K is a normal subgroup of G with quotient $G/K \simeq Q$. A reasonable generalization of Theorem 4.8

4.2 From the Compressed Word Problem to the Word Problem

would be WP(G) \leq_m^{\log} (WP(G/K), CWP(K)). But this cannot be true: there exist finitely generated groups G, Q, and K such that (i) Q = G/K, (ii) Q and K have computable word problems, and (iii) G has an undecidable word problem [14]. On the other hand, if we require additionally, that Q is finitely presented (in fact, Qrecursively presented suffices), then G must have a computable word problem [36]. For the special case that the quotient Q = G/K has a polynomial time word search problem (see Definition 2.24), we can prove the following:

Theorem 4.9. Let *K* be a finitely generated normal subgroup of *G* such that the quotient Q = G/K is finitely presented, has a polynomial Dehn function, and WSP(Q) can be solved in polynomial time. Then WP(G) $\leq_m^P \text{CWP}(K)$.

Proof. Let Σ be a finite generating set for K and let $Q = G/K = \langle \Gamma | R \rangle$ with Γ a finite generating set for Q and $R \subseteq (\Gamma \cup \Gamma^{-1})^*$ a finite set of relators for Q. Let $\varphi : G \to Q$ be the canonical surjective homomorphism and choose a mapping $h : Q \to G$ with h(1) = 1 and $\varphi(h(a)) = a$ for $a \in Q$. The set $\Sigma \cup h(\Gamma)$ generates G and there exists a so called factor set $f : Q \times Q \to K$ such that h(a)h(b) = f(a,b)h(ab) for $a, b \in Q$. Note that in general h is not a homomorphism.

Let us take a word $w \in (\Sigma \cup \Sigma^{-1} \cup h(\Gamma \cup \Gamma^{-1}))^*$ and factorize *w* as

 $w = w_0 h(a_1) w_1 h(a_2) \cdots w_{n-1} h(a_n) w_n$

with $w_i \in (\Sigma \cup \Sigma^{-1})^*$ $(0 \le i \le n)$ and $a_i \in \Gamma \cup \Gamma^{-1}$ $(1 \le i \le n)$.

The word $a_1a_2 \cdots a_n \in (\Gamma \cup \Gamma^{-1})^*$ represents the group element $\varphi(w) \in Q$. In a first step, we check in polynomial time, whether $\varphi(w) = 1$ in Q. Note that WP(Q) can be solved in polynomial time, since it reduces to WSP(Q).

If $\varphi(w) \neq 1$ in Q, we know that $w \neq 1$ in G. Hence, assume that $\varphi(w) = a_1 a_2 \cdots a_n = 1$ in Q for the rest of the proof. Hence, w represents an element of the normal subgroup K. Our goal will be to construct in polynomial time an SLP \mathbb{C} over the alphabet $\Sigma \cup \Sigma^{-1}$ such that $w = \text{val}(\mathbb{C})$ in G. Hence, w = 1 in G if and only if $\text{val}(\mathbb{C}) = 1$ in K.

We first construct in polynomial time (using WSP(Q)) a representation

$$a_1 a_2 \cdots a_n = \prod_{i=1}^m u_i r_i u_i^{-1} \text{ in the free group } F(\Gamma), \qquad (4.1)$$

where $r_1, \ldots, r_m \in R \cup R^{-1}$ are relators or inverse relators for Q.

Consider the semi-Thue system

$$S = \{(aa^{-1}, \varepsilon), (\varepsilon, aa^{-1}) \mid a \in \Gamma \cup \Gamma^{-1}\} \cup \{(r, \varepsilon) \mid r \in R \cup R^{-1}\}.$$

For every rule $(v,w) \in S$, we have $\varphi(h(v)) = \varphi(h(w))$ in Q; here h is extended to a homomorphism $h : (\Gamma \cup \Gamma^{-1})^* \to G$. Hence, there exists a word $s_{v,w} \in (\Sigma \cup \Sigma^{-1})^*$ such that $h(v) = h(w)s_{v,w}$ in G. Let us fix these words $s_{v,w}$.

Using the identity (4.1), we can construct in polynomial time a derivation

$$a_1 a_2 \cdots a_n = u_0 \to_S u_1 \to_S u_2 \to_S \cdots \to_S u_k = \varepsilon \tag{4.2}$$

of polynomial length in *n*.

Note that $h(a_1)h(a_2)\cdots h(a_n)$ represents an element of *K* in *G*. Using the derivation (4.2), we will compute in polynomial time an SLP \mathbb{A} over $\Sigma \cup \Sigma^{-1}$ (the monoid generating set of the normal subgroup *K*) such that in the group *G* we have

$$h(a_1)h(a_2)\cdots h(a_n) = \mathsf{val}(\mathbb{A}). \tag{4.3}$$

For this, we will compute for every $0 \le i \le k$ an SLP \mathbb{A}_i over $\Sigma \cup \Sigma^{-1}$ such that

$$h(a_1)h(a_2)\cdots h(a_n) = h(u_i) \operatorname{val}(\mathbb{A}_i)$$

in the group *G*. Clearly, for \mathbb{A}_0 we choose an SLP that generates the empty word. For the induction step, let us take $0 \le i < k$ and assume that we have an SLP \mathbb{A}_i such that $h(a_1)h(a_2)\cdots h(a_n) = h(u_i) \operatorname{val}(\mathbb{A}_i)$ in the group *G*. Since $u_i \to_S u_{i+1}$ there exists a rule $(v, w) \in S$ and $x, y \in (\Gamma \cup \Gamma^{-1})^*$ such that $u_i = xvy$ and $u_{i+1} = xwy$. Since $h(v) = h(w)s_{v,w}$ in *G*, we get

$$h(u_{i}) = h(x)h(v)h(y)$$

= $h(x)h(w)s_{v,w}h(y)$
= $h(x)h(w)h(y)(h(y)^{-1}s_{v,w}h(y))$
= $h(u_{i+1})(h(y)^{-1}s_{v,w}h(y))$

in the group *G*. Since *K* is a normal subgroup of *G*, the word $h(y)^{-1}s_{v,w}h(y)$ can be certainly rewritten as a word over $\Sigma \cup \Sigma^{-1}$. At this point, we need the following claim:

Claim. Given words $h(b_1)h(b_2)\cdots h(b_j)$ with $b_1,\ldots,b_j \in \Gamma \cup \Gamma^{-1}$ and $c_1c_2\cdots c_\ell \in (\Sigma \cup \Sigma^{-1})^*$, we can construct in polynomial time an SLP \mathbb{B} over $\Sigma \cup \Sigma^{-1}$ such that

$$h(b_j)^{-1}\cdots h(b_2)^{-1}h(b_1)^{-1}c_1c_2\cdots c_\ell h(b_1)h(b_2)\cdots h(b_j) = val(\mathbb{B})$$

in the group G.

Proof of the claim. It suffices to construct in polynomial time SLPs \mathbb{B}_i such that

$$h(b_j)^{-1}\cdots h(b_2)^{-1}h(b_1)^{-1}c_ih(b_1)h(b_2)\cdots h(b_j) = val(\mathbb{B}_i)$$

in the group *G*. Then \mathbb{B} can be defined as an SLP that generates the concatenation $val(\mathbb{B}_1)\cdots val(\mathbb{B}_\ell)$.

For $b \in \Gamma \cup \Gamma^{-1}$ let $\psi_b : K \to K$ be the automorphism of K defined by $\psi_b(x) = h(b)^{-1}xh(b)$. Thus, we have

$$h(b_j)^{-1}\cdots h(b_2)^{-1}h(b_1)^{-1}c_ih(b_1)h(b_2)\cdots h(b_j) = \psi_{b_j}(\cdots \psi_{b_2}(\psi_{b_1}(c_i))\cdots)$$

An application of Lemma 3.12 therefore proves the claim.

Using our claim, we can construct in polynomial time an SLP $\mathbb B$ over $\Sigma\cup\Sigma^{-1}$ such that

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$$h(y)^{-1}s_{v,w}h(y) = val(\mathbb{B})$$

in the group G (note that the word y is a suffix of the word u_i that was constructed in polynomial time before). Hence, in the group G we have

$$\begin{split} h(a_1)h(a_2)\cdots h(a_n) &= h(u_i) \text{val}(\mathbb{A}_i) \\ &= h(u_{i+1})(h(y)^{-1}s_{v,w}h(y))\text{val}(\mathbb{A}_i) \\ &= h(u_{i+1})\text{val}(\mathbb{B})\text{val}(\mathbb{A}_i). \end{split}$$

Hence, we can define \mathbb{A}_{i+1} as an SLP that produces the concatenation $val(\mathbb{B})val(\mathbb{A}_i)$. Now, we can finish the proof of the theorem. We have

$$w = w_0 h(a_1) w_1 h(a_2) w_2 h(a_3) \cdots w_{n-1} h(a_n) w_n$$

= $w_0 (h(a_1) w_1 h(a_1)^{-1}) (h(a_1) h(a_2) w_2 h(a_2)^{-1} h(a_1)^{-1}) \cdots (h(a_1) \cdots h(a_n) w_n h(a_n)^{-1} \cdots h(a_1)^{-1}) (h(a_1) \cdots h(a_n))$

in the group *G*. Using our claim, we can compute in polynomial time for every $1 \le i \le n$ an SLP \mathbb{B}_i over $\Sigma \cup \Sigma^{-1}$ such that

$$w = w_0 \operatorname{val}(\mathbb{B}_1) \cdots \operatorname{val}(\mathbb{B}_n)(h(a_1) \cdots h(a_n)) \stackrel{(4.3)}{=} w_0 \operatorname{val}(\mathbb{B}_1) \cdots \operatorname{val}(\mathbb{B}_n) \operatorname{val}(\mathbb{A}),$$

where the SLP \mathbb{A} over $\Sigma \cup \Sigma^{-1}$ was computed in polynomial time before. Hence, to check whether w = 1 in K, it suffices to check whether $w_0 val(\mathbb{B}_1) \cdots val(\mathbb{B}_n)val(\mathbb{A}) = 1$ in the normal subgroup K. But this is an instance of CWP(K), since one can easily construct an SLP for $w_0val(\mathbb{B}_1) \cdots val(\mathbb{B}_n)val(\mathbb{A})$ from $w_0, \mathbb{B}_1, \dots, \mathbb{B}_n$, and \mathbb{A} . This concludes the proof. \Box

Theorem 4.9 is stated in [116] for the special case that Q is an automatic group.

4.3 The Compressed Word Problem in Finite Groups

The simplest finitely generated groups are the finite groups. So let us continue our investigations on the compressed word problem with finite groups.

Theorem 4.10. For every finite group G, CWP(G) can be solved in polynomial time. Moreover, if G is a non-solvable finite group, then CWP(G) is **P**-complete.

Proof. The first statement is an immediate corollary of Theorem 3.11: Choose *G* is the generating set for *G*. The set of all words over *G* that evaluate to the identity in the finite group can be accepted by a finite automaton (with state set *G*). Hence, for a given SLP \mathbb{A} over the alphabet *G* we can check in polynomial time, whether val(\mathbb{A}) evaluates to the identity of *G*.

The second statement is implicitly shown in [15] and is based on Barrington's proof of NC^1 -completeness of the word problem for a finite non-solvable group

[11]. Let *G* be a finite non-solvable group. Hence, there exists a subgroup *H* such that H = [H,H] ([H,H] is the commutator subgroup of *G*, i.e., the subgroup generated by all commutators $aba^{-1}b^{-1}$ with $a, b \in G$). We can without loss of generality assume that G = H and thus G = [G,G]. We choose the generating set $G \setminus \{1\}$ for *G*. We prove **P**-hardness of CWP(*G*) by a reduction from circuit value problem, see Example 1.40. So, let \mathscr{C} be a boolean circuit. Since \vee can be expressed with \wedge and \neg , we can assume that \mathscr{C} has no \vee -gates. We now construct an SLP \mathbb{A} as follows: For every gate *A* of the circuit \mathscr{C} and every non-trivial group element $g \in G \setminus \{1\}$ we introduce a variable A_g in the SLP \mathbb{A} . We will have $val_{\mathbb{A}}(A_g) = 1$ in *G* if gate *A* evaluates to 0 and $val_{\mathbb{A}}(A_g) = g$ in *G* if gate *A* is labeled with 0 and $rhs(A_g) = g$ if gate *A* is labeled with 1. Next, assume that *A* is a \neg -gate and let *B* be the unique input gate for *A*. We set $rhs(A_g) = B_{g^{-1}g}$. Finally, let *A* be an \wedge -gate and let *B* and *C* be the two input gates for *A*. Since G = [G,G], we can write *g* as a product of commutators $g = \prod_{i=1}^{n} (g_i^{-1}h_i^{-1}g_ih_i)$, where without loss of generality $n \leq |G|$ (which is a constant in our consideration) and $g_1, h_1, \ldots, g_n, h_n \in G \setminus \{1\}$. We define

rhs
$$(A_g) = \prod_{i=1}^n (B_{g_i^{-1}} C_{h_i^{-1}} B_{g_i} C_{h_i}).$$

Note that if *B* evaluates to 0, then for all $1 \le i \le n$, $\mathsf{val}_{\mathbb{A}}(B_{g_i^{-1}}) = \mathsf{val}_{\mathbb{A}}(B_{g_i}) = 1$ in the group *G*. Hence, also

$$\mathsf{val}_{\mathbb{A}}(B_{g_i^{-1}})\mathsf{val}_{\mathbb{A}}(C_{h_i^{-1}})\mathsf{val}_{\mathbb{A}}(B_{g_i})\mathsf{val}_{\mathbb{A}}(C_{h_i}) = 1$$

in *G* and thus $\operatorname{val}_{\mathbb{A}}(A_g) = 1$ in *G*. If *C* evaluates to 0, we can argue analogously. On the other hand, if both *B* and *C* evaluate to 1, then for all $1 \le i \le n$,

$$\mathsf{val}_{\mathbb{A}}(B_{g_{i}^{-1}})\mathsf{val}_{\mathbb{A}}(C_{h_{i}^{-1}})\mathsf{val}_{\mathbb{A}}(B_{g_{i}})\mathsf{val}_{\mathbb{A}}(C_{h_{i}}) = g_{i}^{-1}h_{i}^{-1}g_{i}h_{i}$$

in G. Hence, $\operatorname{val}_{\mathbb{A}}(A_g) = g$ in G.

Finally, if *O* is the output gate of the circuit \mathscr{C} , then we add a new variable *S* to \mathbb{A} (the start variable) and set $\operatorname{rhs}_{\mathbb{A}} = O_g g^{-1}$ for an arbitrary $g \in G \setminus \{1\}$. We get $\operatorname{val}(\mathbb{A}) = 1$ in *G* if and only if the circuit \mathscr{C} evaluates to 1. It is not hard to show that the SLP \mathbb{A} can be constructed with a logspace transducer from the circuit \mathscr{C} . \Box

From Theorem 4.10 it follows that there exists a fixed regular language *L* for which it is **P**-complete to check whether $val(\mathbb{A}) \in L$ for a given SLP \mathbb{A} (see the remark after Theorem 3.11): Take any non-solvable finite group *G* (e.g., $G = A_5$). Then the set of all words over $G \setminus \{1\}$ whose product in *G* is 1 is a regular language.

For a finite solvable group, the compressed word problem is unlikely to be **P**-hard. Theorem 4.2 from [15] implies that the compressed word problem for a finite solvable group belongs to the complexity class **DET**, which is the class of all problems that are \mathbf{NC}^1 -reducible to the problem of computing the determinant of a given integer matrix. It is known that **DET** \subseteq **NC**²; see [163] for more details concerning these classes.

4.4 The Compressed Word Problem in Free Groups

In this section, we prove that the compressed word problem for a free group can be solved in polynomial time. This was shown in [110]. Later, we will prove more general results (see Chapter 5.1). Nevertheless, we decided to present details for the free group case since it shows the principal ideas for other more technical constructions in Chapter 5.1 and 6. Recall the definition of CSLPs (Definition 3.3).

Theorem 4.11. *The compressed word problem for a finitely generated free group belongs to* **P***.*

Proof. Consider a free group $F(\Gamma)$ with Γ finite, and let $\mathbb{A} = (V, \Gamma \cup \Gamma^{-1}, S, \operatorname{rhs}_{\mathbb{A}})$ be an SLP in Chomsky normal form over the terminal alphabet $\Gamma \cup \Gamma^{-1}$. We will compute in polynomial time a CSLP $\mathbb{B} = (V, \Gamma \cup \Gamma^{-1}, S, \operatorname{rhs}_{\mathbb{B}})$ such that $\operatorname{val}(\mathbb{B}) = \operatorname{NF}(\operatorname{val}(\mathbb{A}))$ (recall the definition of the normal form mapping NF from Section 2.1). By Theorem 3.14 one can transform in polynomial time \mathbb{B} into an equivalent SLP \mathbb{B}' . Then, $\operatorname{val}(\mathbb{A}) = 1$ in $F(\Gamma)$ if and only if $\operatorname{val}(\mathbb{B}') = \varepsilon$, which can be easily checked in polynomial time. The right-hand side mapping $\operatorname{rhs}_{\mathbb{B}}$ will be defined inductively over the hierarchical order of \mathbb{A} in such a way that $\operatorname{val}_{\mathbb{B}}(A) = \operatorname{NF}(\operatorname{val}_{\mathbb{A}}(A))$ for every $A \in V$.

Consider a variable $A \in V$. If $\operatorname{rhs}_{\mathbb{A}}(A) = a \in \Gamma \cup \Gamma^{-1}$, then we set $\operatorname{rhs}_{\mathbb{B}}(A) = a$. Now assume that $\operatorname{rhs}_{\mathbb{A}}(A) = BC$ for variables $B, C \in V$. So, for the current CSLP \mathbb{B} we already have $\operatorname{val}_{\mathbb{B}}(B) = \operatorname{NF}(\operatorname{val}_{\mathbb{A}}(B))$ and $\operatorname{val}_{\mathbb{B}}(C) = \operatorname{NF}(\operatorname{val}_{\mathbb{A}}(C))$. Using Theorem 3.14 for the current CSLP \mathbb{B} , we can construct in polynomial time two SLPs \mathbb{B}_B and \mathbb{B}_C such that $\operatorname{val}_{\mathbb{B}}(B) = \operatorname{val}(\mathbb{B}_B)$ and $\operatorname{val}_{\mathbb{B}}(C) = \operatorname{val}(\mathbb{B}_C)$.

Let $\operatorname{val}(\mathbb{B}_B) = u$ and $\operatorname{val}(\mathbb{B}_C) = v$. By Proposition 3.9(2) we can compute the lengths m = |u| and n = |v| in polynomial time. Let x be the longest word such that there exist u' and v' with u = u'x and $v = x^{-1}v'$. Then, $\operatorname{NF}(\operatorname{val}_{\mathbb{A}}(A)) = u'v'$. If we can compute the length k = |x| in polynomial time, then we can define $\operatorname{rhs}_{\mathbb{B}}(A) = B[1:m-k]C[k+1:n]$.

Hence, it remains to compute the length of *x* in polynomial time. This can be done using a binary search approach. First, from the SLP \mathbb{B}_B we can easily compute (by inverting all right-hand sides) an SLP \mathbb{B}'_B such that $\operatorname{val}(\mathbb{B}'_B) = u^{-1}$. Then, it remains to compute the length of the longest common prefix of $\operatorname{val}(\mathbb{B}'_B)$ and $\operatorname{val}(\mathbb{B}_C)$. We first check in polynomial time whether $\operatorname{val}(\mathbb{B}'_B) = \operatorname{val}(\mathbb{B}_C)$ using Theorem 3.17. If this holds, then |x| = m = n. Now assume that $\operatorname{val}(\mathbb{B}'_B) \neq \operatorname{val}(\mathbb{B}_C)$. We can assume that m = n is a power of 2. If e.g. $m \leq n$ and 2^e is the smallest power of 2 that is at least *n*, then modify \mathbb{B}'_B and \mathbb{B}_C such that they generate words $u^{-1}b^{2^e-m}$ and vb^{2^e-n} where $b \notin \Gamma \cup \Gamma^{-1}$ is a new symbol.

So, assume that $m = n = 2^e$. Note that $2^e \le 2n$. We start our binary search with $\ell = p = 2^{e-1}$ and check in polynomial time (using Theorem 3.17 and 3.14) whether $\operatorname{val}(\mathbb{B}'_B)[1:\ell] = \operatorname{val}(\mathbb{B}_C)[1:\ell]$. If this is true, we set p := p/2 and $\ell := \ell + p$, otherwise set p := p/2 and $\ell := \ell - p$. We continue until p = 1/2, then ℓ is the length of *x*. The number of iterations is $e \in \mathcal{O}(\log n)$ and hence bounded by $\mathcal{O}(|\mathbb{A}|)$. This proves the theorem. \Box

Schleimer proved a far reaching generalization of Theorem 4.11:

Theorem 4.12 (cf. [152]). For every word hyperbolic group G, CWP(G) can be solved in polynomial time.

In Chapter 5.1 we prove another generalization of Theorem 4.11: For every graph group G, CWP(G) can be solved in polynomial time (Corollary 5.6).

We can also show that the compressed word problem for a free group of rank at least 2 is **P**-complete:

Theorem 4.13. *The compressed word problem for a finitely generated free group of rank at least 2 is* **P***-complete.*

Proof. It suffices to prove **P**-hardness for $F_2 = F(\{a, b\})$, which will be done by a reduction from the monotone circuit value problem, see Example 1.40. Let $\Gamma = \{a, b\}$.

Robinson has shown in [148, Theorem 6.3] that the (uncompressed) word problem for F_2 is **NC**¹-hard. We will use the following facts from his proof: Let $x, y \in (\Gamma \cup \Gamma^{-1})^*$ such that |x| = |y| = k and $|x|_a - |x|_{a^{-1}} = |y|_a - |y|_{a^{-1}} = 0$. Then, if we interpret *x* and *y* as elements from F_2 , the following holds:

$$\begin{aligned} &(x=1) \lor (y=1) &\Leftrightarrow a^{-3k}xa^{3k}ya^{-3k}x^{-1}a^{3k}y^{-1} = 1 \\ &(x=1) \land (y=1) &\Leftrightarrow a^{-3k}xa^{3k}ya^{-3k}xa^{3k}y = 1 \end{aligned}$$

Note that the words on the right of these equivalences have length 16k and that the number of *a*'s minus the number of a^{-1} 's is again 0.

Now let \mathscr{C} be a monotone Boolean circuit. Without loss of generality we can assume that \mathscr{C} is layered, i.e., the gates of \mathscr{C} are partitioned into *n* layers and a gate in layer i > 1 receives its inputs from layer i - 1 see, e.g., [67, Problem A.1.6]. Layer 1 contains the input gates and layer *n* contains the unique output gate. We now construct an SLP \mathbb{A} as follows. For every gate *z* of \mathscr{C} , *G* contains two variables A_z and $A_{z^{-1}}$. We will have $\operatorname{val}_{\mathbb{A}}(A_z) = 1$ in F_2 if and only if gate *z* of the circuit evaluates to 1. The variable $A_{z^{-1}}$ evaluates to the inverse of $\operatorname{val}_{\mathbb{A}}(A_z)$ in F_2 . Moreover, we will have $|\operatorname{val}_{\mathbb{A}}(A_z)| = |\operatorname{val}_{\mathbb{A}}(A_{z^{-1}})| = 2 \cdot 16^{i-1}$ if *z* is located in the *i*-th layer of the circuit $(1 \le i \le n)$.

For every input gate x in layer 1 we define the right-hand sides of A_x and $A_{x^{-1}}$ as follows:

$$\operatorname{rhs}(A_x) = \begin{cases} aa^{-1} & \text{if gate } x \text{ is labeled with } 1\\ b^2 & \text{if gate } x \text{ is labeled with } 0 \end{cases}$$
$$\operatorname{rhs}(A_{x^{-1}}) = \begin{cases} aa^{-1} & \text{if gate } x \text{ is labeled with } 1\\ b^{-2} & \text{if gate } x \text{ is labeled with } 0 \end{cases}$$

If z is an \lor -gate in the *i*-th layer ($i \ge 2$) with input gates x and y from the (i-1)-th layer, then the right-hand sides for A_z and $A_{z^{-1}}$ are

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$$\operatorname{rhs}(A_z) = a^{-6 \cdot 16^{i-2}} A_x a^{6 \cdot 16^{i-2}} A_y a^{-6 \cdot 16^{i-2}} A_{x^{-1}} a^{6 \cdot 16^{i-2}} A_{y^{-1}} \text{ and}$$

$$\operatorname{rhs}(A_{z^{-1}}) = A_y a^{-6 \cdot 16^{i-2}} A_x a^{6 \cdot 16^{i-2}} A_{y^{-1}} a^{-6 \cdot 16^{i-2}} A_{x^{-1}} a^{6 \cdot 16^{i-2}}.$$

Note that the binary codings of the exponents $6 \cdot 16^{i-2}$ have polynomial length and hence each of the above productions can be replaced by a sequence of ordinary productions. Moreover, if $|val(A_u)| = 2 \cdot 16^{i-2}$ for $u \in \{x, x^{-1}, y, y^{-1}\}$ (which is true if *x* and *y* are located in the first layer, i.e., i = 2), then $|val(A_z)| = |val(A_{z^{-1}})| = 2 \cdot 16^{i-1}$. If *z* is an \wedge -gate in the *i*-th layer ($i \ge 2$) with input gates *x* and *y*, then the right-hand sides for A_z and $A_{z^{-1}}$ are

rhs
$$(A_z) = a^{-6 \cdot 16^{i-2}} A_x a^{6 \cdot 16^{i-2}} A_y a^{-6 \cdot 16^{i-2}} A_x a^{6 \cdot 16^{i-2}} A_y$$
 and
rhs $(A_{z^{-1}}) = A_{y^{-1}} a^{-6 \cdot 16^{i-2}} A_{x^{-1}} a^{6 \cdot 16^{i-2}} A_{y^{-1}} a^{-6 \cdot 16^{i-2}} A_{x^{-1}} a^{6 \cdot 16^{i-2}}$.

Once again, these definitions can be replaced by sequences of ordinary definitions. Let *o* be the unique output gate of the circuit \mathscr{C} . Then, by the result from [148], the circuit \mathscr{C} evaluates to 1 if and only if $\mathsf{val}_{\mathbb{A}}(A_o) = 1$ in F_2 . \Box

Let us conclude this section with a slight generalization of Theorem 4.11 to a uniform setting, where the rank of the free group is part of the input.

Theorem 4.14. *The following problem is* **P***-complete: input:* A *finite alphabet* Γ *and an SLP* \mathbb{A} *over the alphabet* $\Gamma \cup \Gamma^{-1}$ *. question: Does* val(\mathbb{A}) = 1 *hold in* $F(\Gamma)$?

Proof. By Theorem 4.13 it suffices to prove membership in **P**. Let $\Gamma = \{a_1, \ldots, a_n\}$. Then the mapping *h* with $h(a_i) = a^i b a^{-i}$ extends to an embedding of $F(\Gamma)$ into F(a,b), see e.g. [119, Proposition 3.1]. By Proposition 3.9(4) we can compute an SLP \mathbb{B} for $h(val(\mathbb{A}))$ from \mathbb{A} and Γ in polynomial time. This proves the theorem by Theorem 4.11. \Box

4.5 The Compressed Word Problem for Finitely Generated Linear Groups

Recall the definition of the randomized complexity classes **RP** and **coRP** from Section 1.3.7. These classes are located between **P** and **NP**. Moreover, there is some evidence from complexity theory that $\mathbf{P} = \mathbf{RP} = \mathbf{coRP}$. This makes the following result from [116] for finitely generated linear groups interesting:

Theorem 4.15. *Let G be a finitely generated linear group. Then, the compressed word problem for G belongs to* **coRP***.*

Proof. Let *G* be linear over the field *F*. Assume first that *F* has characteristic 0. Recall the polynomial identity testing problem $PIT(\mathbb{Z}) \in \mathbf{coRP}$, see Definition 1.48

and Theorem 1.49. Since **coRP** is closed under polynomial time many-one reductions, it suffices to show CWP(G) $\leq_m^P PIT(\mathbb{Z})$. Let Γ be a finite generating set of Gand let $\mathbb{A} = (V, S, \text{rhs})$ be an SLP in Chomsky normal form over $\Gamma \cup \Gamma^{-1}$. By Theorem 2.19 we can assume that G is a finitely generated group of $(d \times d)$ -matrices over the field of fractions $\mathbb{Q}(x_1, \ldots, x_n)$. Let M_a be the matrix corresponding to generator $a \in \Gamma \cup \Gamma^{-1}$. These matrices are fixed; they are not part of the input. We can write M_a as $\frac{1}{p(x_1, \ldots, x_n)}N_a$, where N_a is a $(d \times d)$ -matrix over $\mathbb{Z}[x_1, \ldots, x_n]$ and $p(x_1, \ldots, x_n)$ is the same polynomial over \mathbb{Z} for all generators a. For $A \in V$ let n_A be the length of the word val_A(A); it can be computed in polynomial time for every $A \in V$ by Proposition 3.9(2). From the SLP \mathbb{A} we can now build in polynomial time arithmetic circuits $\mathscr{C}_{i,j}$ $(1 \le i, j \le d)$ in the variables x_1, \ldots, x_n such that val $(\mathscr{C}_{i,j}) = 0$ for all $1 \le i, j \le d$ if and only if val $(\mathbb{A}) = 1$ in G. For this, we associate d^2 defined circuit variables $A_{i,j}$ $(1 \le i, j \le d)$ with every SLP-variable $A \in V$. The circuit variable $A_{i,j}$ will evaluate to entry (i, j) of the matrix $p(x_1, \ldots, x_n)^{n_A}$ val_A(A). If rhs $(A) = a \in \Gamma \cup \Gamma^{-1}$ then rhs $(A_{i,j})$ is set to entry (i, j) of the matrix N_a . If rhs(A) = BC, then we set

$$\operatorname{rhs}(A_{i,j}) = \sum_{k=1}^d B_{i,k} C_{k,j}.$$

Finally, we set the output variable of the circuit $\mathscr{C}_{i,j}$ to $S_{i,j}$ for $i \neq j$ and to $S_{i,j} - p(x_1, \ldots, x_n)^{n_s}$ for i = j.

From the circuits $\mathscr{C}_{i,j}$ we can easily construct an arithmetic circuit for the polynomial

$$p(x_1,\ldots,x_n,y,z) = \sum_{1 \le i,j \le d} y^i z^j \operatorname{val}(\mathscr{C}_{i,j}).$$

Then $p(x_1,...,x_n,y,z)$ is the zero polynomial if and only if every polynomial val $(\mathscr{C}_{i,j})$ is the zero polynomial.

The same arguments apply if *F* has prime characteristic *p*. In that case (using again Theorem 2.19) we can show $\text{CWP}(G) \leq_m^p \text{PIT}(\mathbb{Z}_p)$. By Theorem 1.49, also polynomial identity testing over the coefficient ring \mathbb{Z}_p belongs to **coRP**. \Box

Examples of finitely generated linear groups are: finitely generated polycyclic groups (which include finitely generated nilpotent groups), Coxeter groups, braid groups, and graph groups. Hence, for all these groups the compressed word problem belongs to **coRP**. The same holds for finitely generated metabelian groups since they embed into finite direct products of linear groups [165]. For finitely generated nilpotent groups, Coxeter groups, and graph groups, we will show that the compressed word problem even belongs to **P** (Theorem 4.19, Corollary 5.6 and 5.7). In the next section, we will present a concrete group for which the compressed word problem is equivalent (with respect to polynomial time many-one reductions) to polynomial identity testing over the ring \mathbb{Z} .

4.6 The Compressed Word Problem for $SL_3(\mathbb{Z})$

Recall that the *special linear group* $SL_d(\mathbb{Z})$ is the group of all $(d \times d)$ -matrices over \mathbb{Z} with determinant 1. The group $SL_2(\mathbb{Z})$ is virtually free (has a free subgroup of finite index). Hence, by Theorem 4.4 and 4.11 its compressed word problem can be solved in polynomial time. For $SL_3(\mathbb{Z})$, the complexity of the compressed word problem exactly coincides with the complexity of polynomial identity testing over \mathbb{Z} , which is not known to be in **P**.

Theorem 4.16. $\text{CWP}(SL_3(\mathbb{Z}))$ and $\text{PIT}(\mathbb{Z})$ are polynomial time many-one reducible to each other.

Proof. Since $SL_3(\mathbb{Z})$ is linear over the field \mathbb{Q} of characteristic zero, the proof of Theorem 4.15 shows that $CWP(SL_3(\mathbb{Z})) \leq_m^P PIT(\mathbb{Z})$.

The proof for $PIT(\mathbb{Z}) \leq_m^p CWP(SL_3(\mathbb{Z}))$ is based on a construction from Ben-Or and Cleve [16], which can be seen as an arithmetic version of Barrington's construction (that we used in the proof of Theorem 4.10.) By Theorem 1.51 it suffices to construct in polynomial time from a variable-free arithmetic circuit $\mathscr{C} = (V, S, \text{rhs})$ over \mathbb{Z} an SLP \mathbb{A} over generators of $SL_3(\mathbb{Z})$ such that $val(\mathscr{C}) = 0$ if and only if $val(\mathbb{A})$ evaluates to the identity matrix.

The SLP \mathbb{A} contains for every gate $A \in V$ and all $b \in \{-1,1\}$ and $1 \le i, j \le 3$ with $i \ne j$ a variable $A_{i,j,b}$. Let us denote the matrix to which $A_{i,j,b}$ evaluates with $A_{i,j,b}$ as well. The SLP \mathbb{A} is constructed in such a way that for every column vector $(x_1, x_2, x_3)^T \in \mathbb{Z}^3$ the following holds for the vector $(y_1, y_2, y_3)^T = A_{i,j,b}(x_1, x_2, x_3)^T$: $y_i = x_i + b \cdot \mathsf{val}_{\mathscr{C}}(A) \cdot x_j$ and $y_k = x_k$ for $k \in \{1, 2, 3\} \setminus \{j\}$.

Consider a gate *A* of the variable-free arithmetic circuit \mathscr{C} . Without loss of generality assume that \mathscr{C} is in normal form. We make a case distinction on the right-hand side of *A*.

Case 1. $rhs(A) = c \in \{-1, 1\}$. Then we set $rhs(A_{i,j,b}) = Id_3 + M_{i,j,b\cdot c}$, where Id_3 is the (3×3) identity matrix and all entries in the matrix $M_{i,j,b\cdot c}$ are 0, except for the entry at position (i, j), which is $b \cdot c$.

Case 2. rhs(A) = B + C. Then we set $rhs(A_{i,j,b}) = B_{i,j,b}C_{i,j,b}$.

Case 3. $rhs(A) = B \cdot C$. Let $\{k\} = \{1, 2, 3\} \setminus \{i, j\}$. Then we set

$$rhs(A_{i,j,1}) = B_{k,j,-1}C_{i,k,1}B_{k,j,1}C_{i,k,-1}$$

$$rhs(A_{i,j,-1}) = B_{k,j,-1}C_{i,k,-1}B_{k,j,1}C_{i,k,1}$$

If $(y_1, y_2, y_3)^T = A_{i,j,1}(x_1, x_2, x_3)^T = B_{k,j,-1}C_{i,k,1}B_{k,j,1}C_{i,k,-1}(x_1, x_2, x_3)^T$, then we get $y_j = x_j$, $y_k = x_k + \mathsf{val}_{\mathscr{C}}(B) \cdot x_j - \mathsf{val}_{\mathscr{C}}(B) \cdot x_j = x_k$, and

$$y_i = x_i - \mathsf{val}_{\mathscr{C}}(C) \cdot x_k + \mathsf{val}_{\mathscr{C}}(C) \cdot (x_k + \mathsf{val}_{\mathscr{C}}(B) \cdot x_j) = x_i + \mathsf{val}_{\mathscr{C}}(C) \cdot \mathsf{val}_{\mathscr{C}}(B) \cdot x_j.$$

Similarly, if $(y_1, y_2, y_3)^T = A_{i,j,-1}(x_1, x_2, x_3)^T = B_{k,j,-1}C_{i,k,-1}B_{k,j,1}C_{i,k,1}(x_1, x_2, x_3)^T$, then we get $y_j = x_j$, $y_k = x_k + \mathsf{val}_{\mathscr{C}}(B) \cdot x_j - \mathsf{val}_{\mathscr{C}}(B) \cdot x_j = x_k$, and

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$$y_i = x_i + \mathsf{val}_{\mathscr{C}}(C) \cdot x_k - \mathsf{val}_{\mathscr{C}}(C) \cdot (x_k + \mathsf{val}_{\mathscr{C}}(B) \cdot x_j) = x_i - \mathsf{val}_{\mathscr{C}}(C) \cdot \mathsf{val}_{\mathscr{C}}(B) \cdot x_j.$$

Finally, let $S_{1,2,1}$ be the start variable of \mathbb{A} . Then, we have $\mathsf{val}(\mathscr{C}) = 0$ if and only if for all $(x_1, x_2, x_3) \in \mathbb{Z}^3$ we have $S_{1,2,1}(x_1, x_2, x_3)^T = (x_1 + \mathsf{val}(\mathscr{C}) \cdot x_2, x_2, x_3) = (x_1, x_2, x_3)$ if and only if $\mathsf{val}(\mathbb{A})$ evaluates to Id_3 . This proves the theorem. \Box

4.7 The Compressed Word Problem for Finitely Generated Nilpotent Groups

Let us first recall the definition of a nilpotent group.

Definition 4.17 (lower central series, nilpotent group). The *lower central series* of the group *G* is the sequence of subgroups $G = G_1 \ge G_2 \ge G_3 \ge \cdots$ where $G_{i+1} = [G_i, G]$ (which is the subgroup of G_i generated by all commutators $g^{-1}h^{-1}gh$ for $g \in G_i$ and $h \in G$; by induction one can show that indeed $G_{i+1} \le G_i$). The group *G* is nilpotent if there exists $i \ge 1$ with $G_i = 1$.

Robinson [148] has shown that the word problem for a finitely generated linear group belongs to the circuit complexity class $\mathbf{TC}^0 \subseteq \mathbf{L}$. Moreover, every nilpotent group is linear, see e.g. [95]. Hence, by Theorem 4.15 the compressed word problem for a finitely generated nilpotent group belongs to **coRP**. This upper bound was improved in [74] to **P**. Our proof of this result uses a fact about unitriangular matrices. Recall that a $(d \times d)$ -matrix $M = (a_{i,j})_{1 \le i,j \le d}$ over \mathbb{Z} is unitriangular if $a_{i,i} = 1$ for all $1 \le i \le d$ and $a_{i,j} = 0$ for i > j, i.e., all entries below the diagonal are zero. For a matrix $M = (a_{i,j})_{1 \le i,j \le d}$ over \mathbb{Z} let $|M| = \sum_{1 \le i,j \le d} |a_{i,j}|$. It is straightforward to show that $|M_1 \cdot M_2| \le d^2 |M_1| \cdot |M_2|$ for two $(d \times d)$ -matrices M_1 and M_2 , see [108, Lemma 3]. Hence, for a product of *m* matrices we have

$$|M_1 \cdot M_2 \cdots M_m| \le d^{2(m-1)} |M_1| \cdot |M_2| \cdots |M_n|.$$

The estimate in the following proposition is very rough but sufficient for our purpose:

Proposition 4.18. Let M_1, \ldots, M_m be a unitriangular $(d \times d)$ -matrices over \mathbb{Z} with $m \ge 2d$ and let $n = \max\{|M_i| \mid 1 \le i \le m\}$. For the product of these matrices we have

$$|M_1M_2\cdots M_m| \le d + (d-1)\binom{m}{d-1}d^{2(d-2)}n^{d-1}.$$

Proof. Let $A_i = M_i - Id_d$, this is a matrix which has only zeros on the diagonal and below. Hence any product of at least *d* many matrices A_i is zero. We get

$$M_1 M_2 \cdots M_m = \prod_{i=1}^m (A_i + \mathsf{Id}_d) = \sum_{I \subseteq \{1, \dots, m\}, |I| < d} \prod_{i \in I} A_i.$$

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We have $|A_i| \leq n$ and hence

$$\prod_{i \in I} A_i | \le d^{2(|I|-1)} \prod_{i \in I} |A_i| \le d^{2(|I|-1)} n^{|I|}$$

for $I \neq \emptyset$. Finally, we get

$$|M_1M_2\cdots M_m| \le d + \sum_{i=1}^{d-1} \binom{m}{i} d^{2(i-1)} n^i$$

(the summand *d* is due to $|\mathsf{Id}_d| = d$). Since we assume $m \ge 2d$ we have $\binom{m}{i} \le \binom{m}{d-1}$ for all $1 \le i \le d-1$. Hence, we get

$$|M_1M_2\cdots M_m| \le d + (d-1)\binom{m}{d-1}d^{2(d-2)}n^{d-1}.$$

Theorem 4.19. *Let* G *be a finitely generated nilpotent group. Then* CWP(G) *can be solved in polynomial time.*

Proof. Let *G* be a finitely generated nilpotent group. Then *G* has a finitely generated torsion-free nilpotent subgroup *H* such that the index [G : H] is finite [95, Theorem 17.2.2]. By Theorem 4.4, it suffices to solve CWP(H) in polynomial time. Let Γ be a finite generating set for *H*. There exists $d \ge 1$ such that the finitely generated torsion-free nilpotent group *H* can be embedded into the group $UT_d(\mathbb{Z})$ of unitriangular $(d \times d)$ -matrices over \mathbb{Z} [95, Theorem 17.2.5]. Let $\varphi : H \to UT_d(\mathbb{Z})$ be this embedding. Let $n = \max\{|\varphi(a)| \mid a \in \Gamma \cup \Gamma^{-1}\}$. Note that *n* and *d* are constants in our consideration.

If the word $w \in (\Gamma \cup \Gamma^{-1})^*$ is given by an SLP $\mathbb{A} = (V, \Gamma \cup \Gamma^{-1}, S, \text{rhs})$ in Chomsky normal form of size *m*, we can evaluate the SLP bottom-up in the group $UT_d(\mathbb{Z})$ as follows: For every variable $A \in V$ we compute the matrix $\varphi(val(A))$. If rhs(A) = BC and the matrices $\varphi(val(B))$ and $\varphi(val(C))$ are already computed, then $\varphi(val(A))$ is set to the product of these two matrices. Since $|val_{\mathbb{A}}(A)| \leq |w| \leq 2^m$, Proposition 4.18 implies

$$|\varphi(\mathsf{val}(A))| \le d + (d-1) \binom{2^m}{d-1} d^{2(d-2)} n^{d-1} \in 2^{\mathscr{O}(m)}.$$

Hence, every entry in the matrix $\varphi(val(A))$ can be represented with $\mathcal{O}(m)$ bits. Therefore, the evaluation can be accomplished in polynomial time. \Box

By [9], the automorphism group of a finitely generated nilpotent group is finitely generated (even finitely presented) and hence, by Theorem 4.19 has a polynomial time word problem.

4.8 Wreath Products: Easy Word Problem but Difficult Compressed Word Problem

In this section, we will present a group *G*, for which the word problem can be solved in logarithmic space, but the compressed word problem is **coNP**-hard, and thus not solvable in polynomial time unless $\mathbf{P} = \mathbf{NP}$ (which is equivalent to $\mathbf{P} = \mathbf{coNP}$). We start with the definition of a wreath product of two groups:

Definition 4.20 (wreath product). Let G and H be groups. Consider the direct sum

$$K = \bigoplus_{g \in G} H_g,$$

where H_g is a copy of H. We view K as the set

$$H^{(G)} = \{ f : G \to H \mid f(g) \neq 1 \text{ for only finitely many } g \in G \}$$

of all mappings from *G* to *H* with finite support together with pointwise multiplication as the group operation, i.e., $(f_1f_2)(g) = f_1(g)f_2(g)$. The group *G* has a natural left action on $H^{(G)}$ given by

$$gf(a) = f(g^{-1}a)$$

where $f \in H^{(G)}$ and $g, a \in G$. The corresponding homomorphism $\varphi : G \to \operatorname{Aut}(H^{(G)})$ is defined by $\varphi(g)(f) = gf$ for $g \in G$ and $f \in H^{(G)}$. The corresponding semidirect product $H^{(G)} \rtimes_{\varphi} G$ is the *wreath product* $H \wr G$.¹ In other words:

- Elements of $H \wr G$ are pairs (f, g), where $g \in G$ and $f \in H^{(G)}$.
- The multiplication in $H \wr G$ is defined as follows: Let $(f_1, g_1), (f_2, g_2) \in H \wr G$. Then $(f_1, g_1)(f_2, g_2) = (f, g_1g_2)$, where $f(a) = f_1(a)f_2(g_1^{-1}a)$.

The following intuition might be helpful: An element $(f,g) \in H \wr G$ can be thought of as a finite multiset of elements of $H \setminus \{1\}$ that are sitting at certain elements of G (the mapping f) together with the distinguished element $g \in G$, which can be thought of as a cursor moving in G. If we want to compute the product $(f_1,g_1)(f_2,g_2)$, we do this as follows: First, we shift the finite collection of H-elements that corresponds to the mapping f_2 by g_1 (the result is the mapping g_1f_2): If the element $h \in H \setminus \{1\}$ is sitting at $a \in G$ (i.e., $f_2(a) = h$), then we remove h from a and put it to the new location $g_1a \in H$. This new collection corresponds to the mapping $f'_2: a \mapsto$ $f_2(g_1^{-1}a)$. After this shift, we multiply the two collections of H-elements pointwise: If in $a \in G$ the elements h_1 and h_2 are sitting (i.e., $f_1(a) = h_1$ and $f'_2(a) = h_2$), then we put the product h_1h_2 into the location a. Finally, the new distinguished G-element (the new cursor position) becomes g_1g_2 .

Assume that $H = \langle \Sigma | R_H \rangle$ and $G = \langle \Gamma | R_G \rangle$ with $\Sigma \cap \Gamma = \emptyset$. Then we have

$$H \wr G \cong \langle \Sigma \cup \Gamma \mid R_G \cup R_H \cup \{ [waw^{-1}, b] \mid a, b \in \Sigma, w \in (\Gamma \cup \Gamma^{-1})^*, w \neq 1 \text{ in } G \} \rangle,$$

¹ This wreath product is also called the restricted wreath product since only finitely supported mappings from G to H are considered and not all mappings.

see e.g. [125]. In terms of the above intuition, the relator $[waw^{-1},b]$ (recall that $[x,y] = xyx^{-1}y^{-1}$) expresses that the following two actions have the same effect:

- (i) Moving the cursor to (the *G*-element represented by) *w*, (ii) multiplying the *H*-element at the new cursor position with *a*, (iii) moving the cursor back to the origin, and (iv) finally multiplying the *H*-element at the origin with *b*.
- (i) Multiplying the *H*-element at the current cursor with *b*, (ii) moving the cursor to *w*, (iii) multiplying the *H*-element at the new cursor position with *a*, and finally (iv) moving the cursor back to the origin.

If *G* and *H* are finitely generated, then also $H \wr G$ is finitely generated. On the other hand, $H \wr G$ is finitely presented if and only if one of the following two cases holds: (i) H = 1 and *G* is finitely presented or (ii) *H* is finitely presented and *G* is finite, see [12]. The complexity of the word problem for wreath products was studied in [164].

Theorem 4.21. *If G is finitely generated non-abelian and* $\mathbb{Z} \leq H$ *, then* $\mathsf{CWP}(G \wr H)$ *is* **coNP***-hard.*

Proof. It suffices to prove the theorem for the wreath product $G \wr \mathbb{Z}$. Let $g, h \in G$ such that $gh \neq hg$ and let \mathbb{Z} be generated by t. We prove the theorem by a reduction from the problem from Theorem 3.13. Hence, let \mathbb{A} and \mathbb{B} be SLPs over the alphabet $\{a, b\}$. Let $n = |val(\mathbb{A})|$ and $m = |val(\mathbb{B})|$. Moreover, let \mathbb{A}_1 (respectively, \mathbb{B}_1) be the SLP that results from \mathbb{A} by replacing every occurrence of the symbol a by the \mathbb{Z} -generator t and every occurrence of the symbol b by tg (respectively, th). Similarly, let \mathbb{A}_2 (respectively, \mathbb{B}_2) be the SLP that results from \mathbb{A} by replacing every occurrence of the symbol a by tg^{-1} (respectively, th^{-1}). From these SLPs is it easy to construct in logspace an SLP \mathbb{C} such that

$$\mathsf{val}(\mathbb{C}) = \mathsf{val}(\mathbb{A}_1)t^{-n}\mathsf{val}(\mathbb{B}_1)t^{-m}\mathsf{val}(\mathbb{A}_2)t^{-n}\mathsf{val}(\mathbb{B}_2)t^{-m}$$

(SLPs for t^{-n} and t^{-m} can be obtained in logspace by replacing in \mathbb{A} and \mathbb{B} , respectively, all occurrences of a and b by t^{-1}). Then, if there is no position $i \in \mathbb{N}$ such that $\operatorname{val}(\mathbb{A})[i] = \operatorname{val}(\mathbb{B})[i] = b$, we have $\operatorname{val}(\mathbb{C}) = 1$ in $G \wr \mathbb{Z}$. On the other hand, if there is a position $i \in \mathbb{N}$ such that $\operatorname{val}(\mathbb{A})[i] = \operatorname{val}(\mathbb{B})[i] = b$, then, if $(f, 0) \in G \wr \mathbb{Z}$ is the element represented by the word $\operatorname{val}(\mathbb{C})$, we have $f(i) = ghg^{-1}h^{-1} \neq 1$. Hence $\operatorname{val}(\mathbb{C}) \neq 1$ in $G \wr \mathbb{Z}$. \Box

If *G* is a finite group, then the word problem for $G \wr \mathbb{Z}$ can be solved in logspace. This follows from [164], where it has been shown that if G_1 and G_2 are groups for which the word problem belongs to the circuit complexity class (uniform) \mathbf{NC}^1 (and this is the case for finite groups and \mathbb{Z}), then also the word problem for $G_1 \wr G_2$ belongs to $\mathbf{NC}^1 \subseteq \mathbf{L}$. Hence, for a finite non-abelian group *G*, the word problem for $G \wr \mathbb{Z}$ belongs to **L** but the compressed word problem is **coNP**-hard. Another group with an easy word problem but difficult compressed word problem is *Thompson's group*

$$F = \langle x_0, x_1, x_2, \dots \mid x_n x_k = x_k x_{n+1} \text{ for all } k < n \rangle.$$

This group is actually finitely presented: $F = \langle a, b | [ab^{-1}, a^{-1}ba], [ab^{-1}, a^{-2}ba^2] \rangle$. The group *F* has several other nice representations, e.g. by piecwiese linear homeomorphisms of the unit interval [0,1] or by certain tree diagrams, see [26] for more details. Thompson's group *F* is a subgroup of Thompson's group *V*, for which the word problem belongs to the circuit complexity class \mathbf{AC}^1 [18], which satisfies $\mathbf{NL} \subseteq \mathbf{AC}^1 \subseteq \mathbf{NC}^2 \subseteq \mathbf{P}$.

Theorem 4.22. CWP(F) is **coNP**-hard.

Proof. It is known that the wreath product $F \wr \mathbb{Z}$ is a subgroup of F [69]. Since F is non-abelian, the theorem follows from Theorem 4.21. \Box

If *G* and *H* are finitely generated abelian groups, then the wreath product $H \wr G$ is metabelian $(H^{(G)})$ is a normal subgroup of $H \wr G$ with $(H \wr G)/H^{(G)} = G$. Hence, as remarked earlier, $H \wr G$ can be embedded into a direct product of linear groups and $CWP(H \wr G)$ belongs to **coRP**. This fact can be slightly extended:

Corollary 4.23. For every finitely generated abelian group H and every finitely generated virtually abelian group H (i.e., H is a finite extension of a finitely generated abelian group), $CWP(H \wr G)$ belongs to **coRP**.

Proof. Assume that *K* is a finitely generated subgroup of index *m* in *G*. Then $H^m \wr K$ is isomorphic to a subgroup of index *m* in $H \wr G$ (see e.g. [118]). If *H* is finitely generated abelian then H^m is finitely generated abelian too and therefore $\text{CWP}(H^m \wr K)$ belongs to **coRP**. Finally, we can apply Theorem 4.4 and the fact that **coRP** is closed under \leq_m^P . \Box

It is well known that if N is a normal subgroup of G, then also [N,N] is a normal subgroup of G. Hence, one can consider the quotient group G/[N,N]. The following result of Magnus [122] has many applications in combinatorial group theory.

Theorem 4.24 (Magnus embedding theorem). Let F_k be a free group of rank k and let N be a normal subgroup of F_k . Then $F_k/[N,N]$ embeds into the wreath product $\mathbb{Z}^k \wr (F_k/N)$.

We can use the Magnus embedding theorem to get:

Theorem 4.25. Let F_k be a free group of rank k and let N be a normal subgroup of F_k such that F_k/N is finitely generated virtually abelian. Then $\text{CWP}(F_k/[N,N])$ belongs to **coRP**.

Proof. By the Magnus embedding theorem, the group $F_k/[N,N]$ embeds into the wreath product $\mathbb{Z}^k \wr (F_k/N)$. For the latter group, the compressed word problem belongs to **coRP** by Corollary 4.23. \Box

Chapter 5 The Compressed Word Problem in Graph Products

In this chapter we will introduce an important operation in combinatorial group theory: graph products. A graph product is specified by a finite undirected graph, where every node is labeled with a group. The graph product specified by this group-labeled graph is obtained by taking the free product of all groups appearing in the graph, but elements from adjacent groups are allowed to commute. This operation generalizes free products as well as direct products. Graph groups were introduced by Green in her thesis [66]. Further results for graph products can be found in [54, 75, 83, 129].

The main result of this chapter states that there is a polynomial time Turingreduction from the compressed word problem for a graph product to the compressed word problems of the groups labeling the nodes of the graph. The material of this chapter is taken from [74].

5.1 Graph Products

In this section, we formally define graph products and state the main result of this chapter.

Definition 5.1 ((in)dependence alphabet). An independence alphabet is a pair (A, I), where A is an arbitrary set and $I \subseteq A \times A$ is an irreflexive and symmetric relation on A. The *dependence alphabet* associated with (A, I) is (A, D), where $D = (A \times A) \setminus I$. Note that the relation D is reflexive.

Let us fix for this subsection a *finite* independence alphabet (W, E) with $W = \{1, ..., n\}$ and finitely generated groups G_i for $i \in \{1, ..., n\}$. Let $G_i = \langle \Gamma_i | R_i \rangle$ with $\Gamma_i \cap \Gamma_j = \emptyset$ for $i \neq j$.

Definition 5.2 (graph product). The *graph product* defined by $(W, E, (G_i)_{i \in W})$ is the following group:

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$$\mathbb{G}(W, E, (G_i)_{i \in W}) = \left\langle \bigcup_{i=1}^n \Gamma_i \mid \bigcup_{i=1}^n R_i \cup \bigcup_{(i,j) \in E} \{ [a,b] \mid a \in \Sigma_i, b \in \Sigma_j \} \right\rangle$$

In other words: We take the free product of all the groups G_1, \ldots, G_n but elements $x \in G_i, y \in G_j$ with $(i, j) \in E$ are allowed to commute.

Clearly, if every G_i is finitely generated (respectively, finitely presented) then the same holds for $\mathbb{G}(W, E, (G_i)_{i \in W})$. If $E = \emptyset$, then $\mathbb{G}(W, E, (G_i)_{i \in W})$ is the free product $\mathbb{G}_1 * \mathbb{G}_2 * \cdots * \mathbb{G}_n$ and if (W, E) is a complete graph, then $\mathbb{G}(W, E, (G_i)_{i \in W})$ is the direct product $\prod_{i=1}^n G_i$. In this sense, the graph product construction generalizes free and direct products.

Note that graph groups (see Example 2.5) are exactly the graph products of copies of \mathbb{Z} . Graph products of copies of $\mathbb{Z}/2\mathbb{Z}$ are known as *right-angled Coxeter groups*, see [56] for more details.

Recently, it was shown that the word problem for a graph product of groups with logspace word problem can be solved in logspace too [51]:

Theorem 5.3. Let (W, E) be a fixed finite independence alphabet and for every $i \in W$ let G_i be a finitely generated group. If $WP(G_i) \in L$ for all $i \in W$, then also $WP(\mathbb{G}(W, E, (G_i)_{i \in W})) \in L$.

Recall the definition of polynomial time Turing reducibility \leq_T^P (Definition 1.29). The main result of this chapter is:

Theorem 5.4. *Let* (W, E) *be a finite independence alphabet and for every* $i \in W$ *let* G_i *be a finitely generated group. Then we have*

$$\mathsf{CWP}(\mathbb{G}(W, E, (G_i)_{i \in W})) \leq_T^P \{\mathsf{CWP}(G_i) \mid i \in W\}.$$

By taking $(W, E) = (\{1, 2\}, \emptyset)$, we get:

Corollary 5.5. Let G_1 and G_2 be finitely generated groups. Then $\text{CWP}(G_1 * G_2) \leq_T^P \{\text{CWP}(G_1), \text{CWP}(G_2)\}.$

By taking $G_I = \mathbb{Z}$ (respectively, $\mathbb{Z}/2\mathbb{Z}$) for every $i \in W$, we get:

Corollary 5.6. For every graph group G (respectively, right-angled Coxeter group G), CWP(G) belongs to **P**.

Building on results from [155], Laurence has shown in [102] that automorphism groups of graph groups are finitely generated. Recently, Day [44] proved that automorphism groups of graph groups are in fact finitely presented. Further structural results on automorphism groups of graph groups can be found in [33, 34]. Generalizing the main result from [102], it was shown in [43] that the automorphism group of a graph product of finitely generated Abelian groups is finitely generated. In particular, the automorphism group of a right-angled Coxeter group is finitely generated. From Corollary 5.6 and Theorem 4.6 it follows that the word problem

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for the automorphism group of a graph group or a right-angled Coxeter group can be solved in polynomial time. More generally, Theorem 4.6 and 5.4 yield a polynomial time algorithm for the word problem of a finitely generated subgroup of $Aut(\mathbb{G}(W, E, (G_i)_{i \in W}))$, where every vertex group G_i has a polynomial time compressed word problem. It is not clear, whether the full group $Aut(\mathbb{G}(W, E, (G_i)_{i \in W}))$ is finitely generated in case every group $Aut(G_i)$ is finitely generated.

Proposition 4.3, Theorem 4.4, and Corollary 5.6 imply that for every finite extension G of a subgroup of a graph group (one also says that G virtually embedds into a graph group), CWP(G) belongs to **P**. Recently, this class of groups turned out be very rich. It contains the following classes of groups:

- Coxeter groups (not only right-angled ones) [72]
- one-relator groups with torsion [166]
- fully residually free groups [166]
- fundamental groups of hyperbolic 3-manifolds [2]

Hence, we can state the following corollary:

Corollary 5.7. For every group from one of the following classes the compressed word problem belongs to **P**: Coxeter groups, one-relator groups with torsion, fully residually free groups, fundamental groups of hyperbolic 3-manifolds.

The existence of a polynomial time algorithm for the compressed word problem of a fully residually free groups was also shown by Macdonald [120].

5.2 Trace Monoids

5.2.1 General definitions

Our approach to the compressed word problem for graph products will be based on the theory of traces (partially commutative words). In the following we introduce some notions from trace theory, see [49, 55] for more details. Let us fix an independence alphabet (Σ , I) and let (Σ , D) be the corresponding dependence alphabet, see Definition 5.1. The set Σ may be infinite, but most of the time, it will be finite in this chapter.

Definition 5.8 (trace monoid). The *trace monoid* $\mathbb{M}(\Sigma, I)$ is defined as the quotient monoid $\mathbb{M}(\Sigma, I) = \Sigma^* / \{(ab, ba) \mid (a, b) \in I\}$. Its elements are called *traces*.

Trace monoids are known to be cancellative. We denote by $[w]_I$ the trace represented by the word $w \in \Sigma^*$. The trace $[\varepsilon]_I$ is the empty trace; it is the identity of the monoid $\mathbb{M}(\Sigma, I)$ and we denote it simply by ε . Since the relations (ab, ba) do not change the length or the alphabet of a word, we can define $\operatorname{alph}([w]_I) = \operatorname{alph}(w)$ and $|[w]_I| =$ |w|. For $a \in \Sigma$ let $I(a) = \{b \in \Sigma \mid (a, b) \in I\}$ be the letters that commute with *a* and $D(a) = \Sigma \setminus I(a)$. For traces $u, v \in \mathbb{M}(\Sigma, I)$ with $\operatorname{alph}(u) \times \operatorname{alph}(v) \subseteq I$ we also write uIv. **Definition 5.9 (independence clique).** An *independence clique* is a subset $\Delta \subseteq \Sigma$ such that $(a,b) \in I$ for all $a, b \in \Delta$ with $a \neq b$. For a *finite* independence clique Δ , we write $[\Delta]_I$ for the trace $[a_1a_2\cdots a_n]_I$, where a_1, a_2, \ldots, a_n is an arbitrary enumeration of Δ (the precise enumeration is not important).

The following lemma is known as Levi's Lemma. It is one of the most fundamental facts for trace monoids, see e.g. [55, p 74]:

Lemma 5.10 (Levi's Lemma). Let $u_1, \ldots, u_m, v_1, \ldots, v_n \in \mathbb{M}$. Then $u_1u_2 \cdots u_m = v_1v_2 \cdots v_n$ if and only if there exist $w_{i,j} \in \mathbb{M}$ $(1 \le i \le m, 1 \le j \le n)$ such that

- $u_i = w_{i,1}w_{i,2}\cdots w_{i,n}$ for every $1 \le i \le m$,
- $v_j = w_{1,j} w_{2,j} \cdots w_{m,j}$ for every $1 \le j \le n$, and
- $(w_{i,j}, w_{k,\ell}) \in I$ if $1 \le i < k \le m$ and $n \ge j > \ell \ge 1$.

The situation in the lemma will be visualized by a diagram of the following kind. The *i*-th column corresponds to u_i , the *j*-th row corresponds to v_j , and the intersection of the *i*-th column and the *j*-th row represents $w_{i,j}$. Furthermore $w_{i,j}$ and $w_{k,\ell}$ are independent if one of them is left-above the other one.

v_n	$w_{1,n}$	$w_{2,n}$	<i>w</i> _{3,<i>n</i>}	• • •	$w_{m,n}$
:	÷	••••	:	••••	:
v_3	<i>w</i> _{1,3}	w _{2,3}	W3,3	• • •	$W_{m,3}$
v_2	<i>w</i> _{1,2}	w _{2,2}	w3,2	• • •	$w_{m,2}$
v_1	$w_{1,1}$	$w_{2,1}$	W3,1		$w_{m,1}$
	u_1	u_2	<i>u</i> ₃	• • •	u_m

A convenient representation for traces are *dependence graphs*, which are nodelabeled directed acyclic graphs. For a word $w \in \Sigma^*$ the dependence graph D_w has vertex set $\{1, \ldots, |w|\}$ where the node *i* is labeled with w[i]. There is an edge from vertex *i* to *j* if and only if i < j and $(w[i], w[j]) \in D$. It is easy to see that for two words $w, w' \in \Sigma^*$ we have $[w]_I = [w']_I$ if and only if D_w and $D_{w'}$ are isomorphic node-labeled graphs. Hence, we can speak of *the* dependence graph of a trace.

Example 5.11. We consider the following independence alphabet (Σ, I) :

$$c \xrightarrow{a}_{e \xrightarrow{a}_{d} \xrightarrow{b}_{d}} b$$

Then the corresponding dependence alphabet is:



We consider the words u = aeadbacdd and v = eaabdcaeb. Then the dependence graphs D_u of u and D_v of v look as follows, where we label the vertex i with the letter u[i] (respectively, v[i]):

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Note that we only show Hasse diagrams and hence omit for instance the edge from the first *d* to the last *d* in D_u .

Definition 5.12 (downward-closed set, convex set). Let E_w be the edge relation for the dependence graph D_w for a trace w. A subset $V \subseteq \{1, \ldots, |w|\}$ is called *downward-closed*, if $(i, j) \in E_w$ and $j \in V$ implies $i \in V$. A subset $V \subseteq \{1, \ldots, |w|\}$ is called *convex*, if $(i, j), (j, k) \in E_w^*$ and $i, k \in V$ implies $j \in V$.

Definition 5.13 (projection homomorphism). For $\Delta \subseteq \Sigma$ we define the *projection* homomorphism $\pi_{\Delta} : \mathbb{M}(\Sigma, I) \to \mathbb{M}(\Delta, I \cap (\Delta \times \Delta))$ by $\pi_{\Delta}(a) = \varepsilon$ for $a \in \Sigma \setminus \Delta$ and $\pi_{\Delta}(a) = a$ for $a \in \Delta$.

With this definition, we get the following projection lemma:

Lemma 5.14. For $u, v \in \mathbb{M}(\Sigma, I)$ we have u = v if and only if $\pi_{\{a,b\}}(u) = \pi_{\{a,b\}}(v)$ for all $(a,b) \in D$.

5.2.2 The Prefix and Suffix Order on Traces.

Definition 5.15 (prefix and suffix of a trace). Let $u, v \in \mathbb{M}(\Sigma, I)$. Then u is a *prefix* (respectively, *suffix*) of v if there exists some $w \in \mathbb{M}(\Sigma, I)$ such that uw = v (respectively, wu = v) in $\mathbb{M}(\Sigma, I)$, for short $u \leq_p v$ (respectively, $u \leq_s v$).

Prefixes of a trace u exactly correspond to downward-closed subsets of the dependence graph of u.

Definition 5.16 $(u \sqcap_p v, u \sqcap_s v, u \setminus_p v, u \setminus_s v)$. The *prefix infimum* (respectively, *suffix infimum*) $u \sqcap_p v$ (respectively, $u \sqcap_s v$) is the largest trace w with respect to \preceq_p (respectively, \preceq_s) such that $w \preceq_p u$ and $w \preceq_p v$ (respectively, $w \preceq_s u$ and $w \preceq_s v$); it always exists [41]. With $u \setminus_p v$ (respectively, $u \setminus_s v$) we denote the unique trace w such that $u = (u \sqcap_p v)w$ (respectively, $u = w(u \sqcap_s v)$). Uniqueness follows from the fact that $\mathbb{M}(\Sigma, I)$ is cancellative.

Note that $u \setminus_p v = u \setminus_p (u \sqcap_p v)$ and $u \setminus_s v = u \setminus_s (u \sqcap_s v)$.

Definition 5.17 (min(u) and max(u)). For $u \in \mathbb{M}(\Sigma, I)$, we define

$$\min(u) = \{a \in \Sigma \mid a \preceq_p u\} \text{ and} \\ \max(u) = \{a \in \Sigma \mid a \preceq_s u\}.$$

Clearly, $\min(u)$ and $\max(u)$ are finite independence cliques and $[\min(u)]_I \leq_p u$ and $[\max(u)]_I \leq_s u$. Occasionally, we will identify the traces $[\min(u)]_I$ and $[\max(u)]_I$ with the independence cliques $\min(u)$ and $\max(u)$, respectively.

Example 5.18. We continue Example 5.11 above. We have $u \sqcap_p v = [aeadbac]_I =: w$ and its dependence graph is:



Furthermore we have $min(w) = \{a, d, e\}$ and $max(w) = \{a, c\}$.

We also need the following lemma from [109]:

Lemma 5.19. For $u, v \in \mathbb{M}(\Sigma, I)$ we have $u \leq_p v$ if and only if the word $\pi_{\{a,b\}}(u)$ is a prefix of the word $\pi_{\{a,b\}}(v)$ for all $(a,b) \in D$.

5.2.3 Trace Rewriting Systems.

Trace rewriting systems are defined analogously to semi-Thue systems (i.e., word rewriting systems).

Definition 5.20 (trace rewriting system). A *trace rewriting system R* over the trace monoid $\mathbb{M}(\Sigma, I)$ is a finite subset of $\mathbb{M}(\Sigma, I) \times \mathbb{M}(\Sigma, I)$ [49]. We define the *one-step rewrite relation* $\rightarrow_R \subseteq \mathbb{M}(\Sigma, I) \times \mathbb{M}(\Sigma, I)$ by: $x \rightarrow_R y$ if and only if there are $u, v \in \mathbb{M}(\Sigma, I)$ and $(\ell, r) \in R$ such that $x = u\ell v$ and y = urv.

As for semi-Thue systems, we say that the trace rewriting system *R* is Noetherian (confluent, locally confluent) if \rightarrow_R is Noetherian (confluent, locally confluent). Let $IRR(R) = IRR(\rightarrow_R)$ (the set of *irreducible traces* with respect to *R*) and $NF_R(w) = NF_{\rightarrow_R}(w)$ (if *R* is Noetherian and confluent) be the *normal form* of the trace *w*. Trace rewriting systems are studied in detail in [49].

5.2.4 Confluent and Terminating Trace Rewriting Systems for Graph Products

Let us fix for this subsection a *finite* independence alphabet (W, E) with $W = \{1, ..., n\}$ and finitely generated groups G_i for $i \in \{1, ..., n\}$. For pairwise disjoint nonempty sets $C_1, ..., C_n$ we define the independence relation

$$E[C_1, \dots, C_n] = \bigcup_{(i,j) \in E} C_i \times C_j$$
(5.1)

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on the alphabet $\bigcup_{i=1}^{n} C_i$. Every independence clique of $(\bigcup_{i=1}^{n} C_i, E[C_1, \dots, C_n])$ has size at most *n*. We define a (possibly infinite) independence alphabet as in [54, 100]: Let

$$A_i = G_i \setminus \{1\}$$
 and $A = \bigcup_{i=1}^n A_i$.

We assume that A_1, \ldots, A_n are pairwise disjoint. We fix the independence relation

$$I = E[A_1, \ldots, A_n]$$

on *A* for the rest of this subsection. The independence alphabet (A, I) is the only independence alphabet in this chapter, which may be infinite. On $\mathbb{M}(A, I)$ we define the trace rewriting system

$$R = \bigcup_{i=1}^{n} \left(\{ ([aa^{-1}]_{I}, \varepsilon) \mid a \in A_{i} \} \cup \{ ([ab]_{I}, [c]_{I}) \mid a, b, c \in A_{i}, ab = c \text{ in } G_{i} \} \right).$$
(5.2)

Clearly, *R* is terminating (it reduces the length of traces). The following lemma was shown in [100]:

Lemma 5.21. *The trace rewriting system R is confluent.*

Proof. Since *R* is terminating, it suffices by Newman's Lemma [134] to show that *R* is locally confluent, i.e., for all $s, s_1, s_2 \in \mathbb{M}(A, I)$ with $s \to_R s_1$ and $s \to_R s_2$ there exists $s' \in \mathbb{M}(A, I)$ with $s_1 \to_R^* s'$ and $s_2 \to_R^* s'$.

Thus, assume that $s \to_R s_1$ and $s \to_R s_2$. Hence, $s = t_i a_i b_i u_i$ and $s_i = t_i r_i u_i$ for $i \in \{1, 2\}$, where $(a_i b_i, r_i) \in R$. Thus, $r_i \in A \cup \{\varepsilon\}$. By applying Levi's Lemma 5.10 to the identity $t_1 a_1 b_1 u_1 = t_2 a_2 b_2 u_2$, we obtain the following diagram:

u_2	w_2	q_1	v_2
a_2b_2	p_2	t	q_2
<i>t</i> ₂	v_1	p_1	w_1
	t_1	a_1b_1	u_1

Thus, w_1Iw_2 . Since the trace monoid is cancellative, we can assume $v_1 = v_2 = \varepsilon$ for the further arguments. Assume that $a_i, b_i \in A_{\sigma_i}$ with $\sigma_i \in \{1, ..., n\}$. Let us first consider the case $t \neq \varepsilon$. Thus, $\sigma_1 = \sigma_2 = \sigma$, $r_1, r_2 \in A_{\sigma} \cup \{\varepsilon\}$, and cIw_i for all $c \in A_{\sigma}$ and $i \in \{1, 2\}$. Moreover, since p_1Ip_2 but both traces only contain symbols from A_{σ} , we have $p_1 = \varepsilon$ or $p_2 = \varepsilon$ and similarly $q_1 = \varepsilon$ or $q_2 = \varepsilon$. If $p_1 = p_2 = q_1 = q_2 = \varepsilon$ then $a_1b_1 = t = a_2b_2$ and hence $r_1 = r_2$. We get $s_1 = w_2r_1w_1 = w_1r_2w_2 = s_2$. Otherwise, since a_1b_1 cannot be a proper factor of a_2b_2 and vice versa, we obtain up to symmetry the following diagram (recall that we assume $v_1 = v_2 = \varepsilon$):

u_2	w_2	b_1	ε	
a_2b_2	a_2	$b_2 = a_1$	ε	
t_2	ε	ε	w_1	
	t_1	a_1b_1	u_1	

Thus, $s_1 = a_2w_2r_1w_1 = w_1a_2r_1w_2$ and $s_2 = w_1r_2w_2b_1 = w_1r_2b_1w_2$. In the group G_{σ} we have $a_2r_1 = a_2a_1b_1 = a_2b_2b_1 = r_2b_1$. But this implies that s_1 and s_2 can be reduced to the same trace. This concludes the case $t \neq \varepsilon$.

Now assume that $t = \varepsilon$. Thus, we have the following diagram:

u_2	w_2	q_1	ε
a_2b_2	p_2	ε	q_2
<i>t</i> ₂	ε	p_1	w_1
	t_1	a_1b_1	u_1

If also $p_1 = \varepsilon$, the diagram looks as follows:

u_2	w_2	a_1b_1	ε
a_2b_2	p_2	ε	q_2
t_2	ε	ε	w_1
	t_1	a_1b_1	u_1

In particular, $w_1q_2Ia_1$ implying $w_1q_2Ir_1$. We have to show that $s_1 = p_2w_2r_1w_1q_2$ and $s_2 = w_1r_2w_2a_1b_1$ can be reduced to the same trace. We have $s_2 \rightarrow_R w_1r_2w_2r_1$. Moreover with the independencies listed above, we obtain

 $s_1 = p_2 w_2 r_1 w_1 q_2 = p_2 w_2 w_1 q_2 r_1 = w_1 p_2 q_2 w_2 r_1 \rightarrow_R w_1 r_2 w_2 r_1.$

If one of the traces p_2 , q_1 , or q_2 is empty, then we can argue analogously. Thus, we may assume that p_1 , p_2 , q_1 , and q_2 are nonempty. It follows $p_1 = a_1$, $q_1 = b_1$, $p_2 = a_2$, and $q_2 = b_2$. Then all traces from $\{w_1, w_2, a_1b_1, a_2b_2\}$ are pairwise independent, from which it follows again easily that s_1 and s_2 can be reduced to $w_1w_2r_1r_2$. \Box

Since *R* is terminating and confluent it defines unique normal forms. Alternatively to Definition 5.2, one can define the graph product $\mathbb{G}(W, E, (G_i)_{i \in W})$ of G_1, \ldots, G_n as the quotient monoid

$$\mathbb{G}(W, E, (G_i)_{i \in W}) = \mathbb{M}(A, I)/R.$$

The following lemma is important for solving the word problem in a graph product $G = \mathbb{G}(W, E, (G_i)_{i \in W})$:

Lemma 5.22. Let $u, v \in A^*$. Then u = v in G if and only if $\mathsf{NF}_R([u]_I) = \mathsf{NF}_R([v]_I)$. In particular we have u = 1 in G if and only if $\mathsf{NF}_R([u]_I) = \varepsilon$.

Proof. The if-direction is trivial. Let on the other hand $u, v \in A^*$ and suppose that u = v in *G*. By definition this is the case if and only if $[u]_I$ and $[v]_I$ represent the same element from $\mathbb{M}(A, I)/R$ and are hence congruent. Since *R* produces a normal form for elements from the same congruence class, this implies that $\mathsf{NF}_R([u]_I) = \mathsf{NF}_R([v]_I)$. \Box

On the trace monoid $\mathbb{M}(A,I)$ we can define a natural involution $^{-1}: \mathbb{M}(A,I) \to \mathbb{M}(A,I)$. For a letter $a \in A_{\sigma}$, a^{-1} is the inverse of a in the group G_{σ} . This defines an involution on A, which can be extended to the trace monoid $\mathbb{M}(A,I)$ by $[a_1 \cdots a_n]_I^{-1} = [a_n^{-1} \cdots a_1^{-1}]_I$.

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For the normal form of the product of two *R*-irreducible traces we have the following lemma, which was shown in [54] (equation (21) in the proof of Lemma 22) using a slightly different notation.

Lemma 5.23. Let $u, v \in \text{IRR}(R)$ be irreducible traces from $\mathbb{M}(A, I)$. Let $x = u \setminus_s v^{-1}$, $y = v \setminus_p u^{-1}$, $x' = x \setminus_s \max(x)$ and $y' = y \setminus_p \min(y)$. Then

$$NF_R(uv) = x'NF_R(\max(x)\min(y))y'$$

Before we prove this lemma, let us give some intuition. Since *u* and *v* both belong to IRR(*R*), rules of *R* can be only applied at the border of *u* and *v*. We have $u = x(u \sqcap_s v^{-1})$ and $v = (u^{-1} \sqcap_p v)y$. Moreover, $(u \sqcap_s v^{-1})^{-1} = (u^{-1} \sqcap_p v)$ and $(u^{-1} \sqcap_p v)$ is the longest trace *p* for which there exist traces *x* and *y* with $u = xp^{-1}$ and v = py. This means that $uv \to_R^* xy$, and in the trace *xy* no rule of the form $([aa^{-1}]_I, \varepsilon)$ can be applied. Hence, only rules of the form $([ab]_I, c) \in R$ can be applied and rule application can only occur at the border between *x* and *y*.

Proof of Lemma 5.23. As remarked above, we have $u = x(u \Box_s v^{-1})$ and $v = (u^{-1} \Box_p v)y$. Moreover, $(u \Box_s v^{-1})^{-1} = (u^{-1} \Box_p v)$ and $(u^{-1} \Box_p v)$ is the longest trace p for which there exist traces x and y with $u = xp^{-1}$ and v = py.

With x' and y' as defined in the lemma we get

$$uv = x' \max(x)(u \sqcap_s v^{-1})(u^{-1} \sqcap_p v) \max(y)y' \to_R^* x' \max(x) \max(y)y' \to_R^* x' \mathsf{NF}_R(\max(x)\min(y))y'.$$

Let $q = NF_R(\max(x)\min(y)) \in IRR(R)$. It remains to show that $x'qy' \in IRR(R)$. Note that also $x', y' \in IRR(R)$ (since x' is a prefix of $u \in IRR(R)$ and y' is a suffix of $v \in IRR(R)$).

Recall that $\max(x)$ and $\min(y)$ are independence cliques. Moreover, there cannot exist $a \in \max(x)$ with $a^{-1} \in \min(y)$, because this *a* could be moved to $(u^{-1} \sqcap_p v)$. It follows that *q* contains a symbol from A_{σ} if and only if $A_{\sigma} \cap (\max(x) \cup \min(y)) \neq \emptyset$.

In order to get a contradiction, let us assume that there exist $([ab]_I, r) \in R$ and traces q_1, q_2 such that $x'qy' = q_1abq_2$. By Levi's Lemma 5.10 and $x', q, y' \in IRR(R)$ we obtain up to symmetry one of the following two diagrams:

z_2	<i>s</i> ₂	q_2	t_2	Z	72	<i>s</i> ₂	q_2	t_2
ab	a	ε	b	a	ıb	а	b	ε
z_1	s_1	q_1	t_1	2	71	s_1	q_1	t_1
	<i>x</i> ′	q	y'			<i>x</i> ′	q	y'

Assume that $a, b \in A_{\sigma}$ ($\sigma \in W$). Let us first consider the left diagram. Since aIq_1 , bIq_2 , and $q = q_1q_2$, we obtain aIq and thus $aI\max(x)$. Furthermore, from the diagram we obtain also bIs_2 . Thus, aIs_2 , which implies $a \in \max(x')$. Together with $aI\max(x)$ it follows that $a \in \max(x'\max(x)) = \max(x)$, which contradicts $aI\max(x)$.

Now let us consider the right diagram. Again we have $a \in \max(x')$. Furthermore, aIq_1 , i.e., bIq_1 . Hence, $b \in \min(q) \cap A_{\sigma}$. Recall that $q = \mathsf{NF}_R(\max(x)\min(y))$.

Hence, there are two possibilities: Either there exists $a' \in \max(x) \cap A_{\sigma}$ or $b \in \min(y)$ and $bI\max(x)$. If $a' \in \max(x) \cap A_{\sigma}$, then $x = x'\max(x)$ would contain the factor $[aa']_I$, which contradicts $x \in IRR(R)$. If $b \in \min(y)$ and $bI\max(x)$, then also $aI\max(x)$, which implies $a \in \max(x'\max(x)) = \max(x)$; the same contradiction as in the previous paragraph. \Box

Note that in Lemma 5.23 $|\max(x)|$ as well as $|\min(y)|$ are bounded by n = |W|. Hence, there are at most *n* rewrite steps in the derivation of NF_{*R*}(max(*x*)min(*y*)) from max(*x*)min(*y*).

5.2.5 Simple Facts for Compressed Traces.

SLPs allow to represent traces in a succinct way. In this section, we collect some tools for manipulating SLP-represented traces. These tools will be important in order to solve the compressed word problem for a graph product.

Lemma 5.24. *The following problem can be decided in polynomial time:*

input: A finite independence alphabet (Σ, I) and SLPs \mathbb{A} and \mathbb{B} over the terminal alphabet Σ .

question: Does $[val(\mathbb{A})]_I = [val(\mathbb{B})]_I$ *hold?*

Proof. From A and B we can compute by Proposition 3.9(4) in polynomial time for all $(a,b) \in D$ SLPs $\mathbb{A}_{a,b}$ and $\mathbb{B}_{a,b}$ with $val(\mathbb{A}_{a,b}) = \pi_{\{a,b\}}(val(\mathbb{A}))$ and $val(\mathbb{B}_{a,b}) = \pi_{\{a,b\}}(val(\mathbb{B}))$. By Lemma 5.14, it suffices to check $val(\mathbb{A}_{a,b}) = val(\mathbb{B}_{a,b})$, which is possible in polynomial time by Theorem 3.17. \Box

The previous lemma is slightly generalized by the following one:

Lemma 5.25. *The following problem can be decided in polynomial time:*

input: A finite independence alphabet (Σ, I) and SLPs \mathbb{A} and \mathbb{B} over the terminal alphabet Σ .

question: Does $[val(\mathbb{A})]_I \preceq_p [val(\mathbb{B})]_I$ *hold?*

Proof. Compute $\mathbb{A}_{a,b}$ and $\mathbb{B}_{a,b}$ as above. By Lemma 5.19, we have to check for all $(a,b) \in D$, whether the word $val(\mathbb{A}_{a,b})$ is a prefix of the word $val(\mathbb{B}_{a,b})$. But this can be easily reduced to an equivalence check: Compute in polynomial time $\ell_{a,b} = |val(\mathbb{A}_{a,b})|$ (using Proposition 3.9(2)) and an SLP $\mathbb{C}_{a,b}$ with $val(\mathbb{C}_{a,b}) = val(\mathbb{B}_{a,b})[$: $\ell_{a,b}]$ (using Theorem 3.14). Finally check in polynomial time whether $val(\mathbb{C}_{a,b}) = val(\mathbb{A}_{a,b})$ for all $(a,b) \in D$ using Theorem 3.17. \Box

Lemma 5.26. There is a polynomial time algorithm for the following problem:

input: A finite independence alphabet (Σ, I) and an SLP \mathbb{A} over the alphabet Σ . *output:* The sets $\max([val(\mathbb{A})]_I)$ and $\min([val(\mathbb{A})]_I)$

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Proof. Without loss of generality we can assume that $\mathbb{A} = (V, \Sigma, S, \text{rhs})$ is in Chomsky normal form. We show how to compute $\max([val(\mathbb{A})]_I)$. First we compute $alph(val(\mathbb{A}))$ in polynomial time using Proposition 3.9(1). For $a \in alph(val(\mathbb{A}))$ let $p_a \in \{1, ..., |val(\mathbb{A})|\}$ maximal such that $val(\mathbb{A})[p_a] = a$. These numbers can be computed in polynomial time by Proposition 3.9(5). Using Theorem 3.14 we compute in polynomial time an SLP \mathbb{B} such that $val(\mathbb{B}) = val(\mathbb{A})[p_a + 1 :]$ Then $a \in \max([val(\mathbb{A})]_I)$ if and only if aI alph $(val(\mathbb{B}))$. This property can be checked in polynomial time by computing alph $(val(\mathbb{B}))$ (using Proposition 3.9(1)). Repeating this procedure for all $a \in alph(val(\mathbb{A}))$ we get the set $\max([val(\mathbb{A})]_I)$. The set $\min([val(\mathbb{A})]_I)$ can be determined similarly. □

For the following, recall the definition of a C-expression (Definition 3.3).

Lemma 5.27. There is a polynomial time algorithm for the following problem:

input: A finite independence alphabet (Σ, I) and an SLP \mathbb{A} over the terminal alphabet Σ .

output: C-expressions α and β with $Var(\alpha) = Var(\beta) = \{S\}$ (where S is the start variable of \mathbb{A}), $[val_{\mathbb{A}}(\alpha)]_I = [val(\mathbb{A})]_I \setminus_s max([val(\mathbb{A})]_I)$, and $[val_{\mathbb{A}}(\beta)]_I = [val(\mathbb{A})]_I \setminus_p min([val(\mathbb{A})]_I)$

Moreover, $|\alpha|$ (respectively, $|\beta|$) can be bounded by $\mathcal{O}(|\min([val(\mathbb{A})]_I)| \cdot \log_2(|val(\mathbb{A})|))$ (respectively, $\mathcal{O}(|\max([val(\mathbb{A})]_I)| \cdot \log_2(|val(\mathbb{A})|)))$.

Proof. We show how to compute the expression α in polynomial time; for β one can argue analogously. By Lemma 5.26 we can find the set $\max([val(\mathbb{A})]_I)$ in polynomial time. Let $p_a \in \{1, ..., |val(\mathbb{A})|\}$ be maximal such that $val(\mathbb{A})[p_a] = a$ for $a \in \max([val(\mathbb{A})]_I)$ and let $\{k_1, ..., k_m\} = \{p_a \mid a \in \max([val(\mathbb{A})]_I)\}$ with $k_1 < k_2 < \cdots < k_m$. These numbers can be computed in polynomial time by Proposition 3.9(5). We set

$$\alpha = S[:k_1 - 1]S[k_1 + 1:k_2 - 1] \cdots S[k_{m-1} + 1:k_m - 1]S[k_m + 1:].$$

Then $[\operatorname{val}_{\mathbb{A}}(\alpha)]_I = [\operatorname{val}(\mathbb{A})]_I \setminus_s \max([\operatorname{val}(\mathbb{A})]_I)$. Since the positions k_1, \ldots, k_m are represented in binary, each of them needs $\mathscr{O}(\log_2(|\operatorname{val}(\mathbb{A})|))$ many bits. Hence $|\alpha|$ can be bounded by $\mathscr{O}(m \cdot \log_2(|\operatorname{val}(\mathbb{A})|))$. Since $m = |\max([\operatorname{val}(\mathbb{A})]_I)|$ we have $|\alpha| \le \mathscr{O}(|\max([\operatorname{val}(\mathbb{A})]_I)| \cdot \log_2(|\operatorname{val}(\mathbb{A})|))$. \Box

5.3 The Compressed Word Problem for Graph Products

In this section, we will prove Theorem 5.4. Our technique will generalize our algorithm for free groups (Theorem 4.11). There are two aspects, which make the proof of Theorem 5.4 more complicated than the proof of Theorem 4.11 for free groups:

• We have to deal with partial commutation, i.e., traces instead of words.

• We have to prove a preservation theorem: Whereas Theorem 4.11 deals with a fixed group (a finitely generated free group), the G_i ($i \in W$) in Theorem 5.4 are arbitrary finitely generated groups and we have to reduce the compressed word problem for the graph product to the compressed word problems for the groups G_i .

Let us fix the *finite* independence alphabet (W, E) with $W = \{1, ..., n\}$ and finitely generated groups G_i for $i \in \{1, ..., n\}$ for the rest of this section. Let furthermore Σ_i be a finite generating set for G_i for $i \in \{1, ..., n\}$. Without loss of generality we can assume that Σ_i does not contain the identity element and that $\Sigma_i \cap \Sigma_j = \emptyset$ for $i \neq j$. We define $\Sigma = \bigcup_{i=1}^n \Sigma_i$. Let *G* denote the graph product $\mathbb{G}(W, E, (G_i)_{i \in W})$ for the rest of this section. Moreover, let A_i , A, I, and R have the same meaning as in Section 5.2.4. Note that $\Sigma_i \subseteq A_i$ for all $1 \leq i \leq n$.

Recall the definition of a 2-level PCSLP (Definition 3.24). For the following discussion, let us fix a 2-level PCSLP

$$\mathbb{B} = (\mathsf{Up}, \mathsf{Lo}, \Sigma \cup \Sigma^{-1}, S, \mathsf{rhs})$$

over the terminal alphabet $\Sigma \cup \Sigma^{-1}$ (the monoid generating set of our graph product *G*). We introduce several properties for \mathbb{B} .

Definition 5.28 (pure). The 2-level PCSLP \mathbb{B} is *pure* if for every $X \in \text{Lo}$ there exists $i \in W$ such that $\operatorname{val}_{\mathbb{B}}(X) \in (\Sigma_i \cup \Sigma_i^{-1})^+$ and $\operatorname{val}_{\mathbb{B}}(X) \neq 1$ in G_i (hence $\operatorname{val}_{\mathbb{B}}(X)$) represents a group element from the set A).

For the following notations, assume that \mathbb{B} is pure. Then, we can define the mapping type_{\mathbb{B}} : Lo \rightarrow *W* by type_{\mathbb{B}}(*X*) = *i* if val_{\mathbb{B}}(*X*) $\in (\Sigma_i \cup \Sigma_i^{-1})^+$. For *i* \in *W* let

$$\mathsf{Lo}(i) = \{ X \in \mathsf{Lo} \mid \mathsf{type}_{\mathbb{B}}(X) = i \}.$$

Then the sets $Lo(1), \ldots, Lo(n)$ form a partition of Lo. Moreover, using (5.1) on page 86 we can define an independence relation $I_{\mathbb{B}}$ on Lo by

$$I_{\mathbb{B}} = E[\mathsf{Lo}(1), \dots, \mathsf{Lo}(n)].$$

Definition 5.29 (nicely projecting). The 2-level PCSLP \mathbb{B} is nicely projecting if for every subexpression of the form $\pi_{\Delta}(\alpha)$ ($\Delta \subseteq Lo$) that appears in a right-hand side of up(\mathbb{B}), there exists $K \subseteq W$ with $\Delta = \bigcup_{i \in K} Lo(i)$.

This condition will be needed in order to apply Lemma 3.16. Note that the number of all sets $\bigcup_{i \in K} Lo(i)$ with $K \subseteq W$ is bounded by $2^n = \mathcal{O}(1)$ (the size of *W* is a fixed constant in our consideration).

Definition 5.30 (irredundant). The 2-level PCSLP \mathbb{B} is irredundant if for all $X, Y \in$ Lo such that $X \neq Y$ and type_B(X) = type_B(Y) = i, we have val_B $(X) \neq$ val_B(Y) in the group G_i .

One can think of a pure and irredundant 2-level PCSLP \mathbb{B} as a PCSLP, where the terminal alphabet is a finite subset $B \subseteq A$, with $A = \bigcup_{i \in W} G_i \setminus \{1\}$ from Section 5.2.4:

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Take up(\mathbb{B}), replace every variable $X \in Lo(i)$ ($i \in W$) by the group element from G_i represented by val_B(X), and remove the lower part lo(\mathbb{B}). Moreover, each element from $B \cap A_i$ ($i \in W$) is represented by a unique SLP over the terminal alphabet $\Sigma_i \cup$ Σ_i^{-1} (namely the lower part lo(\mathbb{B}) with the appropriate start variable). If \mathbb{B} is pure but not irredundant then, using the compressed word problems for the groups G_i as oracles, one can compute a pure and irredundant 2-level PCSLP \mathbb{C} such that val(\mathbb{B}) = val(\mathbb{C}) in G as follows: If \mathbb{B} contains two variables $X, Y \in Lo$ such that $X \neq Y$, type_B(X) = type_B(Y) = i and val_B(X) = val_B(Y) in G_i , one has to replace Yin all right-hand sides by X. Note that this process does not change the set of upper level variables of \mathbb{B} .

Definition 5.31 (saturated). The 2-level PCSLP \mathbb{B} is *saturated* if for every $X \in Lo$ with type_{\mathbb{B}}(X) = i, there exists $Y \in Lo$ with type_{\mathbb{B}}(Y) = i and $val_{\mathbb{B}}(Y) = val_{\mathbb{B}}(X)^{-1}$ in G_i .

If \mathbb{B} is pure, irredundant and saturated, then for every $X \in \mathsf{Lo}$ with $\mathsf{type}_{\mathbb{B}}(X) = i$, there must be a unique $Y \in \mathsf{Lo}$ with $\mathsf{type}_{\mathbb{B}}(Y) = i$ and $\mathsf{val}_{\mathbb{B}}(Y) = \mathsf{val}_{\mathbb{B}}(X)^{-1}$ in G_i (we may have Y = X in case $\mathsf{val}_{\mathbb{B}}(X)^2 = 1$ in G_i). This Y is denoted by X^{-1} , and we define $(X_1 \cdots X_n)^{-1} = X_n^{-1} \cdots X_1^{-1}$ for $X_1, \ldots, X_n \in \mathsf{Lo}$.

Definition 5.32 (well-formed). The 2-level PCSLP \mathbb{B} is *well-formed*, if it is pure, irredundant, saturated, and nicely projecting.

Assume that \mathbb{B} is well-formed. We call a trace $w \in \mathbb{M}(\mathsf{Lo}, I_{\mathbb{B}})$ reduced if it contains no factor $[YZ]_{I_{\mathbb{B}}}$ with $Y, Z \in \mathsf{Lo}$ and $\mathsf{type}_{\mathbb{B}}(Y) = \mathsf{type}_{\mathbb{B}}(Z)$. Note that $[X_1 \cdots X_m]_{I_{\mathbb{B}}} \in$ $\mathbb{M}(\mathsf{Lo}, I_{\mathbb{B}})$ with $X_1, \ldots, X_m \in \mathsf{Lo}$ is reduced if and only if $[a_1 \cdots a_m]_I \in \mathsf{IRR}(R)$, where $a_j \in A$ is the group element represented by $\mathsf{val}_{\mathbb{B}}(X_j)$ for $1 \leq j \leq m$. A variable $X \in \mathsf{Up} \cup \mathsf{Lo}$ is reduced if either $X \in \mathsf{Lo}$ or $X \in \mathsf{Up}$ and the trace $[\mathsf{uval}(X)]_{I_{\mathbb{B}}}$ is reduced. Finally, \mathbb{B} is reduced, if every variable X of \mathbb{B} is reduced. We have:

Lemma 5.33. Let \mathbb{B} be a well-formed and reduced 2-level PCSLP. Then $val(\mathbb{B}) = 1$ in *G* if and only if $uval(\mathbb{B}) = \varepsilon$.

Proof. Clearly, if $uval(\mathbb{B}) = \varepsilon$, then also $val(\mathbb{B}) = \varepsilon$ and hence $val(\mathbb{B}) = 1$ in *G*. For the other direction we assume that $uval(\mathbb{B}) = X_1 \cdots X_m$ for some m > 0. Since \mathbb{B} is pure there are $a_1, \ldots, a_m \in A$ such that $val(X_i)$ represents the group element a_i for $i \in \{1, \ldots, m\}$. Since \mathbb{B} is reduced, we have $[a_1 \cdots a_m]_I \in IRR(R)$ and hence $\mathsf{NF}_R([a_1 \cdots a_m]_I) = [a_1 \cdots a_m]_I \neq \varepsilon$. From Lemma 5.22 it follows that $a_1 \cdots a_m \neq 1$ in *G* and hence $val(\mathbb{B}) \neq 1$ in *G*. \Box

Together with Lemma 5.33, the following proposition can be used to solve the compressed word problem for the graph product G.

Proposition 5.34. Given an SLP \mathbb{A} over $\Sigma \cup \Sigma^{-1}$ we can compute a well-formed and reduced 2-level PCSLP \mathbb{B} with $val(\mathbb{A}) = val(\mathbb{B})$ in G in polynomial time using oracle access to the decision problems $CWP(G_i)$ $(1 \le i \le n)$.

Proof. Let $\mathbb{A} = (V_{\mathbb{A}}, \Sigma \cup \Sigma^{-1}, S, \operatorname{rhs}_{\mathbb{A}})$ be the given input SLP over $\Sigma \cup \Sigma^{-1}$. We assume without loss of generality that \mathbb{A} is in Chomsky normal form. Moreover, we exclude the trivial case that $\operatorname{rhs}_{\mathbb{A}}(S) \in \Sigma \cup \Sigma^{-1}$. We construct a sequence of 2-level PCSLPs $\mathbb{A}_j = (\operatorname{Up}_j, \operatorname{Lo}_j, \Sigma \cup \Sigma^{-1}, S, \operatorname{rhs}_j)$ $(0 \le j \le r \le |V_{\mathbb{A}}|)$ such that the following holds for all $0 \le j \le r$:

(a) \mathbb{A}_i is well-formed.

(b) $|\mathbb{A}_j| \leq 2 \cdot |\mathbb{A}| + \mathcal{O}(j \cdot |\mathbb{A}|) \leq 2 \cdot |\mathbb{A}| + \mathcal{O}(|V_{\mathbb{A}}| \cdot |\mathbb{A}|)$

(c) $\operatorname{val}(\mathbb{A}) = \operatorname{val}(\mathbb{A}_j)$ in G for all $0 \le j \le r$.

(d) If $X \in Up_j$ is not reduced, then $rhs_j(X) \in (Up_j \cup Lo_j)^2$.

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(e) |uval(\mathbb{A}_i)| \leq |val(\mathbb{A})|
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Moreover, the final 2-level PCSLP $\mathbb{B} = \mathbb{A}_r$ will be reduced. Let us write type_{*j*} for type_{\mathbb{A}_i} and I_j for $I_{\mathbb{A}_i}$ in the following.

During the construction of \mathbb{A}_{j+1} from \mathbb{A}_j , we will replace the right-hand side $YZ(Y, Z \in Up_j \cup Lo_j)$ for a non-reduced (with respect to \mathbb{A}_j) variable $X \in Up_j$ by a new right-hand side of size $\mathscr{O}(|\mathbb{A}|)$, so that X is reduced in \mathbb{A}_{j+1} and $val_{\mathbb{A}_j}(X) = val_{\mathbb{A}_{j+1}}(X)$ in G. All other right-hand sides for upper level variables will be kept, and constantly many new lower level variables will be added.

We start the construction with the 2-level PCSLP

$$({X \in V_{\mathbb{A}} \mid \operatorname{rhs}_{\mathbb{A}}(X) \in V_{\mathbb{A}}^{2}}, {X \in V_{\mathbb{A}} \mid \operatorname{rhs}_{\mathbb{A}}(X) \in \Sigma \cup \Sigma^{-1}}, \Sigma \cup \Sigma^{-1}, S, \operatorname{rhs}_{\mathbb{A}}).$$

Note that *S* is an upper level variable in this system (which is required for 2-level PCSLPs) since we assume $rhs_{\mathbb{A}}(S) \notin \Sigma \cup \Sigma^{-1}$. Moreover, the system is pure and nicely projecting (there are no projection operations in right-hand sides), but not necessarily irredundant and saturated. The latter two properties can be easily enforced by adding for every variable *X* with $rhs_{\mathbb{A}}(X) = a \in \Sigma \cup \Sigma^{-1}$ a variable X^{-1} for a^{-1} and then eliminating redundant lower level variables. The resulting 2-level PCSLP \mathbb{A}_0 is well-formed and satisfies $|\mathbb{A}_0| \leq 2 \cdot |\mathbb{A}|$ and $val(\mathbb{A}_0) = val(\mathbb{A})$. Hence (a), (b), and (c) are satisfied and also (d) and (e) clearly hold.

For the inductive step of the construction, assume that we have constructed $\mathbb{A}_j = (Up_j, Lo_j, \Sigma \cup \Sigma^{-1}, S, rhs_j)$ and let $X \in Up_j, Y, Z \in Up_j \cup Lo_j$ such that $rhs_j(X) = YZ$, X is not reduced, but Y and Z are already reduced. In order to make X reduced, we will apply Lemma 5.23. The following proposition, whose proof is postponed to the next Section 5.3.1, makes this application possible.

Proposition 5.35. *Let* (W, E) *be a fixed independence alphabet with* $W = \{1, ..., n\}$ *. The following problem can be solved in polynomial time:*

input: Pairwise disjoint finite alphabets $\Gamma_1, \ldots, \Gamma_n$, an SLP \mathbb{B} over the terminal alphabet $\Gamma = \bigcup_{i=1}^n \Gamma_i$, and two variables Y and Z from \mathbb{B} .

output: PC-expressions α , β with $Var(\alpha) = Var(\beta) = \{Y\}$ such that the following holds, where $J = E[\Gamma_1, ..., \Gamma_n]$:

(1) For every subexpression of the form $\pi_{\Delta}(\gamma)$ in α and β there exists $K \subseteq \{1, ..., n\}$ with $\Delta = \bigcup_{i \in K} \Gamma_i$.

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- (2) $[\operatorname{val}_{\mathbb{B}}(\alpha)]_J = [\operatorname{val}_{\mathbb{B}}(Y)]_J \setminus_p [\operatorname{val}_{\mathbb{B}}(Z)]_J$
- (3) $[\operatorname{val}_{\mathbb{B}}(\beta)]_J = [\operatorname{val}_{\mathbb{B}}(Y)]_J \sqcap_p [\operatorname{val}_{\mathbb{B}}(Z)]_J$
- (4) $|\alpha|, |\beta| \leq \mathcal{O}(\log|\mathsf{val}(\mathbb{B})|)$

An analogous statement can be shown for the operations \backslash_s and \sqcap_s which refer to the suffix order on traces. Actually, we only need the PC-expression α for the trace difference.

In order to apply Proposition 5.35 to our situation we transform the upper level part up(\mathbb{A}_j) into an equivalent SLP \mathbb{C} over the terminal alphabet Lo_j using Lemma 3.16. This is possible, since \mathbb{A}_j is nicely projecting by (a). Every upper level variable of \mathbb{A}_j is also present in \mathbb{C} and we have uval $_{\mathbb{A}_j}(C) = \operatorname{val}_{\mathbb{C}}(C)$ for every $C \in$ Up_j. The SLP \mathbb{C} can be constructed in time polynomially bounded in $|\operatorname{up}(\mathbb{A}_j)|$ and hence in $|\mathbb{A}|$. Note that we have $|\operatorname{val}(\mathbb{C})| = |\operatorname{uval}(\mathbb{A}_j)| \leq |\operatorname{val}(\mathbb{A})| \leq 2^{|\mathbb{A}|}$ by (e). We can add to \mathbb{C} symbols Y^{-1} and Z^{-1} such that $\operatorname{val}_{\mathbb{C}}(Y^{-1}) = \operatorname{val}_{\mathbb{C}}(Y)^{-1} = \operatorname{uval}_{\mathbb{A}_j}(Y)^{-1}$ and $\operatorname{val}_{\mathbb{C}}(Z^{-1}) = \operatorname{val}_{\mathbb{C}}(Z)^{-1} = \operatorname{uval}_{\mathbb{A}_j}(Z)^{-1}$. In case $Y \in \operatorname{Lo}_j$ (respectively, $Z \in \operatorname{Lo}_j$), the symbol Y^{-1} (respectively, Z^{-1}) is already present (since \mathbb{A}_j is saturated).

Now we set $\Gamma_i = Lo_j(i)$ and apply Proposition 5.35 (and the analogous statement for \backslash_s and \sqcap_s) to Γ_i ($i \in W$) and \mathbb{C} to obtain two PC-expressions α and β such that $|\alpha|, |\beta| \leq \mathcal{O}(|\mathbb{A}|)$, $Var(\alpha) = \{Y\}$, $Var(\beta) = \{Z\}$, and

$$\begin{split} [\mathsf{val}_{\mathbb{C}}(\alpha)]_{I_j} &= [\mathsf{val}_{\mathbb{C}}(Y)]_{I_j} \setminus_s [\mathsf{val}_{\mathbb{C}}(Z^{-1})]_{I_j}, \\ [\mathsf{val}_{\mathbb{C}}(\beta)]_{I_i} &= [\mathsf{val}_{\mathbb{C}}(Z)]_{I_i} \setminus_p [\mathsf{val}_{\mathbb{C}}(Y^{-1})]_{I_i}. \end{split}$$

But due to the correspondence between \mathbb{C} and $up(\mathbb{A}_j)$, this means (uval denotes $uval_{\mathbb{A}_j}$)

$$\begin{split} [\mathsf{uval}(\alpha)]_{I_j} &= [\mathsf{uval}(Y)]_{I_j} \setminus_s [\mathsf{uval}(Z)]_{I_j}^{-1}, \\ [\mathsf{uval}(\beta)]_{I_j} &= [\mathsf{uval}(Z)]_{I_j} \setminus_p [\mathsf{uval}(Y)]_{I_i}^{-1}. \end{split}$$

Moreover, for every subexpression of the form $\pi_{\Delta}(\gamma)$ in α or β there exists $K \subseteq \{1, ..., n\}$ with $\Delta = \bigcup_{i \in K} Lo_j(i)$. Intuitively, α and β represent the parts of uval(Y) and uval(Z) that remain after cancellation in the graph group generated by the alphabet Lo_j. Hence, $[uval(\alpha)]_{I_j}[uval(\beta)]_{I_j}$ does not contain a factor of the form $[XX^{-1}]_{I_j}$ for $X \in Lo_j$. Using Lemma 5.26 we can compute the sets $V_{\max} = \max([uval(\alpha)]_{I_j})$ and $V_{\min} = \min([uval(\beta)]_{I_j})$ in polynomial time. In order to apply Lemma 5.26 we have to compute, using Lemma 3.16, temporary SLPs for the words $uval(\alpha)$ and $uval(\beta)$. These SLPs are temporary in the sense that they are not needed for the next iteration of the algorithm. Recall that V_{\max} and V_{\min} are subsets of Lo_j. Since every independence clique of (Lo_j, I_j) has size at most $|W| = n = \mathcal{O}(1)$, we have $|V_{\max}|, |V_{\min}| = \mathcal{O}(1)$.

Next, Lemma 5.27 allows us to compute in polynomial time PC-expressions α', β' such that $Var(\alpha') = Var(\alpha) = \{Y\}$, $Var(\beta') = Var(\beta) = \{Z\}$, and

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$$\begin{aligned} [\mathsf{uval}(\alpha')]_{I_j} &= [\mathsf{uval}(\alpha)]_{I_j} \setminus_s [V_{\max}]_{I_j}, \\ [\mathsf{uval}(\beta')]_{I_i} &= [\mathsf{uval}(\beta)]_{I_i} \setminus_p [V_{\min}]_{I_i}. \end{aligned}$$

The length bound in Lemma 5.27 implies that $|\alpha'|, |\beta'| \leq \mathcal{O}(|\mathbb{A}|)$. Moreover, for every $1 \leq i \leq n$ we must have $|V_{\max} \cap \mathsf{Lo}_j(i)| \leq 1$ and $|V_{\min} \cap \mathsf{Lo}_j(i)| \leq 1$. Let

$$egin{aligned} &V'_{\max} = \{X \in V_{\max} \mid \mathsf{type}_j(X)
ot\in \mathsf{type}_j(V_{\min})\}, \ &V'_{\min} = \{X \in V_{\min} \mid \mathsf{type}_j(X)
ot\in \mathsf{type}_j(V_{\max})\}. \end{aligned}$$

If $(X_1, X_2) \in V_{\max} \times V_{\min}$ is such that $type_j(X_1) = type_j(X_2) = i$, then by the definition of $[uval(\alpha)]_{I_j}$ and $[uval(\beta)]_{I_j}$, we must have $val(X_1)val(X_2) \neq 1$ in G_i (no further cancellation is possible in the product $[uval(\alpha)]_{I_j}[uval(\beta)]_{I_j}$). For each such pair we add a new lower level variable X_{X_1,X_2} to Lo_j with right-hand side X_1X_2 ; let V' be the set of these new variables. Clearly, $|V'| \leq n = \mathcal{O}(1)$. Finally, the right-hand side for X is changed to the PC-expression

$$\gamma = \alpha' v'_{\max} v' v'_{\min} \beta', \qquad (5.3)$$

where v'_{max} (respectively, v', v'_{min}) is an arbitrary word that enumerates all variables from V'_{max} (respectively, V', V'_{min}). We have $|\gamma| = |\alpha'| + |\beta'| + \mathcal{O}(1) \le \mathcal{O}(|\mathbb{A}|)$. Clearly, γ evaluates in G to the same group element as $val_{A_i}(X)$. By adding at most $|V'| = \mathcal{O}(1)$ many further lower level variables, we obtain a saturated system. The resulting 2-level PCSLP is not necessarily irredundant, but this can be ensured, as explained in the paragraph after Definition 5.30, using oracle calls to the compressed word problems for the vertex groups G_i (this does not increase the size of the 2-level PCSLP). The resulting 2-level PCSLP is pure, irredundant, and saturated, but not necessarily nicely projecting, because of the new lower level variables from V'. But note that these variables do not occur in the scope of a projection operator π_{Δ} ; they only occur in the words v' in (5.3). Hence, we may add the new lower level variables to the appropriate sets appearing in projection operators, so that the 2-level PCSLP becomes nicely projecting as well. The resulting 2-level PCSLP is \mathbb{A}_{i+1} ; it is wellformed. Its size can be bounded by $|\mathbb{A}_j| + \mathcal{O}(|\mathbb{A}|) \leq 2 \cdot |\mathbb{A}| + \mathcal{O}(j \cdot |\mathbb{A}|) + \mathcal{O}(|\mathbb{A}|) \leq 2 \cdot |\mathbb{A}| + \mathcal{O}(j \cdot |\mathbb{A}|) + \mathcal{O}(|\mathbb{A}|) \leq 2 \cdot |\mathbb{A}| + \mathcal{O}(j \cdot |\mathbb{A}|) + \mathcal{O}(|\mathbb{A}|) \leq 2 \cdot |\mathbb{A}| + \mathcal{O}(j \cdot |\mathbb{A}|) + \mathcal{O}(|\mathbb{A}|) \leq 2 \cdot |\mathbb{A}| + \mathcal{O}(j \cdot |\mathbb{A}|) + \mathcal{O}(|\mathbb{A}|) \leq 2 \cdot |\mathbb{A}| + \mathcal{O}(j \cdot |\mathbb{A}|) + \mathcal{O}(|\mathbb{A}|) \leq 2 \cdot |\mathbb{A}| + \mathcal{O}(j \cdot |\mathbb{A}|) + \mathcal{O}(|\mathbb{A}|) \leq 2 \cdot |\mathbb{A}| + \mathcal{O}(j \cdot |\mathbb{A}|) + \mathcal{O}(|\mathbb{A}|) \leq 2 \cdot |\mathbb{A}| + \mathcal{O}(j \cdot |\mathbb{A}|) + \mathcal{O}(|\mathbb{A}|) \leq 2 \cdot |\mathbb{A}| + \mathcal{O}(j \cdot |\mathbb{A}|) + \mathcal{O}(|\mathbb{A}|) \leq 2 \cdot |\mathbb{A}| + \mathcal{O}(j \cdot |\mathbb{A}|) + \mathcal{O}(|\mathbb{A}|) \leq 2 \cdot |\mathbb{A}| + \mathcal{O}(j \cdot |\mathbb{A}|) + \mathcal{O}(|\mathbb{A}|) \leq 2 \cdot |\mathbb{A}| + \mathcal{O}(j \cdot |\mathbb{A}|) + \mathcal{O}(|\mathbb{A}|) \leq 2 \cdot |\mathbb{A}| + \mathcal{O}(j \cdot |\mathbb{A}|) + \mathcal{O}(j \cdot |$ $2 \cdot |\mathbb{A}| + \mathcal{O}((j+1) \cdot |\mathbb{A}|)$; hence (a) and (b) above hold for \mathbb{A}_{j+1} . Moreover, in the group G we have $val(\mathbb{A}_{j+1}) = val(\mathbb{A}_j) = val(\mathbb{A})$, hence (c) holds. Lemma 5.23 implies that X is reduced in \mathbb{A}_{j+1} which implies property (d) for \mathbb{A}_{j+1} . Finally, for (e) note that $|uval(\mathbb{A}_{i+1})| \leq |uval(\mathbb{A}_i)| \leq |val(\mathbb{A})|$.

After $r \leq |V_{\mathbb{A}}|$ steps, our construction yields the well-formed and reduced 2-level PCSLP \mathbb{A}_r with $val(\mathbb{A}_r) = val(\mathbb{A})$ in *G*. This proves Proposition 5.34. \Box

We can now easily finish the proof of Theorem 5.4.

Proof of Theorem 5.4. Let \mathbb{A} be an SLP over the monoid generating set $\Sigma \cup \Sigma^{-1}$ of the graph product *G*. By Proposition 5.34 we can translate \mathbb{A} into a reduced and well-formed 2-level PCSLP \mathbb{B} with $val(\mathbb{A}) = val(\mathbb{B})$ in *G*. This translation can be done in polynomial time using oracle access to the problems $CWP(G_i)$ for $i \in W$. By Lemma 5.33, we have $val(\mathbb{A}) = 1$ in *G* if and only if $uval(\mathbb{B}) = \varepsilon$. By Lemma 3.16

we can translate $up(\mathbb{B})$ in polynomial time into an equivalent SLP, for which it is trivial to check whether it produces the empty word. This proves Theorem 5.4. \Box

5.3.1 Proof of Proposition 5.35

We will prove Proposition 5.35 in this section. Recall that we fixed the finite undirected graph (W, E) with $W = \{1, ..., n\}$.

Proposition 5.35 (restated). *Let* (W, E) *be a fixed independence alphabet with* $W = \{1, ..., n\}$ *. The following problem can be solved in polynomial time:*

input: Pairwise disjoint finite alphabets $\Gamma_1, \ldots, \Gamma_n$, an SLP \mathbb{B} over the terminal alphabet $\Gamma = \bigcup_{i=1}^n \Gamma_i$, and two variables Y and Z from \mathbb{B} .

output: PC-expressions α , β with $Var(\alpha) = Var(\beta) = \{Y\}$ such that the following holds, where $I = E[\Gamma_1, ..., \Gamma_n]$:

(1) For every subexpression of the form $\pi_{\Delta}(\gamma)$ in α or β there exists $K \subseteq W$ with $\Delta = \bigcup_{i \in K} \Gamma_i$.

(2) $[\operatorname{val}_{\mathbb{B}}(\alpha)]_{I} = [\operatorname{val}_{\mathbb{B}}(Y)]_{I} \setminus_{p} [\operatorname{val}_{\mathbb{B}}(Z)]_{I}$

(3)
$$[\operatorname{val}_{\mathbb{B}}(\beta)]_{I} = [\operatorname{val}_{\mathbb{B}}(Y)]_{I} \sqcap_{p} [\operatorname{val}_{\mathbb{B}}(Z)]_{I}$$

(4) $|\alpha|, |\beta| \leq \mathcal{O}(\log|\mathsf{val}(\mathbb{B})|)$

In the following, we will write \setminus and \sqcap for \setminus_p and \sqcap_p , respectively. Moreover, if $\Delta = \bigcup_{i \in K} \Gamma_i$, we will write π_K for the projection morphism $\pi_\Delta : \Gamma^* \to \Gamma^*$. Let us fix $\Gamma = \bigcup_{i=1}^n \Gamma_i$ and let $I = E[\Gamma_1, \dots, \Gamma_n]$.

Let $s \in \Gamma^*$ be a word and $J \subseteq \{1, ..., |s|\}$ a set of positions in *s*. Below, we identify the dependence graph D_s with the edge relation of D_s . We are looking for a succinct representation for the set of all positions *p* such that $\exists j \in J : (j, p) \in D_s^*$. This is the set of positions *p* for which there exists a path in the dependence graph D_s from some position $j \in J$ to position *p*. For $i \in W$ define

$$\mathsf{pos}(s, J, i) = \min(\{|s|+1\} \cup \{p \mid 1 \le p \le |s|, s[p] \in \Gamma_i, \exists j \in J : (j, p) \in D_s^*\}).$$

Example 5.36. To ease the reading we will consider the set $W = \{a, b, c, d, e\}$ instead of $W = \{1, ..., 5\}$. The dependence relation *D* is:



Let $\Gamma_x = \{x\}$ for $x \in W$. We consider the following word *s*, where we write the position number on top of each symbol:

1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 s = d b c d b a c d b d e a b d c

The dependence graph of *s* looks as follows:



Let $J = \{5, 6, 9\}$. We want to determine pos(s, J, 4). In the following picture of the dependence graph of s we mark positions from J with boxes and all positions $p \notin J$ with $(j, p) \in D_s^*$ for some $j \in J$ with circles.



The positions with letters from $\Gamma_4 = \{d\}$ which depend from positions from J are $\{8, 10, 14\}$ with the minimum 8, hence pos(s, J, 4) = 8.

For the set $J = \{6, 9\}$ we get the following picture for pos(s, J, 4):



Since there are no positions with letters from $\Gamma_4 = \{d\}$ which depend from positions from *J*, it follows that pos(s, J, 4) = |s| + 1 = 16.

Instead of $pos(s, \{p\}, i)$, we simply write pos(s, p, i). Note that $pos(s, \emptyset, i) = |s| + 1$. The definition of pos(s, J, i) and the fact that symbols from a set Γ_i are pairwise dependent implies:

Lemma 5.37. Let $s \in \Gamma^*$ and $J \subseteq \{1, \dots, |s|\}$. Then for every position $1 \le p \le |s|$ the following two properties are equivalent:

- $\exists j \in J : (j, p) \in D_s^*$ If $s[p] \in \Gamma_i$ then $p \ge pos(s, J, i)$.

We will also need the following lemma:

Lemma 5.38. For a given SLP \mathbb{A} , a position $1 \le p \le |val(\mathbb{A})|$ and $i \in W$, we can *compute the position* $pos(val(\mathbb{A}), p, i)$ *in polynomial time.*
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Proof. We first need a few definitions: Let $D = (W \times W) \setminus E$ be the dependence relation for our fixed independence alphabet (W, E). A path in (W, D) (viewed as an undirected graph) is called *simple*, if it does not visit a node twice. For $j \in W$ let \mathcal{P}_j be the set of all simple paths in the dependence alphabet (W, D) that start in the node j. The path, which only consists of the node j belongs to \mathcal{P}_j . The size of each set \mathcal{P}_j is bounded by $2^{|W|}|W|!$, which is a fixed constant in our consideration.

Let us now fix \mathbb{A} , p, and i as in the lemma. By Proposition 3.9(3), we can compute in polynomial time the unique node $j \in W$ such that $val(\mathbb{A})[p] \in \Gamma_j$. For a simple path $\rho \in \mathscr{P}_j$ let us define $pos(p,\rho) \in \{1,\ldots,|val(\mathbb{A})|+1\}$ inductively. Let $\rho = (j_1, j_2, \ldots, j_\ell)$ with $j = j_1$. If $\ell = 1$, then $pos(p,\rho) = p$. Otherwise let $\rho' = (j_1, j_2, \ldots, j_{\ell-1})$ and let $pos(p,\rho)$ be the smallest position $q > pos(p,\rho')$ such that $val(\mathbb{A})[q] \in \Gamma_{j_\ell}$ if such a position exists, otherwise $pos(p,\rho) = |val(\mathbb{A})| + 1$.

We can compute the position $pos(p,\rho)$ in polynomial time as follows: Assume that the position $q' = pos(p,\rho')$ is already computed. Using Theorem 3.14 we can compute in polynomial time an SLP \mathbb{A}' with $val(\mathbb{A}') = val(\mathbb{A})[q'+1:]$. Then $pos(p,\rho)$ is the smallest position in $val(\mathbb{A}')$ that carries a letter from Γ_{j_ℓ} . This position can be computed in polynomial time using a straightforward variation of Proposition 3.9(5). This shows that the number $pos(p,\rho)$ can be computed in polynomial time for every simple path $\rho \in \mathscr{P}_j$. Finally, $pos(val(\mathbb{A}), p, i)$ is the minimum over all these positions for all simple paths from j to i. \Box

Let us now come back to the problem of constructing PC-expressions, which evaluates to $[val_{\mathbb{B}}(Y)]_I \setminus [val_{\mathbb{B}}(Z)]_I$ and $[val_{\mathbb{B}}(Y)]_I \sqcap [val_{\mathbb{B}}(Z)]_I$. Let us first solve this problem for explicitly given words. Then we will argue that our algorithm leads to a polynomial time algorithm for SLP-represented input words. Hence, let $s, t \in \Gamma^*$ be words. Our goal is to compute words inf, diff $\in \Gamma^*$ such that $[inf]_I = [s]_I \sqcap [t]_I$ and $[diff]_I = [s]_I \setminus [t]_I$.

In Algorithm 6 (Compute-Infimum-Difference) we accumulate the words inf and diff by determining for every position from $\{1, ..., |s|\}$ (viewed as a node of the dependence graph D_s) whether it belongs to $[\inf]_I$ or $[\dim]_I$. For this, we will store a current position ℓ in the word s, which will increase during the computation. Initially, we set $\ell := 1$ and $\inf := \varepsilon$, diff $:= \varepsilon$. At the end, we have $[\inf]_I = [s]_I \cap [t]_I$ and $[\dim]_I = [s]_I \setminus [t]_I$.

For a set of positions $K = \{\ell_1, \dots, \ell_k\} \subseteq \{1, \dots, |s|\}$ with $\ell_1 < \ell_2 < \dots < \ell_k$ we define the word

$$s \upharpoonright K = s[\ell_1] \cdots s[\ell_k].$$

Consider a specific iteration of the while-loop body in algorithm Compute-Infimum-Difference and let ℓ denote the value of the corresponding program variable at the beginning of the iteration. Assume in the following that $\text{Diff}_{\ell} \subseteq \{1, \dots, \ell - 1\}$ is the set of all positions from $\{1, \dots, \ell - 1\}$, which belong to the difference $[s]_I \setminus [t]_I$, i.e., they do not belong to the common prefix $[s]_I \sqcap [t]_I$. Moreover, let

$$\operatorname{Inf}_{\ell} = \{1, \ldots, \ell - 1\} \setminus \operatorname{Diff}_{\ell}$$

Algorithm 6: Compute-Infimum-Difference

input : words $s, t \in \Gamma$ **output**: words inf, diff $\in \Gamma^*$ such that $[\inf]_I = [s]_I \sqcap [t]_I$ and $[diff]_I = [s]_I \setminus [t]_I$ $\ell := 1;$ (stores a position in s) $\inf := \varepsilon$; (stores a word) diff := ε ; (stores a word) for $i \in W$ do pos(i) := |s| + 1;(stores positions in s) end while $\ell \leq |s|$ do $U := \{i \in W \mid \mathsf{pos}(i) < \ell\}$ $next := \min(\{pos(i) \mid i \in W \setminus U\} \cup \{|s|+1\});$ $j := \max\{i \mid \ell - 1 \le i \le next - 1, [\inf \pi_{W \setminus U}(s[\ell : i])]_I \preceq [t]_I\};$ (*) $\inf := \inf \pi_{W \setminus U}(s[\ell : j])$ (let $s[|s|+1] = \varepsilon$) diff := diff $\pi_U(s[\ell:j])s[j+1]$; for $i \in W$ do $pos(i) := min\{pos(i), pos(s, j+1, i)\};$ (let pos(s, |s| + 1, i) = |s| + 1) end $\ell := j + 2$ end

be the set of all positions from $\{1, \ldots, \ell - 1\}$, which belong to the trace prefix $[s]_I \sqcap [t]_I$. Thus, $\ln f_\ell$ is downward-closed in D_s , which means that $(i, j) \in D_s^*$ and $j \in \ln f_\ell$ imply $i \in \ln f_\ell$. Moreover, we have $[s \upharpoonright \ln f_\ell]_I \preceq [s]_I \sqcap [t]_I$. Note that the algorithm neither stores the set Diff_ℓ nor the set $\ln f_\ell$. This will be important later, when the input words *s* and *t* are represented by SLPs, because the sets Diff_ℓ and $\ln f_\ell$ may be of exponential size in that case. If ℓ , \inf , \dim , \dim pos(i) ($i \in W$) denote the values of the corresponding program variables at the beginning of the current iteration of the while-loop, then the algorithm will maintain the following two invariants:

- (I1) $\inf = s \upharpoonright \inf_{\ell}, \dim s \upharpoonright \mathsf{Diff}_{\ell},$
- (I2) $pos(i) = pos(s, Diff_{\ell}, i)$ for all $i \in W$

In each iteration of the while-loop, we investigate the subword of *s* from position ℓ to the next position of the form pos(i), and we determine for each position from some initial segment of this interval, whether it belongs to $[s]_I \sqcap [t]_I$ or $[s]_I \setminus [t]_I$. More precisely, we search for the largest position $j \in \{\ell - 1, \ldots, \text{next} - 1\}$ such that $[\inf \pi_{W \setminus U}(s[\ell : j])]_I$ is a trace prefix of $[t]_I$. Recall that $\inf = s \mid \ln f_\ell$ is the already collected part of the common trace prefix. We update inf and diff by $\inf := \inf \pi_{W \setminus U}(s[\ell : j])$ and $\dim := \dim \pi_U(s[\ell : j])s[j+1]$.

Before we prove that the algorithm indeed preserves the invariants (I1) and (I2), let us first consider a detailed example.

Example 5.39. To ease the reading we will consider the set $W = \{a, b, c, d, e, f, g\}$ instead of $W = \{1, ..., 7\}$ together with the following dependence relation *D*:



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Let $\Gamma_x = \{x\}$ for all $x \in W$. We consider the following words:

1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 16 17 s = f b g c c g b c c e a g f e f d gt = b c g c f g b e a g g f e d f b g

The dependence graphs of $[s]_I$ and $[t]_I$ look as follows:



We want to determine $s \sqcap_p t$ and $s \setminus_p t$ using algorithm Compute-Infimum-Difference. Initially, we set $\ell = 1$, inf = diff = ε , and pos(x) = |s| + 1 = 18 for all $x \in W$. Since $\ell \le |s|$ the while loop is executed.

First iteration: The algorithm first sets

$$U = \emptyset$$
 and next = 18.

Hence, we have

$$\inf \pi_{W \setminus U}(s[\ell: \mathsf{next}-1]) = |f \ b \ g \ c \ c \ g \ b \ c \ c \ e \ a \ g \ f \ e \ f \ d \ g$$

1 2 3 4 5 6 7 8 9 1011121314151617.

Here, we denote with '|' the position between inf and $\pi_{W\setminus U}(s[\ell : next - 1])$. The algorithm computes the largest number $0 \le j \le 17$ such that $[\inf \pi_{W\setminus U}(s[\ell : j])]_I$ is a trace prefix of $[t]_I$. From the dependence graphs above it can be easily seen that j = 7. We have

$$\inf \pi_{W \setminus U}(s[\ell:j]) = |f \ b \ g \ c \ c \ g \ b \\ \operatorname{diff} \pi_U(s[\ell:j])s[j+1] = c ,$$

which are the new values for inf and diff, respectively. Moreover, the pos-values are reset as follows:

$$pos(a) = pos(b) = 18$$
, $pos(c) = 8$, $pos(d) = 16$,
 $pos(e) = pos(f) = 18$, $pos(g) = 17$.

Finally, ℓ is set to 9. Since $\ell = 9 \le |s|$ the while loop is repeated.

Second iteration: The algorithm first sets

$$U = \{c\}$$
 and next = 16.

We have

$$\inf \pi_{W \setminus \{c\}}(s[9:15]) = f \ b \ g \ c \ c \ g \ b \ | \ e \ a \ g \ f \ e \ f \ 1 \ 2 \ 3 \ 4 \ 5 \ 6 \ 7 \ 8 \ 9 \ 10 \ 11 \ 12 \ 13 \ 14 \ 15 \ .$$

Searching for the largest position $\ell - 1 = 8 \le j \le 15 = \text{next} - 1$ such that the trace $[\inf \pi_{W \setminus U}(s[\ell : j])]_I$ is a prefix of $[t]_I$ gives j = 15. We have

which are the new values for inf and diff. The pos-values do not change in the second iteration, i.e., we still have

$$pos(a) = pos(b) = 18$$
, $pos(c) = 8$, $pos(d) = 16$,
 $pos(e) = pos(f) = 18$, $pos(g) = 17$.

Finally, ℓ is set to 17. Since $\ell \leq |s|$ the while loop is repeated.

Third iteration: The algorithm first sets

$$U = \{c, d\} \quad \text{and} \quad \mathsf{next} = 17.$$

We have

 $\inf \pi_{W \setminus U}(s[17:16]) = \begin{array}{ccccccc} f & b & g & c & c & g & b \\ 1 & 2 & 3 & 4 & 5 & 6 & 7 & 8 & 9 & 10111213141516. \end{array}$

We find j = 16. We have

$$\inf \pi_{W \setminus U}(s[17:16]) = f b g c c g b e a g f e f|$$

$$\dim \pi_U(s[17:16])s[17] = c c d g.$$

Also in the third iteration, the pos-values do not change. Finally, ℓ is set to 18. Since $\ell > |s|$ the algorithm stops and produces $[\inf]_I = [fbgccgbeagfef]_I$ and $[diff]_I = [ccdg]_I$. These traces are indeed $[s]_I \sqcap [t]_I$ and $[s]_I \setminus [t]_I$. This is visualized in the next picture with $[s]_I \sqcap [t]_I$ on the left side of the dotted line and $[s]_I \setminus [t]_I$ on the right side.



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Let us now prove the correctness of the algorithm. We start with invariant (I1):

Lemma 5.40. Algorithm Compute-Infimum-Difference preserves invariant (11).

Proof. Let us take $\ell \in \{1, ..., |s|\}$ and assume that the invariants (I1) and (I2) hold at the beginning of an execution of the body of the while-loop. Hence,

• $\inf = s \upharpoonright \inf_{\ell}$, $\dim s \upharpoonright \mathsf{Diff}_{\ell}$, and

r

• $pos(i) = pos(s, Diff_{\ell}, i)$ for all $i \in W$.

We have to show that invariant (I1) holds after the execution of the loop body as well. As in the algorithm, let:

$$U = \{i \in W \mid \mathsf{pos}(s, \mathsf{Diff}_{\ell}, i) < \ell\},\tag{5.4}$$

$$\mathsf{next} = \min(\{\mathsf{pos}(s, \mathsf{Diff}_\ell, i) \mid i \in W \setminus U\} \cup \{|s|+1\}), \tag{5.5}$$

$$j = \max\{i \mid \ell - 1 \le i \le \text{next} - 1, [\inf \pi_{W \setminus U}(s[\ell:i])]_I \le [t]_I\}.$$
(5.6)

We have to prove the following statements:

- A position p ∈ {ℓ,..., j} belongs to the common trace prefix [s]_I ⊓ [t]_I if and only if s[p] ∈ Γ_i for some i ∈ W \ U.
- If $j + 1 \le |s|$, then j + 1 does not belong to the common trace prefix $[s]_I \sqcap [t]_I$.

For the first point, assume that $s[p] \in \Gamma_i$, where $\ell \le p \le j$ and $i \in U$. By definition of U in (5.4), we have $pos(s, Diff_{\ell}, i) < \ell \le p$. Lemma 5.37 implies that there exists a path in D_s from some position in Diff_{ℓ} to position p. Since positions in Diff_{ℓ} do not belong to $[s]_I \sqcap [t]_I$, position p does not belong to $[s]_I \sqcap [t]_I$ as well.

For the other direction, consider the set of positions

$$P = \{p \mid \ell \le p \le j, s[p] \in \Gamma_i \text{ for some } i \in W \setminus U\}.$$

We claim that $\ln f_{\ell} \cup P$ is a downward-closed subset in D_s . Since $[s \upharpoonright (\ln f_{\ell} \cup P)]_I = [\inf \pi_{W \setminus U}(s[\ell : j])]_I \preceq [t]_I$ by (5.6), this implies that all positions from P indeed belong to $[s]_I \sqcap [t]_I$. That $\ln f_{\ell} \cup P$ is downward-closed in D_s follows from the following three facts:

- $\ln f_{\ell}$ is downward-closed in D_s .
- There does not exist a path from a node in Diff_{ℓ} to a node from *P*: Assume that such a path, ending in $p \in P$, would exist. Let $s[p] \in \Gamma_i$ with $i \in W \setminus U$. Lemma 5.37 implies $\text{pos}(s, \text{Diff}_{\ell}, i) \leq p$. Moreover, $i \in W \setminus U$ implies $\text{pos}(s, \text{Diff}_{\ell}, i) \geq \ell$ by (5.4). Hence, $\ell \leq \text{pos}(s, \text{Diff}_{\ell}, i) \leq p \leq j < \text{next}$, where the last inequality follows from (5.6). But this contradicts the definition of next in (5.5).
- There does not exist a path from a node in $\{\ell, \ldots, j\} \setminus P$ to a node of *P*: We have $\{\ell, \ldots, j\} \setminus P = \{p \mid \ell \le p \le j, s[p] \in \Gamma_i \text{ for some } i \in U\}$. Lemma 5.37 and the definition of *U* from (5.4) imply that every node from $\{\ell, \ldots, j\} \setminus P$ can be reached via a path starting in Diff $_\ell$. Hence, the existence of a path from $\{\ell, \ldots, j\} \setminus P$ to *P* contradicts the previous point.

It remains to be shown that position j + 1 does not belong to the common trace prefix $[s]_I \sqcap [t]_I$ in case $j + 1 \le |s|$. We distinguish several cases: If j = next - 1, then $j+1 = \text{next} = \text{pos}(s, \text{Diff}_{\ell}, i)$ for some $i \in W \setminus U$ by (5.5). Hence, there exists a path from Diff_{ℓ} to j+1 in D_s . Therefore j+1 cannot belong to $[s]_I \sqcap [t]_I$. Now, assume that j < next - 1. If $s[j+1] \in \Gamma_i$ for some $i \in U$, then (5.4) implies $\text{pos}(s, \text{Diff}_{\ell}, i) < \ell \le j+1$. Lemma 5.37 again yields the existence of a path from Diff_{ℓ} to j+1. Finally, let $s[j+1] \in \Gamma_i$ for some $i \in W \setminus U$. Maximality of j in (5.6) implies that the trace

$$[\inf \pi_{W\setminus U}(s[\ell,j+1])]_I = [\inf \pi_{W\setminus U}(s[\ell:j])]_I s[j+1]$$

is not a trace prefix of $[t]_I$. Since we already know that the trace $[\inf \pi_{W\setminus U}(s[\ell:j])]_I$ consists exactly of those positions from $\{1, \ldots, j\}$ that belong to the common trace prefix $[s]_I \sqcap [t]_I$, this implies that j + 1 does not belong to $[s]_I \sqcap [t]_I$. \square

Lemma 5.41. Algorithm Compute-Infimum-Difference preserves invariant (I2).

Proof. We consider a specific iteration of the while loop and assume that (I1) and (I2) hold at the beginning of the loop, i.e.,

- $\inf = s \upharpoonright \inf_{\ell}, \text{ diff} = s \upharpoonright \text{Diff}_{\ell} \text{ and }$
- $pos(i) = pos(s, Diff_{\ell}, i)$ for all $i \in W$.

We infer that (I2) holds after the execution of the loop. Let U, next, and j be defined by (5.4)–(5.6). Let $\ell' = j + 2 > \ell$ be the new value of ℓ after the execution of the loop body and let $i \in W$. We have to show that $pos(s, Diff_{\ell'}, i)$ is the new value of pos(i) after the execution of the loop body. Since we already know by Lemma 5.40 that (I1) holds after the execution of the loop, we have

$$s \upharpoonright \mathsf{Diff}_{\ell'} = \mathsf{diff} \, \pi_U(s[\ell:j]) \, s[j+1] = (s \upharpoonright \mathsf{Diff}_{\ell}) \, \pi_U(s[\ell:j]) \, s[j+1],$$

which means that

$$\mathsf{Diff}_{\ell'} = \mathsf{Diff}_{\ell} \cup \{p \mid \ell \le p \le j, \exists k \in U : s[p] \in \Gamma_k\} \cup \{j+1\}$$
(5.7)

(in case j = |s|, we omit $\{j+1\}$ from the right-hand side). Hence, we have to show that

$$pos(s, Diff_{\ell'}, i) = min\{pos(s, Diff_{\ell}, i), pos(s, \{j+1\}, i)\}.$$
(5.8)

for all $i \in W$. By (5.7), $\text{Diff}_{\ell} \cup \{j+1\} \subseteq \text{Diff}_{\ell'}$, which implies

$$pos(s, Diff_{\ell'}, i) \le min\{pos(s, Diff_{\ell}, i), pos(s, j+1, i)\}.$$

It remains to show that

$$pos(s, Diff_{\ell'}, i) \ge min\{pos(s, Diff_{\ell}, i), pos(s, j+1, i)\}.$$

The case that $pos(s, Diff_{\ell'}, i) = |s| + 1$ is trivial. Hence, assume that $pos(s, Diff_{\ell'}, i) \le |s|$ and consider a path in D_s from a position $p \in Diff_{\ell'}$ to a position $q \le |s|$ such that $s[q] \in \Gamma_i$. It suffices to show that there is a path from a position in $Diff_{\ell} \cup \{j+1\}$ to p (then, there exists a path from $Diff_{\ell} \cup \{j+1\}$ to q as well). By (5.7), we have

5.3 The Compressed Word Problem for Graph Products

Algorithm 7: Compute-Compressed-Infimum-Difference

```
input : SLP \mathbb{B} and two variables Y and Z
output: PC-expressions \alpha, \beta with val(\alpha) = [val(Y)]_I \sqcap [val(Z)]_I and
             \mathsf{val}(\beta) = [\mathsf{val}(Y)]_I \setminus [\mathsf{val}(Z)]_I
\ell := 1
\alpha := \varepsilon
\beta := \varepsilon
for i \in W do
 \mathsf{pos}(i) := |\mathsf{val}(Y)| + 1
end
while \ell \leq |val(Y)| do
      U := \{i \in W \mid \mathsf{pos}(i) < \ell\}
      \mathsf{next} := \min(\{\mathsf{pos}(i) \mid i \in W \setminus U\} \cup \{|\mathsf{val}(Y)| + 1\})
       j := \max\{i \mid \ell - 1 \le i \le \mathsf{next} - 1, [\mathsf{val}(\alpha \circ \pi_{W \setminus U}(Y[\ell : i]))]_I \preceq [\mathsf{val}(Z)]_I\};
                                                                                                                                         (*)
      \alpha := \alpha \circ \pi_{W \setminus U}(Y[\ell : j])
       \beta := \beta \circ \pi_U(Y[\ell:j]) \circ Y[j+1];
                                                                                            (let val(Y)[|val(Y)|+1] = \varepsilon)
      for i \in W do
        pos(i) := min\{pos(i), pos(val(Y), j+1, i)\};
                                                                                                                                       (**)
      end
      \ell := i + 2
end
```

 $p \in \mathsf{Diff}_{\ell} \cup \{p \mid \ell \le p \le j, \exists k \in U : s[p] \in \Gamma_k\} \cup \{j+1\}.$

The case $p \in \text{Diff}_{\ell} \cup \{j+1\}$ is trivial. Hence, assume that $\ell \leq p \leq j$ and $s[p] \in \Gamma_k$ for some $k \in U$. From (5.4), we get $\text{pos}(s, \text{Diff}_{\ell}, k) < \ell \leq p$. Lemma 5.37 implies that there exists a path from Diff_{ℓ} to p. \Box

Lemma 5.42. The number of iterations of the while-loop in algorithm Compute-Infimum-Difference is bounded by |W| + 1 = n + 1 = O(1).

Proof. We claim that in each execution of the loop body except for the last one, the set $U = \{i \in W \mid pos(i) < \ell\}$ strictly grows, which proves the lemma. Let us consider an execution of the loop body. Note that for every $i \in W$, position pos(i) cannot increase. There are two cases to distinguish. If j < next - 1, then the symbol s[j+1] must belong to some alphabet Γ_i with $i \in W \setminus U$ due to the maximality of j in line (*) of the algorithm. Clearly, $pos(s, \{j+1\}, i) = j+1$, hence pos(i) will be set to a value ≤ j + 1 in the loop body. Since the new value ℓ will be j+2, the new set U will also contain i, i.e., U strictly grows. If j = next - 1 < |s|, then again, since j+1 = next = pos(i) for some $i \in W \setminus U$ and the new value ℓ will be j+2, the set U strictly grows. Finally, if j = next - 1 = |s|, then ℓ will be set to |s| + 2 and the algorithm terminates. □

Algorithm Compute-Infimum-Difference for computing $[s]_I \setminus [t]_I$ and $[s]_I \sqcap [t]_I$ leads to Algorithm 7 (Compute-Compressed-Infimum-Difference), which computes PCexpressions for (we write val for val_B in the following) $[val(Y)]_I \sqcap [val(Z)]_I$ and $[val(Y)]_I \setminus [val(Z)]_I$. For better readability we denote the concatenation operation in PC-expressions by \circ in Algorithm 7. The idea is to consider the statements for updating inf and diff in algorithm Compute-Infimum-Difference as statements for computing PC-expressions α and β with $[val(\alpha)]_I = [val(Y)]_I \sqcap [val(Z)]_I$ and $[val(\beta)]_I = [val(Y)]_I \setminus [val(Z)]_I$. So, (2) and (3) from Proposition 5.35 are satisfied. Moreover, property (1) follows directly from the construction of α and β . For the size estimate in (4), note that by Lemma 5.42, α and β are concatenations of $\mathcal{O}(1)$ many expressions of the form $\pi_K(Y[p_1, p_2])$. Moreover, each of the positions p_1 and p_2 is bounded by $|val(Y)| \leq |val(\mathbb{B})|$ and hence needs only $\mathcal{O}(\log |val(\mathbb{B})|)$ many bits.

It remains to argue that Algorithm 7 can be implemented such that it runs in polynomial time. By Lemma 5.42, the number of iterations of the loop body is bounded by the constant |W| + 1. Hence, it suffices to show that a single iteration only needs polynomial time. The condition $[val(\alpha \circ \pi_{W\setminus U}(Y[\ell : j]))]_I \leq [val(Z)]_I$ in line (*) of Algorithm 7 can be checked in polynomial time by Lemma 5.25. For this, note that by Lemma 3.16 we can compute in polynomial time an SLP for the word val $(\alpha \circ \pi_{W\setminus U}(Y[\ell : j]))$. Hence, the number *j* in line (*) can be computed in polynomial time via binary search in the same way as in the proof of Theorem 4.11 for free groups. Finally, the position pos(val(Y), j+1, i) in line (**) of Algorithm 7 can be computed in polynomial time by Lemma 5.38. This concludes the proof of Proposition 5.35 and hence the proof of Theorem 5.4, which is the main result of this chapter.

Chapter 6 The Compressed Word Problem in HNN-Extensions

In this chapter we prove two further important transfer theorems for the compressed word problem:

- The compressed word problem for a multiple HNN-extension of a base group *H* over finite associated subgroups is polynomial time Turing-reducible to the compressed word problem for *H*.
- The compressed word problem for an amalgamated product of group H_1 and H_2 with finite amalgamated subgroups is polynomial time Turing-reducible to the compressed word problems for H_1 and H_2 .

"HNN" stands for the authors Higman, B.H. Neumann and, H. Neumann of [78], where they introduced HNN-extension. An HNN-extension is specified by a base group *H* and two isomorphic subgroups *A* and *B* (the associated subgroup) together with an isomorphism $\varphi : A \to B$. One would like to extend this isomorphism to an automorphism on *H*. But in general this is not possible. But *H* embedds into a group on which φ is extended to an automorphism. This group is obtained from *H* by adding a new generator *t* (the so called stable letter) together with the relations $t^{-1}at = \varphi(a)$ for all $a \in A$. Thus, conjugation of *A* by *t* gives the isomorphism φ . This operation can be generalized to multiple HNN-extensions, where several stable letters are added in one step.

The amalgamated free product of two groups H_1 and H_2 with isomorphic subgroups A_1 and A_2 and an isomorphism $\varphi : A_1 \to A_2$ is obtained by identifying in the free product $H_1 * H_2$ the elements *a* and $\varphi(a)$ for all $a \in A_1$.

HNN-extension and amalgamated free products are extremely important in combinatorial group theory. For instance, finitely presented groups with an undecidable word problem (see Theorem 2.14) can be constructed from free groups using a series of HNN-extensions. Bass-Serre theory [154] relates the action of a group on a tree with an iterated decomposition of the group via HNN-extensions and amalgamated free products. By Stallings famous end theorem [157], a finitely generated group has infinitely many ends (a certain geometric invariant of a group) if and only if the group can be written as an HNN-extension with finite associated subgroups or an amalgamated free product with finite amalgamated subgroups.

In contrast to general HNN-extensions and amalgamated products, the restriction to finite associated (respectively, amalgamated) subgroups is algorithmically tame. It is not too difficult to show that the word problem for an HNN-extension G with base group H and finite associated subgroups is polynomial time Turing reducible to the word problem for H, and a similar result holds for amalgamated free products. By the results of this chapter, this tameness also holds in the compressed setting. The material of this chapter is taken from [73], which is partly inspired by the work from [117] on solving equations in HNN-extensions.

6.1 HNN-extensions

We introduce multiple HNN-extensions in this section. Let us fix throughout this chapter a *base group* $H = \langle \Sigma | R \rangle$. Let us also fix isomorphic subgroups $A_i, B_i \leq H$ $(1 \leq i \leq n)$ and isomorphisms $\varphi_i : A_i \to B_i$. Let $h : (\Sigma \cup \Sigma^{-1})^* \to H$ be the canonical morphism, which maps a word $w \in (\Sigma \cup \Sigma^{-1})^*$ to the element of H it represents. Let t_1, \ldots, t_n symbols which do not belong to the group H. It is common to write a^{t_i} an abbreviation for $t_i^{-1}at_i$.

Definition 6.1 (multiple HNN-extension). The *(multiple) HNN-extension* defined by *H* and $A_1, B_1, \ldots, A_n, B_n$ is the group

$$G = \langle H, t_1, \dots, t_n \mid a^{t_i} = \varphi_i(a) \ (1 \le i \le n, a \in A_i) \rangle.$$
(6.1)

The first important result about HNN-extensions is:

Theorem 6.2 (cf. [78]). For two words $u, v \in (\Sigma \cup \Sigma^{-1})^*$ we have u = v in *G* if and only if u = v in *H*. Hence, *H* is a subgroup of *G*.

In this chapter, we will be only concerned with the case that all groups A_1, \ldots, A_n are finite and that Σ is finite, i.e., H is finitely generated. In this situation, we may assume that $\bigcup_{i=1}^{n} (A_i \cup B_i) \subseteq \Sigma$. We say that A_i and B_i are *associated subgroups* in the HNN-extension G. For the following, the notations $A_i(+1) = A_i$ and $A_i(-1) = B_i$ are useful. Note that $\varphi_i^{\alpha} : A_i(\alpha) \to A_i(-\alpha)$ for $\alpha \in \{+1, -1\}$.

Definition 6.3 (set Red $(H, \varphi_1, ..., \varphi_n)$ of Britton-reduced words). We say that a word $u \in (\Sigma \cup \Sigma^{-1} \cup \{t_1, t_1^{-1}, ..., t_n, t_n^{-1}\})^*$ is *Britton-reduced* (after John Britton) if *u* does not contain a factor of the form $t_i^{-\alpha} w t_i^{\alpha}$ for $\alpha \in \{1, -1\}$, $w \in (\Sigma \cup \Sigma^{-1})^*$ and $h(w) \in A_i(\alpha)$. With Red $(H, \varphi_1, ..., \varphi_n)$ we denote the set of all Britton-reduced words.

For a word $u \in (\Sigma \cup \Sigma^{-1} \cup \{t_1, t_1^{-1}, \dots, t_n, t_n^{-1}\})^*$ let write $\pi_t(u)$ for the projection $\pi_{\{t_1, t_1^{-1}, \dots, t_n, t_n^{-1}\}}(u)$ of u to the alphabet $\{t_1, t_1^{-1}, \dots, t_n, t_n^{-1}\}$, see Definition 3.1. The following lemma provides a necessary and sufficient condition for equality of Britton-reduced words in an HNN-extension, it follows easily from [119, Theorem 2.1]:

6.1 HNN-extensions



Fig. 6.1 A van Kampen diagram for the identity $u_0 t_{i_1}^{\alpha_1} u_1 t_{i_2}^{\alpha_2} u_2 t_{i_3}^{\alpha_3} u_3 t_{i_4}^{\alpha_4} u_4 = v_0 t_{j_1}^{\beta_1} v_1 t_{j_2}^{\beta_2} v_2 t_{j_3}^{\beta_3} v_3 t_{j_4}^{\beta_4} v_4$ in the HNN-extension $\langle H, t_1, \dots, t_n \mid a^{t_i} = \varphi_i(a) \ (1 \le i \le n, a \in A_i) \rangle$. Light-shaded (respectively, dark-shaded) faces represent relations in H (respectively, relations of the form $ct_i^{\alpha} = t_i^{\alpha} \varphi_i^{\alpha}(c)$ with $c \in A_i(\alpha)$).

Lemma 6.4. Let $u = u_0 t_{i_1}^{\alpha_1} u_1 \cdots t_{i_\ell}^{\alpha_\ell} u_\ell$ and $v = v_0 t_{j_1}^{\beta_1} v_1 \cdots t_{j_m}^{\beta_m} v_m$ be Britton-reduced words such that $u_0, \ldots, u_\ell, v_0, \ldots, v_m \in (\Sigma \cup \Sigma^{-1})^*$, $\alpha_1, \ldots, \alpha_\ell, \beta_1, \ldots, \beta_m \in \{1, -1\}$, and $i_1, \ldots, i_\ell, j_1, \ldots, j_m \in \{1, \ldots, n\}$. Then u = v in the HNN-extension G from (6.1) if and only if the following hold:

- π_t(u) = π_t(v) (*i.e.*, ℓ = m, i_k = j_k, and α_k = β_k for 1 ≤ k ≤ ℓ)
 there exist c₁,..., c_{2m} ∈ ⋃ⁿ_{k=1}(A_k ∪ B_k) such that:
- - $\begin{array}{l} \ u_k c_{2k+1} = c_{2k} v_k \ in \ H \ for \ 0 \le k \le \ell \ (here \ we \ set \ c_0 = c_{2\ell+1} = 1) \\ \ c_{2k-1} \in A_{i_k}(\alpha_k) \ and \ c_{2k} = \varphi_{i_k}^{\alpha_k}(c_{2k-1}) \in A_{i_k}(-\alpha_k) \ for \ 1 \le k \le \ell. \end{array}$

The second condition of the lemma is visualized in Figure 6.1 by a van Kampen diagram for uv^{-1} . The elements $c_1, \ldots, c_{2\ell}$ in such a van Kampen diagram will be also called the connecting elements. Note that Theorem 6.2 is an immediate consequence of Lemma 6.4 since every word $u \in (\Sigma \cup \Sigma^{-1})^*$ is Britton-reduced.

We give a proof of Lemma 6.4, following [50]:

Proof of Lemma 6.4. If a van Kampen diagram as in Figure 6.1 exists, then clearly u = v in G. For the other direction let us define the infinite alphabet $\Gamma = H \setminus \{1\} \cup I$ $\{t, t^{-1}\}$. For every $1 \le i \le n$ let X_i (resp. Y_i) be a traversal for the cosets of A_i (resp., B_i). This means that every $h \in H$ can be uniquely written as h = ax (resp., h = by) for $a \in A_i$ and $x \in X_i$ (resp., $b \in B_i$ and $y \in Y_i$). We can assume that $1 \in X_i \cap Y_i$ for all $1 \le i \le n$. We define an infinite semi-Thue system S over Γ by the rules below, where $1 \le i \le n$, $g, h \in H \setminus \{1\}$, $a \in A_i \setminus \{1\}$, $b \in B_i \setminus \{1\}$, $x \in X_i$, and $y \in Y_i$. Moreover, for $g,h \in H \setminus \{1\}$ we denote with $g \cdot h$ either the empty word ε in case $g = h^{-1}$ or the product $gh \in H \setminus \{1\}$. Similarly, the element $1 \in X_i \cap Y_i$ is identified with the empty word.

$$t_i t_i^{-1} \to \varepsilon \qquad t_i^{-1} t_i \to \varepsilon$$
(6.2)

$$gh \to g \cdot h$$
 $t_i(\varphi_i(a) \cdot y) \to at_i y$ $t_i^{-1}(a \cdot x) \to \varphi_i(a)t_i^{-1} x$ (6.3)

Then the following three points can be easily checked:

- $\Gamma^*/S \cong G$
- *S* is Noetherian and confluent.

• If w is Brittion-reduced and $w \rightarrow_S w'$, then w' is Britton-reduced as well.

Now assume that u = v in *G*. Hence, there exists $w \in IRR(S)$ such that $u \rightarrow_S^* w$ and $v \rightarrow_S^* w$. But since *u* and *v* are Britton-reduced, only rules of the form (6.3) can be applied in the derivations $u \rightarrow_S^* w$ and $v \rightarrow_S^* w$. These derivations can be seen as van Kampen diagrams as in Figure 6.1 for uw^{-1} and wv^{-1} , respectively. By gluing these diagrams together along the *w*-path, we obtain a van Kampen diagram as in Figure 6.1. \Box

The semi-Thue system in (6.2) and (6.3) can be used to give a polynomial time Turing-reduction from the word problem for *G* to the word problem for *H* in case the groups A_i and B_i are finite.

Example 6.5. Consider the HNN-extension $G = \langle a, t | t^{-1}a^2t = a^3 \rangle$. This is the BaumslagSolitar group BS(2,3). We have $G \cong \langle \mathbb{Z}, t | t^{-1}xt = \varphi(x) (x \in 2\mathbb{Z}) \rangle$, where $\varphi : 2\mathbb{Z} \to 3\mathbb{Z}$ is defined by $\varphi(2x) = 3x$. The word $u = ta^2t^{-1}a^3t$ is Britton-reduced, whereas the word $v = ta^3t^{-1}a^2t$ is not Britton-reduced. We have $v = a^4t = ta^6$ in *G* and $u = ta^5t^{-1}at$ in *G*.

The following lemma can be used in order to compute a Britton-reduced word for the group element represented by the concatenation of two Britton-reduced words. Recall that for a free group an irreducible word equivalent to the concatenation of two irreducible words u and v can be computed by computing longest words $u_1 = a_1 \cdots a_m$ and $v_0 = a_m^{-1} \cdots a_1^{-1}$ such that $u = u_0 u_1$ and $v = v_0 v_1$. Then $u_0 v_1$ is irreducible. The same idea holds in the HNN-extension *G* from (6.1).

Lemma 6.6. Assume that $u = u_0 t_{i_1}^{\alpha_1} u_1 \cdots t_{i_n}^{\alpha_n} u_n$ and $v = v_0 t_{j_1}^{\beta_1} v_1 \cdots t_{j_m}^{\beta_m} v_m$ are Brittonreduced words. Let d(u, v) be the largest number $d \ge 0$ such that

(a) $A_{i_{n-d+1}}(\alpha_{n-d+1}) = A_{j_d}(-\beta_d)$ (we set $A_{i_{n+1}}(\alpha_{n+1}) = A_{j_0}(-\beta_0) = 1$) and (b) there exists $c \in A_{j_d}(-\beta_d)$ with

$$t_{i_{n-d+1}}^{\alpha_{n-d+1}}u_{n-d+1}\cdots t_{i_{n}}^{\alpha_{n}}u_{n}v_{0}t_{j_{1}}^{\beta_{1}}\cdots v_{d-1}t_{j_{d}}^{\beta_{d}}=c$$

in the group G from (6.1) (note that this condition is satisfied for d = 0). Moreover, let $c(u,v) \in A_{j_d}(-\beta_d)$ be the element c in (b) (for d = d(u,v)). Then

$$u_0 t_{i_1}^{\alpha_1} u_1 \cdots t_{i_{n-d(u,v)}}^{\alpha_{n-d(u,v)}} (u_{n-d(u,v)} c(u,v) v_{d(u,v)}) t_{j_{d(u,v)+1}}^{\beta_{d(u,v)+1}} v_{d(u,v)+1} \cdots t_{j_m}^{\beta_m} v_m$$

is a Britton-reduced word equal to uv in G.

Lemma 6.6 is visualized by Figure 6.2.

6.2 The Main Computational Problems

The main goal of this chapter is to show that the compressed word problem for an HNN-extension of the form (6.1) is polynomial time Turing-reducible to the



Fig. 6.2 Lemma 6.6

compressed word problem for H. In fact, we will prove the existence of such a reduction for a slightly more general problem, which we introduce below.

For the further consideration, let us fix the finitely generated group H together with the finite subgroups A and B. Let Σ be a finite generating set for H. These data are fixed, i.e., they will not belong to the input of computational problems.

In the following, when writing down a multiple HNN-extension

$$\langle H, t_1, \dots, t_n \mid a^{t_i} = \varphi_i(a) \ (1 \le i \le n, a \in A) \rangle, \tag{6.4}$$

we assume implicitly that every φ_i is in fact an isomorphism between subgroups $A_1 \leq A$ and $B_1 \leq B$. Hence, φ_i can be viewed as a *partial* isomorphism from our fixed subgroup *A* to our fixed subgroup *B*, and (6.4) is in fact an abbreviation for the group

$$\langle H, t_1, \ldots, t_n \mid a^{t_i} = \varphi_i(a) \ (1 \le i \le n, a \in \operatorname{dom}(\varphi_i)) \rangle.$$

Note that there is only a fixed number of partial isomorphisms from *A* to *B*, but we allow $\varphi_i = \varphi_j$ for $i \neq j$ in (6.4).

Let us introduce several restrictions and extensions of CWP(G). Our most general problem is the following computational problem UCWP(H,A,B) (the letter "U"

stands for "uniform", meaning that a list of partial isomorphisms from *A* to *B* is part of the input):

input: Partial isomorphisms $\varphi_i : A \to B$ $(1 \le i \le n)$ and an SLP \mathbb{A} over the alphabet $\Sigma \cup \Sigma^{-1} \cup \{t_1, t_1^{-1}, \dots, t_n, t_n^{-1}\}.$

question: Does val(\mathbb{A}) = 1 hold in $\langle H, t_1, \dots, t_n \mid a^{t_i} = \varphi_i(a) \ (1 \le i \le n, a \in A) \rangle$?

The restriction of this problem UCWP(H,A,B) to Britton-reduced input words is denoted by RUCWP(H,A,B). It is formally defined as the following problem:

input: Partial isomorphisms $\varphi_i : A \to B$ $(1 \le i \le n)$ and SLPs \mathbb{A}, \mathbb{B} over the alphabet $\Sigma \cup \Sigma^{-1} \cup \{t_1, t_1^{-1}, \dots, t_n, t_n^{-1}\}$ such that $val(\mathbb{A}), val(\mathbb{B}) \in \text{Red}(H, \varphi_1, \dots, \varphi_n)$.

question: Does val(\mathbb{A}) = val(\mathbb{B}) hold in $\langle H, t_1, \ldots, t_n | d^{t_i} = \varphi_i(a) \ (1 \le i \le n, a \in A) \rangle$? Let us now consider a fixed list of partial isomorphisms $\varphi_1, \ldots, \varphi_n : A \to B$. Then RCWP($H, A, B, \varphi_1, \ldots, \varphi_n$) is the following computational problem:

input: Two SLPs \mathbb{A} and \mathbb{B} over the alphabet $\Sigma \cup \Sigma^{-1} \cup \{t_1, t_1^{-1}, \dots, t_n, t_n^{-1}\}$ such that $\mathsf{val}(\mathbb{A}), \mathsf{val}(\mathbb{B}) \in \mathsf{Red}(H, \varphi_1, \dots, \varphi_n)$.

question: Does val(\mathbb{A}) = val(\mathbb{B}) hold in $\langle H, t_1, \dots, t_n | a^{t_i} = \varphi_i(a) \ (1 \le i \le n, a \in A) \rangle$? The main result of this chapter is:

Theorem 6.7. UCWP $(H, A, B) \leq_T^P CWP(H)$.

The rest of Chapter 6 is concerned with the proof of Theorem 6.7.

Let us first consider the special case of the compressed word problem for an HNN-extension of the form (6.1) with $H = A_1 = \cdots = A_n = B_1 = \cdots = B_n$ finite. In this case, we can even assume that the finite group *H* (represented by its multiplication table) is part of the input:

Lemma 6.8. The following problem can be solved in polynomial time:

input: A finite group H, automorphisms $\varphi_i : H \to H$ $(1 \le i \le n)$, and an SLP \mathbb{A} over the alphabet $H \cup \{t_1, t_1^{-1}, \dots, t_n, t_n^{-1}\}$. question: Does $val(\mathbb{A}) = 1$ hold in $\langle H, t_1, \dots, t_n | h^{t_i} = \varphi_i(h) (1 \le i \le n, h \in H) \rangle$?

Proof. Let $s \in (H \cup \{t_1, t_1^{-1}, \dots, t_n, t_n^{-1}\})^*$. From the relators of the group $G = \langle H, t_1, \dots, t_n \mid h^{t_i} = \varphi_i(h) \ (1 \le i \le n, h \in H) \rangle$ it follows that there exists a unique $h \in H$ with $s = \pi_t(s)h$ in G. Hence, s = 1 in G if and only if $\pi_t(s) = 1$ in the free group $F(t_1, \dots, t_n)$ and h = 1 in H.

Now, let \mathbb{A} be an SLP over the alphabet $H \cup \{t_1, t_1^{-1}, \dots, t_n, t_n^{-1}\}$. Without loss of generality assume that \mathbb{A} is in Chomsky normal form. We can produce an SLP for the projection $\pi_t(val(\mathbb{A}))$ (see Proposition 3.9(4)) and check in polynomial time whether this SLP produces a word that is the identity in the free group $F(t_1, \dots, t_n)$, see Theorem 4.14. Hence, it suffices to compute for every variable Aof \mathbb{A} the unique $h_A \in H$ with $val(A) = \pi_t(val(A))h_A$ in G. We compute the elements h_A bottom up. The case that the right-hand side for A is a terminal symbol from $H \cup \{t_1, t_1^{-1}, \dots, t_n, t_n^{-1}\}$ is clear. Hence, assume that rhs(A) = BC and assume that $h_B, h_C \in H$ are already computed. In G we have:

 $\mathsf{val}(A) = \mathsf{val}(B)\mathsf{val}(C) = \pi_t(\mathsf{val}(B))h_B\pi_t(\mathsf{val}(C))h_C.$

6.3 Reducing to Britton-Reduced Sequences

Thus, it suffices to compute the unique $h \in H$ with $h_B \pi_t(val(C)) = \pi_t(val(C))h$ in G. Note that if $\pi_t(val(C)) = t_{i_1}^{\alpha_1} t_{i_2}^{\alpha_2} \cdots t_{i_n}^{\alpha_n}$, then

$$h = \boldsymbol{\varphi}_{i_n}^{\alpha_n}(\cdots \boldsymbol{\varphi}_{i_2}^{\alpha_2}(\boldsymbol{\varphi}_{i_1}^{\alpha_1}(h_B))\cdots) = (\boldsymbol{\varphi}_{i_1}^{\alpha_1}\cdots \boldsymbol{\varphi}_{i_n}^{\alpha_n})(h_B).$$

The automorphism $f = \varphi_{i_1}^{\alpha_1} \cdots \varphi_{i_n}^{\alpha_n}$ can be easily computed from an SLP \mathbb{C} for the word $\pi_t(val(C))$ by replacing in \mathbb{C} the terminal symbol t_i (respectively, t_i^{-1}) by φ_i (respectively, φ_i^{-1}). This allows to compute f bottom-up and then to compute $f(h_B)$. \Box

Note that the group $\langle H, t_1, \ldots, t_n | h^{t_i} = \varphi_i(h) \ (1 \le i \le n, h \in H) \rangle$ is the semidirect product $H \rtimes_{\varphi} F$, where $F = F(t_1, \ldots, t_n)$ is the free group generated by t_1, \ldots, t_n and the homomorphism $\varphi : F \to \operatorname{Aut}(H)$ is defined by $\varphi(t_i) = \varphi_i$.

6.3 Reducing to Britton-Reduced Sequences

As a first step in the proof of Theorem 6.7, we show that the problem UCWP(H,A,B) is polynomial time Turing-reducible to the problem RUCWP(H,A,B), where all input words are assumed to be Britton-reduced. Later, it will be important that the Turing-reduction from UCWP(H,A,B) to RUCWP(H,A,B) does not change the list of partial isomorphisms $\varphi_1, \ldots, \varphi_n : A \to B$.

Lemma 6.9. We have $UCWP(H,A,B) \leq_T^P RUCWP(H,A,B)$. More precisely, there is a polynomial time Turing-reduction from the problem UCWP(H,A,B) to the problem RUCWP(H,A,B) that on input $(\varphi_1, \ldots, \varphi_n, \mathbb{A})$ only asks RUCWP(H,A,B)queries of the form $(\varphi_1, \ldots, \varphi_n, \mathbb{A}', \mathbb{B}')$ (thus, the list of partial isomorphisms is not changed).

Proof. Consider partial isomorphisms $\varphi_i : A \to B$ $(1 \le i \le n)$ and let

$$G = \langle H, t_1, \dots, t_n \mid a^{t_i} = \varphi_i(a) \ (1 \le i \le n, a \in A) \rangle.$$

Moreover, let \mathbb{A} be an SLP in Chomsky normal form over the alphabet $\Sigma \cup \Sigma^{-1} \cup \{t_1, t_1^{-1}, \dots, t_n, t_n^{-1}\}$. Using oracle access to RUCWP(H, A, B), we will construct a CSLP \mathbb{A}' with val(\mathbb{A}') = val(\mathbb{A}) in G and val(\mathbb{A}') Britton-reduced, on which finally the RUCWP(H, A, B)-oracle can be asked whether val(\mathbb{A}') = 1 in G. The system \mathbb{A}' has the same variables as \mathbb{A} but for every variable X, val_{\mathbb{A}'}(X) is Britton-reduced and val(\mathbb{A}', X) = val_{\mathbb{A}}(X) in G.

Assume that X is a variable of \mathbb{A} with rhs(X) = YZ, where Y and Z were already processed during our reduction process. Hence, val(Y) and val(Z) are Britton-reduced. Let

$$\mathsf{val}(Y) = u_0 t_{i_1}^{\alpha_1} u_1 \cdots t_{i_\ell}^{\alpha_\ell} u_\ell \quad \text{and} \quad \mathsf{val}(Z) = v_0 t_{j_1}^{\beta_1} v_1 \cdots t_{j_m}^{\beta_m} v_m.$$

with $u_0, \ldots, u_\ell, v_0, \ldots, v_m \in (\Sigma \cup \Sigma^{-1})^*$ and $\alpha_1, \ldots, \alpha_\ell, \beta_1, \ldots, \beta_k \in \{-1, 1\}$. For $1 \le k \le \ell$ (respectively, $1 \le k \le m$) let p(k) (respectively, q(k)) be the unique position within val(*Y*) (respectively, val(*Z*)) such that val(*Y*)[: p(k)] = $u_0 t_{i_1}^{\alpha_1} u_1 \cdots t_{i_k}^{\alpha_k}$ (respectively, val(*Z*)[: q(k)] = $v_0 t_{j_1}^{\beta_1} v_1 \cdots t_{j_k}^{\beta_k}$). By Proposition 3.9(6) the positions p(k) and q(k) can be computed in polynomial time from *k*.

According to Lemma 6.6 it suffices to find $d = d(val(Y), val(Z)) \in \mathbb{N}$ and $c = c(val(Y), val(Z)) \in A \cup B$ in polynomial time. This can be done, using binary search: First, compute min $\{l, m\}$. For a given number $k \leq \min\{\ell, m\}$ we want to check whether

$$t_{i_{\ell-k+1}}^{\alpha_{\ell-k+1}} u_{\ell-k+1} \cdots t_{i_{\ell}}^{\alpha_{\ell}} u_{\ell} v_0 t_{j_1}^{\beta_1} \cdots v_{k-1} t_{j_k}^{\beta_k} \in A_{i_{\ell-k+1}}(\alpha_{\ell-k+1}) = A_{j_k}(-\beta_k)$$
(6.5)

in the group G. Note that (6.5) is equivalent to $t_{i_{\ell-k+1}}^{\alpha_{\ell-k+1}} = t_{j_k}^{-\beta_k}$ and

$$\exists c \in A_{j_k}(-\beta_k) : (\operatorname{val}(Y)[p(\ell-k+1):])^{-1}c = \operatorname{val}(Z)[:q(k)].$$
(6.6)

The two sides of this equation are Britton-reduced words and the number of possible values $c \in A_{j_k}(-\beta_k)$ is bounded by a constant. Hence, (6.6) is equivalent to a constant number of RUCWP(H, A, B)-instances that can be computed in polynomial time.

In order to find with binary search the value *d* (i.e. the largest $k \ge 0$ such that (6.5) holds), one has to observe that (6.5) implies that (6.5) also holds for every smaller value *k*; this follows from Lemma 6.4. From *d*, we can compute in polynomial time the positions $p(\ell - d + 1)$ and q(d). Then, according to Lemma 6.6, the word

$$val(Y)[: p(\ell - d + 1) - 1] c val(Z)[q(d) + 1 :]$$

is Britton-reduced and equal to val(Y)val(Z) in G. Hence, we can set

$$\operatorname{rhs}(X) := Y[: p(\ell - d + 1) - 1] c Z[q(d) + 1 :].$$

This concludes the proof of the lemma. \Box

The above proof can be also used in order to derive the following statement:

Lemma 6.10. Let $\varphi_1, \ldots, \varphi_n : A \to B$ be fixed partial isomorphisms. Then, the problem CWP($\langle H, t_1, \ldots, t_n | a^{t_i} = \varphi_i(a) \ (1 \le i \le n, a \in A) \rangle$) is polynomial time Turingreducible to the problem RCWP($H, A, B, \varphi_1, \ldots, \varphi_n$).

6.4 Reduction to a Constant Number of Stable Letters

In this section, we show that the number of different stable letters can be reduced to a constant. For this, it is important to note that the associated subgroups $A, B \le H$ do not belong to the input; so their size is a fixed constant.

6.4 Reduction to a Constant Number of Stable Letters

Fix the constant $\delta = 2 \cdot |A|! \cdot 2^{|A|}$ for the rest of Chapter 6. Note that the number of HNN-extensions of the form $\langle H, t_1, \ldots, t_k | a^{t_i} = \psi_i(a) \ (1 \le i \le k, a \in A) \rangle$ with $k \le \delta$ is a constant in our consideration. The following lemma says that RUCWP(H, A, B) can be reduced in polynomial time to one of the problems RCWP $(H, A, B, \psi_1, \ldots, \psi_k)$. Moreover, we can determine in polynomial time, which of these problems arises.

Lemma 6.11. There exists a polynomial time algorithm for the following:

input: Partial isomorphisms $\varphi_1, \ldots, \varphi_n : A \to B$ and $SLPs \mathbb{A}, \mathbb{B}$ over the alphabet $\Sigma \cup \Sigma^{-1} \cup \{t_1, t_1^{-1}, \ldots t_n, t_n^{-1}\}$ such that $val(\mathbb{A}), val(\mathbb{B}) \in \text{Red}(H, \varphi_1, \ldots, \varphi_n)$. output: Partial isomorphisms $\psi_1, \ldots, \psi_k : A \to B$ where $k \leq \delta$ and $SLPs \mathbb{A}', \mathbb{B}'$ over the alphabet $\Sigma \cup \Sigma^{-1} \cup \{t_1, t_1^{-1}, \ldots t_k, t_k^{-1}\}$ such that:

- For every $1 \le i \le k$ there exists $1 \le j \le n$ with $\psi_i = \varphi_j$.
- $\operatorname{val}(\mathbb{A}'), \operatorname{val}(\mathbb{B}') \in \operatorname{Red}(H, \psi_1, \dots, \psi_k)$
- $\operatorname{val}(\mathbb{A}) = \operatorname{val}(\mathbb{B})$ in $\langle H, t_1, \dots, t_n \mid a^{t_i} = \varphi_i(a) \ (1 \le i \le n, a \in A) \rangle$ if and only if $\operatorname{val}(\mathbb{A}') = \operatorname{val}(\mathbb{B}')$ in $\langle H, t_1, \dots, t_k \mid a^{t_i} = \psi_i(a) \ (1 \le i \le k, a \in A) \rangle$.

Proof. Fix an instance $(\varphi_1, \ldots, \varphi_n, \mathbb{A}, \mathbb{B})$ of the problem $\mathsf{RUCWP}(H, A, B)$. In particular, $\mathsf{val}(\mathbb{A}), \mathsf{val}(\mathbb{B}) \in \mathsf{Red}(H, \varphi_1, \ldots, \varphi_n)$. Define the function $\tau : \{1, \ldots, n\} \rightarrow \{1, \ldots, n\}$ by

$$\tau(i) = \min\{k \mid \varphi_k = \varphi_i\}.$$

This mapping can be easily computed in polynomial time from the sequence $\varphi_1, \ldots, \varphi_n$. Assume without loss of generality that the range of τ is $\{1, \ldots, \gamma\}$ for some $\gamma \leq n$. Note that $\gamma \leq |A|! \cdot 2^{|A|} = \frac{\delta}{2}$. For every t_i $(1 \leq i \leq \gamma)$ we take two stable letters $t_{i,0}$ and $t_{i,1}$. Hence, the total number of stable letters is at most δ . We define the HNN-extension

$$G' = \langle H, t_{1,0}, t_{1,1}, \dots, t_{\gamma,0}, t_{\gamma,1} \mid a^{t_{i,k}} = \varphi_i(a) \ (1 \le i \le \gamma, k \in \{0,1\}, a \in A) \rangle.$$

This HNN-extension has $2\gamma \leq \delta$ many stable letters; it is the HNN-extension $\langle H, t_1, \ldots, t_k \mid a^{t_i} = \psi_i(a) \ (1 \leq i \leq k, a \in A) \rangle$ from the lemma.

It is straightforward to construct a deterministic rational transducer \mathscr{T} , which transforms the input word $u_0 t_{i_1}^{\alpha_1} u_1 t_{i_2}^{\alpha_2} u_2 t_{i_3}^{\alpha_3} u_3 \cdots t_{i_m}^{\alpha_m} u_m$ (with $u_0, \ldots, u_m \in (\Sigma \cup \Sigma^{-1})^*$ and $1 \le i_1, \ldots, i_m \le n$) into the word

$$\llbracket \mathscr{T} \rrbracket (w) = u_0 t_{\tau(i_1),1}^{\alpha_1} u_1 t_{\tau(i_2),0}^{\alpha_2} u_2 t_{\tau(i_3),1}^{\alpha_3} u_3 \cdots t_{\tau(i_m),m \bmod 2}^{\alpha_m} u_m.$$

Claim: Let $u, v \in \text{Red}(H, \varphi_1, \dots, \varphi_n)$ be Britton-reduced. Then also $[\mathscr{T}](u)$ and $[\mathscr{T}](v)$ are Britton-reduced. Moreover, the following are equivalent:

(a) u = v in $\langle H, t_1, \dots, t_n | a^{t_i} = \varphi_i(a) \ (1 \le i \le n, a \in A) \rangle$ (b) $[\mathscr{T}](u) = [\mathscr{T}](v)$ in the HNN-extension G' and $\pi_t(u) = \pi_t(v)$.

Proof of the claim. Let $u = u_0 t_{i_1}^{\alpha_1} u_1 \cdots t_{i_\ell}^{\alpha_\ell} u_\ell$ and $v = v_0 t_{j_1}^{\beta_1} v_1 \cdots t_{j_m}^{\beta_m} v_m$. The first statement is obvious due to the fact that $[\mathscr{T}](u)$ does not contain a subword of the form $t_{i,k}^{\alpha} w t_{i,k}^{\beta}$ for $k \in \{0,1\}$, and similarly for $[\mathscr{T}](v)$.

For $(a) \Rightarrow (b)$ assume that u = v in $\langle H, t_1, \ldots, t_n | a^{t_i} = \varphi_i(a)$ $(1 \le i \le n, a \in A) \rangle$. Lemma 6.4 implies $\pi_t(u) = \pi_t(v)$ (i.e., $\ell = m$, $\alpha_1 = \beta_1, \ldots, \alpha_m = \beta_m$, $i_1 = j_1, \ldots, i_m = j_m$), and that there exists a van Kampen diagram of the following form:



The relators of G' imply that the following is a valid van Kampen diagram in G':



Hence, $\llbracket \mathscr{T} \rrbracket(u) = \llbracket \mathscr{T} \rrbracket(v)$ in G'.

For $(b) \Rightarrow (a)$ assume that $[[\mathscr{T}]](u) = [[\mathscr{T}]](v)$ in G' and $\pi_t(u) = \pi_t(v)$. We have already argued that $[[\mathscr{T}]](u)$ and $[[\mathscr{T}]](v)$ are Britton-reduced. Hence, $[[\mathscr{T}]](u) =$ $[[\mathscr{T}]](v)$ in G' implies that there exists a van Kampen diagram of the form (\ddagger) . Since $\pi_t(u) = \pi_t(v)$ we can obtain a diagram of the form (\dagger) by replacing the dark-shaded *t*-faces in (\ddagger) by the corresponding *t*-faces of *G*. This proofs the claim.

By the previous claim, $[\mathscr{T}](val(\mathbb{A}))$ and $[\mathscr{T}](val(\mathbb{B}))$ are Britton-reduced. Moreover, SLPs \mathbb{A}' and \mathbb{B}' for these words can be computed in polynomial time by Theorem 3.10. In case $\pi_t(val(\mathbb{A})) \neq \pi_t(val(\mathbb{B}))$ (this can be checked in polynomial time by Proposition 3.9(4) and Theorem 3.17) we choose these SLPs such that e.g. $val(\mathbb{A}') = t_1$ and $val(\mathbb{B}') = t_1^{-1}$. Hence, $val(\mathbb{A}') = val(\mathbb{B}')$ in G' if and only if $val(\mathbb{A}) = val(\mathbb{B})$ in $\langle H, t_1, \ldots, t_n | a^{t_i} = \varphi_i(a)(1 \le i \le n, a \in A) \rangle$. This proves the lemma. \Box

Due to Lemma 6.11 it suffices to concentrate our effort on problems of the form $\mathsf{RCWP}(H, A, B, \varphi_1, \dots, \varphi_k)$, where $k \leq \delta$. Let

$$G_0 = \langle H, t_1, \dots, t_k \mid a^{t_i} = \varphi_i(a) \ (1 \le i \le k, a \in A) \rangle$$

$$(6.7)$$

and let us choose $i \in \{1, ..., k\}$ such that $|\text{dom}(\varphi_i)|$ is maximal. Without loss of generality assume that i = 1. Let $\text{dom}(\varphi_1) = A_1 \leq A$ and let $B_1 = \varphi_1(A_1) \leq B$ be the range of φ_1 . We write *t* for t_1 in the following and define

$$\Gamma = \Sigma \cup \{t_2, \ldots, t_k\}.$$

We can write our HNN-extension G_0 from (6.7) as

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$$G_0 = \langle K, t \mid a^t = \varphi_1(a) \ (a \in A_1) \rangle, \tag{6.8}$$

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where

$$K = \langle H, t_2, \dots, t_k \mid a^{t_i} = \varphi_i(a) \ (2 \le i \le k, a \in A) \rangle.$$
(6.9)

The latter group *K* is generated by Γ . We may have k = 1 in which case K = H. The goal of the next three Sections 6.5–6.7 is to prove the following crucial lemma:

Lemma 6.12. RCWP $(H,A,B,\varphi_1,...,\varphi_k)$ is polynomial time Turing-reducible to the problems RCWP $(H,A,B,\varphi_2,...,\varphi_k)$ and RUCWP (A_1,A_1,A_1) .

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Our aim in this subsection will be to reduce the compressed word problem for G_0 from (6.8) to the compressed word problem for another group, where we have abstracted from most of the concrete structure of the base group *K* in (6.9).

Let us consider an input (\mathbb{A}, \mathbb{B}) for RCWP $(H, A, B, \varphi_1, \dots, \varphi_k)$ with $k \leq \delta$. Without loss of generality assume that $k = \delta$. Thus, \mathbb{A} and \mathbb{B} are SLPs over the alphabet $\Sigma \cup \Sigma^{-1} \cup \{t_1, t_1^{-1}, \dots, t_{\delta}, t_{\delta}^{-1}\} = \Gamma \cup \Gamma^{-1} \cup \{t, t^{-1}\}$ with $\mathsf{val}(\mathbb{A}), \mathsf{val}(\mathbb{B}) \in \mathsf{Red}(H, \varphi_1, \dots, \varphi_{\delta})$. Hence, we also have $\mathsf{val}(\mathbb{A}), \mathsf{val}(\mathbb{B}) \in \mathsf{Red}(K, \varphi_1)$.

Without loss of generality we may assume that $\pi_t(val(\mathbb{A})) = \pi_t(val(\mathbb{B}))$. This property can be checked in polynomial time using Proposition 3.9(4) and Theorem 3.17. If it is not satisfied then we have $val(\mathbb{A}) \neq val(\mathbb{B})$ in G_0 . Hence, there are $m \geq 0, \alpha_1, \ldots, \alpha_m \in \{1, -1\}$, and words $u_0, v_0 \ldots, u_m, v_m \in (\Gamma \cup \Gamma^{-1})^*$ such that

$$\mathsf{val}(\mathbb{A}) = u_0 t^{\alpha_1} u_1 \cdots t^{\alpha_m} u_m \text{ and }$$
(6.10)

$$\mathsf{val}(\mathbb{B}) = v_0 t^{\alpha_1} v_1 \cdots t^{\alpha_m} v_m. \tag{6.11}$$

One might think that the number of different words u_i (respectively, v_i) may grow exponentially in the size of \mathbb{A} (respectively, \mathbb{B}). But we will see that this is actually not the case.

Let us replace every occurrence of t^{α} ($\alpha \in \{1, -1\}$) in \mathbb{A} and \mathbb{B} by $aa^{-1}t^{\alpha}aa^{-1}$, where $a \in \Gamma$ is arbitrary. This is to ensure that any two occurrences of symbols from $\{t, t^{-1}\}$ are separated by a non-empty word over $\Gamma \cup \Gamma^{-1}$, i.e., we can assume that $u_0, v_0, \ldots, u_m, v_m \in (\Gamma \cup \Gamma^{-1})^+$ in (6.10) and (6.11).

Our first goal is to transform \mathbb{A} (and similarly \mathbb{B}) into an equivalent SLP that generates in a first phase a word of the form $X_0 t^{\alpha_1} X_1 \cdots t^{\alpha_m} X_m$, where X_i is a further variable that generates in a second phase the word $u_i \in (\Gamma \cup \Gamma^{-1})^+$. This is similar to the notion of a 2-level PCSLP from Definition 3.24. Assume that the SLP $\mathbb{A} = (U, \{t, t^{-1}\} \cup \Gamma \cup \Gamma^{-1}, S, \text{rhs})$ is in Chomsky normal form.

In a first step, we remove every variable $X \in U$ from \mathbb{A} such that $rhs(X) \in \{t, t^{-1}\}$ by replacing X in all right-hand sides of \mathbb{A} by rhs(X). Now, all right-hand sides of \mathbb{A} are of the form YZ, $t^{\alpha}Z$, Yt^{α} , or $x \in \Gamma \cup \Gamma^{-1}$, where $Y, Z \in U$.

Next we split the set U of variables of \mathbb{A} into two parts:

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$$U_K = \{X \in U \mid \mathsf{val}(X) \in (\Gamma \cup \Gamma^{-1})^+\}$$
 and $U_t = U \setminus U_K^0$

The subscript K refers to the fact that every variable from U_K defines an element from the new base group $K \leq G_0$, whereas the subscript t refers to the fact that every variable from U_t generates a word where K-generators as well as t or t^{-1} occurs.

Now we manipulate all right-hand sides for variables from U_t in a bottom-up process. Thereby we add further variables to U_K , whereas the set U_t will not change. At each stage, the tuple

$$\mathbb{A}_t := (U_t, \{t, t^{-1}\} \cup U_K, S, \mathsf{rhs}|_{U_t})$$

is a CSLP that generates a word from $(U_K)^+ t^{\alpha_1} (U_K)^+ \cdots t^{\alpha_m} (U_K)^+$.

Consider a variable $X \in U_t$ such that every variable in u := rhs(X) is already processed, but X is not yet processed. If u is of the form $t^{\alpha}Z$ or Yt^{α} , then there is nothing to do. Now assume that u = YZ such that Y and Z are already processed. Consider the last symbol $\omega \in \{t, t^{-1}\} \cup U_K$ of $\mathsf{val}_{\mathbb{A}_t}(Y)$ and the first symbol $\alpha \in$ $\{t, t^{-1}\} \cup U_K$ of val_A(Z) (these symbols can be computed in polynomial time). If either $\omega \in \{t, t^{-1}\}$ or $\alpha \in \{t, t^{-1}\}$, then again nothing is to do. Otherwise, $\omega, \alpha \in \{t, t^{-1}\}$ U_K . We now set $U_K := U_K \cup \{X'\}$, where X' is a fresh variable with $rhs(X') = \omega \alpha$. Finally, we redefine $\operatorname{rhs}(X) := Y[: \ell - 1]X'Z[2:]$, where $\ell = |\operatorname{val}_{\mathbb{A}_t}(Y)|$.

When all variables from U_t are processed, we transform the final CSLP A_t in polynomial time into an equivalent SLP using Theorem 3.14. Let us denote this SLP again by \mathbb{A}_t . Moreover, let

$$\mathbb{A}_K := (U_K, \Gamma \cup \Gamma^{-1}, \mathsf{rhs}|_{U_k}).$$

This is an SLP without initial variable. The construction implies that

$$\mathsf{val}(\mathbb{A}_t) = X_0 t^{\alpha_1} X_1 \cdots t^{\alpha_m} X_m \tag{6.12}$$

with $X_0, \ldots, X_m \in U_K$ and $\operatorname{val}_{\mathbb{A}_K}(X_k) = u_i$. Note that the number of different X_i is polynomially bounded, simply because the set U_K was computed in polynomial time. Hence, also the number of different u_i in (6.10) is polynomially bounded.

For the SLP \mathbb{B} the same procedure yields the following data:

- An SLP B_t = (V_t, {t,t⁻¹} ∪ V_K, S, rhs ↾_{V_t}) such that val(B_t) = Y₀t^{α₁}Y₁ ··· t^{α_m}Y_m.
 An SLP B_K = (V_K, Γ ∪ Γ⁻¹, rhs ↾_{V_k}) without initial variable such that Y₁,..., Y_m ∈ V_K and $\operatorname{val}_{\mathbb{B}_K}(Y_i) = v_i$.

Without loss of generality assume that $U_K \cap V_K = \emptyset$. Let $W_K = U_K \cup V_K$. We assume that we have a single right-hand side mapping rhs with domain $U_t \cup V_t \cup U_K \cup V_K$. Let $\mathbb{C} = (W_K, \Gamma \cup \Gamma^{-1}, \operatorname{rhs}_{W_K})$, In the following, for $Z \in W_K$ we write $\operatorname{val}(Z)$ for $\operatorname{val}_{\mathbb{C}}(Z) \in (\Gamma \cup \Gamma^{-1})^+.$

Let us next consider the free product $F(W_K) * A_1 * B_1$. Recall that A_1 (respectively, B_1) is the domain (respectively, range) of the partial isomorphism φ_1 . Clearly, in this free product, A_1 and B_1 have trivial intersection (even if $|A_1 \cap B_1| > 1$ in H). We now

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define the finite set of relators

$$\mathscr{E} = \{ Z_1 c_1 Z_2^{-1} c_2^{-1} \mid Z_1, Z_2 \in W_K, c_1, c_2 \in A_1 \cup B_1, \mathsf{val}(Z_1) c_1 = c_2 \mathsf{val}(Z_2) \text{ in } K \}.$$
(6.13)

We can compute the set \mathscr{E} in polynomial time using oracle access to $\mathsf{CWP}(K)$ or alternatively, by Lemma 6.10, using oracle access to $\mathsf{RCWP}(H,A,B,\varphi_2,\ldots,\varphi_k)$. This is the only step, where we need oracle access to $\mathsf{RCWP}(H,A,B,\varphi_2,\ldots,\varphi_k)$ in the proof of Lemma 6.12. Note that the relator $Z_1c_1Z_2^{-1}c_2^{-1}$ stands for the relation $Z_1c_1 = c_2Z_2$.

Consider the group

$$G_{1} = \langle F(W_{K}) * A_{1} * B_{1}, t | \mathscr{E}, t^{-1}at = \varphi_{1}(a) (a \in A_{1}) \rangle$$

= $\langle (F(W_{K}) * A_{1} * B_{1}) / N, t | a^{t} = \varphi_{1}(a) (a \in A_{1}) \rangle$,

where

$$N = \langle \mathscr{E} \rangle^{F(W_K) * A_1 * B_1}$$

is the normal closure of \mathscr{E} in $F(W_K) * A_1 * B_1$. We can define a homomorphism

$$\psi: F(W_K) * A_1 * B_1 \to K$$

by $\psi(Z) = \operatorname{val}(Z)$ for $Z \in W_K$, $\psi(a) = a$ for $a \in A_1$, and $\psi(b) = b$ for $b \in B_1$. Of course, the restrictions of ψ to A_1 as well as B_1 are injective. Moreover, for every relator $Z_1c_1Z_2^{-1}c_2^{-1} \in \mathscr{E}$ we have $\psi(Z_1c_1Z_2^{-1}c_2^{-1}) = \operatorname{val}(Z_1)c_1\operatorname{val}(Z_2)^{-1}c_2^{-1} = 1$ in *K*. Thus, ψ defines a homomorphism

$$\widehat{\psi}: (F(W_K) * A_1 * B_1)/N \to K.$$

Moreover, $A_1 \cap N = 1$: If $a \in N \cap A_1$ then $\psi(a) \in \psi(N) = 1$; thus a = 1, since ψ is injective on A_1 . Similarly, $B_1 \cap N = 1$. This means that A_1 and B_1 can be naturally embedded in $(F(W_K) * A_1 * B_1)/N$ and $\varphi_1 : A_1 \to B_1$ can be considered as an isomorphism between the images of this embedding in $(F(W_K) * A_1 * B_1)/N$. Therefore, the above group G_1 is an HNN-extension with base group $(F(W_K) * A_1 * B_1)/N \leq G_1$. Moreover, $\hat{\psi} : (F(W_K) * A_1 * B_1)/N \to K$ can be lifted to a homomorphism

$$\widehat{\psi}: G_1 \to G_0 = \langle K, t \mid a^t = \varphi_1(a) \ (a \in A_1) \rangle.$$

Here, G_0 is from (6.8).

The idea for the construction of G_1 is to abstract as far as possible from the concrete structure of the original base group *K*. We only keep those *K*-relations that are necessary to prove (or disprove) that $val(\mathbb{A}) = val(\mathbb{B})$ in the group G_0 . These are the relators from \mathscr{E} .

Lemma 6.13. We have $val(\mathbb{A}_t)$, $val(\mathbb{B}_t) \in Red((F(W_K) * A_1 * B_1)/N, \varphi_1)$.

Proof. Recall that $val(\mathbb{A})$, $val(\mathbb{B}) \in \text{Red}(K, \varphi_1)$. Consider for instance a factor $t^{-1}X_i t$ of $val(\mathbb{A}_t)$ from (6.12). If $X_i = a$ in $(F(W_K) * A_1 * B_1)/N$ for some $a \in A_1$, then after

applying $\widehat{\psi}$ we have $val(X_i) = u_i = a$ in *K*. Hence, $val(\mathbb{A})$ from (6.10) would not be Britton-reduced. \Box

Lemma 6.14. The following statements are equivalent:

(a) $\operatorname{val}(\mathbb{A}) = \operatorname{val}(\mathbb{B})$ in G_0 from (6.8). (b) $\operatorname{val}(\mathbb{A}_t) = \operatorname{val}(\mathbb{B}_t)$ in G_1

Proof. For $(b) \Rightarrow (a)$ assume that $val(\mathbb{A}_t) = val(\mathbb{B}_t)$ in G_1 . We obtain in G_0 : $val(\mathbb{A}) = \widehat{\psi}(val(\mathbb{A}_t)) = \widehat{\psi}(val(\mathbb{B}_t)) = val(\mathbb{B})$.

For $(a) \Rightarrow (b)$ assume that $val(\mathbb{A}) = val(\mathbb{B})$ in the group G_0 . Since $val(\mathbb{A})$ and $val(\mathbb{B})$ are Britton-reduced and $\pi_t(val(\mathbb{A})) = \pi_t(val(\mathbb{B}))$, we obtain a van Kampen diagram of the form:



In this diagram, we can replace every light-shaded face, representing the *K*-relation $u_ic_{2i+1} = c_{2i}v_i$, by a face representing the valid \mathscr{E} -relation $X_ic_{2i+1} = c_{2i}Y_i$, see (6.13). We obtain the following van Kampen diagram, which shows that $val(\mathbb{A}_t) = val(\mathbb{B}_t)$ in G_1 :



This proves the lemma. \Box

By Lemma 6.14, it remains to check, whether $val(\mathbb{A}_t) = val(\mathbb{B}_t)$ in the HNN-extension G_1 , where $val(\mathbb{A}_t)$ and $val(\mathbb{B}_t)$ are both Britton-reduced.

6.6 Eliminating letters from $B_1 \cup \{t, t^{-1}\}$

Recall the Tietze transformations from Section 2.3. We can use the defining relations $b = t^{-1}\varphi_1^{-1}(b)t$ ($b \in B_1 \setminus \{1\}$) of G_1 for Tietze transformations of type 4. For this, note that $A_1 \cap B_1 = \{1\}$ in the group $F(W_K) * A_1 * B_1$. In this way we eliminate in the group G_1 the generators from $B_1 \setminus \{1\}$. After this transformation, we may have apart from relations of the form

$$Z_1 a_1 = a_2 Z_2 \text{ with } a_1, a_2 \in A_1 \tag{6.14}$$

6.6 Eliminating letters from $B_1 \cup \{t, t^{-1}\}$

also defining relations of the forms

$$Z_1 t^{-1} a_1 t = a_2 Z_2$$

$$Z_1 a_1 = t^{-1} a_2 t Z_2$$

$$Z_1 t^{-1} a_1 t = t^{-1} a_2 t Z_2,$$

where $a_1, a_2 \in A_1$ (here and in the following, we implicitly assume all valid relations $a_1a_2 = a$ to get the structure of the free factor A_1). We can replace these relations by relations of the following types

$$Z_1 t^{-1} a_1 = a_2 Z_2 t^{-1} \tag{6.15}$$

$$tZ_1a_1 = a_2 tZ_2 (6.16)$$

$$tZ_1t^{-1}a_1 = a_2tZ_2t^{-1} (6.17)$$

and end up with the group

$$G_2 = \langle F(W_K) * A_1, t \mid (6.14) - (6.17) \rangle$$

that is isomorphic to G_1 . Let us now introduce for every $Z \in W_K$ the new generators

$$[Zt^{-1}], [tZ], [tZt^{-1}]$$

together with the defining relations

$$[Zt^{-1}] = Zt^{-1}, \ [tZ] = tZ, \ [tZt^{-1}] = tZt^{-1}.$$
(6.18)

Formally, we make a Tietze-type-3 transformation. This allows to replace the defining relations (6.15)-(6.17) by

$$[Z_1 t^{-1}]a_1 = a_2 [Z_2 t^{-1}] (6.19)$$

$$\begin{bmatrix} tZ_1 \end{bmatrix} a_1 = a_2 \begin{bmatrix} tZ_2 \end{bmatrix}$$
(6.20)
$$\begin{bmatrix} zZ_1 t^{-1} \end{bmatrix} a_1 = a_2 \begin{bmatrix} tZ_2 t^{-1} \end{bmatrix}$$
(6.21)

$$[tZ_1t^{-1}]a_1 = a_2[tZ_2t^{-1}] (6.21)$$

leading to the group

$$G_3 = \langle F(\{Z, [Zt^{-1}], [tZ], [tZt^{-1}] | Z \in W_K\}) * A_1, t \mid (6.14), (6.18) - (6.21) \rangle.$$
(6.22)

Finally, we can eliminate t and t^{-1} by replacing (6.18) by

$$[tZ] = [Zt^{-1}]^{-1}Z^2, \ [tZt^{-1}] = [tZ]Z^{-1}[Zt^{-1}], \tag{6.23}$$

which is a Tietze-type-4 transformation. It yields the group

$$G_4 = \langle F(\{Z, [Zt^{-1}], [tZ], [tZt^{-1}] \mid Z \in W_K\}) * A_1 \mid (6.14), (6.19) - (6.21), (6.23) \rangle.$$



Fig. 6.3 The transitions of the deterministic rational transducer \mathcal{T} .

Since each transformation from G_1 to G_4 is a Tietze transformation, G_1 is isomorphic to G_4 . We now want to rewrite the SLPs \mathbb{A}_t and \mathbb{B}_t into new SLPs over the generators of G_4 . This can be done with a deterministic rational transducer \mathscr{T} that reads a word $X_0 t^{\alpha_1} X_1 t^{\alpha_2} X_2 \cdots t^{\alpha_m} X_m$ from the input tape, where \$ is an end marker and

- replaces every occurrence of a factor tX_i with $\alpha_{i+1} \neq -1$ by the symbol $[tX_i]$,
- replaces every occurrence of a factor $X_i t^{-1}$ with $\alpha_i \neq 1$ by the symbol $[X_i t^{-1}]$, and finally
- replaces every occurrence of a factor tX_it^{-1} by the symbol $[tX_it^{-1}]$.

The set of states of the transducer \mathscr{T} is $\{\varepsilon, t, q_f\} \cup \{Z, tZ \mid Z \in W_K\}$, and the transitions are shown in Figure 6.3 (for all $Z, Z' \in W_k$). The initial state is ε and the unique final state is q_f . By Theorem 3.10 we can construct in polynomial time SLPs that generate the words $[[\mathscr{T}]](val(\mathbb{A}_t)\$)$ and $[[\mathscr{T}]](val(\mathbb{B}_t)\$)$.

Let G_5 be the group that is obtained by removing the relations (6.23) in the above presentation of the group G_4 , i.e.,

$$G_5 = \langle F(\{Z, [Zt^{-1}], [tZ], [tZt^{-1}] \mid Z \in W_K\}) * A_1 \mid (6.14), (6.19) - (6.21) \rangle.$$
(6.24)

Lemma 6.15. The following statements are equivalent:

(a) $\operatorname{val}(\mathbb{A}) = \operatorname{val}(\mathbb{B})$ in G_0 (b) $\operatorname{val}(\mathbb{A}_t) = \operatorname{val}(\mathbb{B}_t)$ in G_1 (c) $[[\mathcal{T}]](\operatorname{val}(\mathbb{A}_t)\$) = [[\mathcal{T}]](\operatorname{val}(\mathbb{B}_t)\$)$ in G_4 (d) $[[\mathcal{T}]](\operatorname{val}(\mathbb{A}_t)\$) = [[\mathcal{T}]](\operatorname{val}(\mathbb{B}_t)\$)$ in G_5

Proof. The equivalence of (a) and (b) was stated in Lemma 6.14. The equivalence of (b) and (c) is clear since G_1 and G_4 are isomorphic and the transducer \mathscr{T} rewrites a word over the generators of G_1 into a word over the generators of G_4 . Moreover, (d)

6.6 Eliminating letters from $B_1 \cup \{t, t^{-1}\}$

implies (c) because we omit one type of relations, namely (6.23), when going from G_5 to G_4 . It remains to prove that (a) implies (d). If $val(\mathbb{A}) = val(\mathbb{B})$ in G_0 , then, as argued in the proof of Lemma 6.14, we obtain a van Kampen diagram of the form (\bigstar) (page 120) in the group G_1 . The boundary of every light-shaded face is labeled with a relation from \mathscr{E} . We obtain a van Kampen diagram for $[[\mathscr{T}]](val(\mathbb{A}_t)\$) = [[\mathscr{T}]](val(\mathbb{B}_t)\$)$ in G_5 by removing all vertical edges that connect (i) target nodes of *t*-labeled edges or (ii) source nodes of t^{-1} -labeled edges. The boundary cycle of every remaining face is labeled with a relator of type (6.14) or (6.19)–(6.21), which are the relators of G_5 . An example is shown below. \Box

Example 6.16. Let us give an example of the transformation from a diagram of the form (\bigstar) into a van Kampen diagram for the group G_5 . Assume that the diagram in G_1 is:



Then we obtain the following van Kampen diagram in the group G_5 :



Only the relations (6.14) and (6.19)–(6.21) are used in this diagram.

For the further considerations, we denote the SLPs for the words $[[\mathscr{T}]](val(\mathbb{A}_t)\$)$ and $[[\mathscr{T}]](val(\mathbb{B}_t)\$)$ again with \mathbb{A} and \mathbb{B} , respectively. It remains to check whether $val(\mathbb{A}) = val(\mathbb{B})$ in G_5 . Let

$$\mathscr{Z} = \{Z, [Zt^{-1}], [tZ], [tZt^{-1}] \mid Z \in W_K\}$$

and let us redefine the set of defining relations \mathscr{E} as the set of all defining relations of the form (6.14), (6.19)–(6.21). Thus,

$$G_5 = \langle F(\mathscr{Z}) * A_1 \mid \mathscr{E} \rangle,$$

where every defining relation in \mathscr{E} is of the form $Z_1a_1 = a_2Z_2$ for $Z_1, Z_2 \in \mathscr{Z}$ and $a_1, a_2 \in A_1$.

6.7 Transforming G₅ into an HNN-Extension

By further Tietze transformations we show that the group $G_5 = \langle F(\mathscr{Z}) * A_1 | \mathscr{E} \rangle$ is an HNN-extension with the base group A_1 and associated subgroups A_1 and A_1 . This will prove Lemma 6.12. To this end, let us take a relation $Z_1a_1 = a_2Z_2$ with $Z_1 \neq Z_2$. With a Tietze-type-4 transformation we can eliminate Z_2 by replacing it with $a_2^{-1}Z_1a_1$. Subwords of the form aa' with $a, a' \in A_1$ that arise after this transformation can of course be multiplied out in the finite group A_1 . We carry out the same replacement $Z_2 \mapsto a_2^{-1}Z_1a_1$ also in the SLPs \mathbb{A} and \mathbb{B} , which increases the size of the SLPs only by an additive constant, and repeat these steps. After polynomially many Tietze transformations we obtain a group presentation, where all defining relations have the form $Z = a_1Za_2$, i.e. $a_2 = Z^{-1}a_1^{-1}Z$. We can write this group presentation as

 $G_6 = \langle A_1, Z_1, \dots, Z_m \mid Z_i^{-1} a Z_i = \psi_i(a) \ (1 \le i \le m, a \in \operatorname{dom}(\psi_i)) \rangle.$

Note that every mapping ψ_i is a partial automorphism on A_1 since it results from the conjugation by some element in our initial group. Hence, G_6 is indeed an HNN-extension over A_1 .

We can now finish the proof of Lemma 6.12.

Proof of Lemma 6.12. We have to show that the problem $\mathsf{RCWP}(H, A, B, \varphi_1, \ldots, \varphi_k)$ is polynomial time Turing-reducible to the problems $\mathsf{RCWP}(H, A, B, \varphi_2, \ldots, \varphi_k)$ and $\mathsf{RUCWP}(A_1, A_1, A_1)$. Using oracle access to the problem $\mathsf{RCWP}(H, A, B, \varphi_2, \ldots, \varphi_k)$ (which was necessary for computing the set of defining relations \mathscr{E} from (6.13)), we have computed in polynomial time from a given $\mathsf{RCWP}(H, A, B, \varphi_1, \ldots, \varphi_k)$ -instance an $\mathsf{UCWP}(A_1, A_1, A_1)$ -instance, which is a positive instance if and only if the original $\mathsf{RCWP}(H, A, B, \varphi_1, \ldots, \varphi_k)$ -instance is positive. A final application of Lemma 6.9 allows to reduce $\mathsf{UCWP}(A_1, A_1, A_1)$ to $\mathsf{RUCWP}(A_1, A_1, A_1)$. This proves Lemma 6.12. \Box

6.8 Final Step in the Proof of Theorem 6.7

We now apply Lemma 6.11 to the problem $\mathsf{RUCWP}(A_1, A_1, A_1)$ (one of the two target problems in Lemma 6.12). An input for this problem can be reduced in polynomial time to an instance of a problem $\mathsf{RCWP}(A_1, A_1, A_1, \psi_1, \dots, \psi_k)$, where $\psi_1, \dots, \psi_k : A_1 \to A_1$ and $k \leq 2|A_1|! \cdot 2^{|A_1|} \leq 2|A|! \cdot 2^{|A|} = \delta$. Our current HNN-extension is

$$G_7 = \langle A_1, t_1, \dots, t_k \mid a^{t_i} = \psi_i(a) \ (1 \le i \le k, a \in \operatorname{dom}(\psi_i)) \rangle.$$

We next separate the (constantly many) stable letters t_1, \ldots, t_k that occur in the RCWP($A_1, A_1, A_1, \psi_1, \ldots, \psi_k$)-instance into two sets: $\{t_1, \ldots, t_k\} = S_1 \cup S_2$ where $S_1 = \{t_i \mid \text{dom}(\psi_i) = A_1\}$ and $S_2 = \{t_1, \ldots, t_k\} \setminus S_1$. Without loss of generality assume that $S_2 = \{t_1, \ldots, t_\ell\}$. Then we can write the HNN-extension G_7 as

6.8 Final Step in the Proof of Theorem 6.7

$$G_7 = \langle H', t_1, \dots, t_\ell \mid a^{t_i} = \psi_i(a) \ (1 \le i \le \ell, a \in \operatorname{dom}(\psi_i)) \rangle, \tag{6.25}$$

where

$$H' = \langle A_1, t_{\ell+1}, \dots, t_k \mid a^{t_i} = \psi_i(a) \ (\ell+1 \le i \le k, a \in A_1) \rangle$$

Note that (i) $|\operatorname{dom}(\psi_i)| < |A_1|$ for every $1 \le i \le \ell$ and that (ii) $A_1 = \operatorname{dom}(\psi_i)$ for every $\ell + 1 \le i \le k$. By Lemma 6.8, $\operatorname{CWP}(H')$ can be solved in polynomial time. The group H' is in fact the semidirect product $A_1 \rtimes_{\varphi} F(t_{\ell+1}, \ldots, t_k)$, where the homomorphism $\varphi : F(t_{\ell+1}, \ldots, t_k) \to \operatorname{Aut}(A_1)$ is defined by $\varphi(t_i) = \psi_i$. Recall also that at the end of Section 6.4, A_1 was chosen to be of maximal cardinality among the domains of all partial isomorphisms $\varphi_1, \ldots, \varphi_k$. The following proposition summarizes what we have shown so far:

Proposition 6.17. Let $\varphi_1, \ldots, \varphi_k : A \to B$ be partial isomorphisms, where $k \leq \delta$, $A_1 = \operatorname{dom}(\varphi_1)$, and without loss of generality $|A_1| \geq |\operatorname{dom}(\varphi_i)|$ for $1 \leq i \leq k$. The problem RCWP($H, A, B, \varphi_1, \ldots, \varphi_k$) is polynomial time Turing-reducible to the following (constantly many) decision problems:

- (1) $\mathsf{RCWP}(H, A, B, \varphi_2, \dots, \varphi_k)$
- (2) $\mathsf{RCWP}(A_1 \rtimes_{\varphi} F, A_1, A_1, \psi_1, \dots, \psi_{\ell})$, where F is a free group of rank at most δ , $\varphi: F \to Aut(A_1)$ is a homomorphism, $\ell \leq \delta$, and $\psi_1, \dots, \psi_{\ell}: A_1 \to A_1$ are partial automorphisms with $|\mathsf{dom}(\psi_i)| < |A_1|$ for all $1 \leq i \leq \ell$

Note that indeed, in (2) there are only constantly many semidirect products of the form $A_1 \rtimes_{\varphi} F$ and that $\text{CWP}(A_1 \rtimes_{\varphi} F)$ can be solved in polynomial time by Lemma 6.8.

Now, we have all tools needed to prove the main theorem of this chapter:

Proof of Theorem 6.7. By Lemma 6.9 and Lemma 6.11 it suffices to solve a problem $\mathsf{RCWP}(H, A, B, \varphi_1, \dots, \varphi_k)$ (with $k \leq \delta$) in polynomial time. For this we apply Proposition 6.17 repeatedly, i.e., we apply Proposition 6.17 to the two target problems (1) and (2) from the proposition again. Note that in the target problems one of the two properties holds:

- The maximal size of an associated subgroup is smaller than in the input instance.
- The maximal size of an associated subgroup is the same as in the input instance but the number of stable letters is smaller than in the input instance.

This implies that after $|A| \cdot \delta = 2 \cdot |A| \cdot |A|! \cdot 2^{|A|}$ (which is a fixed constant) many applications of Proposition 6.17 we have reduced RCWP($H, A, B, \varphi_1, \ldots, \varphi_k$) to the problems CWP(H) and CWP($C \rtimes_{\varphi} F$), where $C \leq A, F$ is a free group of rank at most δ , and $\varphi : F \to \operatorname{Aut}(C)$ is a homomorphism. Note that this is still a polynomial time Turing-reduction, since the composition of a constant number of polynomial time Turing-reductions is again a polynomial time Turing-reduction. \Box

6.9 Amalgamated Products

In this section we prove a transfer theorem for the compressed word problem for an amalgamated free product, where the amalgamated subgroups are finite. We will deduce this result from our transfer theorem for HNN-extensions. Let us start with the definition of an amalgamated free product:

Definition 6.18 (amalgamated free product). Let H_1 and H_2 be two groups with subgroups $A_1 \leq H_1$ and $A_2 \leq H_2$. Let $\varphi : A_1 \mapsto A_2$ be an isomorphism. The *amal-gamated free product of* H_1 *and* H_2 , *amalgamating the subgroups* A_1 *and* A_2 *by the isomorphism* φ , is the group $G = \langle H_1 * H_2 | a = \varphi(a) \ (a \in A_1) \rangle$.

Theorem 6.19. Let $G = \langle H_1 * H_2 | a = \varphi(a) \ (a \in A_1) \rangle$ be an amalgamated free product of finitely generated groups G_1 and G_2 with $A_1 \leq G_1$ a finite subgroup. Then $\mathsf{CWP}(G) \leq_T^P \{\mathsf{CWP}(H_1), \mathsf{CWP}(H_2)\}.$

Proof. It is well known [119, Theorem 2.6, p. 187] that *G* can be embedded into the HNN-extension

$$G' := \langle H_1 * H_2, t \mid a^t = \varphi(a) \ (a \in A_1) \rangle$$

by the homomorphism Φ with

$$\Phi(x) = \begin{cases} t^{-1}xt & \text{if } x \in H_1 \\ x & \text{if } x \in H_2. \end{cases}$$

Given an SLP \mathbb{A} over generators of *G*, we can compute in polynomial time an SLP \mathbb{B} with val $(\mathbb{B}) = \Phi(val(\mathbb{A}))$, see Proposition 3.9(4). We obtain

$$\mathsf{val}(\mathbb{A}) = 1 \text{ in } G \iff \Phi(\mathsf{val}(\mathbb{A})) = 1 \text{ in } \Phi(G)$$
$$\iff \mathsf{val}(\mathbb{B}) = 1 \text{ in } G'.$$

By Theorem 6.7 and Corollary 5.5, CWP(G') is polynomial time Turing-reducible to the problems $CWP(H_1)$ and $CWP(H_2)$. \Box

Chapter 7 Outlook

We conclude this book with a few remarks about topics related to the compressed word problem for groups, which could not be covered for space reasons.

In this book, we focused on the compressed word problem for groups. But it makes perfectly sense to study the compressed word problem for finitely generated monoids as well. If *M* is a finitely generated monoid with a finite generating set Σ , then the compressed word problem for *M* asks, whether for given SLPs A and B over Σ , val(A) = val(B) holds in *M*. As for groups, the complexity of this problem is independent of the concrete generating set.

Implicitly, we have seen some complexity statements for compressed word problems for monoids. Theorem 3.17 states that the compressed word problem for a free monoid can be solved in polynomial time, and Lemma 5.24 generalizes this statement to trace monoids. In [113] it was shown that the compressed word problem for any finitely generated free inverse monoid of rank at least 2 is complete for the level Π_2^p of the polynomial time hierarchy. Inverse monoids are an important class of monoids that have inverses in a weaker sense than groups have, see [103]. The polynomial time hierarchy is a hierarchy of complexity classes between **P** and **PSPACE** that is believed to be proper. In particular, the class Π_2^p contains **NP** and **coNP**, and it is conjectured that these inclusions are proper. The ordinary word problem for a free inverse monoid can be solved in logarithmic space [115].

We have seen that the compressed word problem for a group G can be used in order to solve the word problem for the automorphism group Aut(G) (or a finitely generated subgroup of Aut(G)), see Theorem 4.6. Compression techniques can be also used in order to solve the word problem for the outer automorphism group Out(G) (the quotient of Aut(G) by the inner automorphism group, which consists of all conjugations $x \mapsto g^1 xg$ for $g \in G$). Schleimer proved in [151] that for a finitely generated free group F, the word problem for Out(F) can be solved in polynomial time. For this, he proved that a variant of the compressed conjugacy problem for F can be solved in polynomial time, for which he used a polynomial time pattern matching algorithm for compressed words, c.f. Section 3.4. In [74], Schleimer's result was generalized to graph groups and graph products.

In the proofs of Theorem 4.6–4.9, we basically used straight-line programs as a compact representation of long words that occur as intermediate data structures in algorithms. This leads to the idea of using other specialized succinct data structures to store intermediate results. In the context of word problems, we mentioned power circuits in Section 2.5. These are succinct representations of huge integers (towers of exponents). Power circuits were designed to solve the word probem in groups like the Baumslag-Gersten group BG(1,2) = $\langle a,b,t | bab^{-1} = t,tat^{-1} = a^2 \rangle$ or Higman's group $H_4 = \langle a_0, a_1, a_2, a_3 | a_1a_0a_1^{-1} = a_0^2, a_2a_1a_2^{-1} = a_1^2, a_3a_2a_3^{-1} = a_2^2, a_0a_3a_0^{-1} = a_3^2 \rangle$. In these groups, standard algorithms for HNN-extensions (Britton reduction) yield big powers a^n , and power circuits can be used to store the exponent *n* succinctly, see [53, 132]. An interesting project for future work might be to combine SLPs with power circuits, so that words of huge length (and not just singly exponential length as for SLPs) can be produced.

Apart from the solution of word problems, the formalism of straight-line programs turned out to be useful also for other algebraic decision problems, in particular for the solution of word equations. A word equation over a finitely generated monoid M (generated by the finite set Γ) is a pair of the form (U,V), where $U, V \in (\Gamma \cup X)^*$. Here, X is a finite set of variables. This word equation is *solvable* if there exists a mapping $\sigma: X \to \Gamma^*$ such that $\sigma(U) = \sigma(V)$ in *M*, where we extend σ to a morphism on $(\Gamma \cup X)^*$ by setting $\sigma(a) = a$ for $a \in \Gamma$. The mapping σ is called a solution of (U, V). In his seminal paper [123], Makanin proved that one can decide whether a given word equation over a free monoid is solvable, and in [140] he extended this result to free groups. Since the work of Makanin, the upper bound on the complexity of solvability of word equations (in free monoids and free groups) was improved several times. An important step was done by Plandowski and Rytter in [141]. To state their result, we need a few definitions (we always refer to equations in free monoids below). Let σ be a solution for a word equation (U, V). We say that σ is *minimal*, if for every solution σ' of (U,V) we have $|\sigma(U)| \leq |\sigma'(U)|$. We say that $|\sigma(U)|$ is the length of a minimal solution of (U, V).

Theorem 7.1 ([141]). Let (U,V) be a word equation and let n = |UV|. Assume that (U,V) has a solution and let N be the length of a minimal solution of (U,V). Then, for every minimal solution σ of (U,V), the word $\sigma(U)$ can be generated by an SLP of size $O(n^2 \log^2(N)(\log n + \log \log N))$.

Thus, minimal solutions for word equations are highly compressible.

In combination with other ingredients, Plandowski used Theorem 7.1 to show that solvability of word equations over a free monoid belongs to **PSPACE** [140]. This is the currently best known upper bound. Solvability of word equations in a free monoid is easily seen to be **NP**-hard, and it has been repeatedly conjectured that the precise complexity is **NP** too. In [91], Jeż applied his recompression technique from [88, 89] (see Section 3.4) to word equations and obtained an alternative **PSPACE**-algorithm for solving word equations over a free monoid. Gutiérrez [70] proved that solvability of word equations over free groups belongs to **PSPACE** as well. Further results regarding the compressibility of solutions of word equations can be found in [52].

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Acronyms and Notations

\leftrightarrow^*	equivalence relation generated by \rightarrow , see p. 2
\rightarrow_R	one-step rewrite relation, see p. 3 and 86
\vdash_M	transition relation between configurations of
	the Turing machine <i>M</i> , see p. 5
\leq_m^P	polynomial time many-one reducible, see p. 10
$<^{\log}_{m}$	logspace many-one reducible, see p. 10
\leq_{ha}^{P}	polynomial time bounded conjunctively reducible.
— bc	see p. 11
$\leq_{\rm hc}^{\rm log}$	logspace bounded conjunctively reducible, see
	p. 11
\leq^P_{T}	polynomial time Turing-reducible, see p. 11
\leq_p	prefix order on traces, see p. 85
\preceq_s	suffix order on traces, see p. 85
[a,b]	commutator of a and b, see p. 28
$\langle B \rangle$	subgroup generated by <i>B</i> , see p. 28
$\langle B \rangle^G$	normal closure of $B \subseteq G$, see p. 28
$H \wr G$	wreath product of H and G , see p. 78
$K \rtimes_{\varphi} Q$	semidirect product of K and Q, see p. 66
s	length of the word <i>s</i> , see p. 1
$ s _a$	number of occurrences of symbol a in the word
	<i>s</i> , see p. 1
S[i]	symbol at position <i>i</i> in <i>s</i> , see p. 1
s[i:j]	factor of <i>s</i> from position <i>i</i> to position <i>j</i> , see p. 1
s[i:]	suffix of <i>s</i> starting at position <i>i</i> , see p. 1
s[:j]	prefix of <i>s</i> ending at position <i>i</i> , see p. 1
$[S]_R$	equivalence class of <i>s</i> with respect to \leftrightarrow_R^* , see
	p. 3
$s[\Sigma_l,\Sigma_r]$	see p. 53
$[\![\mathscr{T}]\!]$	mapping computed by the deterministic ratio-
	nal transducer \mathscr{T} , see p. 46
$u \sqcap_p v$	prefix infimum of the traces <i>u</i> and <i>v</i> , see p. 85

138	Acronyms and Notations
$u \prod_{s} v$	suffix infimum of the traces u and v , see p. 85
$u \setminus_p v$	unique trace w such that $u = (u \sqcap_p v)w$, see
\{	p. 85
$u \setminus_{s} v$	unique trace w such that $u = w(u \sqcap_s v)$, see
	p. 85
$[w]_I$	trace represented by the word <i>w</i> , see p. 83
Γ^*	set of finite words over Γ and free monoid gen-
	erated by Γ , see p. 1
Γ^+	set of finite non-empty words over Γ , see p. 1
Γ^*/R	quotient of Γ^* by the semi-Thue system <i>R</i> , see
	p. 3
$\langle I R \rangle$	group presented by (T, R) , see p. 28
$[\Delta]_I$	trace represented by the independence clique
	Δ , see p. 84
E	empty word, see p. 1
π_{Δ}	projection homomorphism, see p. 41 and 85
accept	set of accepting configurations, see p. 5
$\operatorname{Aut}(C)$	set of fetters that occur in the word s, see p. 1 automorphism group of C , see p. 65
Aut(O)	automorphism group of O, see p. 05
BDD	bounded error probabilistic polynomial time
	see n 18
C-expression	see p. 42
C(M)	Coxeter group defined by the matrix M see
	p. 29
char(R)	characteristic of the ring <i>R</i> , see p. 19
coC	set of all complements of languages from the
	class C , see p. 9
coRP	co-randomized polynomial time, see p. 18
CSLP	straight-line program with cut, see p. 42
CWP(G)	compressed word problem for the group G , see
	p. 64
$CWP(G,\Gamma)$	compressed word problem for the group G with
	respect to the generating set Γ , see p. 63
D(a)	set of letter not commuting with <i>a</i> , see p. 83
$D_{\Gamma,R}$	Dehn function for the group presentation (Γ, R) ,
D	see p. 37
	dependence graph for the word w, see p. 84
	deterministic finite automaton, see p. 2
DSPACE())	class of languages that can be decided by an <i>j</i> -
	space bounded deterministic furning machine,
DTIME(f)	class of languages that can be decided by an
	f-time bounded deterministic Turing machine
	see n 8
	500 P. 0

Acronyms and Notations

$E[C_1,\ldots,C_n]$	see p. 86
$F(\Gamma)$	free group generated by Γ , see p. 27
G(A,I)	graph group defined by the graph (A, I) , see p. 29
$\mathbb{G}(W, E, (G_i)_{i \in W})$	graph product, see p. 82
$\operatorname{GL}_d(F)$	general linear group of dimension d over the field F , see p. 33
$graph(\mathscr{C})$	edge relation of the circuit \mathscr{C} , see p. 14
I(a)	set of letter commuting with <i>a</i> , see p. 83
init(x)	initial configuration for input <i>x</i> , see p. 5
$IRR(\rightarrow)$	set of irreducible elements with respect to the relation \rightarrow , see p. 3
IRR(R)	set of irreducible words or traces with respect
	to <i>R</i> , see p. 3 and 86
L	deterministic logspace, see p. 9
$L(\mathscr{A})$	language accepted by the NFA \mathscr{A} , see p. 2
L(M)	language accepted by the Turing machine M , see p. 6
$lo(\mathbb{A})$	lower part of the 2-level PCSLP \mathbb{A} , see p. 61
$\mathbb{M}(\Sigma, I)$	trace monoid defined by (Σ, I) , see p. 83
$\max(u)$	maximal symbols of the trace <i>u</i> , see p. 85
$\min(u)$	minimal symbols of the trace <i>u</i> , see p. 85
$NF \rightarrow (a)$	normal form of <i>a</i> with respect to the relation
	\rightarrow , see p. 3
$NF_{R}(s)$	normal form of <i>s</i> with respect to the semi-Thue
	system or trace rewrite system <i>R</i> , see p. 3 and 86
NFA	nondeterministic finite automaton, see p. 2
NL	nondeterministic logspace, see p. 9
NP	nondeterministic polynomial time, see p. 9
NSPACE(f)	class of languages that can be decided by an <i>f</i> -space bounded nondeterministic Turing ma-
	chine, see p. 8
NTIME(f)	class of languages that can be decided by an <i>f</i> -time bounded nondeterministic Turing ma-
	chine, see p. 8
Р	deterministic polynomial time, see p. 9
\mathscr{P}_{i}	simple paths in a dependence alphabet that
J	start at node <i>j</i> , see p. 99
PC-expression	see p. 42
PCSLP	straight-line program with projection and cut.
	see p. 42
PIT(R)	polynomial identity testing for the ring R see
(**)	n. 20
pos(s, J, i)	see p. 97
	~ r· / /

Acronyms and Notations

PSPACE	polynomial space, see p. 9
RAM	random access machine, see p. 24
$RCWP(H, A, B, \varphi_1, \dots, \varphi_n)$	see p. 112
$\operatorname{Red}(H, \varphi_1, \ldots, \varphi_n)$	set of Britton-reduced words, see p. 108
rhs	right-hand side mapping of a circuit, see p. 14
RP	randomized polynomial time, see p. 17
RUCWP(H,A,B)	see p. 112
SAT	boolean satisfiability problem, see p. 17
$SL_d(\mathbb{Z})$	special linear group of dimension d over the ring \mathbb{Z} , see p. 75
SLP	straight-line program, see p. 42
SUBSETSUM	subset sum problem, see p. 17
UCWP(H,A,B)	see p. 111
$up(\mathbb{A})$	upper part of the 2-level PCSLP A, see p. 61
val	evaluation mapping of the circuit \mathscr{C} in the algebra \mathscr{A} , see p. 14
Var(e)	variables that occur in the expression e , see p. 13
WP(G)	word problem for the group G, see p. 32
$WP(G,\Gamma)$	word problem for the group G with respect to the generating set Γ , see p. 32
WSP(G)	word search problem for the group G , see p. 40
$WSP(G,\Gamma)$	word search problem for the group G with re-
	spect to the generating set Γ , see p. 39
ZPP	zeror-error probabilistic polynomial time, see p. 18

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